Distinctive Characteristics

- Fully parallel, 8-bit data register and buffer replacing latches, multiplexers and buffers needed in microprocessor systems.
- 4.0V output high voltage for direct interface to MOS microprocessors, such as the Am9080A family.
- Input load current 250μA max.
- Reduces system package count

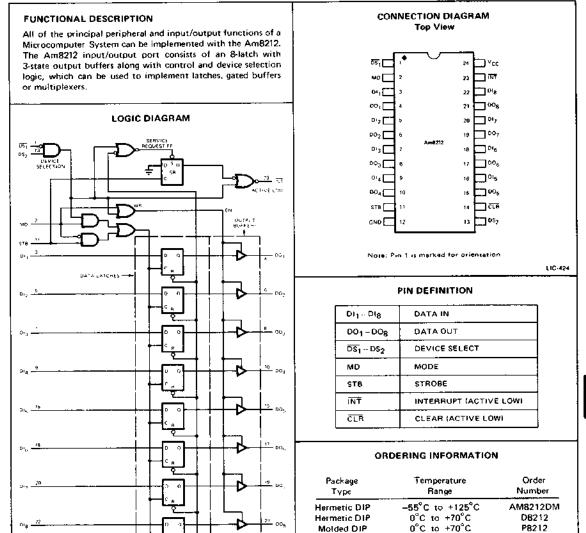
 Available for operation over both commercial and military temperature ranges.

0°C to +70°C

Dice

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- · Service request flip-flop for interrupt generation
- Three-state outputs sink 15mA
- Asynchronous register clear with clock over-ride



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AM8212XC

FUNCTIONAL DESCRIPTION (Cont'd)

Data Latch

The 8 flip-flops that make up the data latch are of a "D" type design. The output (Q) of the flip-flop will follow the data input (D) while the clock input (C) is high. Latching will occur when the clock (C) returns low.

The data (atch is cleared by an asynchronous reset input (CLR), (Note: Clock (C) Overrides Reset (CLR)).

Output Buffer

The outputs of the data latch (Q) are connected to 3-state, non-inverting output buffers. These buffers have a common control line (EN); this control line either enables the buffer to transmit the data from the outputs of the data latch (Q) or disables the buffer, forcing the output into a high impedance state. (3-state). This high-impedance state allows the Am8212 to be connected directly onto the microprocessor hidirectional data bus.

Control Logic

The Am8212 has control inputs DS₁, DS₂, MD and STB. These inputs are used to control device selection, data latching, output buffer state and service request flip-flop.

DS1, DS2 (Device Select)

These 2 inputs are used for device selection. When $\overline{DS_1}$ is low and $\overline{DS_2}$ is high ($\overline{DS_1} + \overline{DS_2}$) the device is selected. In the selected state the output buffer is enabled and the service request flip-flop (SR) is asynchronously set.

MD (Mode)

This input is used to control the state of the output buffer and to determine the source of the clock input (C) to the data larch.

When MD is high (output mode) the output buffers are enabled and the source of clock (C) to the data latch is from the device selection logic ($\overline{DS}_1 \cdot DS_2$).

When MD is low (input mode) the output buffer state is determined by the device selection logic $(\overline{DS}_1 \cdot DS_2)$ and the source of clock (C) to the data latch is the STB (Strobe) input.

STB (Strobe)

This input is used as the clock (C) to the data latch for the input mode MD = 0) and to synchronously reset the service request flip-flop (SR).

Note that the SR flip-flop is negative edge triggered.

Service Request Flip-Flop

The SR flip-flop is used to generate and control interrupts in microcomputer systems. It is asynchronously set by the CLR input (active low). When the (SR) flip-flop is set it is in the non-interrupting state.

The output of the (SR) flip-flop (Q) is connected to an inverting input of a "NOR" gate. The other input to the "NOR" gate is non-inverting and is connected to the device selection logic ($\overline{\rm DS}_1$ · DS₂). The output of the "NOR" gate ($\overline{\rm INT}$) is active low (interrupting state) for connection to active low input priority generating circuits.

