

IBM Field Engineering Education
Supplementary Course Material

SYSTEM/370

Model 165

Phase I

PREFACE

This publication is primarily intended for use by
FE customer engineers enrolled in course 50028.

Second Edition (May 1971)

This is a major revision of, and makes
SR23-3475-0 obsolete.

Address any comments concerning the contents of this publication to:
IBM, Field Engineering Education Media Development Center, Dept 927,
Rochester, Minnesota 55901

FIS Topics

- Introduction and Overview
- I-Unit
- E-Unit
- SCU
- Microdiagnostics
- Maintenance Console Maintenance

Lecture Topics

- Logout
- System Diagnostics
- System Maintenance
- Power
- Cooling
- PM
- M9A Storage Unit
- Console File
- Remote Analysis
- ECs (One Hour Lab to Support Prerequisite)
- NS Instructions
- Machine Language Program Applications
- Diagnostic Utilities

Figure 0-1 - Course Breakdown

Introduction and Overview

- Introduction
- System Components
- Maintenance Tools
- System Data Flow

I-Unit

- Functional Units
- Data Flow
- Error Analysis

E-Unit

- Functional Units
- Data Flow
- Error Analysis

SCU

- Functional Units
- Data Flow
- Display Capabilities
- Error Analysis

Maintenance Console Maintenance

Microdiagnostics

- Introduction
- Load Procedures
- Running and Error Analysis Procedures

Figure 0-2 - FIS Topics

The Model 165 is a large-scale, high-speed, general-purpose computing system with an internal performance of approximately two and a half times the Model 65, depending on the job stream. It offers high performance in both commercial and scientific applications. Fixed-point, floating-point, decimal, logical and I/O operations are performed as defined in System/360 Principles of Operation with the addition of extended precision floating-point, floating-point explicit rounding and the removal of operand boundary alignment restrictions for unprivileged operations. However, specifying off-boundary operands will result in severely reducing the speed of the system.

The Model 165 operates under OS/360, and can serve as a growth system for presently installed System/360 models. Upward compatibility (as defined in System/360 Principles of Operation) is maintained with all models of System/360.

The scientific and commercial throughput of the system is dependent on the size of main storage and high-speed buffer storage as well as the number, type and speed of the attached I/O devices.

Main storage for the Model 165 utilizes the M9A Basic Storage Module (BSM). A maximum of four M9A BSM can be housed in a 165 M9A storage frame. The M9A has a 2.0 microsecond cycle time.

Each 165 M9A storage frame can contain up to a maximum of 512 kilobytes. Frame capacity is determined by storage configuration. The available storage configurations for the 165 M9A storage are 500 kilobytes, 1.0 megabyte, 1.5 megabytes, 2.0 megabytes, and 3.0 megabytes.

All configurations are normally operated four-way interleaved but can be made two-way or serial under configuration control. To increase system throughput, all main storage references in the Model 165 are a doubleword, eight bytes wide, and instruction preparation is overlapped with instruction execution.

The Model 165 makes optimum use of the large main storage by means of a high-speed (C40) buffer storage in the storage control unit (SCU). The basic eight-kilobyte buffer storage retains main-storage data with which the CPU is currently working. The processor achieves high performance by working mostly with the high-speed buffer storage rather than with main storage. Buffer storage is transparent to the program.

The Model 165 also makes optimum use of the interleaved characteristic of its main storage in behalf of I/O operations by means of an I/O buffer in the SCU. The I/O buffer provides dedicated buffering for each attached channel, allowing pending channel requests to access main storage concurrently with other channel or CPU requests when vying for different logical storages.

I/O operations are carried out through the 2860 selector channel, the 2880 channel and the 2870 multiplexer channel via a single channel interface. The Model 165 channel interface allows attachment of two 2870s and any mix of 2860 and 2880 channels up to a total not exceeding seven addressable channels or five channel frames.

The high performance of the Model 165 is enhanced by the implementation of the logic in monolithic system technology (MST-4) circuitry. The system also uses a read only system storage (ROS), as well as a writable control storage (WCS) that provides residence for emulators and diagnostics.

Additional optional features include a high-speed multiply unit that allows faster fixed-point and floating-point multiply operations, 7074/7090 class emulators, an eight-kilobyte expansion of the high-speed buffer storage for a total of 16 kilobytes, and an additional channel feature allowing attachment of up to five additional addressable channels.

Fixed-length fields, such as halfwords and doublewords, must be located in main storage on an integral boundary for that unit of information. A boundary is called integral for a unit of information when its storage address is a multiple of the length of the unit in bytes. For example, words (four bytes) must be located in storage so that their address is a multiple of the number 4. A halfword (two bytes) must have an address that is a multiple of the number 2, and doublewords (eight bytes) must have an address that is a multiple of the number 8.

Storage addresses are expressed in binary form. In binary, integral boundaries for halfwords, words, and doublewords can be specified only by the binary addresses in which one, two, or three of the low-order bits, respectively, are zero (Figure 3). For example, the integral boundary for a word is a binary address in which the two low-order positions are zero.

Variable-length fields are not limited to integral boundaries, and may start on any byte location.

Figure 0-5 - Information Positioning

- Fix the CPU failures that are located by any type of card calling CE aid (microdiagnostics, FLT's, support documentation).
- Fix all power and cooling problems.
- Install all ECs.
- Fix all 2880 channel failures.
- Configure storage.
- Fix all M9A storage unit failures.
- Fix maintenance console mechanical failures, including both microfiche viewers and the minnow file.

Figure 1-1 - Job Responsibilities

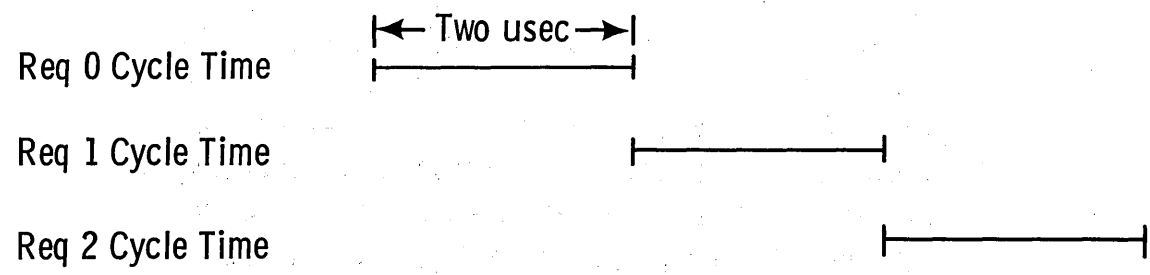
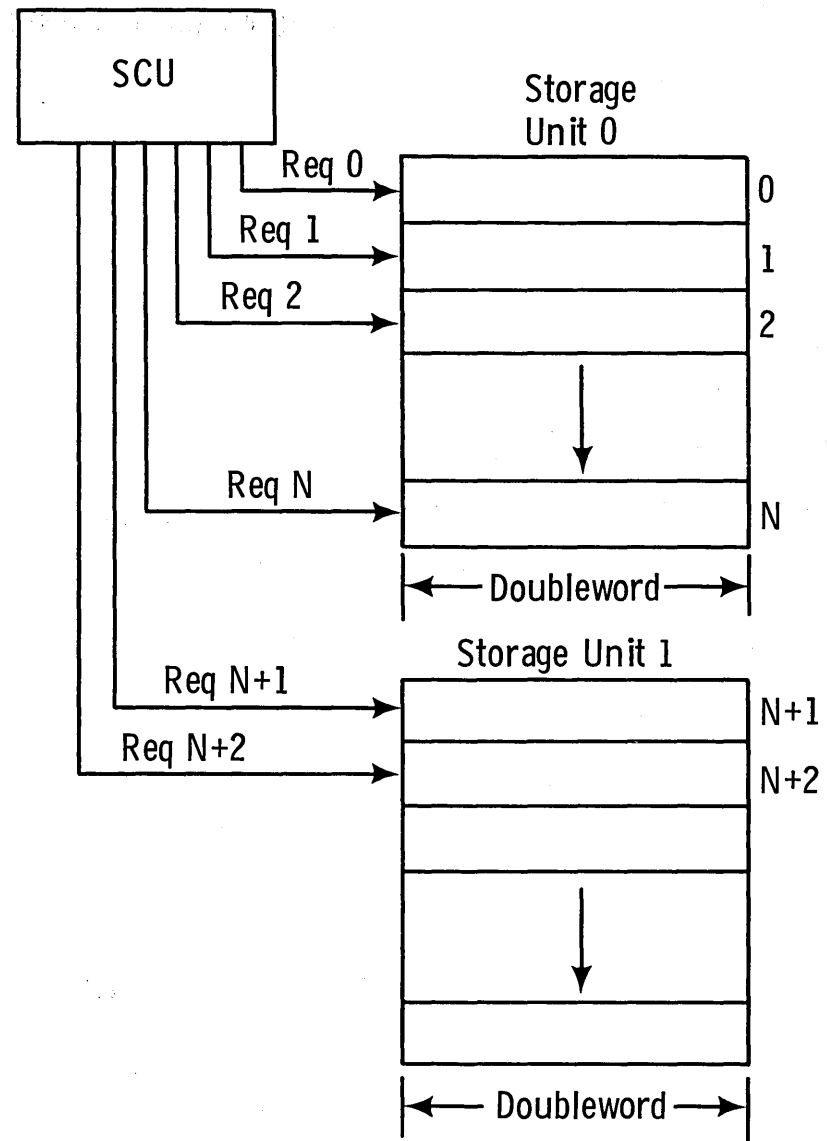


Figure 1-2 - Storage Addressing Number 1

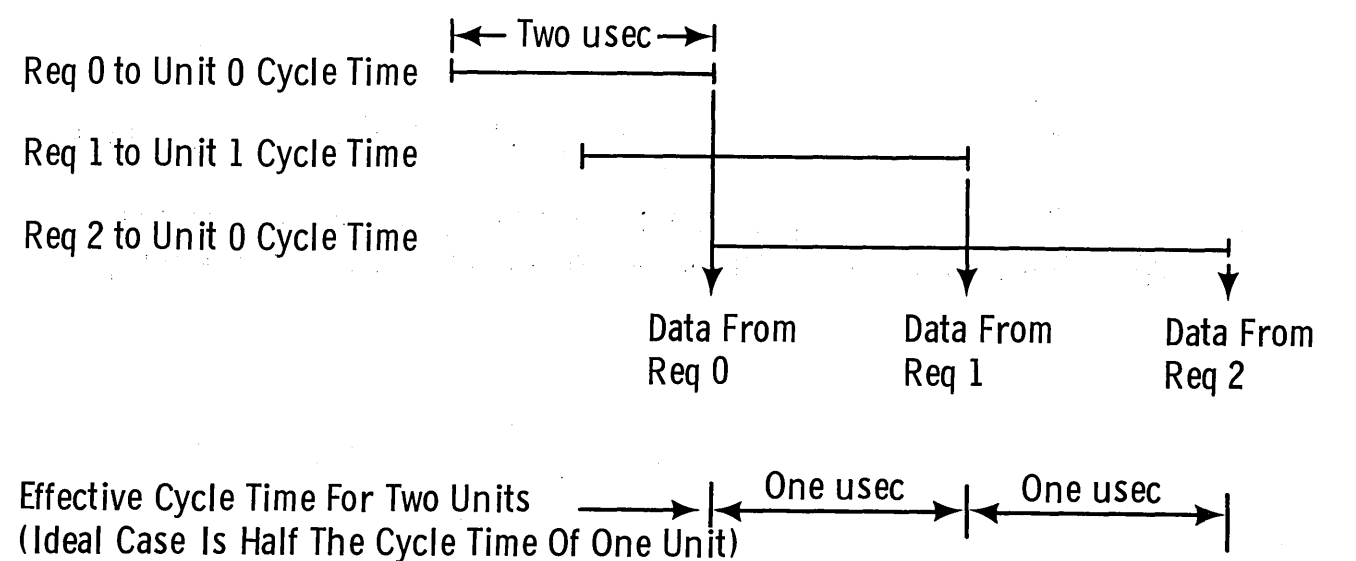
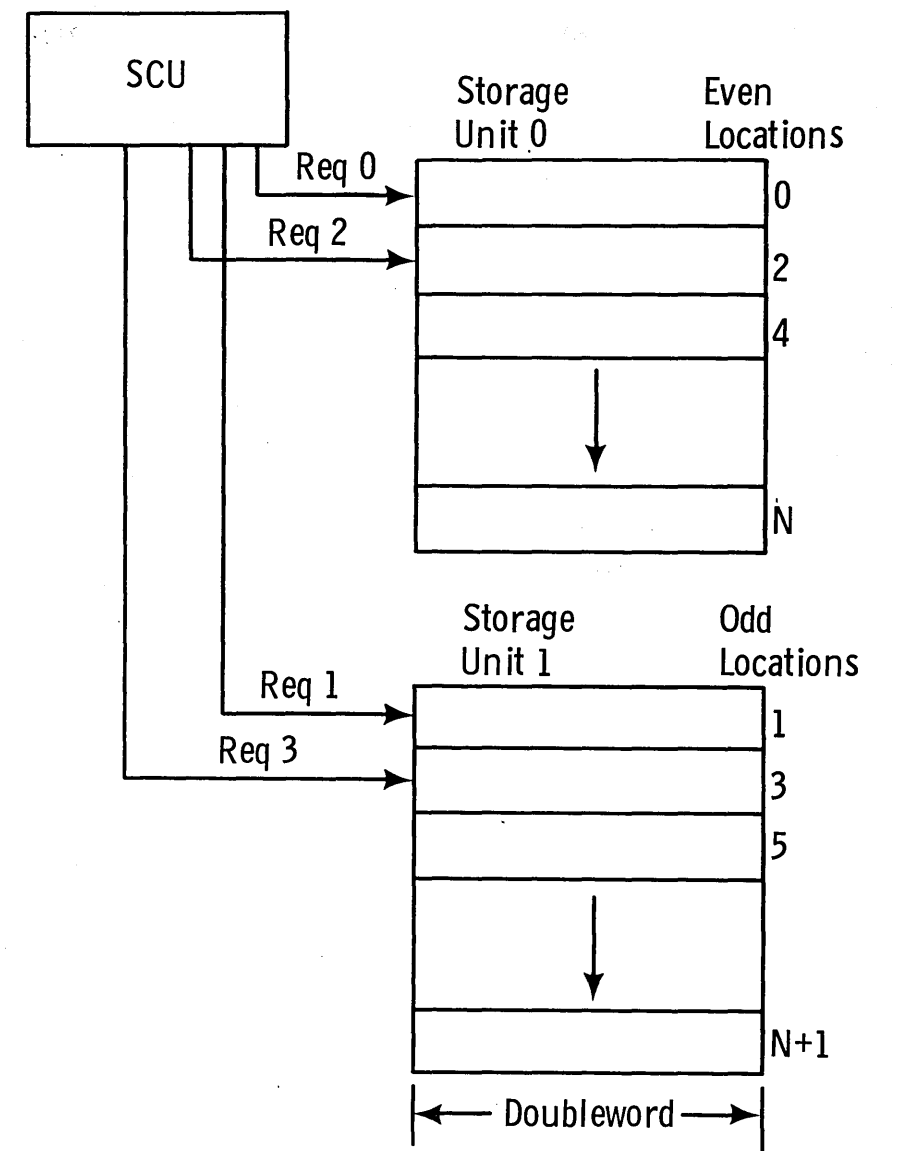


Figure 1-3 - Storage Addressing Number 2

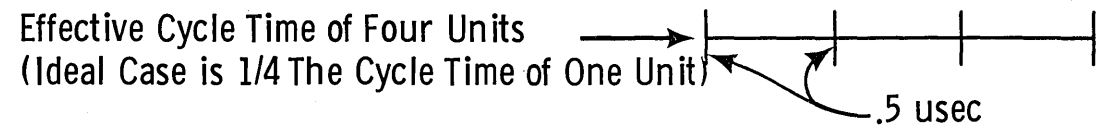
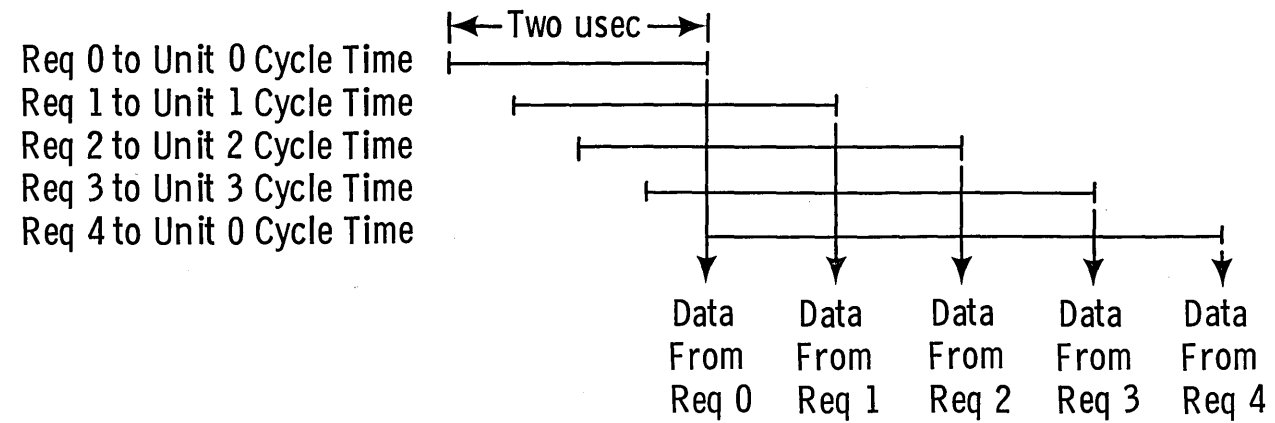
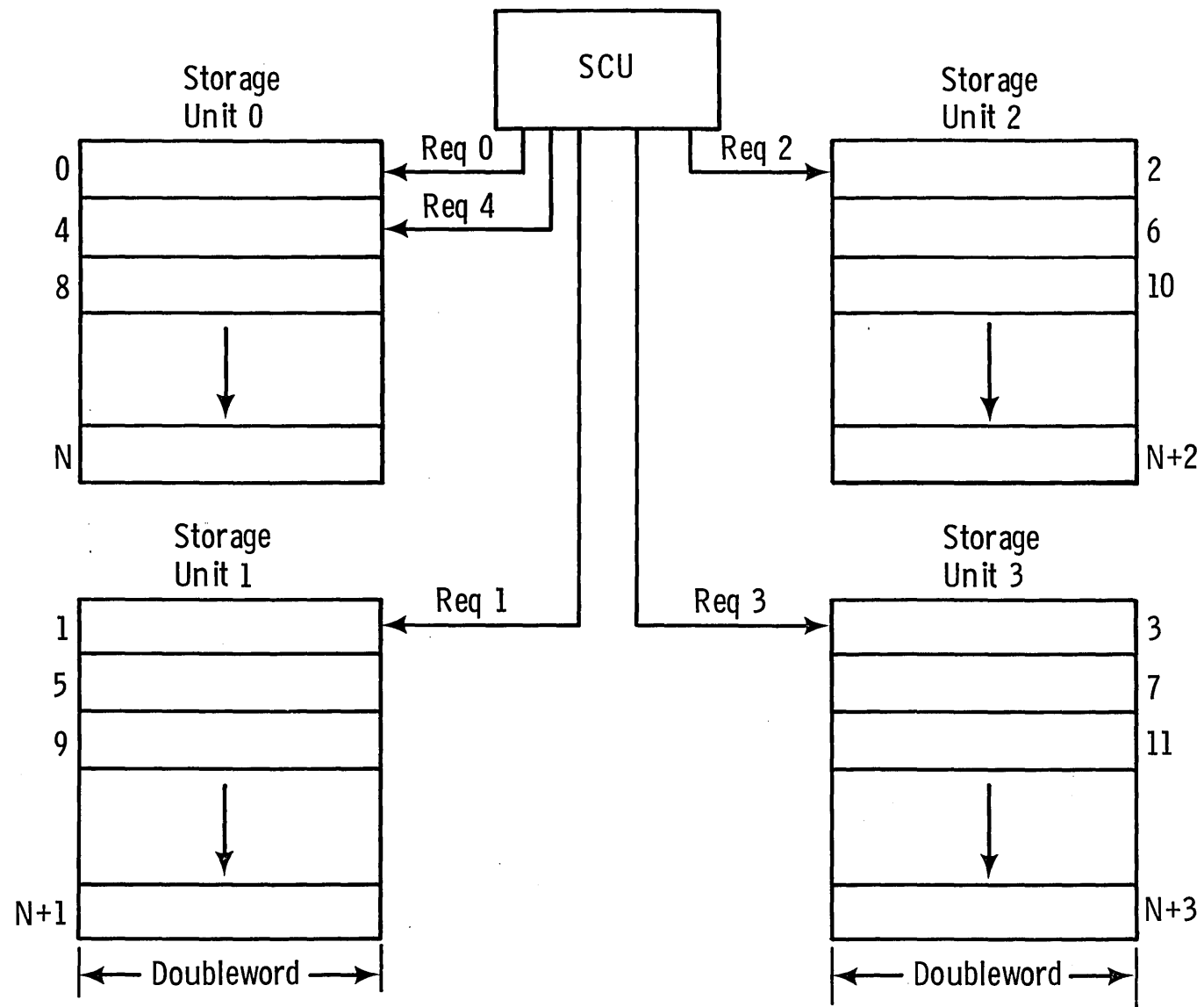


Figure 1-4 - Storage Addressing Number 3

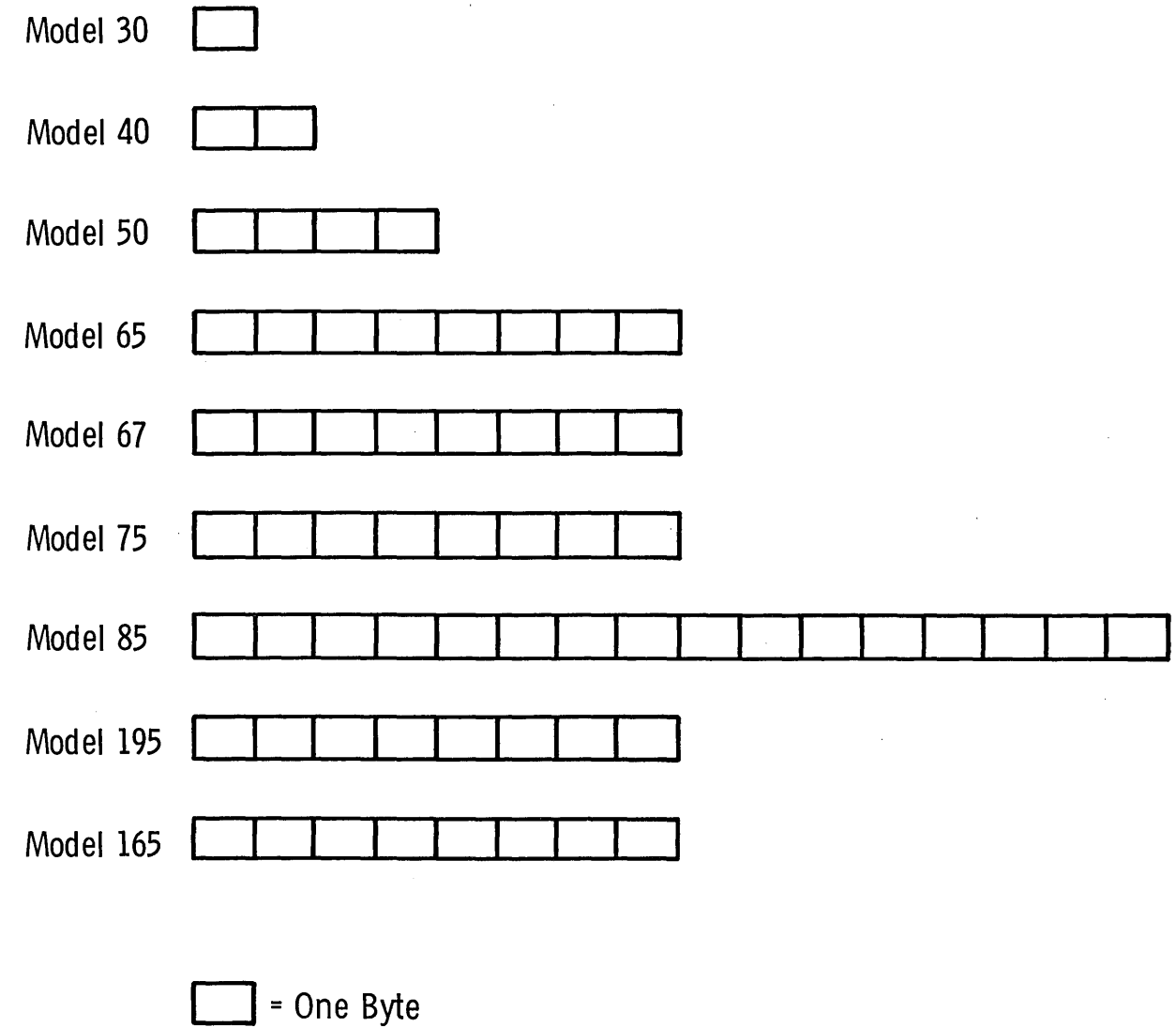


Figure 1-5 - Storage Access Size

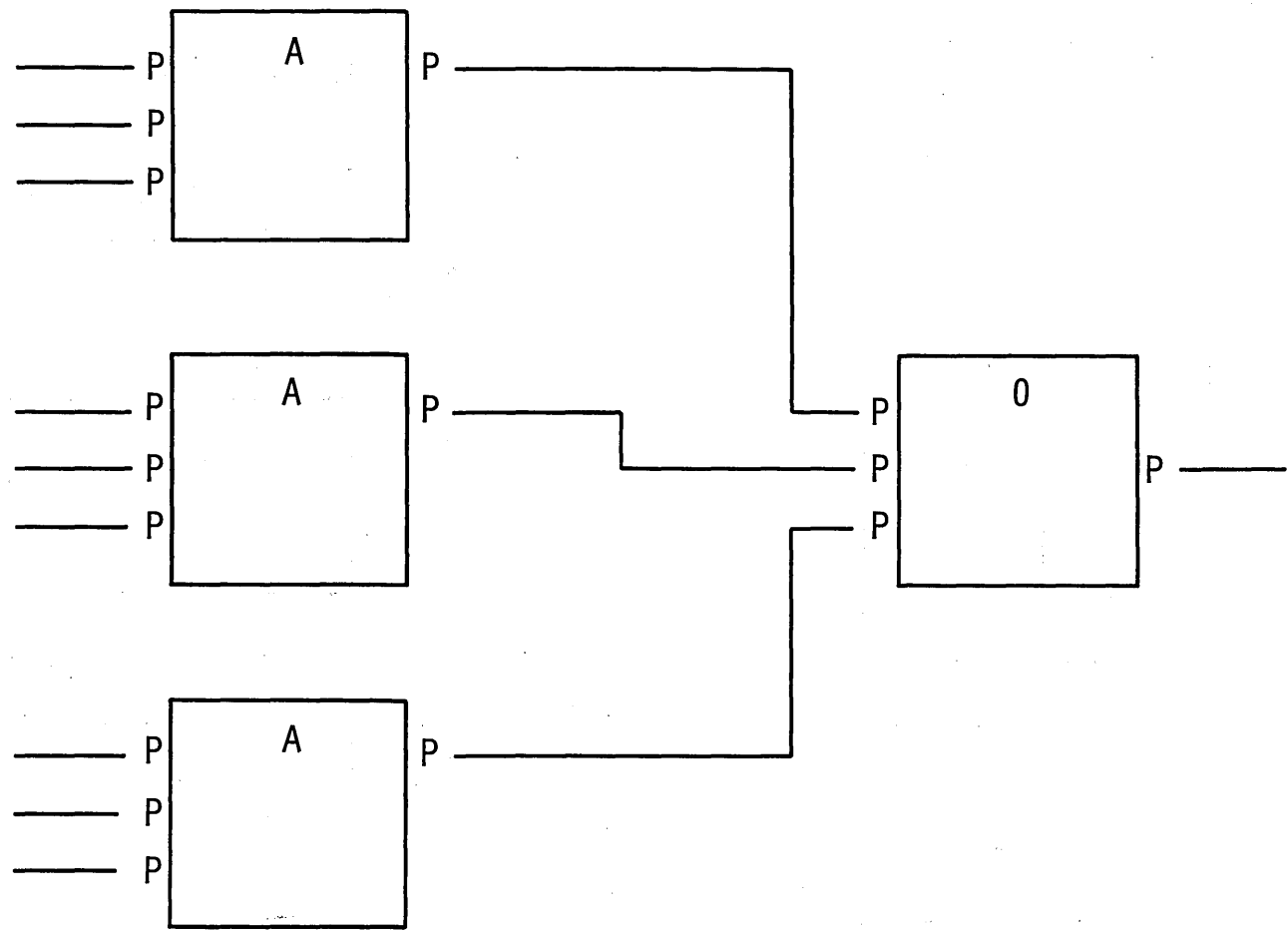


Figure 1-6 - SMS

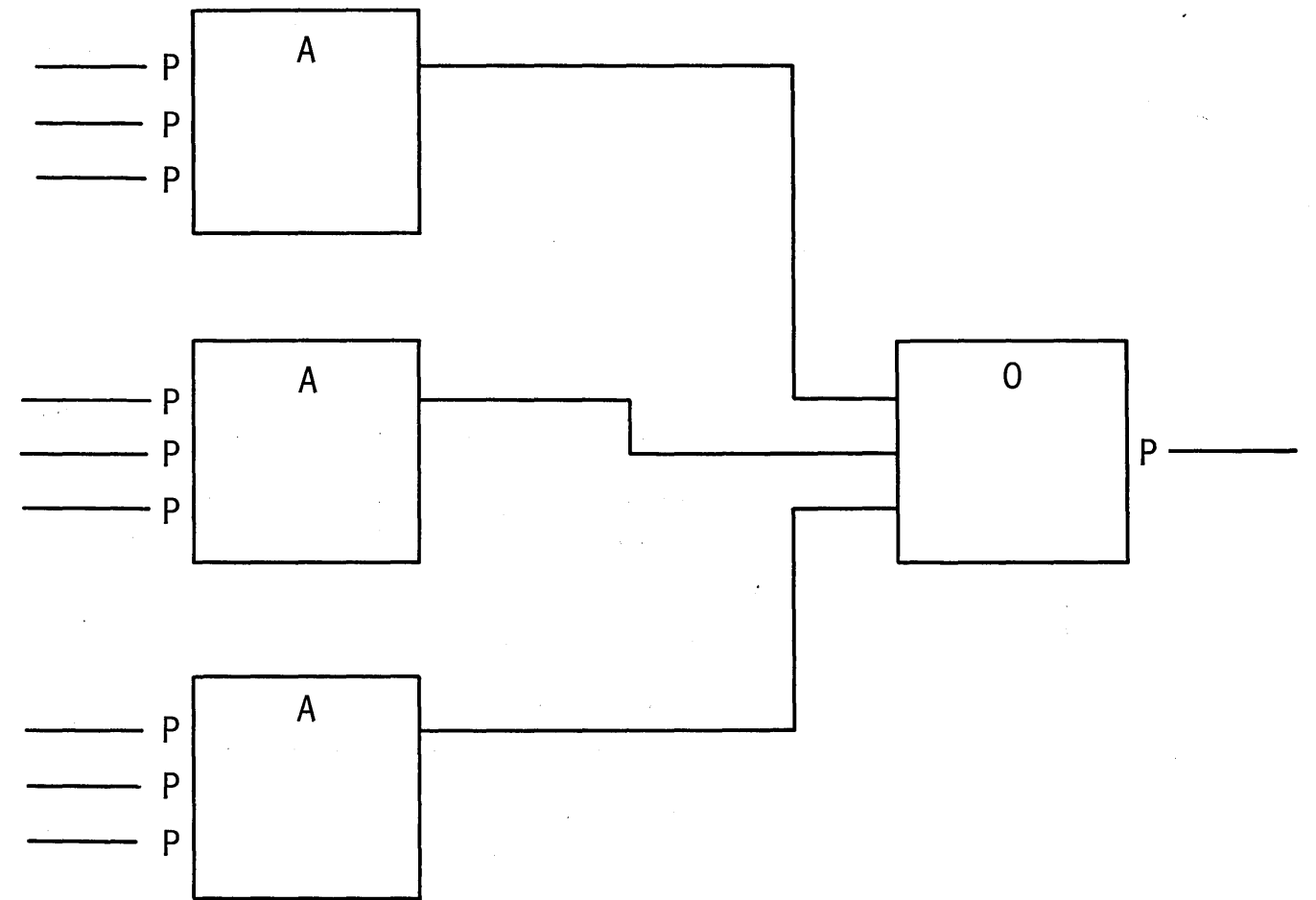


Figure 1-7 - SLT

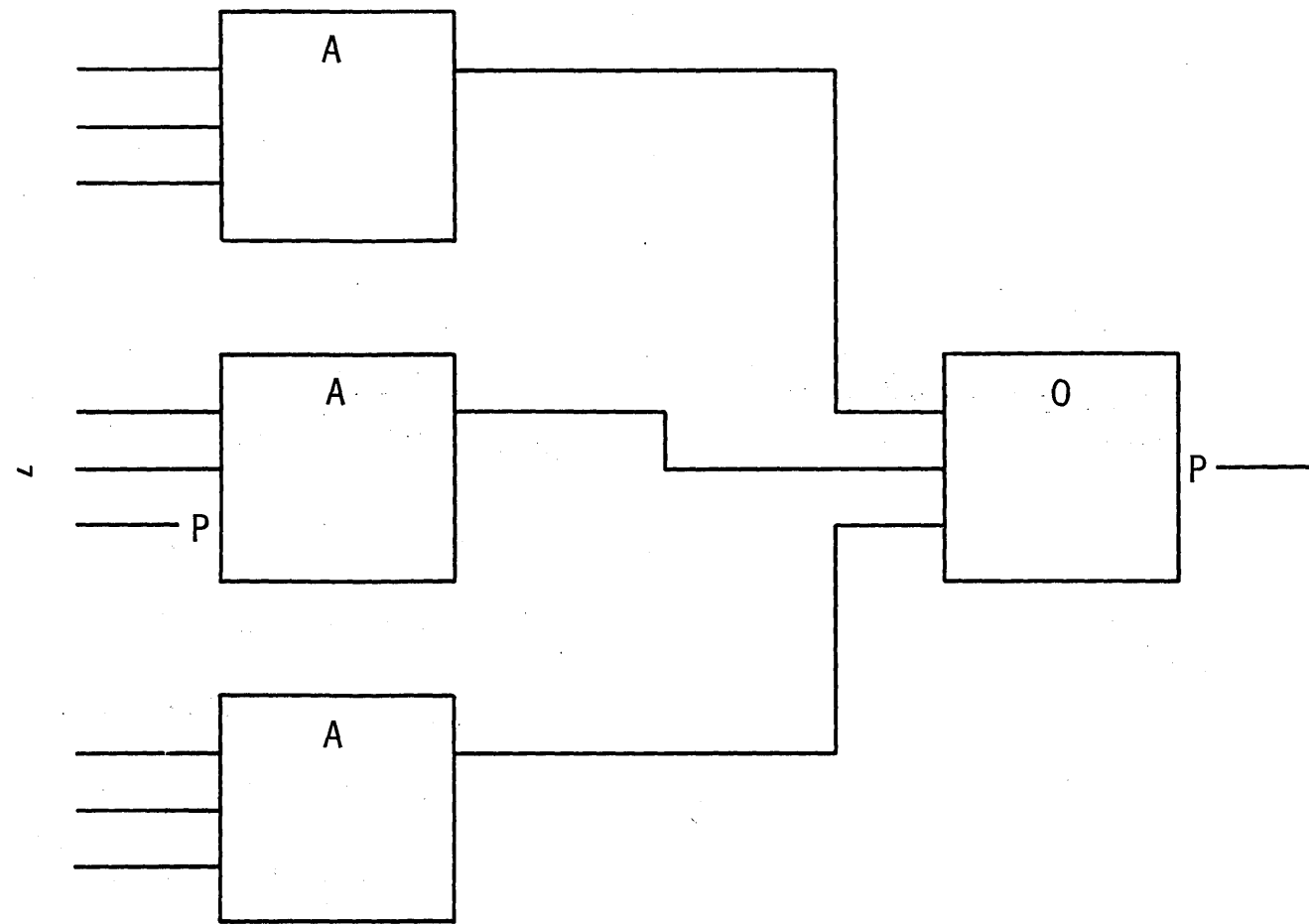


Figure 1-8 - MST

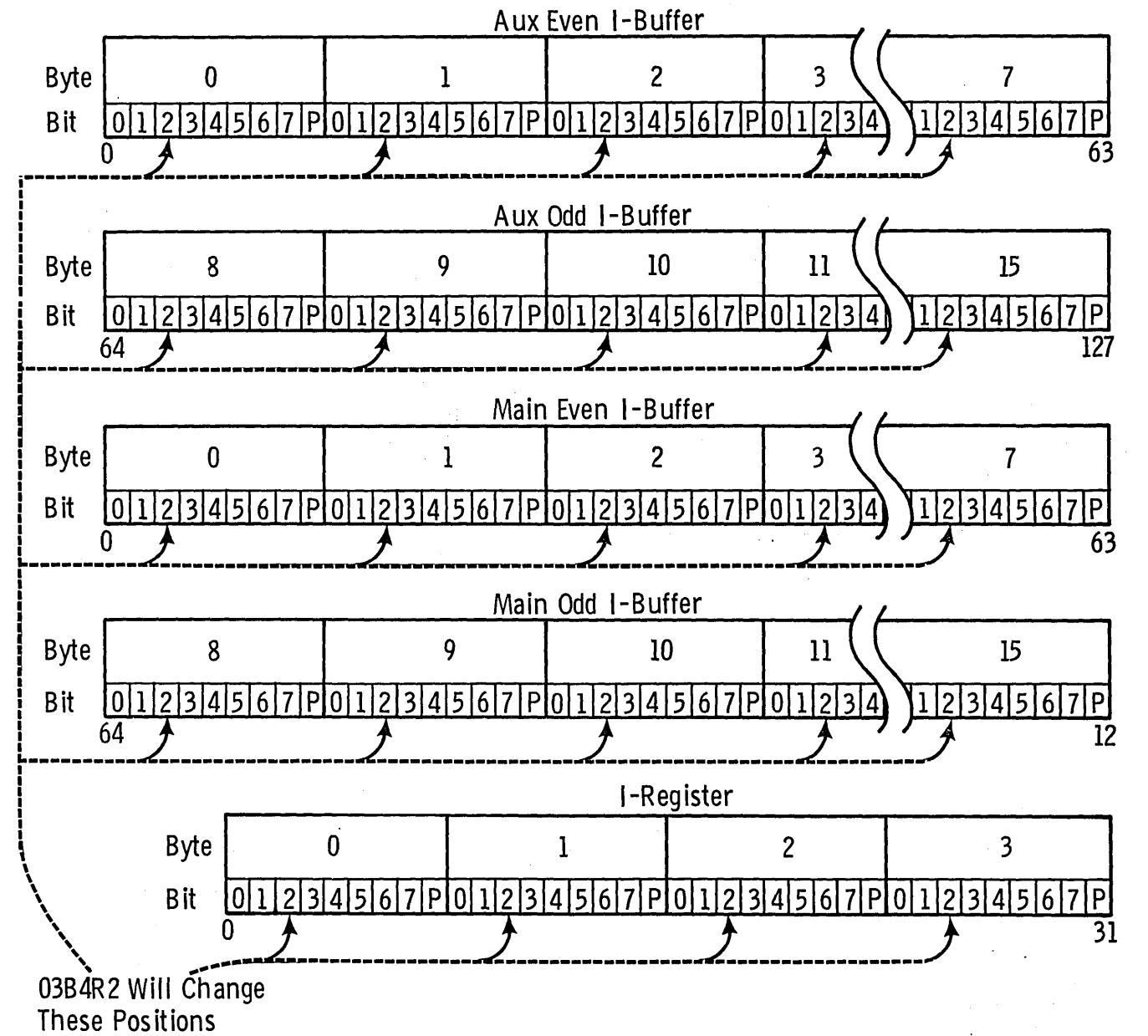


Figure 1-9 - Functional Packaging Example

1. Fix CPU failures that are located by any type of card calling CE aid (microdiagnostics, FLTs, support documentation).
2. Fix all power problems.
3. Fix all E-Unit failures.
4. Fix all cooling problems.
5. Install all ECs.
6. Fix all 2880 channel failures.
7. Configure main storage.
8. Fix all maintenance console failures.
9. Fix all M9A storage unit failures.
10. Fix all SCU failures.
11. Fix maintenance console mechanical failures, including both microfiche viewers and the console file.
12. Fix all operators console-feature failures.