TRUTH TABLE

STB	MD	DS ₁ - DS ₂	Data Out Equal	
0	0	0	Three-State	
1	0	0	Three-State	
0	1	0	Data Latch	
1	1	0	Data Latch	
٥	0	1	Dete Latch	
1	0	1	Data In	
0	1	1	Data in	
1	1	1	Data In	

CLR	DS ₁ - DS ₂	STB	SR*	INT
0	0	0	-	1
٥	1	0	1	0
t	1	$\overline{}$	0	0
1	1	0	1	0
1	0	0	1	1
1	1	~	1	0

CLR - Resets Data Latch

- Sets SR Flip-Flop (no effect on Output Buffer)

* Internal SR File Fice

MAXIMUM RATINGS (Above which the useful life may be impaired)

Storage Temperature	_65°C to +150°C
Temperature (Ambient) Under Bias	-55°C to +125°C
Supply Voltage	-0.5V to +7.0V
Output Voltage	-0.5V to +7.0V
Input Voltages	-1.0V to +5.5V
Output Current (Each Output)	125mA

ELECTRICAL CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (Unless Otherwise Noted)

P8212, D8212 (COM*L) Am8212DM (MIL)

 $T_A = 0^{\circ} C \text{ to } +70^{\circ} C$ TA - -55°C to +125°C V_{CC} = 5.0V ± 5% VCC = 5.0V ± 10%

DC CHARACTERISTICS

arameters	ACTERISTICS Description	Test Condit	ions	Min.	Typ. (Note 1)	Max.	Units
ıe	Input Load Current ACK, DS ₂ , CR, DI ₃ – DI ₈ Inputs	VF = 0.45V		,		-0.25	mA
1 _F	Input Load Current MD Input	VF = 0.45V				-0.75	mA
t _F	Input Load Current OS ₁ Input	Vε = 0.45V	· 		Ţ	-1.0	mA
1A	Input Leakage Current ACK, OS, CR, DI1 - DI8 Inputs	VA = 5.25V				10	Αų
¹R	Input Leakage Current MO Input	V _R = 5.25V	 -			30	μA
¹B	Input Leakage Current DS ₁ Input	VR = 5.25V				40	Aμ
		1 _C = -5.0mA	COM:L	T		-1.0	Volts
v _C	Input Forward Voltage Clamp		MIL			-1.2	
· -			COM.F		Γ΄	0.85	Volts
VIL	Input LOW Voltage		MIL			0.80	
V _{IH}	Input HIGH Voltage			2.0			Volts
VOL	Output LOW Voltage	IOL = 15mA				0.45	Volts
	Output HIGH Voltage	I _{OH} = 1.0mA	COM'L	3.65	4.0		Volus
Voн			MIL	3.3	4.0		
		IOH = -0.5mA	MIL	3 4	4.0		
1 _{SC}	Short Circuit Output Current	V _O = 0V		-15	1	-75	mA
hol	Output Leakage Current High Impedance	V _O = 0.45V/5.25V				20	μА
¹cc	Power Supply Current	Note 2		Τ-	90	130	mA

AC CHARACTERISTICS (Note 3)

C CHARACTERISTICS (Note 3)		Min.	Typ.	Max.	Units
arameters	Description	19901.	(Note 1)	IVIAA.	7
tpw	Pulse Width	30	8		ns
t _{pd}	Data to Output Delay		12	30	N5
twe	Write Enable to Output Delay		18	40	nş
tset	Data Set-up Time	15			ns
4h	Data Hold Time	20			nş
1,	Reset to Output Delay		18	40	ns
t _s	Set to Output Delay		15	30	ns.
te	Output Enable/Disable Time		14	45	ns
t _c	Clear to Gutput Delay		25	55	ns

CAPACITANCE (Note 4)

F = 1.0MHz, VRIAS = 2.5 V, VCC = +5.0 V, TA = 25 C

Parameters	Description	Typ.	Max.	Units
CIN	DS ₁ MD Input Capacitance	9.0	12	ρF
CIN	OS ₂ , CK, ACK, DI ₁ = DI ₈ Input Capacitance	5.0	9.0	ρF
COUT	DO ₁ - DO ₈ Output Capacitance	8.0	12	ρF

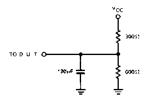
- Notes. 1. Typical limits are at V_{CC} = 5.0V. 25°C ambient and maximum loading.