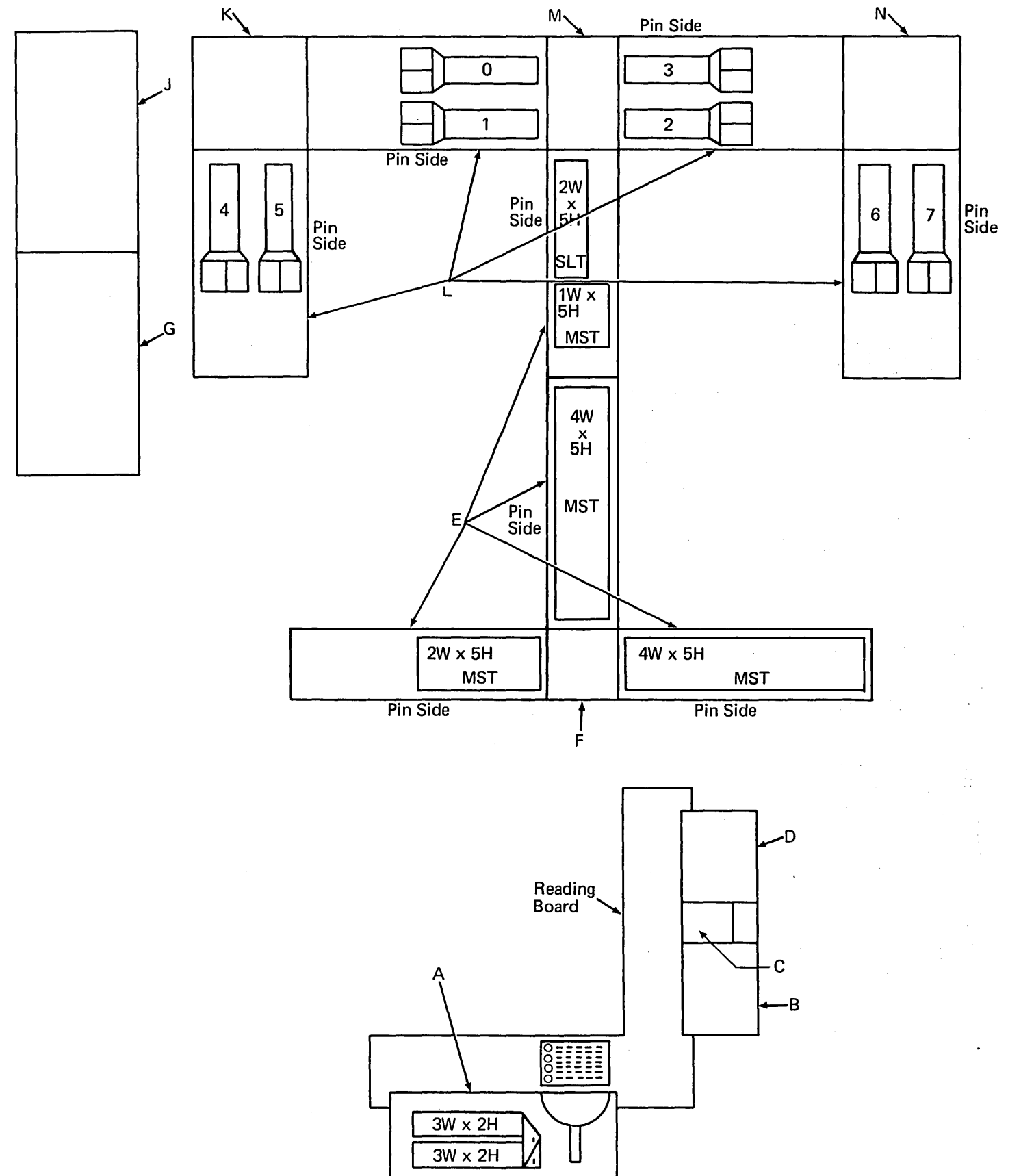


Figure 1-10 - Session 1 Question 3

Figure 2-1 - Session 2 Questions 1-4

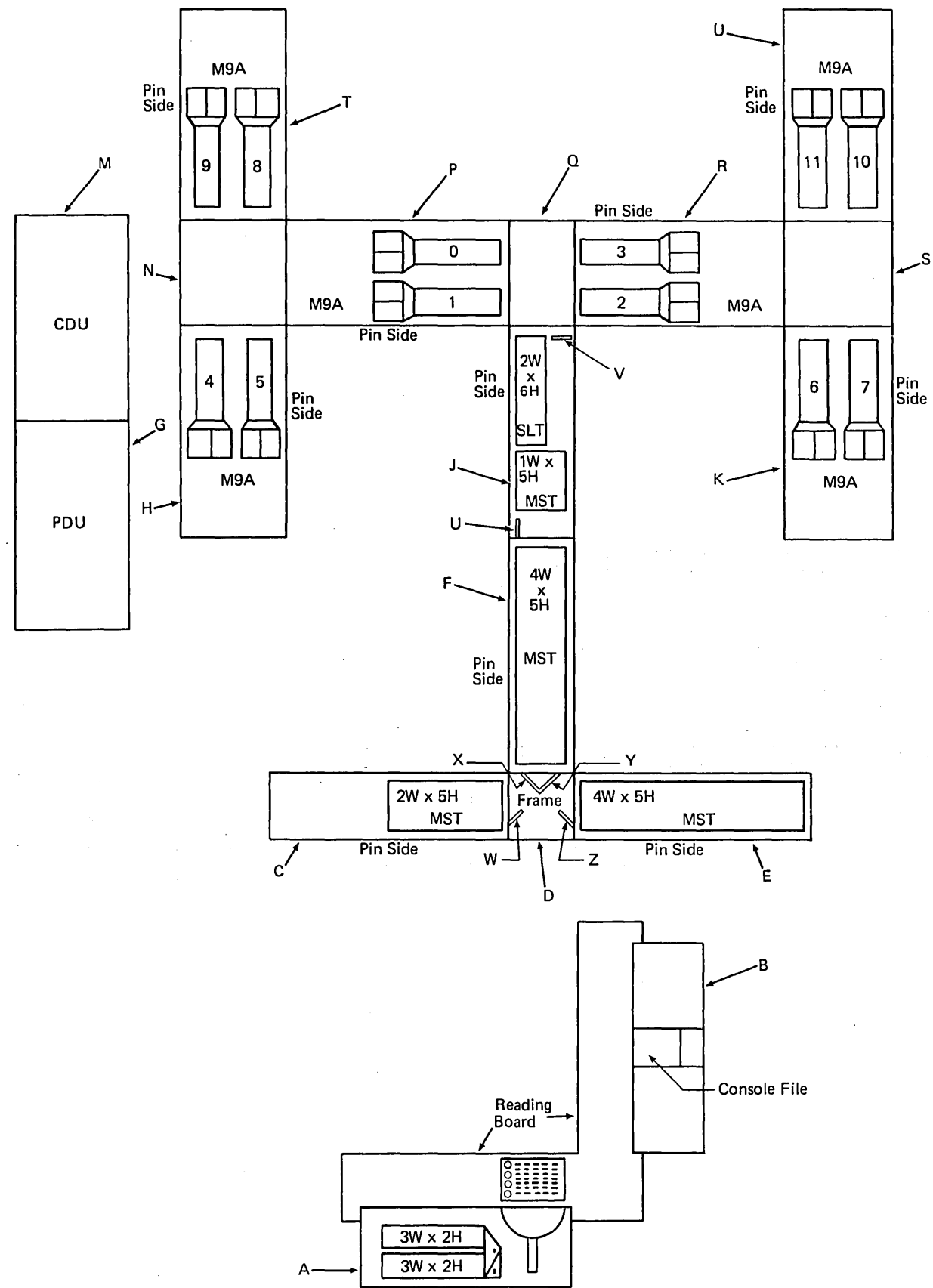


Figure 2-2 - Session 2 Questions 5-8

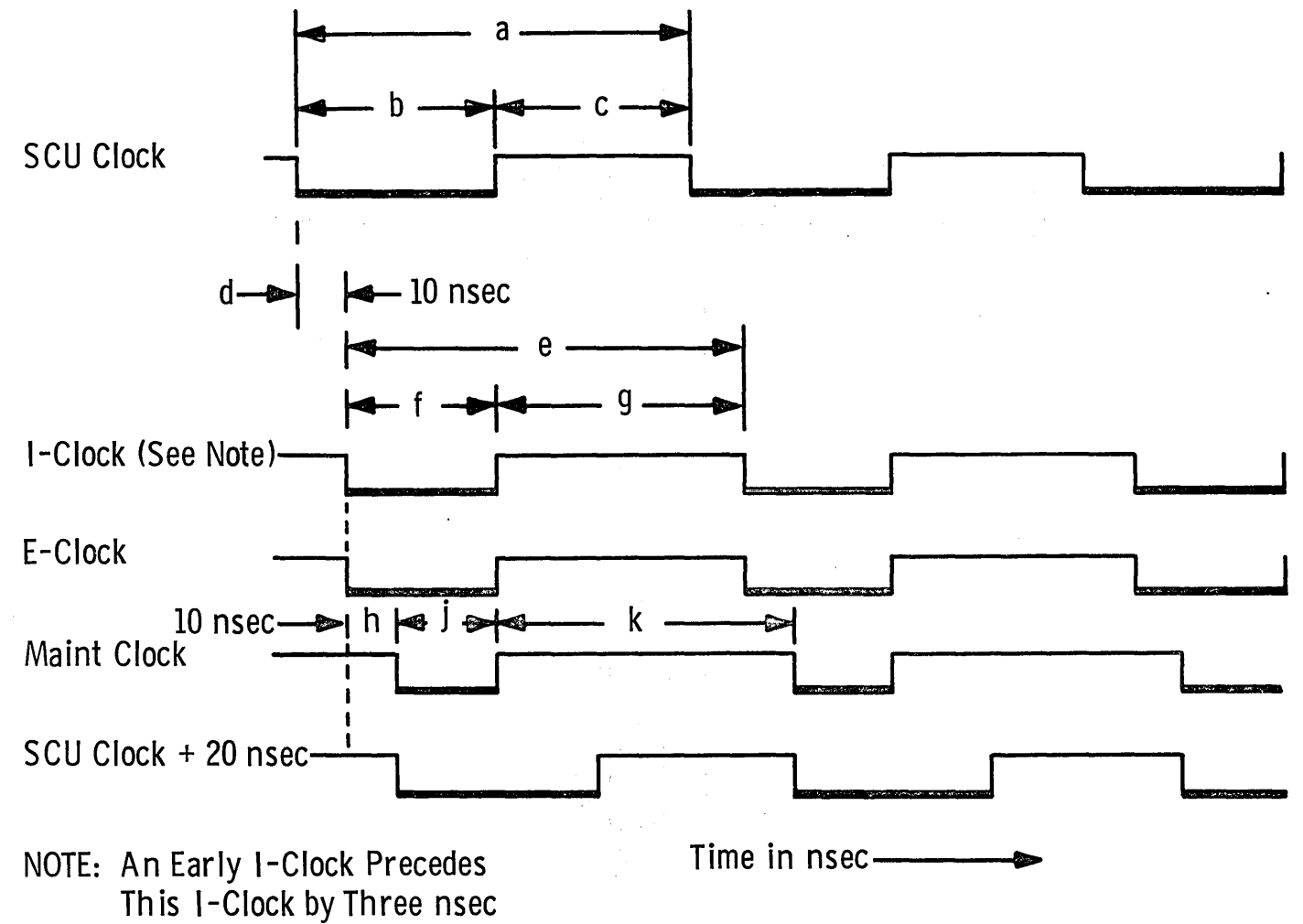


Figure 2-3 - Session 2 Questions 14-17

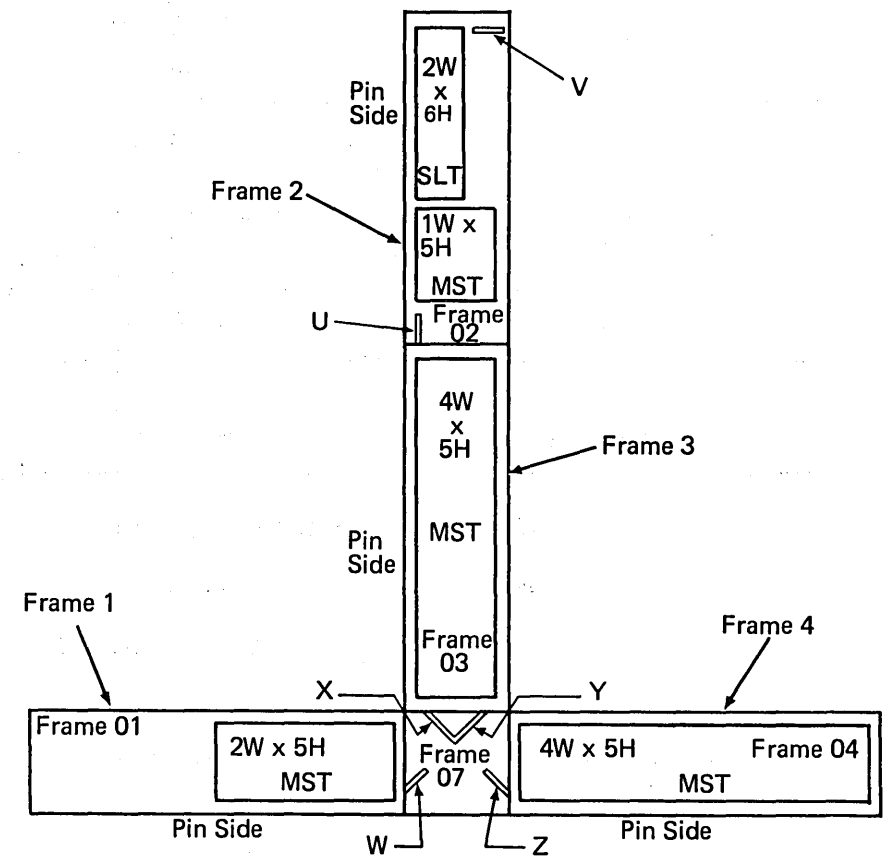
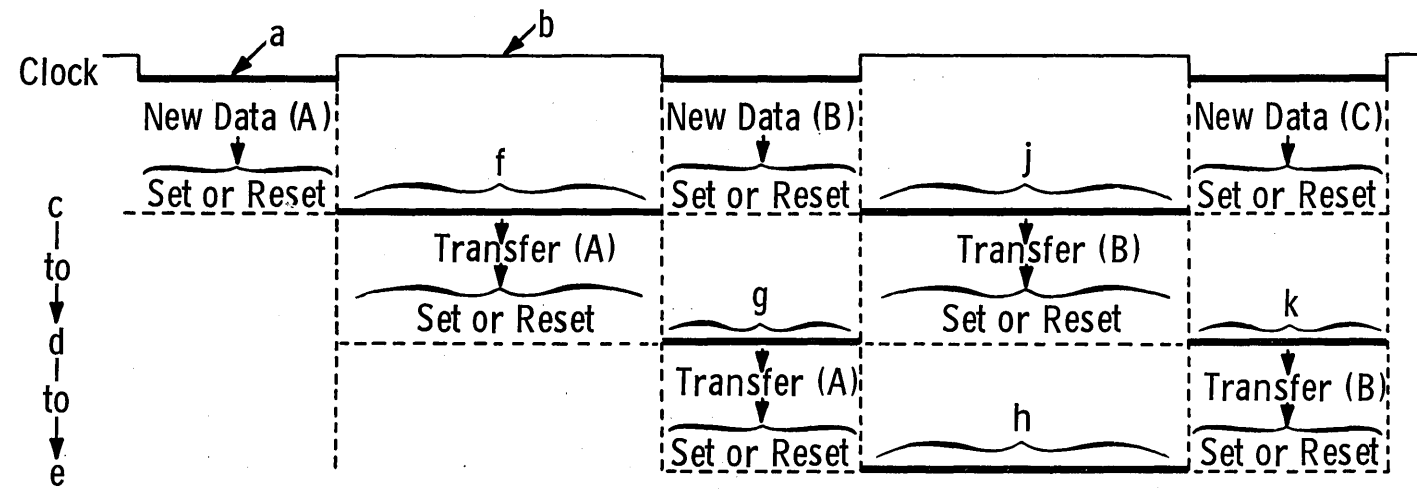