 2. CLR = ST8 = HIGH; DS₁ = DS₂ = MD = LOW; all data inputs are gound, all data outputs are open.

 3. Conditions of Test: | all Input pulse ambitude = 2.5V
- - b) Input rise and fall times 5.0ns
 c) Between 1.0V and 2.0V measurements made at 1.5V with 15mA and 30pF Test Load.

4. This parameter is sampled and not 100% tested.

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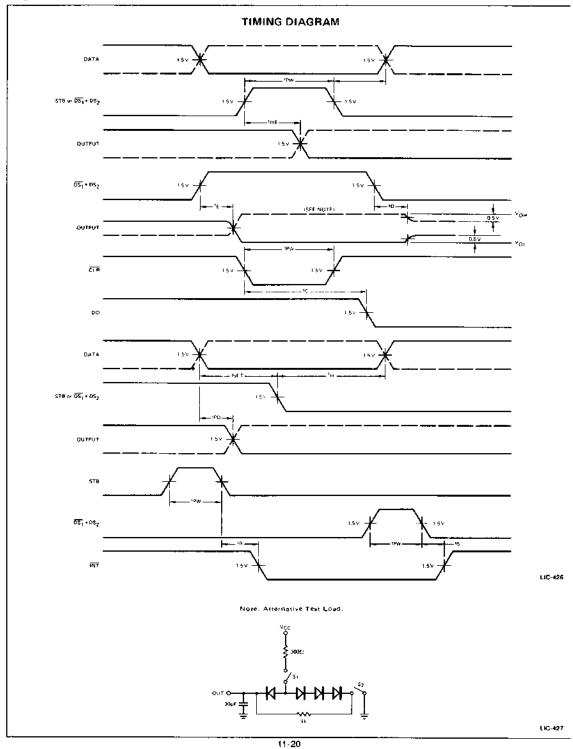


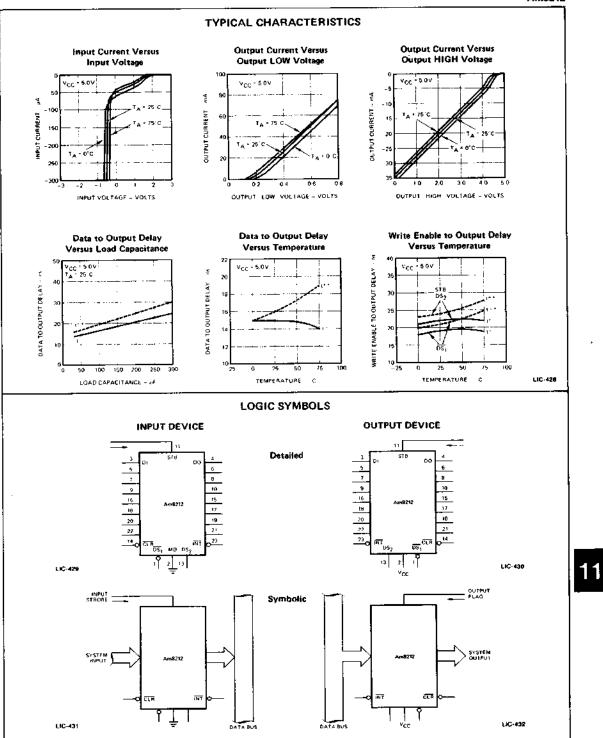
TEST LOAD (15mA and 30pF)

*Including Jig and Probe Capacitance.