Figure 2-4 - Session 2 Questions 23-25

Figure 2-5 - CPU

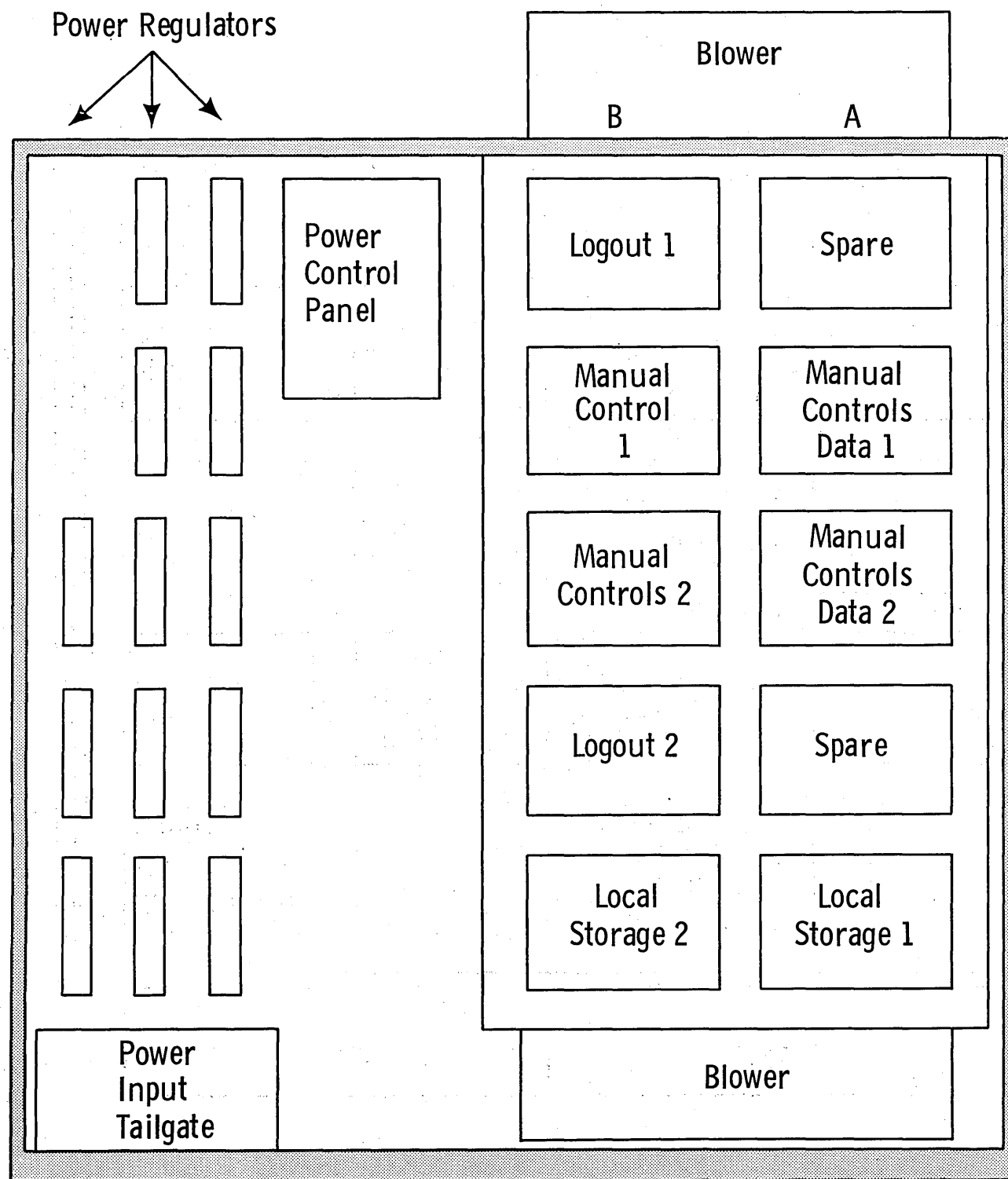


Figure 2-6 - Frame 01 Pin Side

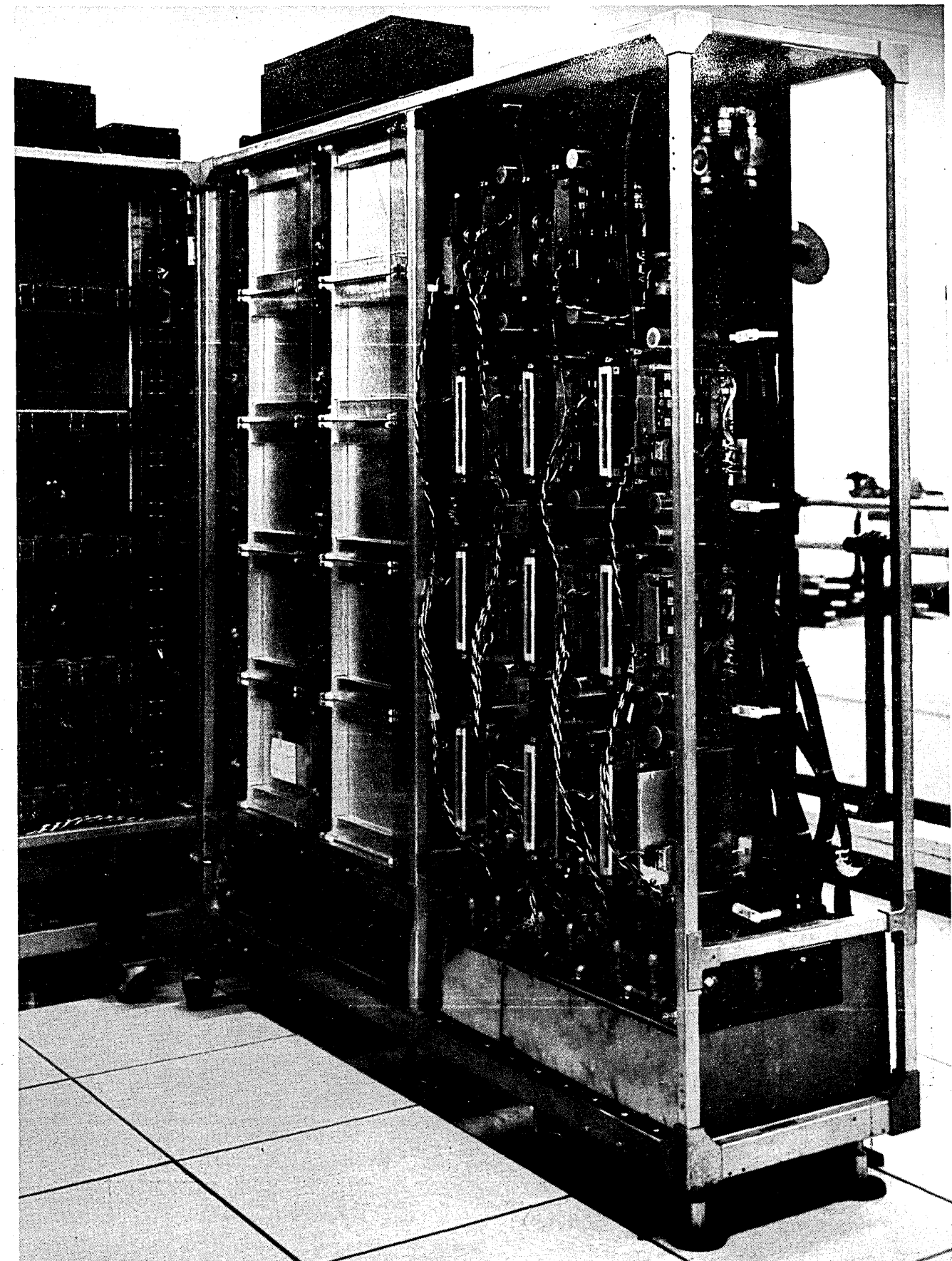


Figure 2-7 - Frame 1

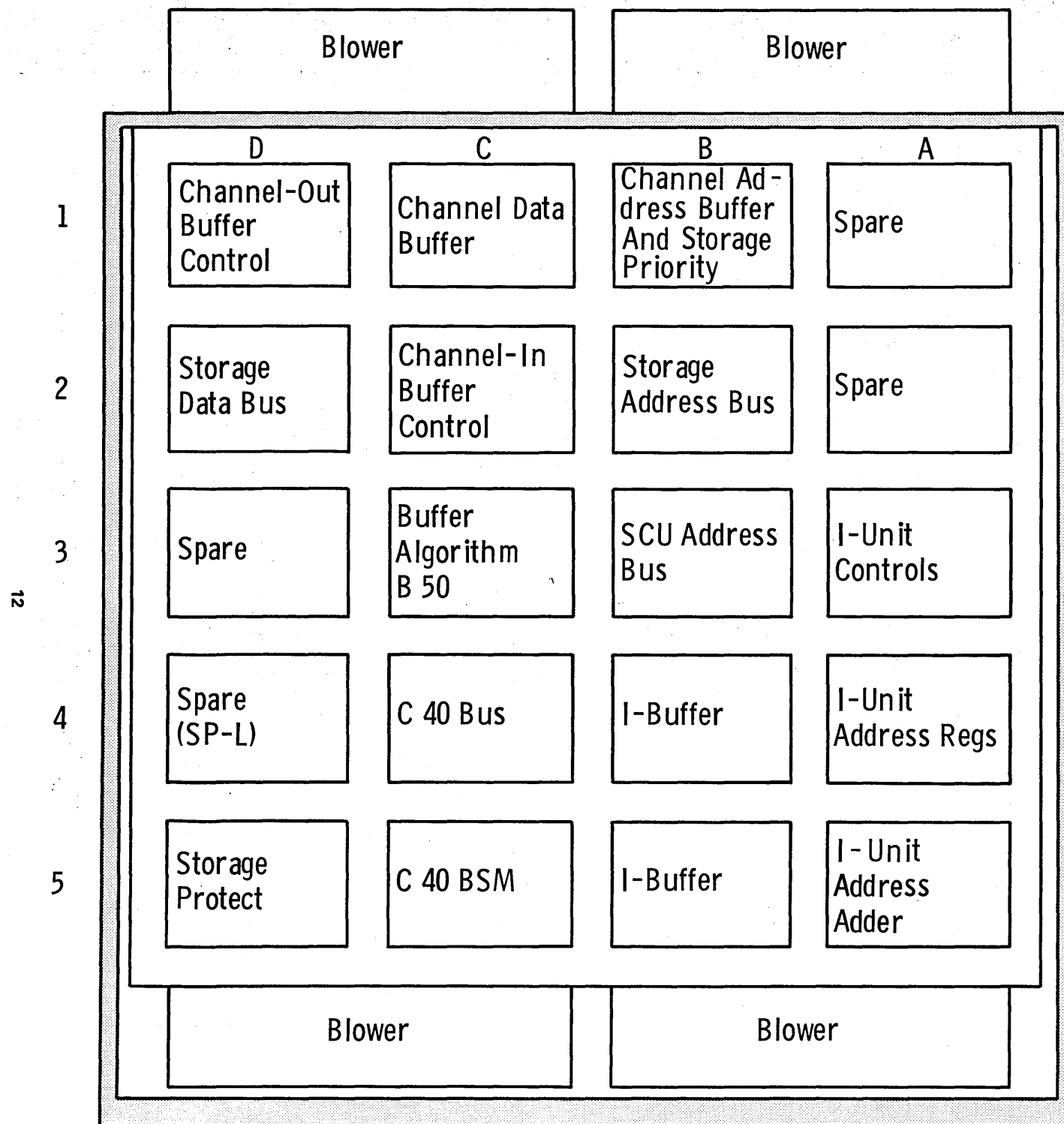
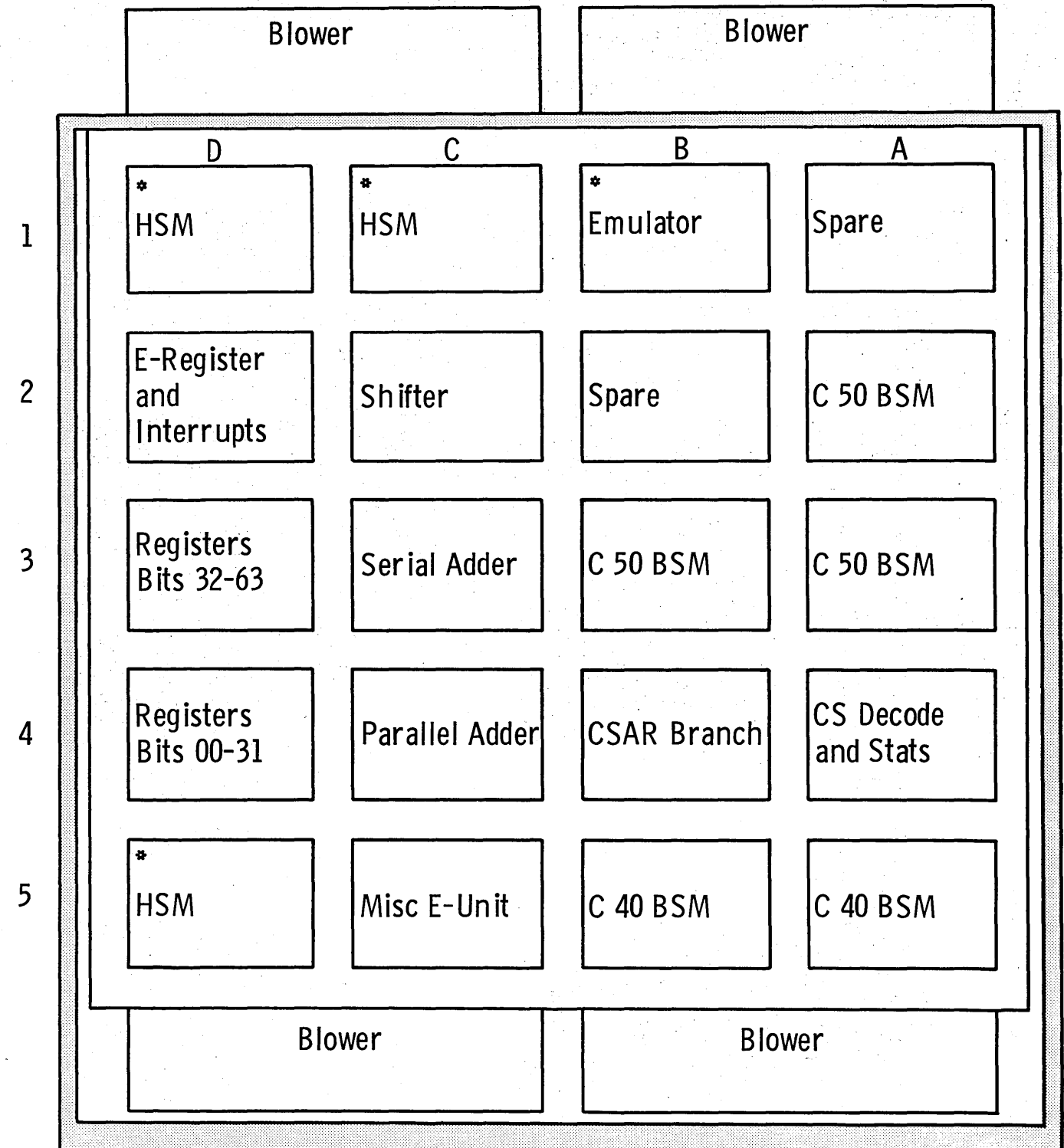


Figure 2-8 - Frame 03 Pin Side



*Feature Board

Figure 2-9 - Frame 04 Pin Side

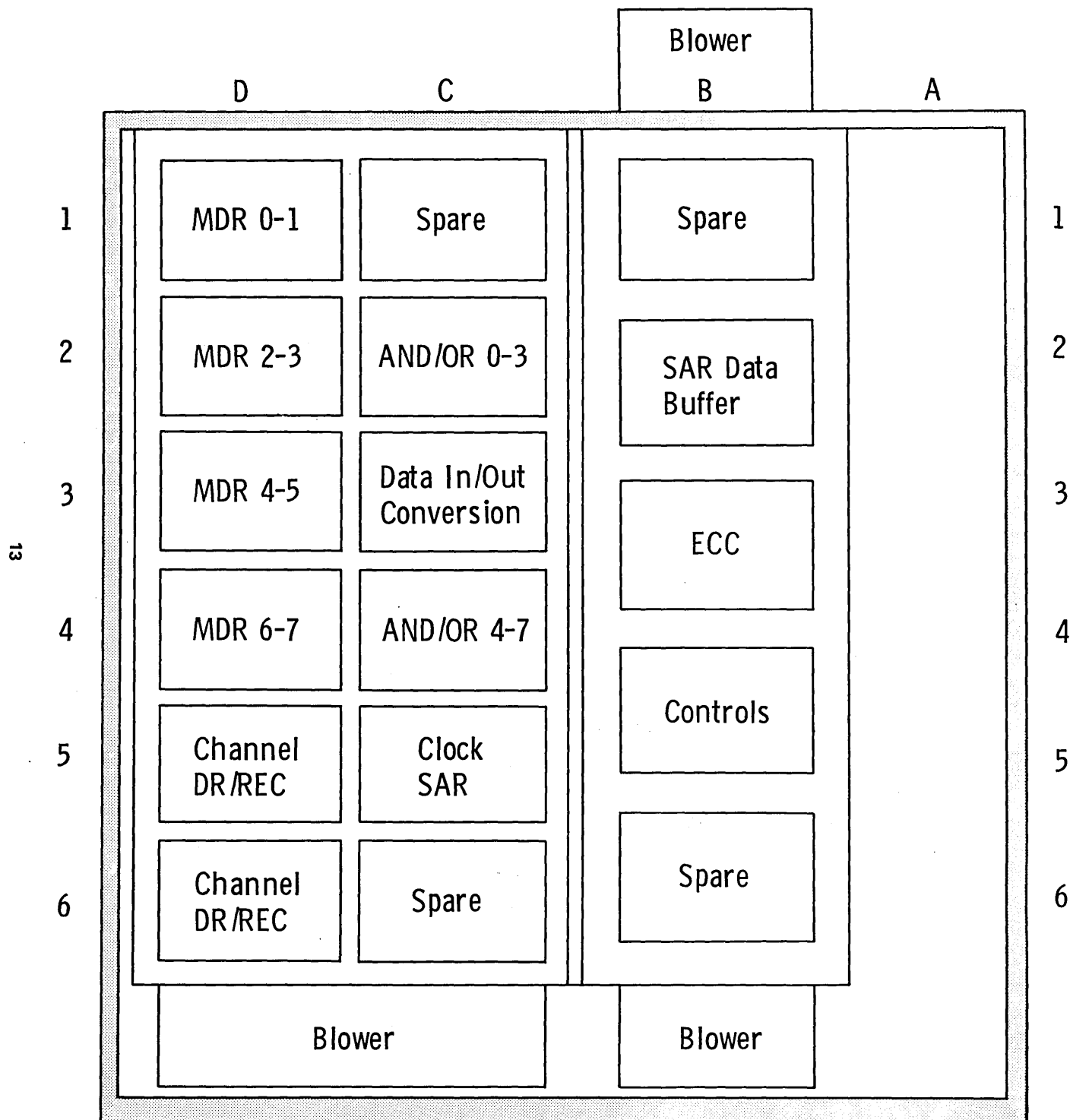


Figure 2-10 - Frame 02 Pin Side

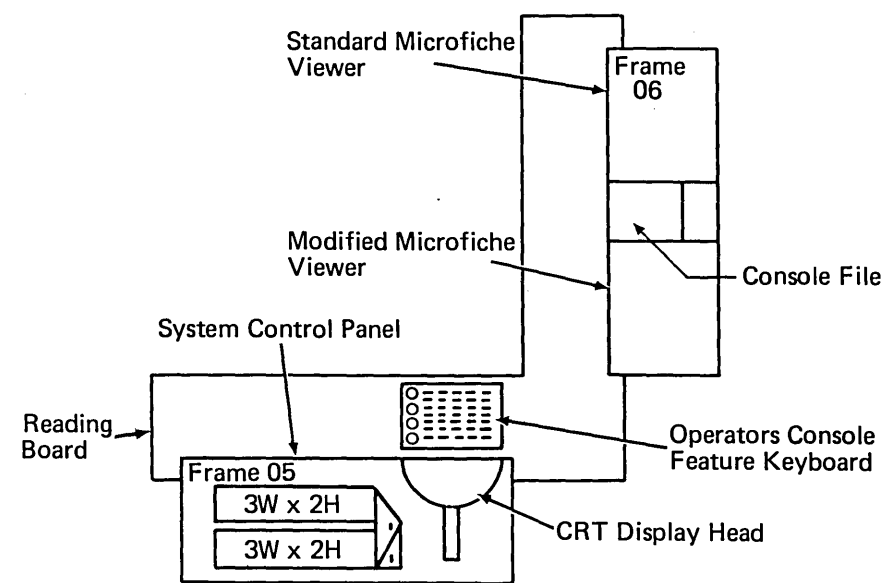
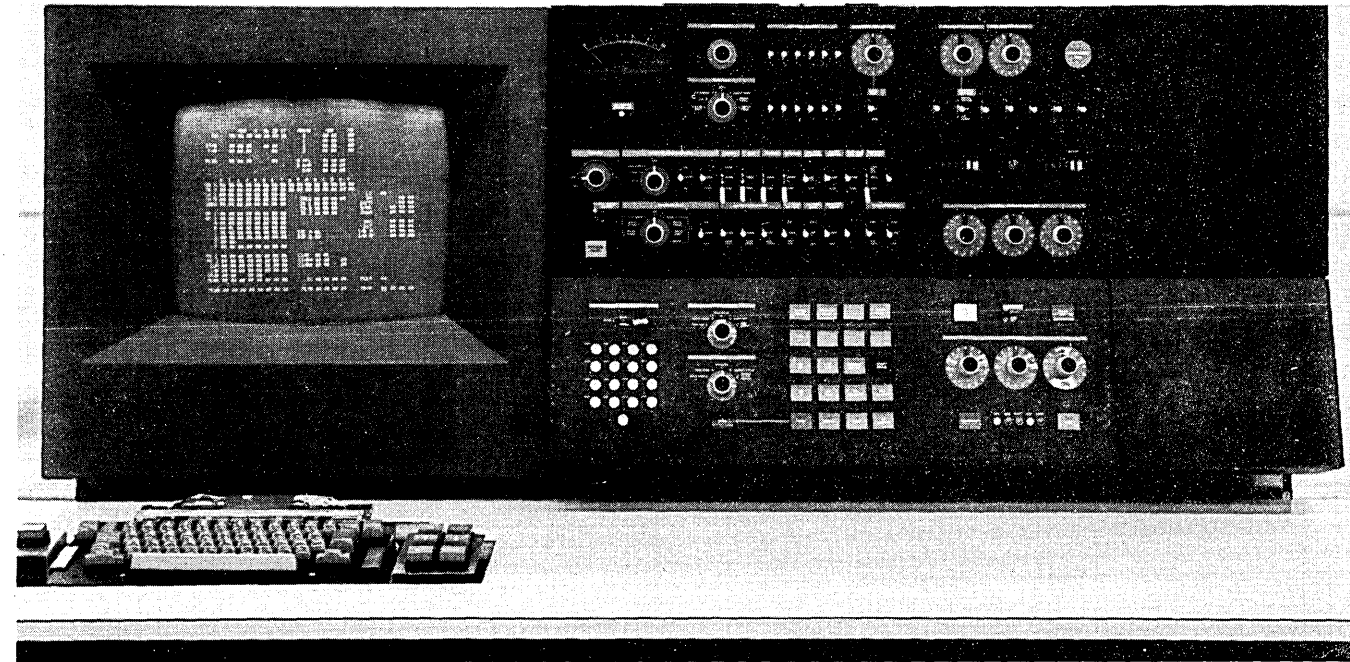


Figure 2-11 - Frames 5 and 6



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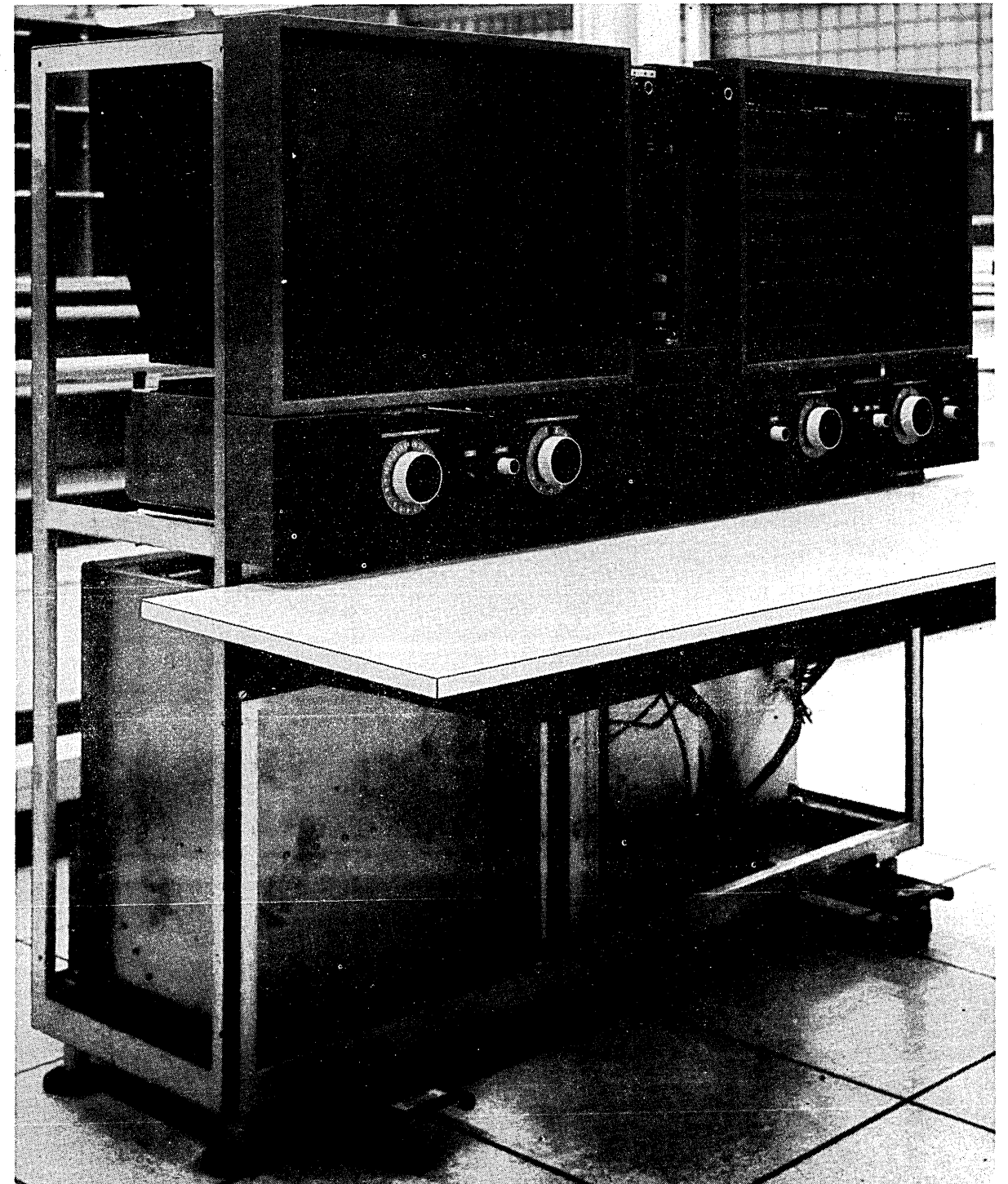


Figure 2-13 - Microfiche Viewers

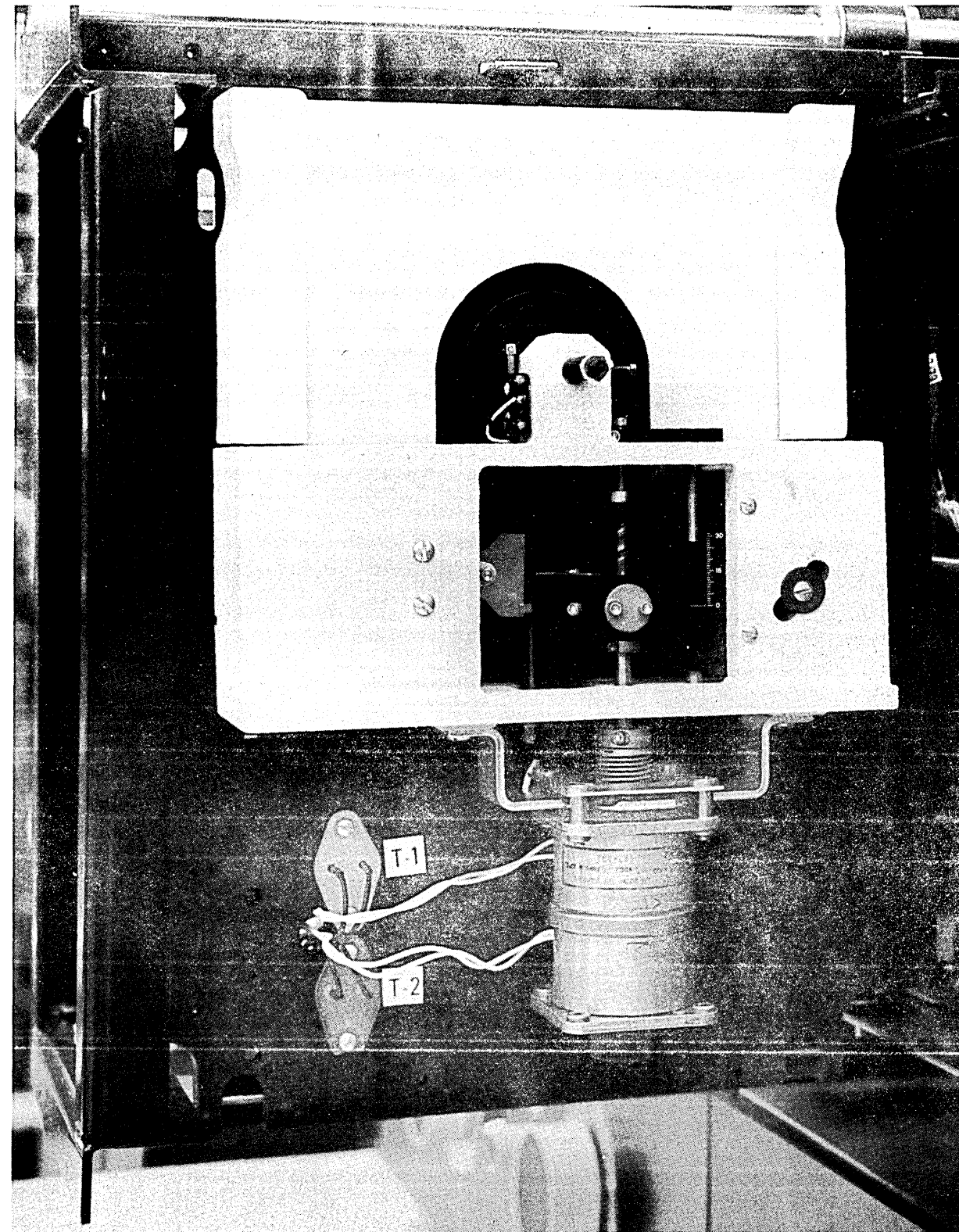


Figure 2-14 - Console File

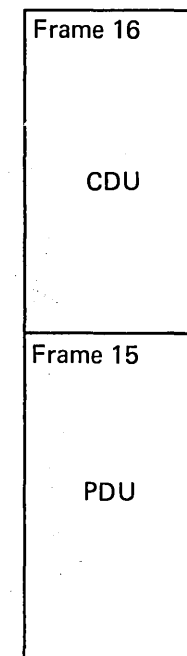


Figure 2-15 - Power and Cooling Frames

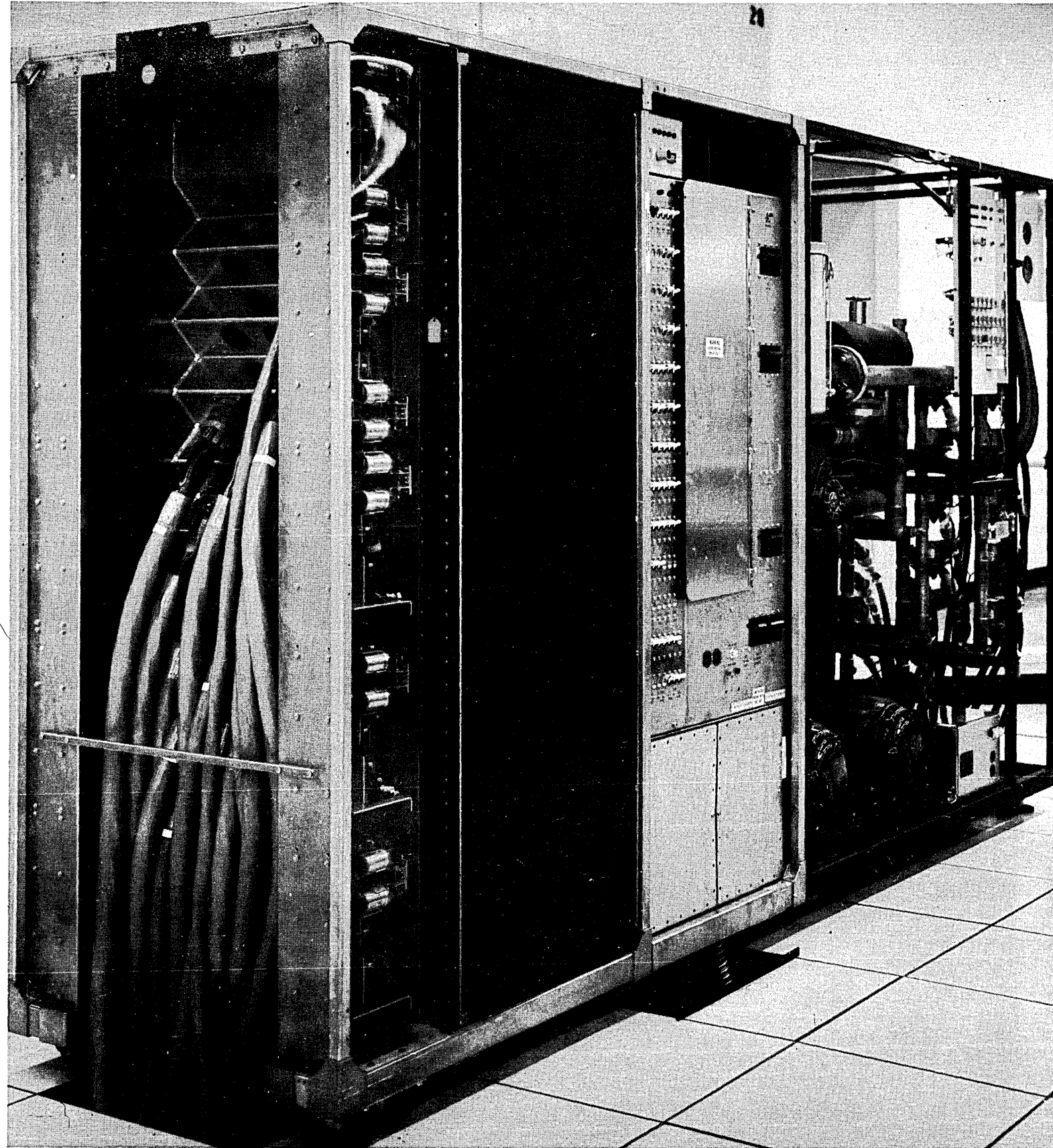
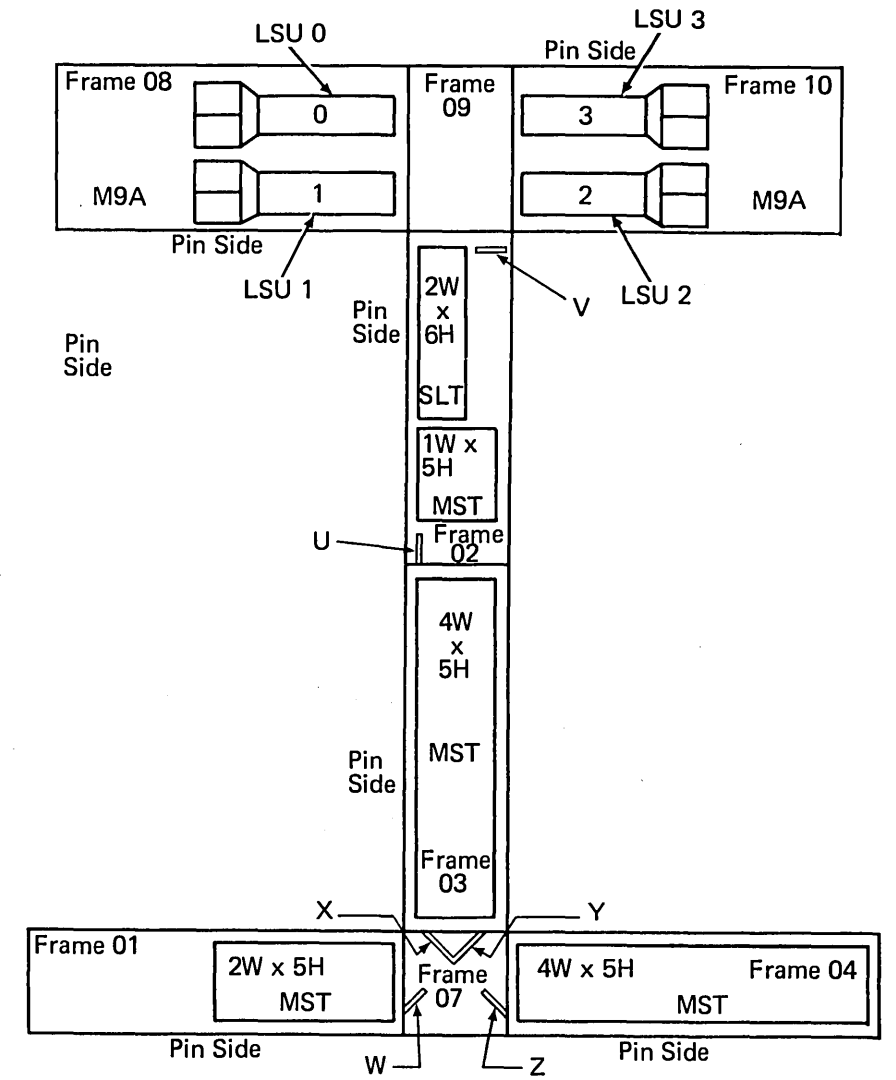
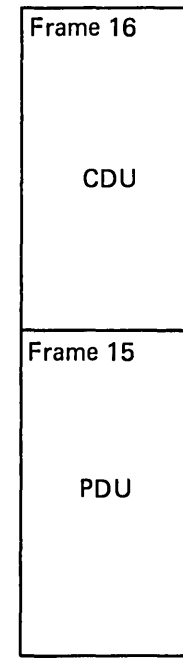
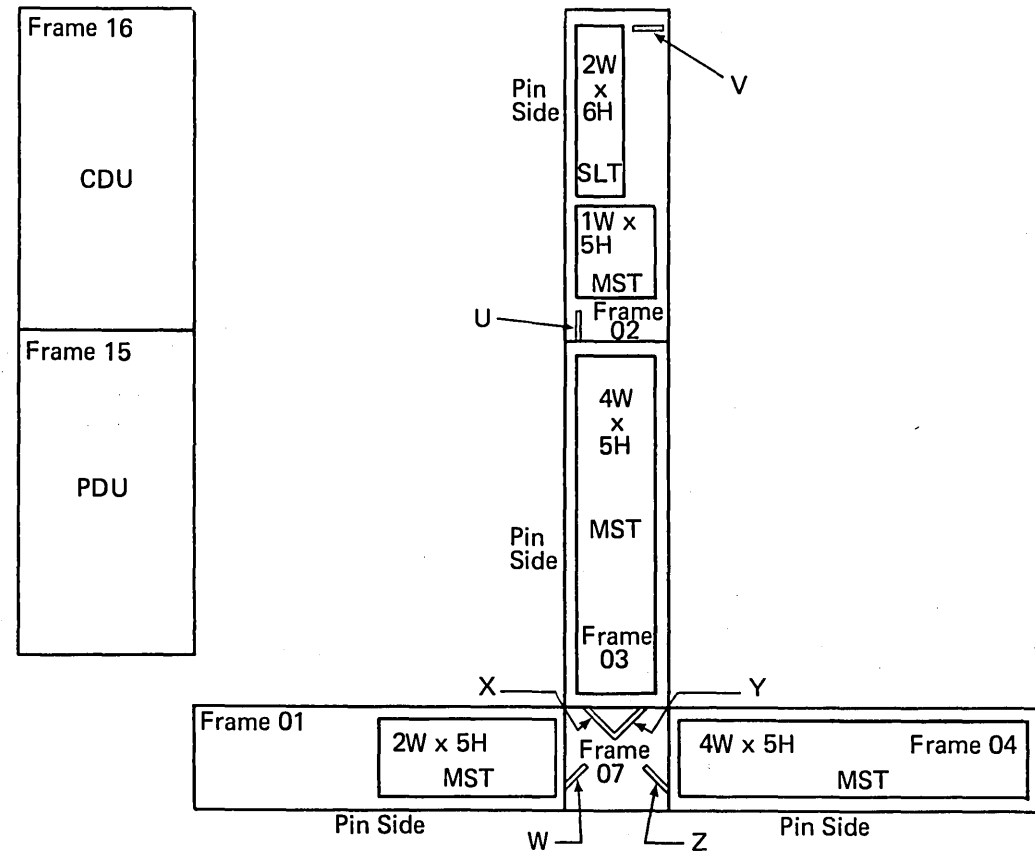
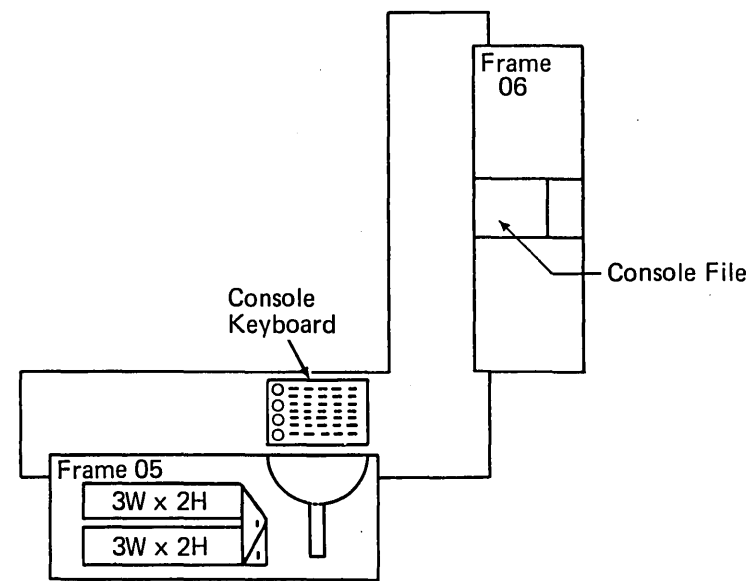


Figure 2-16 - CDU and PDU



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Model	Number Frames	Storage Size (Bytes)
I	2	500,000
J	2	1,000,000

LSU - Logical Storage Unit

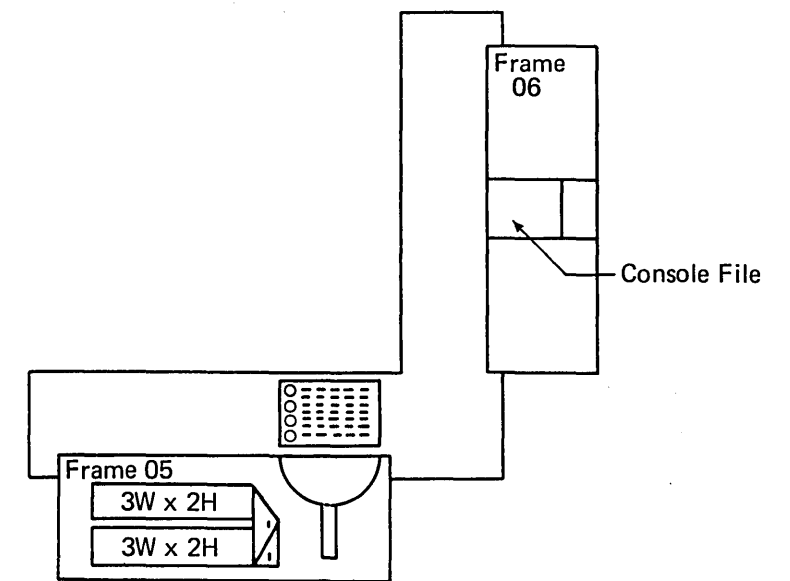
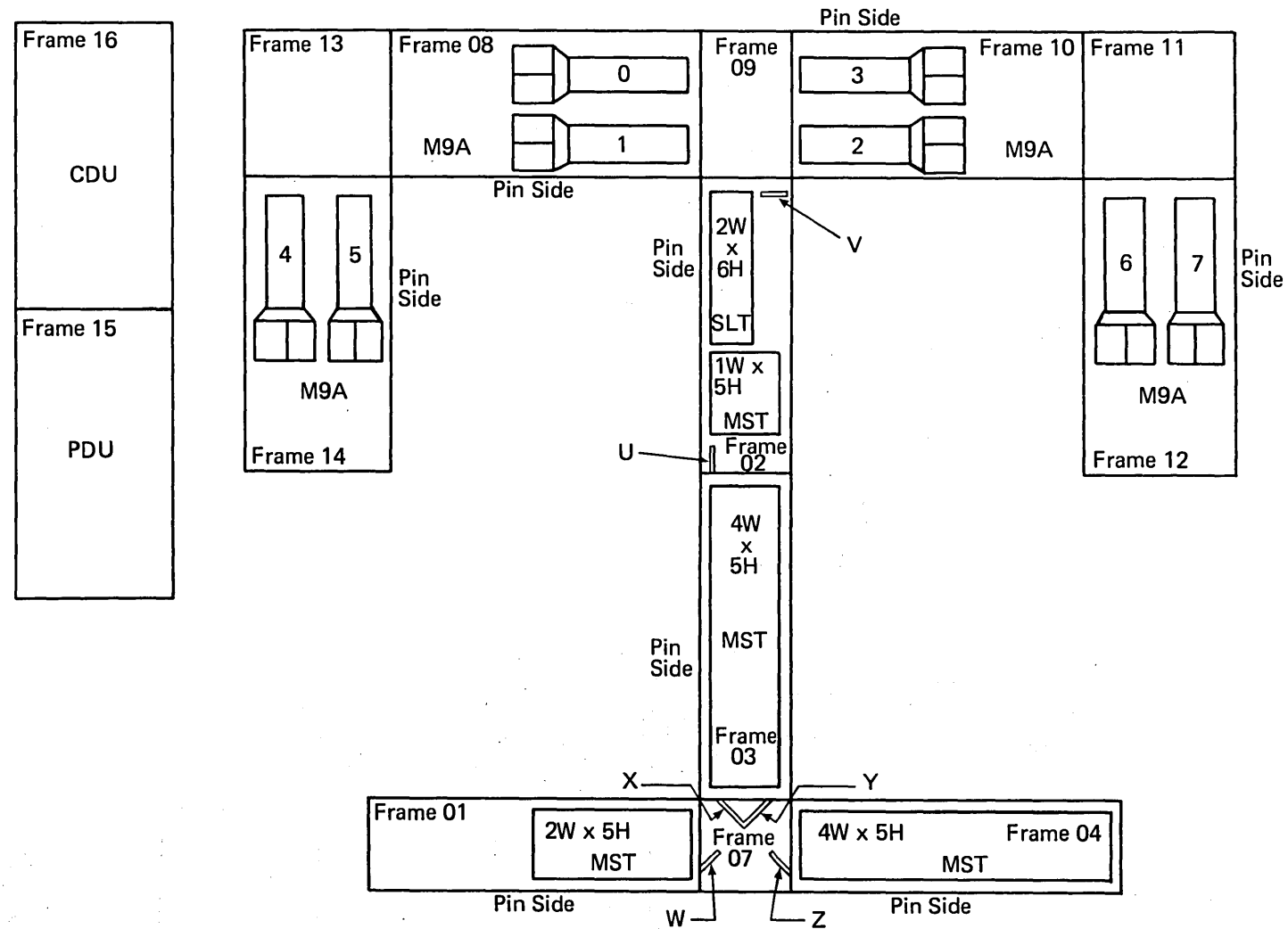