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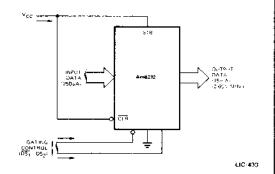
TYPICAL APPLICATIONS OF THE Am8212

GATED BUFFER (3-STATE)

By tying the mode signal low and the strobe input high, the data latch is acting as a straight through gate. The output buffers are then enabled from the device selection logic $\overline{\rm DS}_1$ and ${\rm DS}_2$.

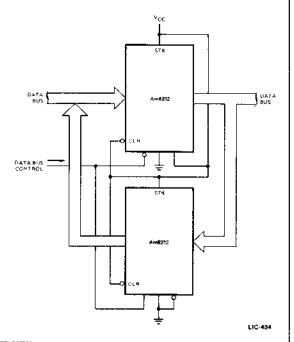
When the device selection logic is false, the outputs are 3-state.

When the device selection logic is true, the input data from the system is directly transferred to the output.



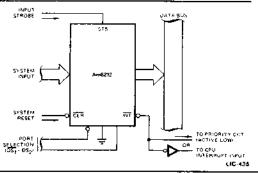
Bi-Directional Bus Driver

Two Am8212s wired back to back can be used as a symmetrical drive, bi-directional bus driver. The devices are controlled by the data bus input control which is connected to \overline{DS}_1 on the first Am8212 and to DS_2 on the second. While one device is active, and acting as a straight through buffer the other is in its 3-state mode.



Interrupting Input Port

The Am8212 accepts a strobe from the system input source, which in turn clears the service request flip-flop and interrupts the processor. The processor then goes through a service rouncine, identifies the port, and causes the device selection logic to go true — enabling the system input data onto the data bus.

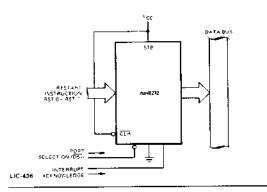


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TYPICAL APPLICATIONS OF THE Am8212 (Cont'd)

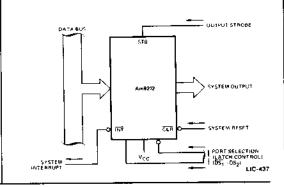
Interrupt Instruction Port

The Am8212 can be used to gate the interrupt instruction, normally RESTART instructions, onto the data bus. The device is enabled from the interrupt acknowledge signal from the microprocessor and from a port selection signal. This signal is normally tied to ground. $(\overline{DS1}$ could be used to multiplex a variety of interrupt instruction ports onto a common bus.)



Output Port (With Hand-Shaking)

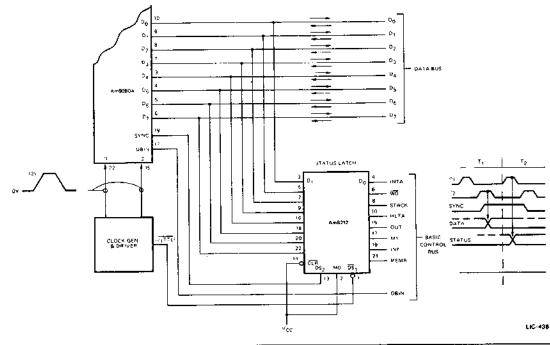
The Am8212 is used to transmit data from the data bus to a system output. The output strobe could be a hand-shaking signal such as "reception of data" from the device that the system is outputting to. It in turn, can interrupt the system signifying the reception of data. The selection of the port comes from the device selection logic. $\{\overline{\rm DS}_1-{\rm DS}_2.\}$



Am9080A Status Latch

The input to the Am8212 latch comes directly from the Am9080A data bus. Timing shows that when the SYNC signal is true $(\overline{DS}_1$ input), and ϕ 1 is true, $(\overline{DS}_1$ input) then the

status data will be latched into the Am8212. The mode signal is tied high so that the output on the latch is active and enabled all the time.



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