Figure 2-17 - System We Have Built

Figure 2-18 - I and J Storage



Model	Number Frames	Storage Size (Bytes)
J-I	4	1,500,000
K	4	2,000,000

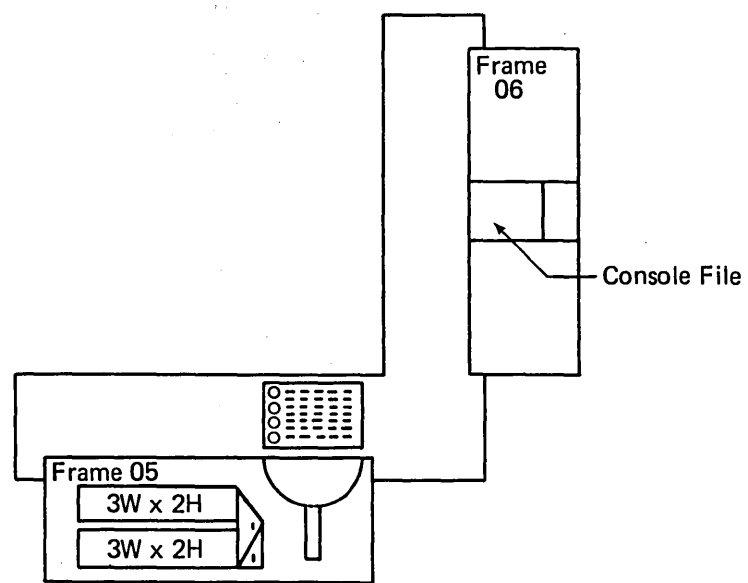
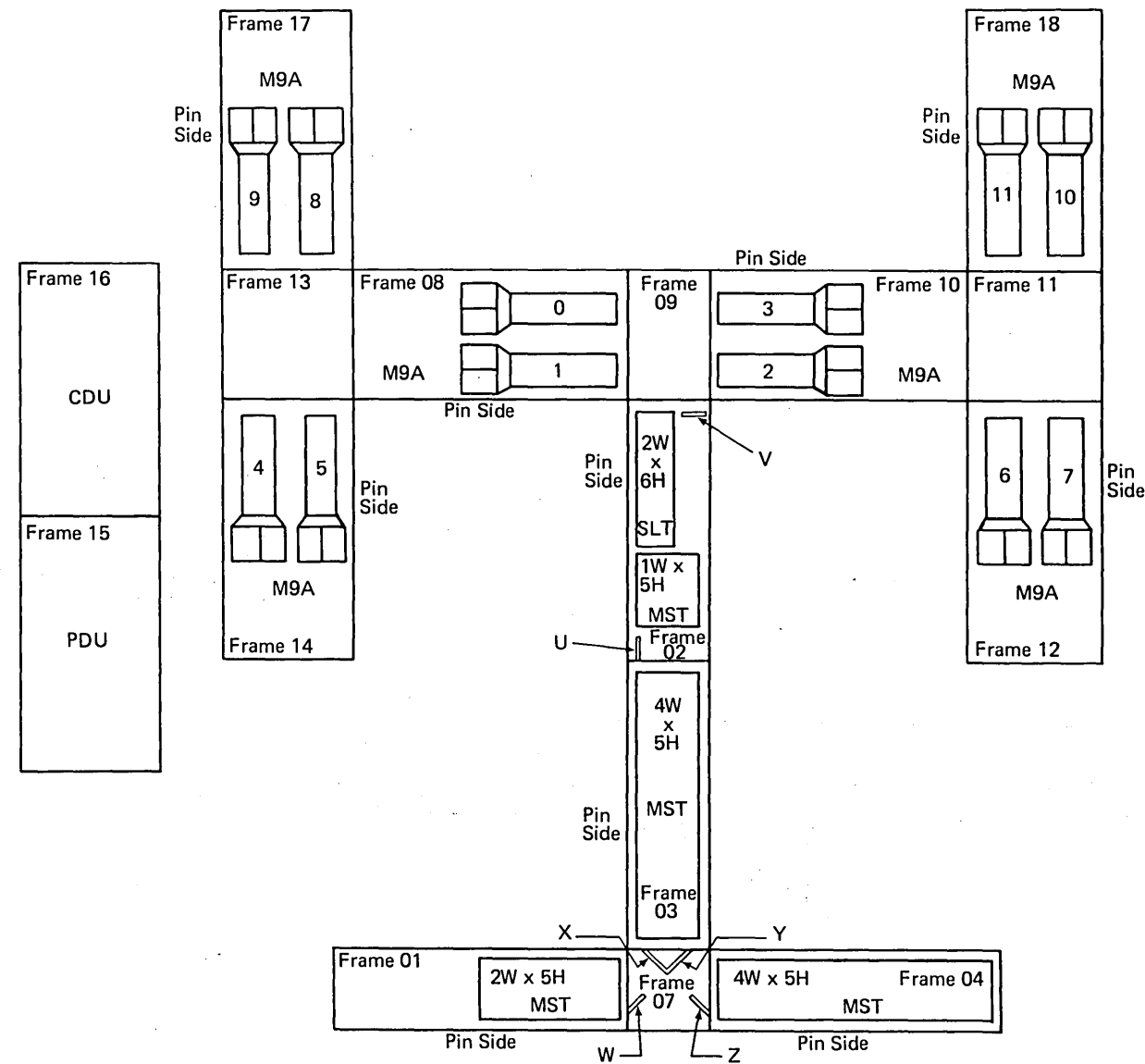


Figure 2-19 - J-I and K Storage



Model	Number Frames	Storage Size (Bytes)
K-J	6	3,000,000

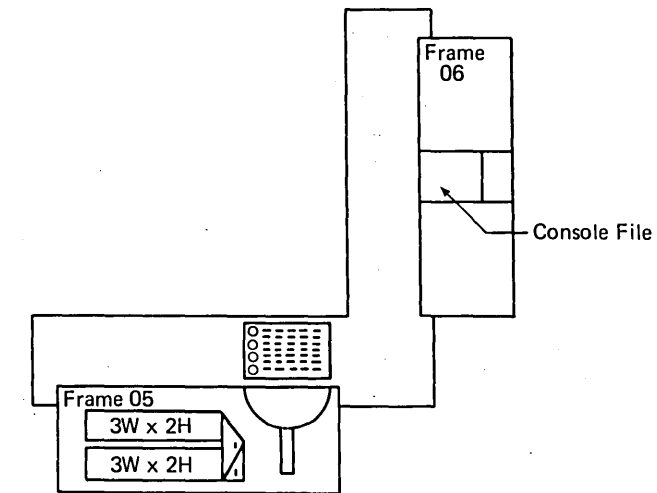


Figure 2-20 - K-J Storage

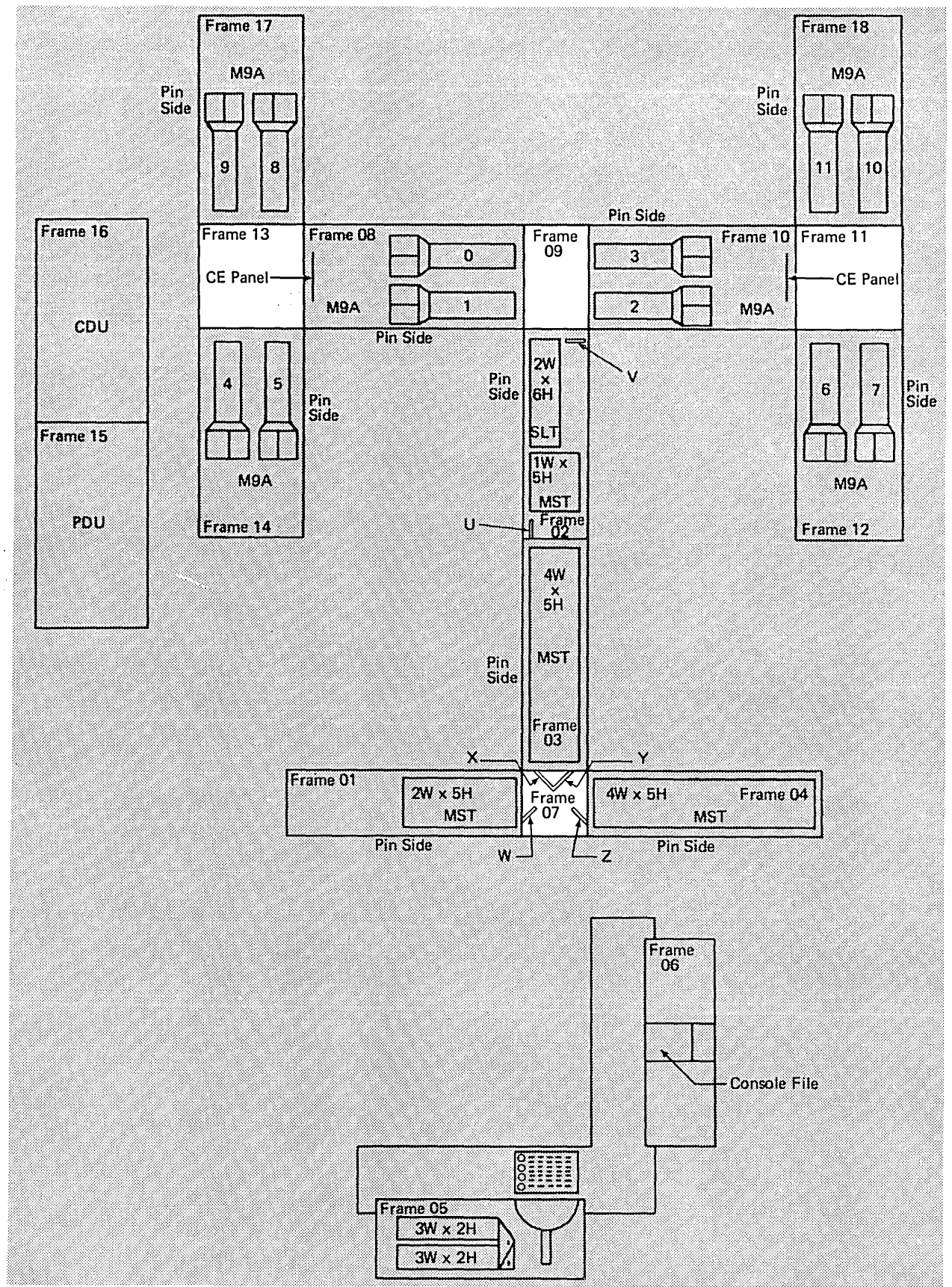
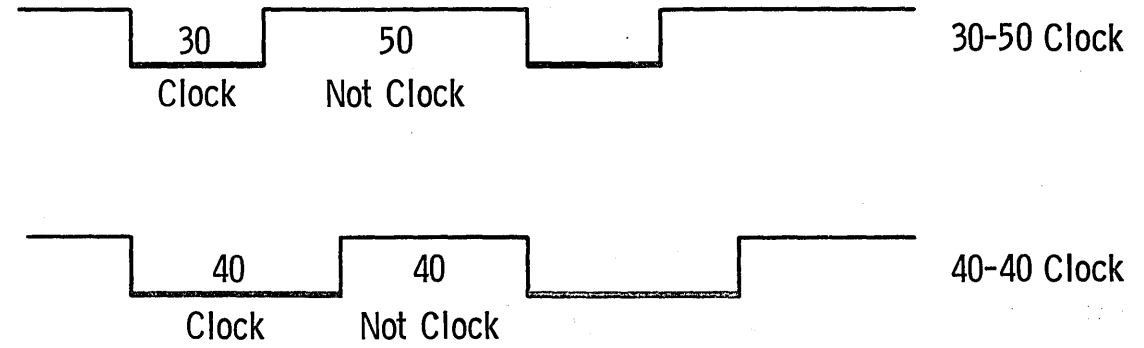


Figure 2-21 - Cable Feed Through Frames



* The term 40-40 refers to the clock and not-clock portions of the 80-nsec clock cycle. In this case, both the clock and not-clock portions of a clock period are equal to 40 nsec. In the 30-50 clock is 30 nsec and not-clock is 50 nsec.

Figure 2-22 - Basic Clock Shapes

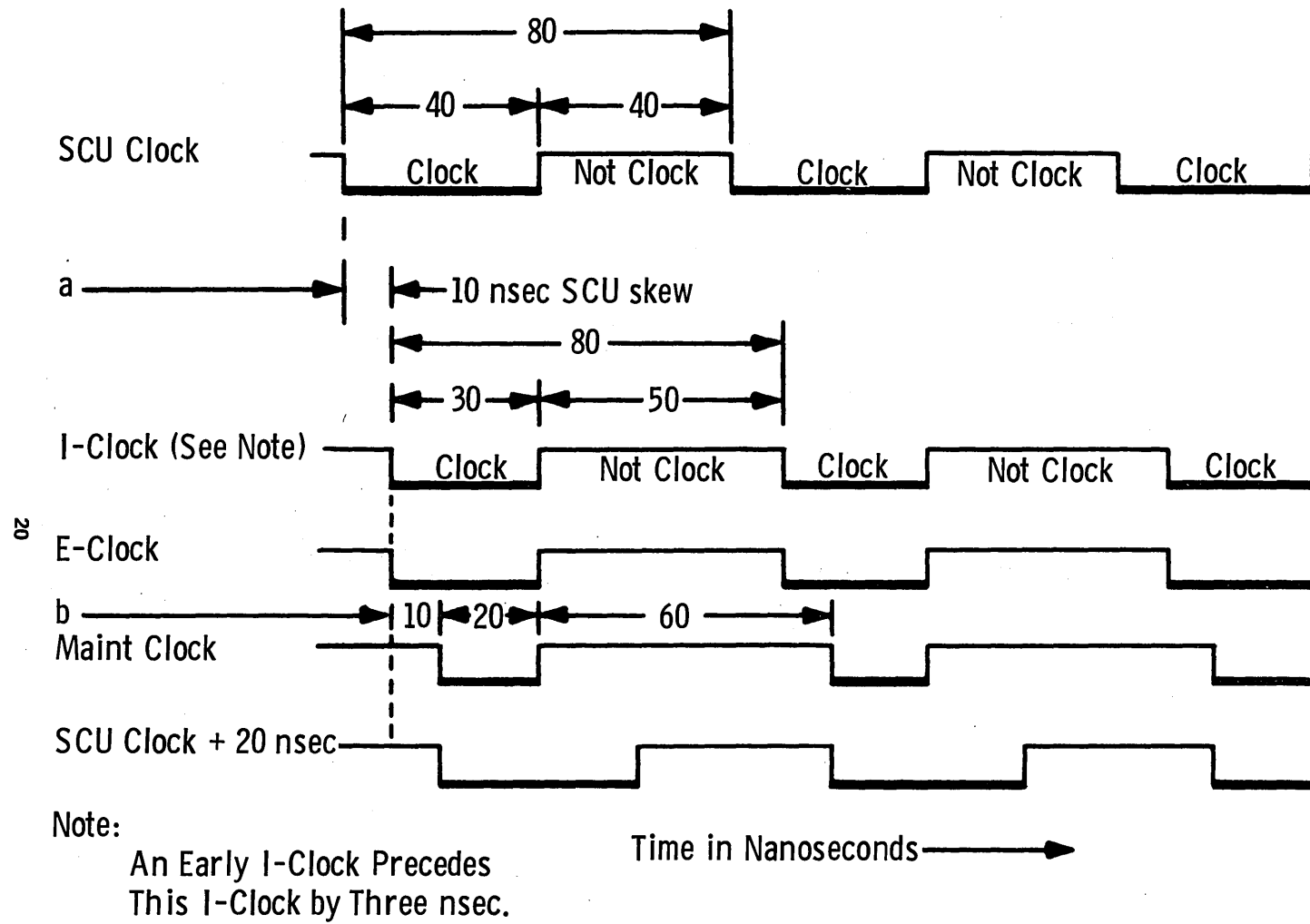


Figure 2-23 - Clock Alignment

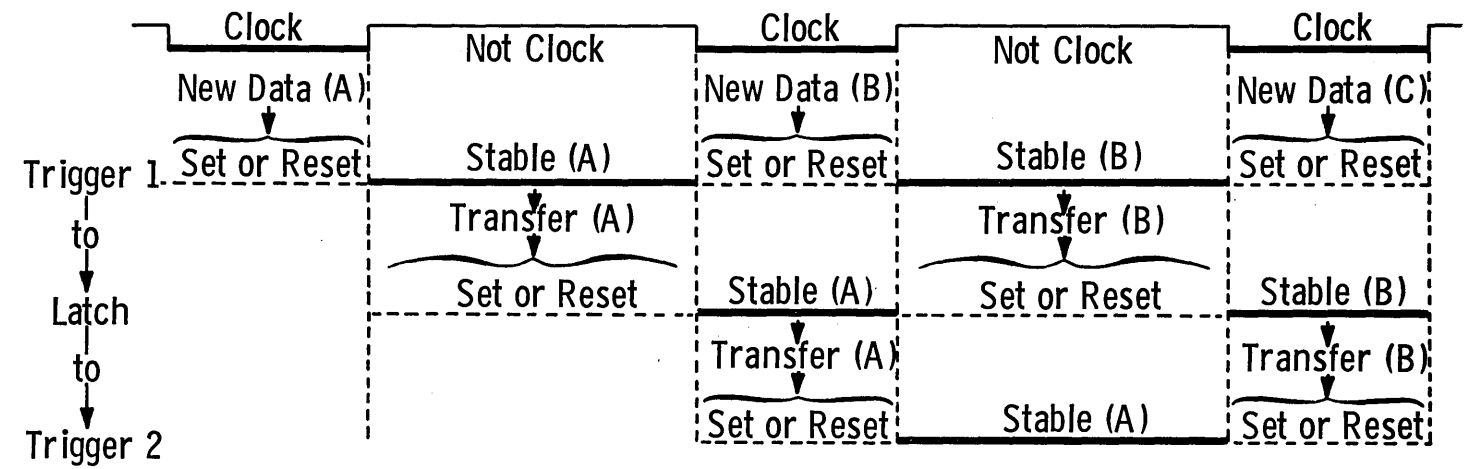


Figure 2-24 - Trigger and Latch Relationship

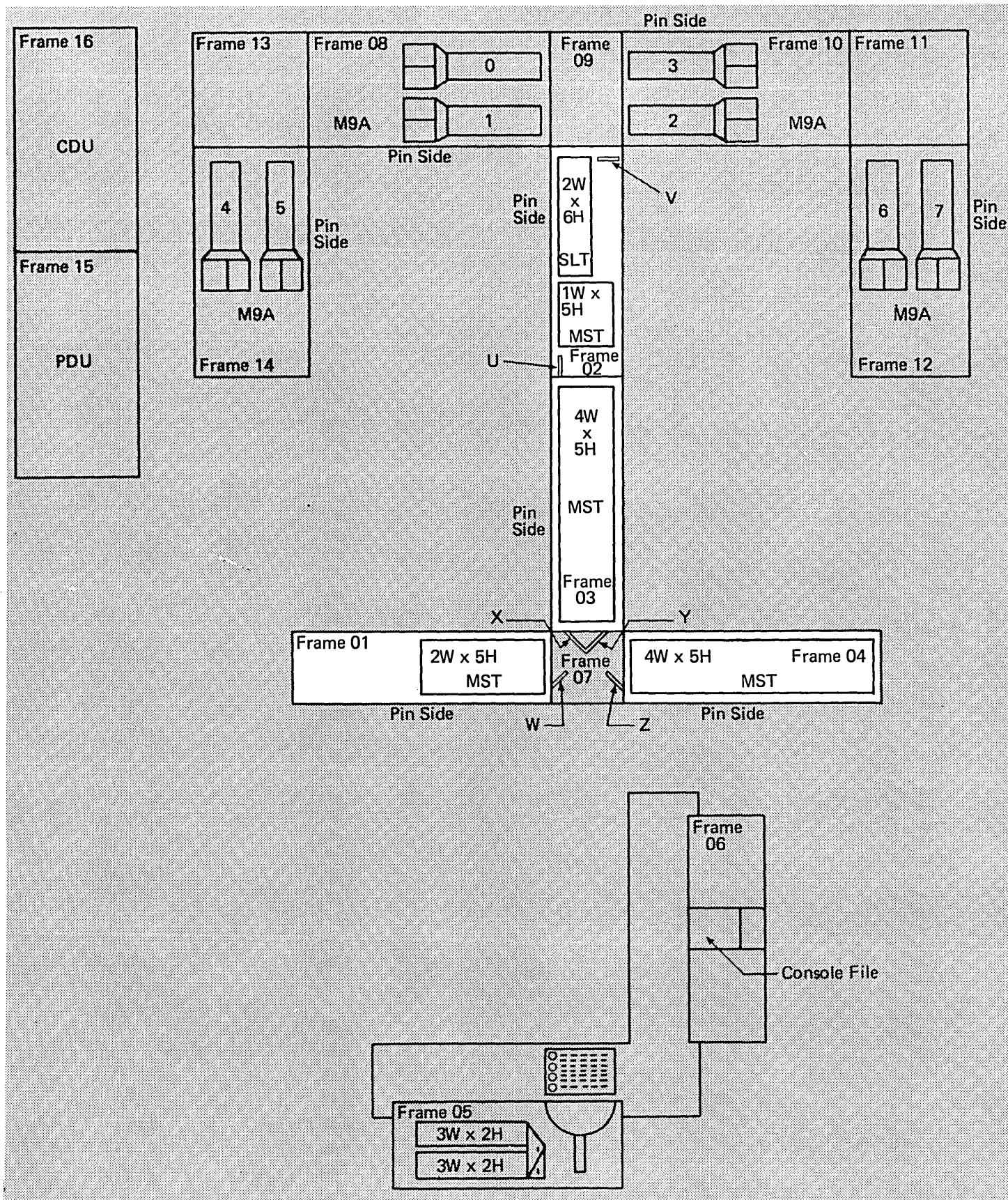


Figure 2-25 - CPU

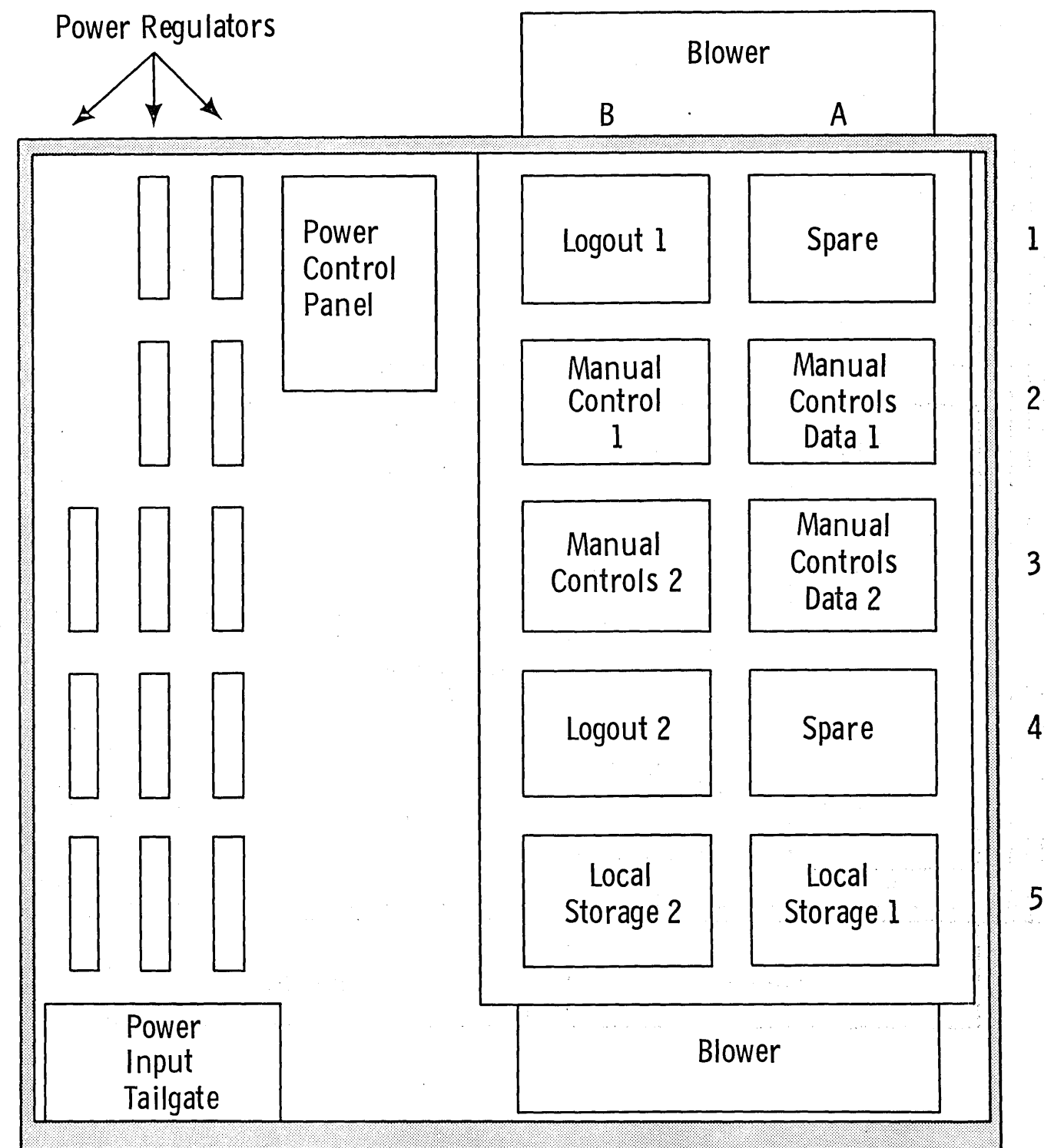


Figure 2-26 - Frame 01 Pin Side

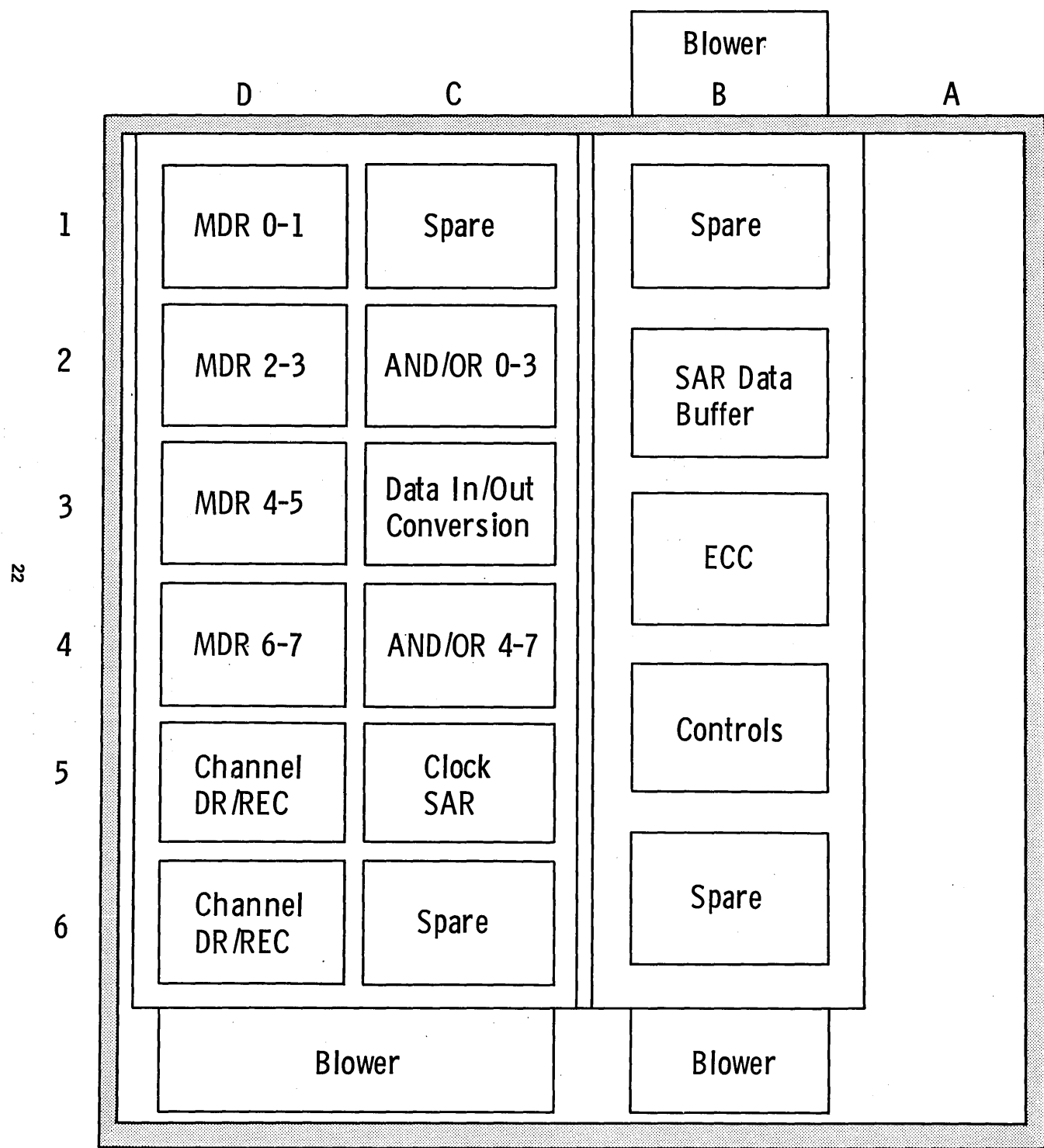


Figure 2-27 - Frame 02 Pin Side

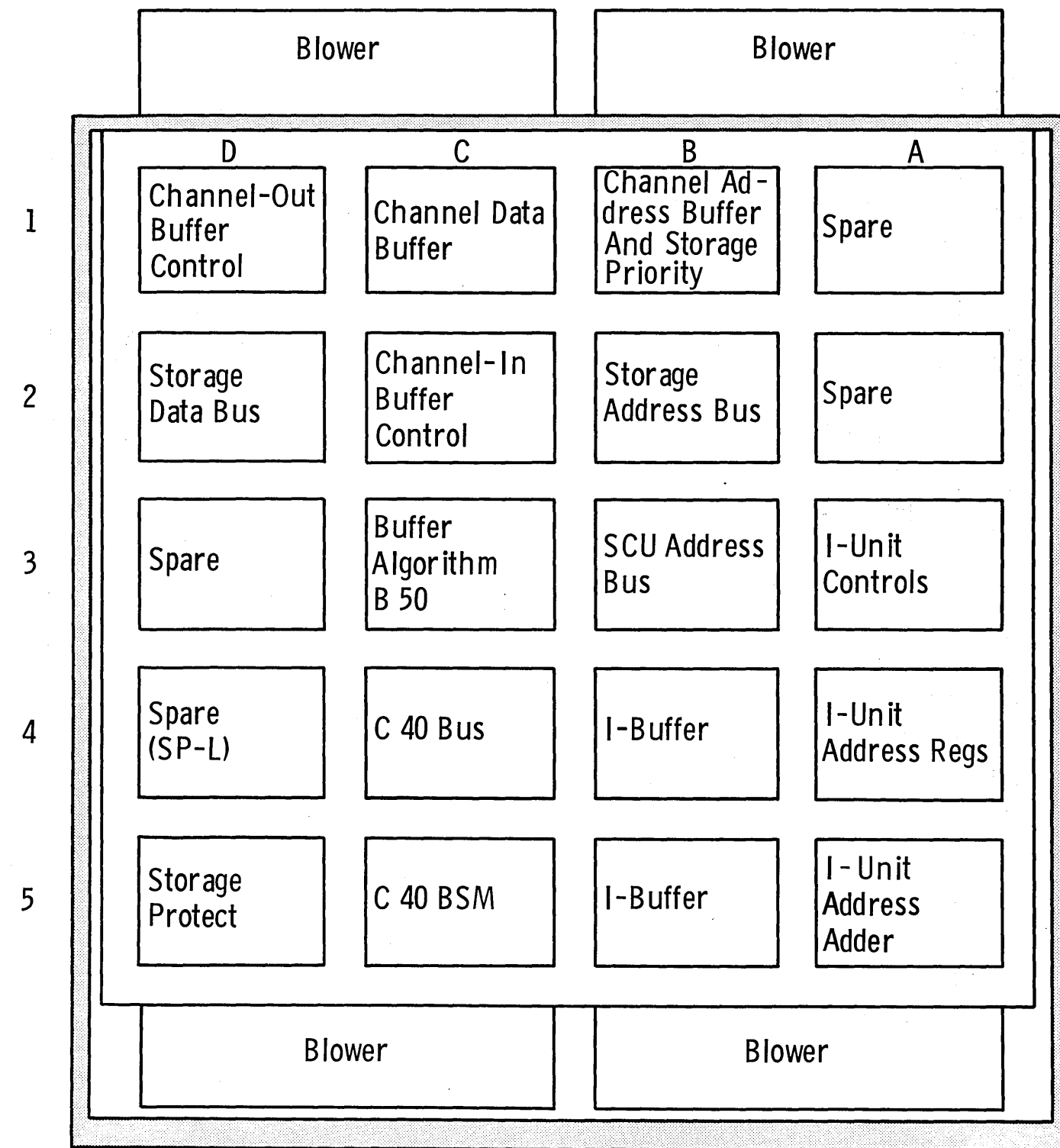
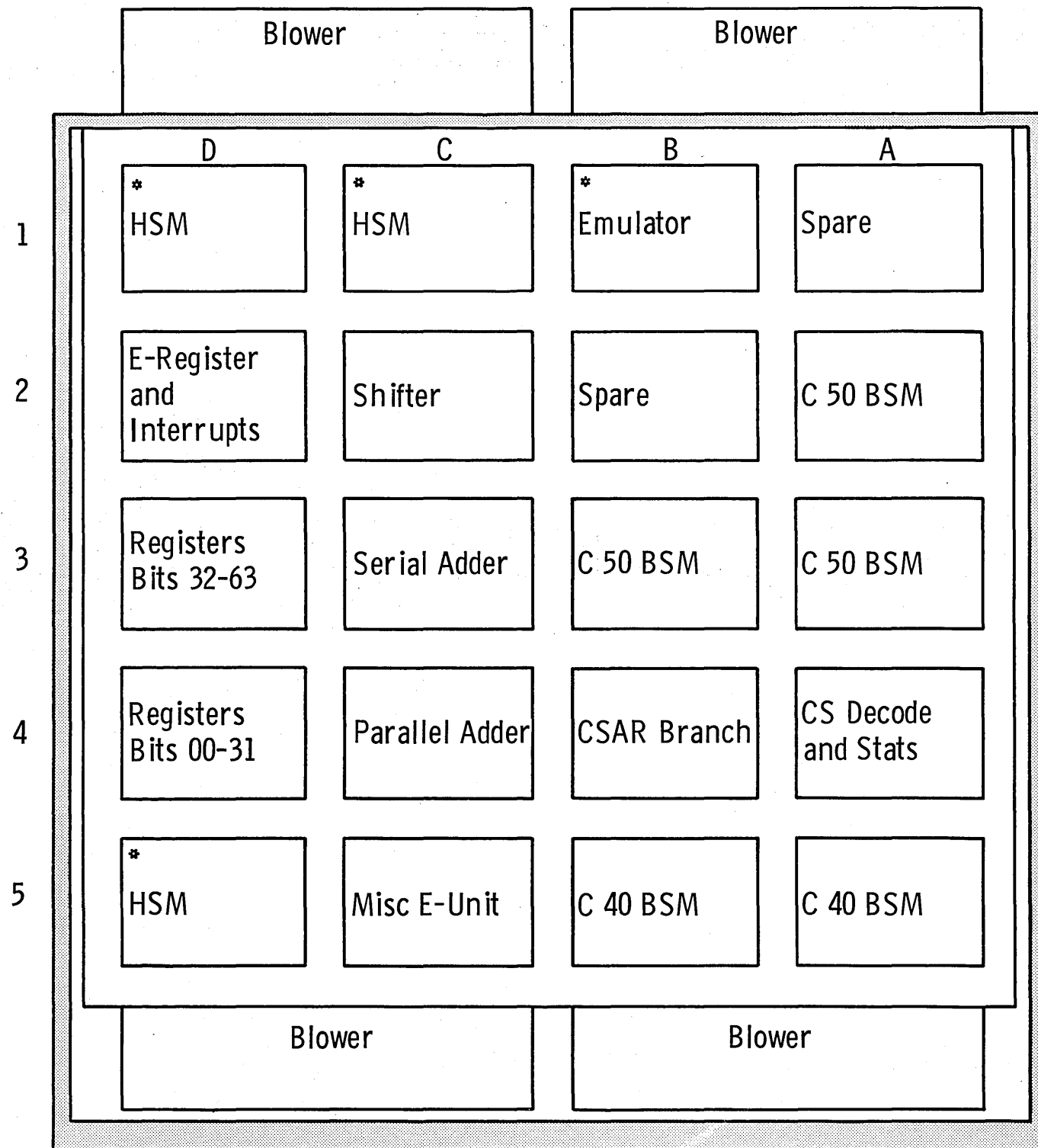


Figure 2-28 - Frame 03 Pin Side



*Feature Board

Figure 2-29 - Frame 04 Pin Side

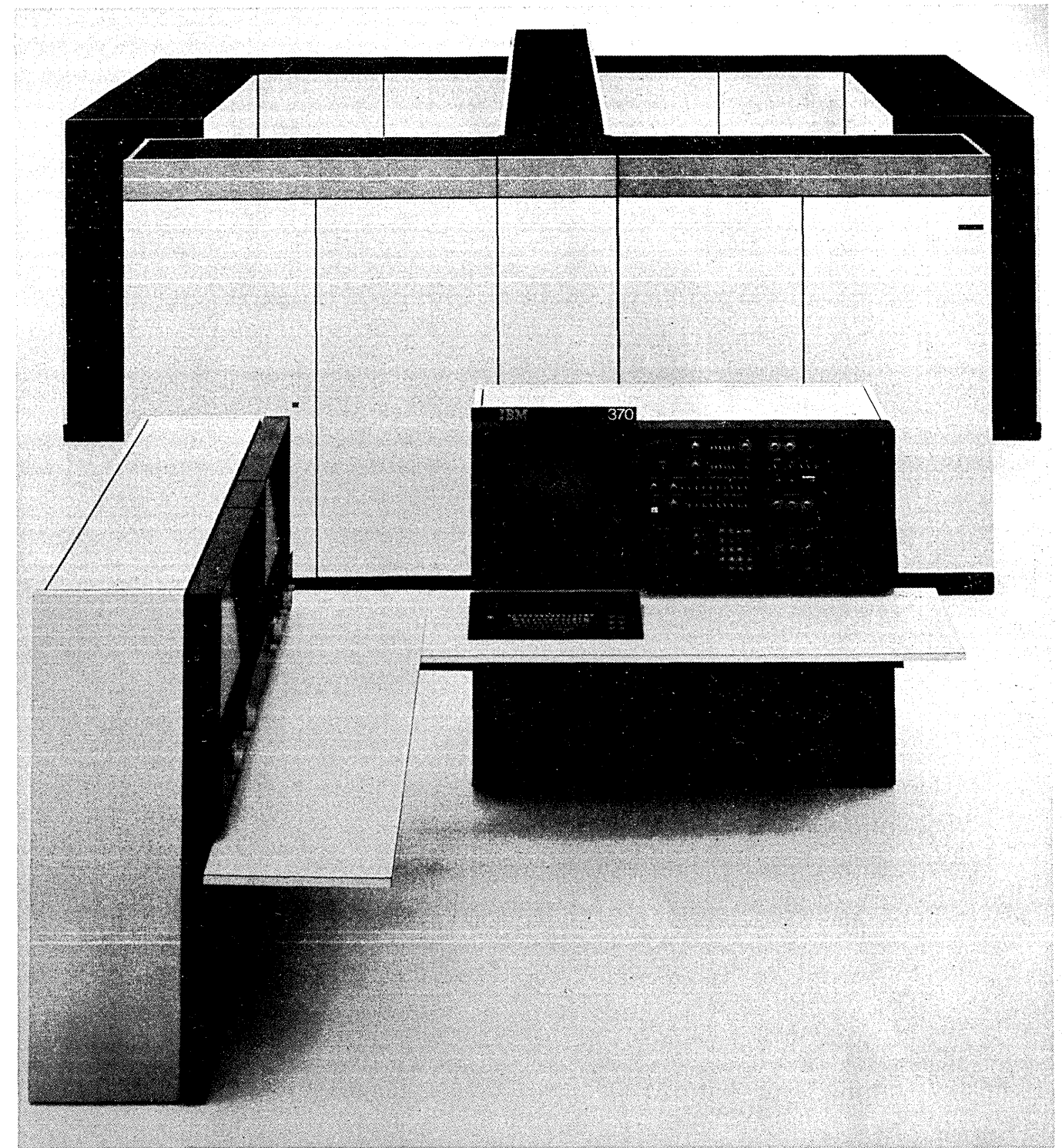


Figure 2-30 - Model 165

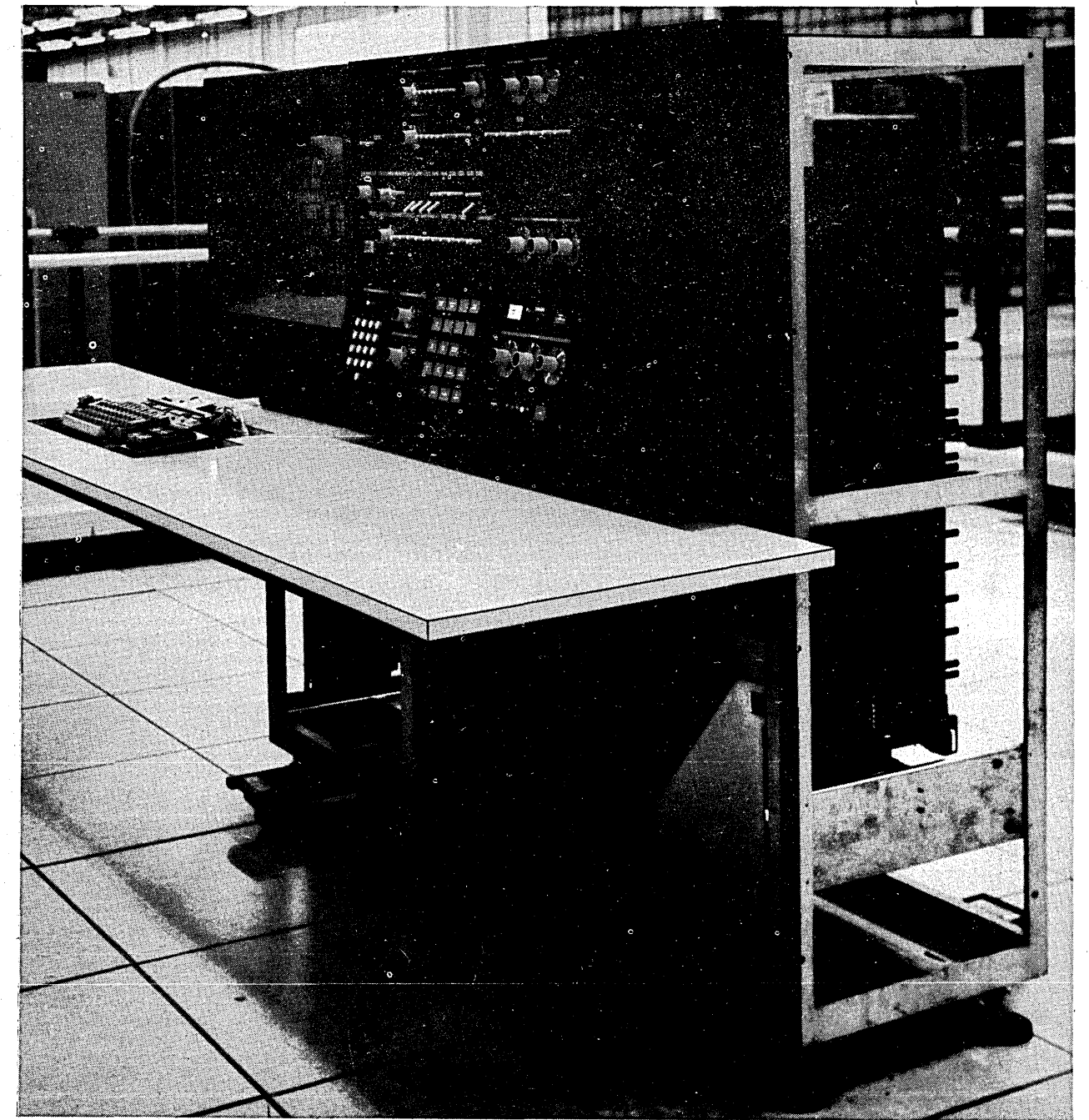
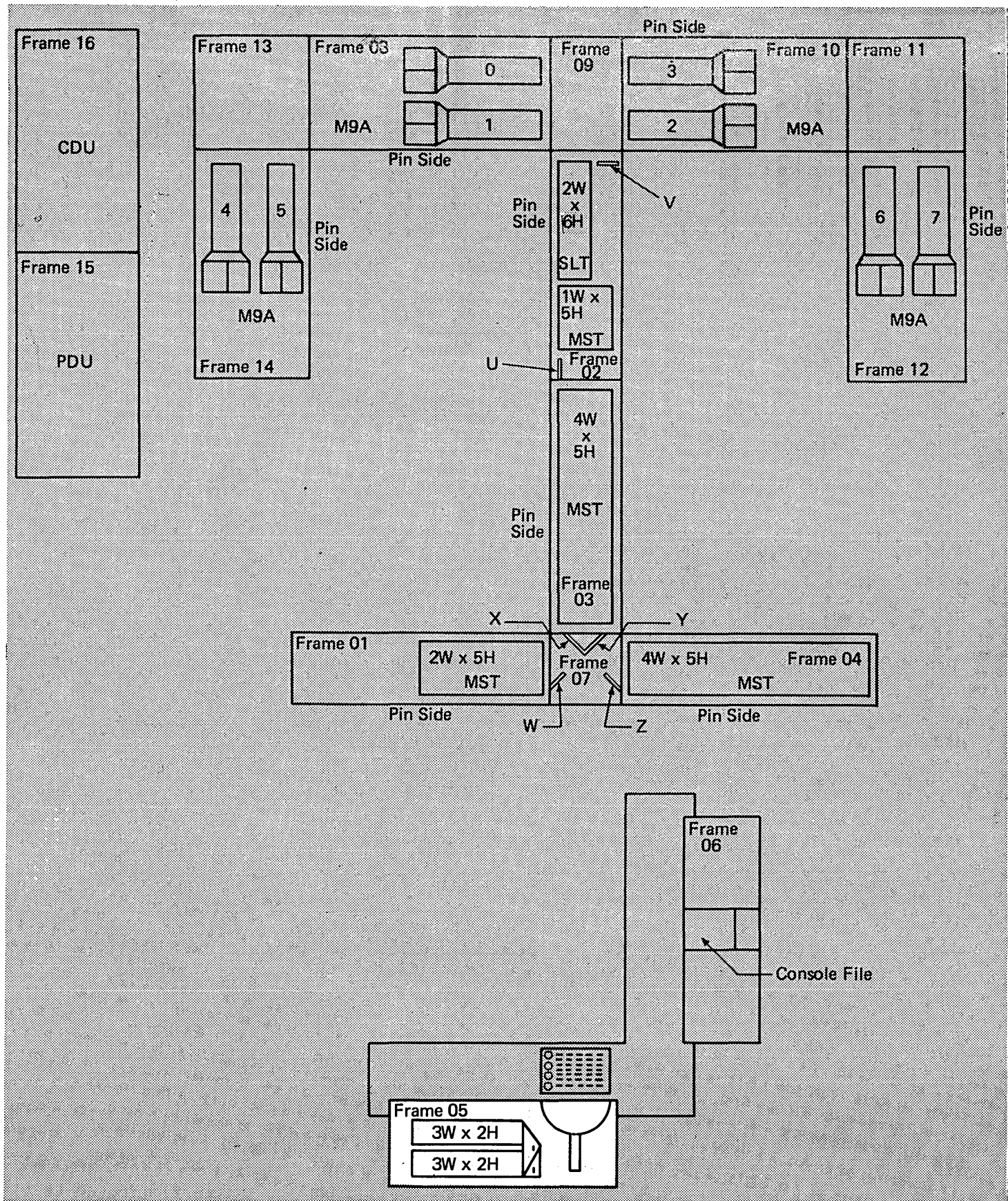


Figure 2-31 - System Control Panel

Figure 2-32 - System Control Panel

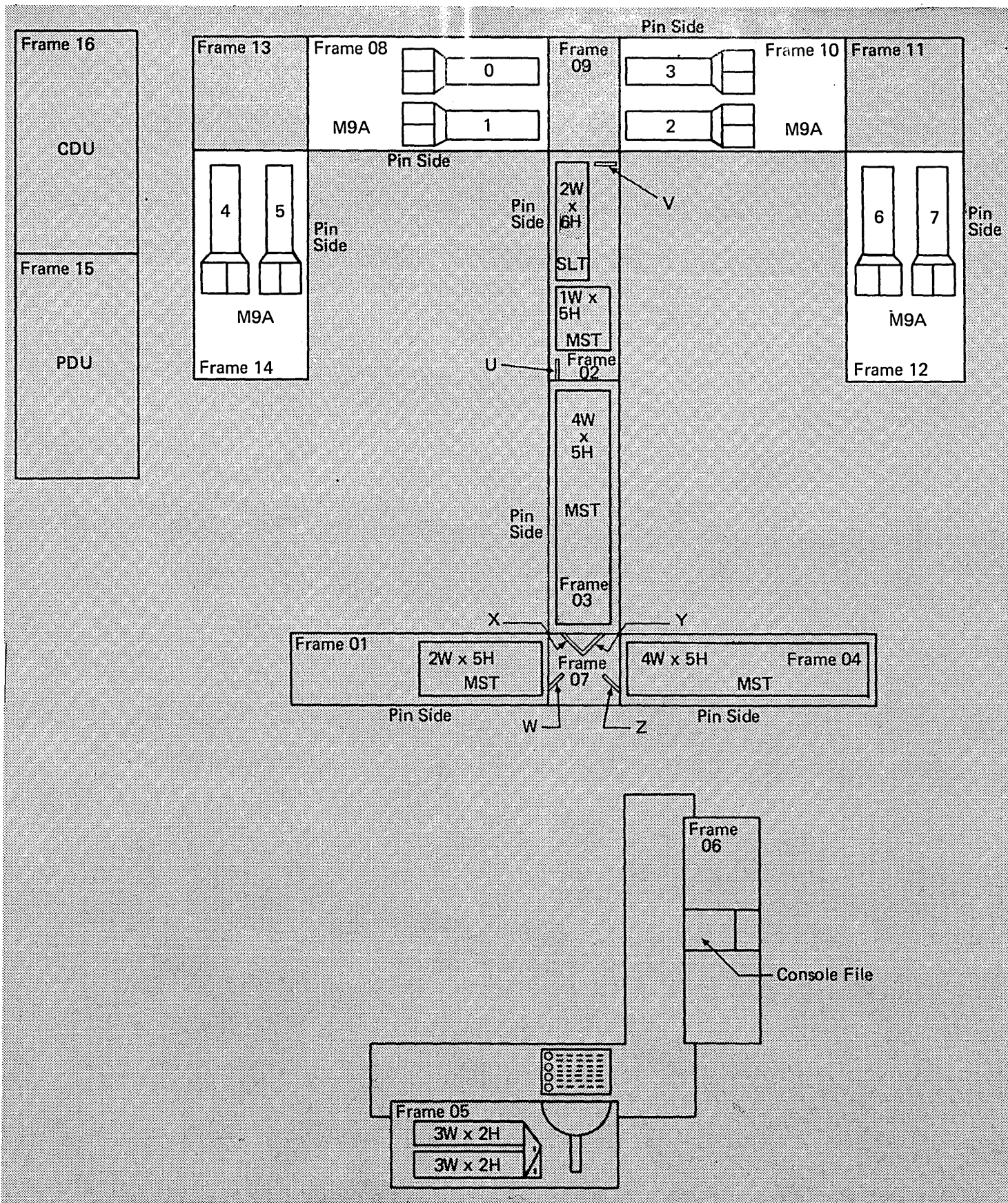


Figure 2-33 - Main Storage

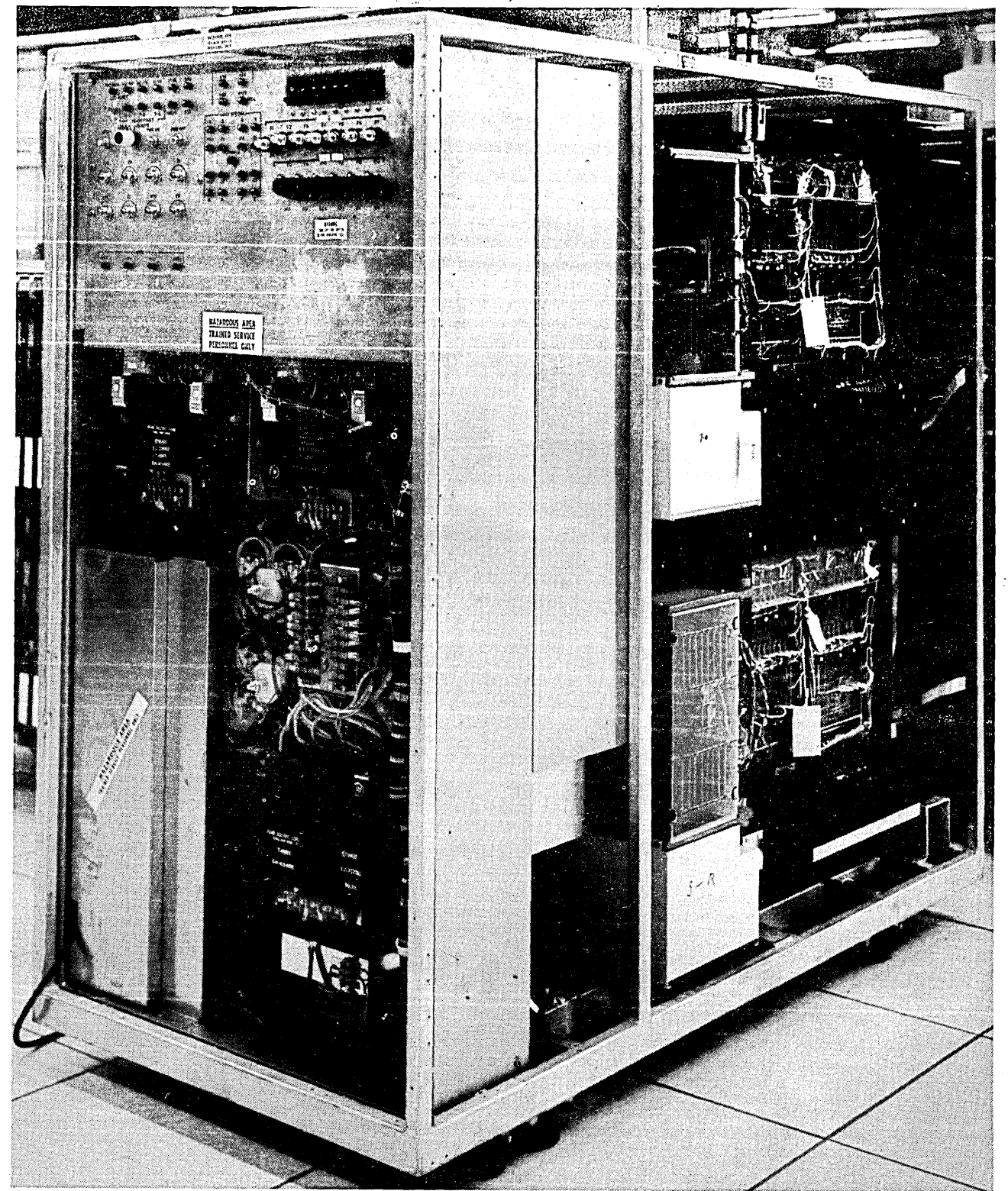


Figure 2-34 - M9A

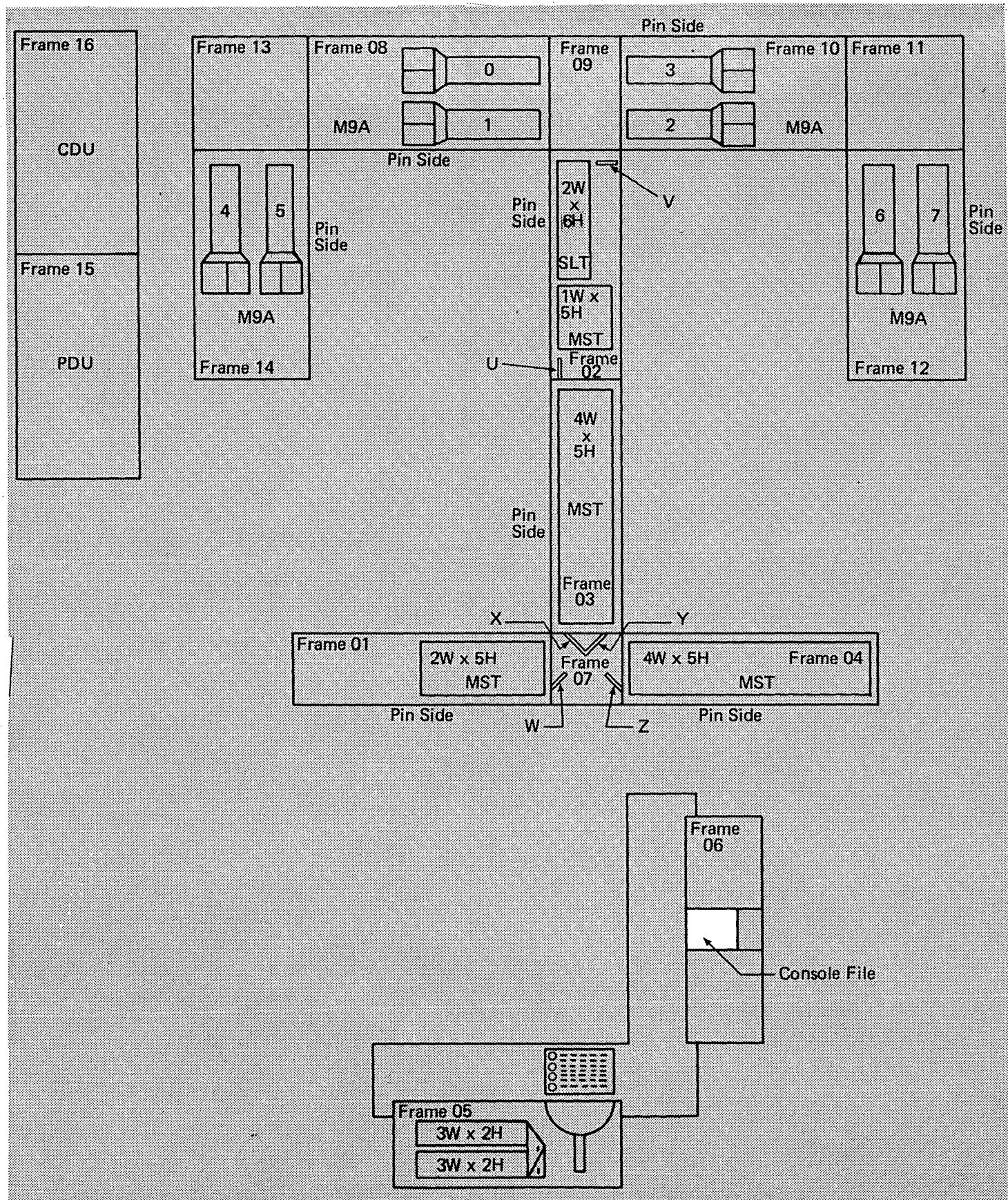


Figure 2-35 - Console File

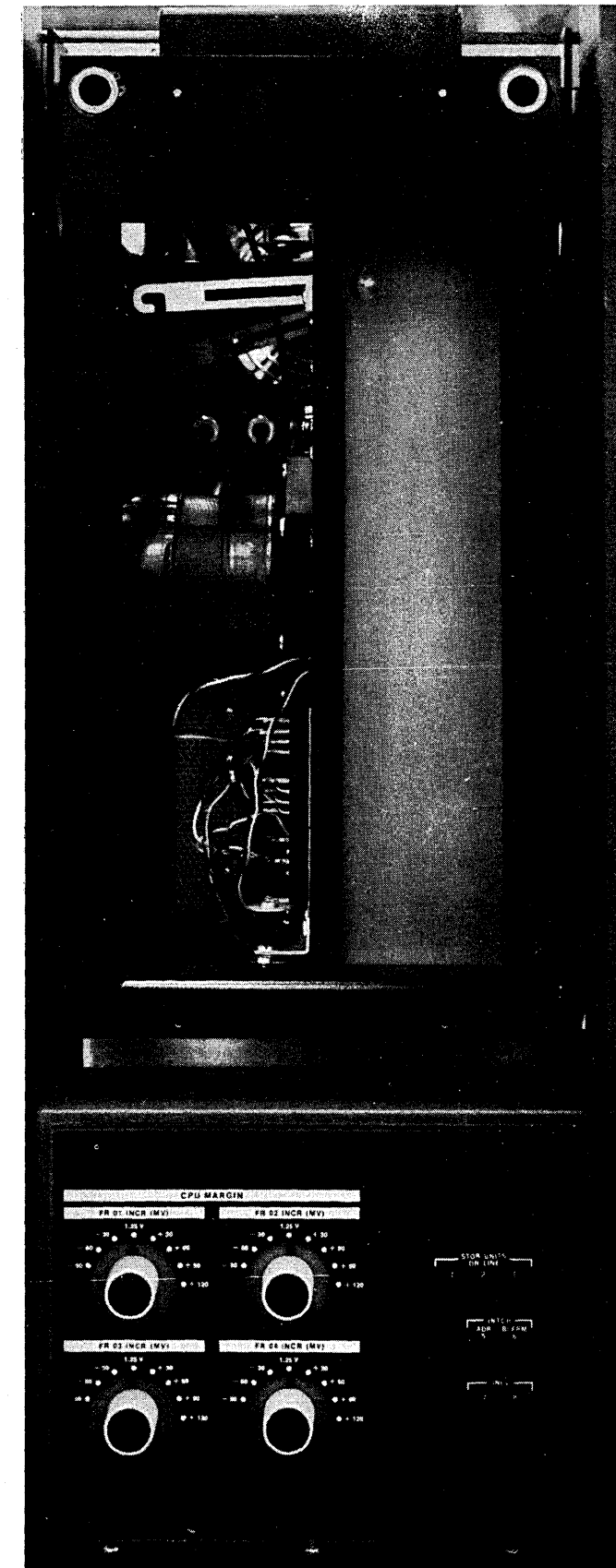


Figure 2-36 - Console File

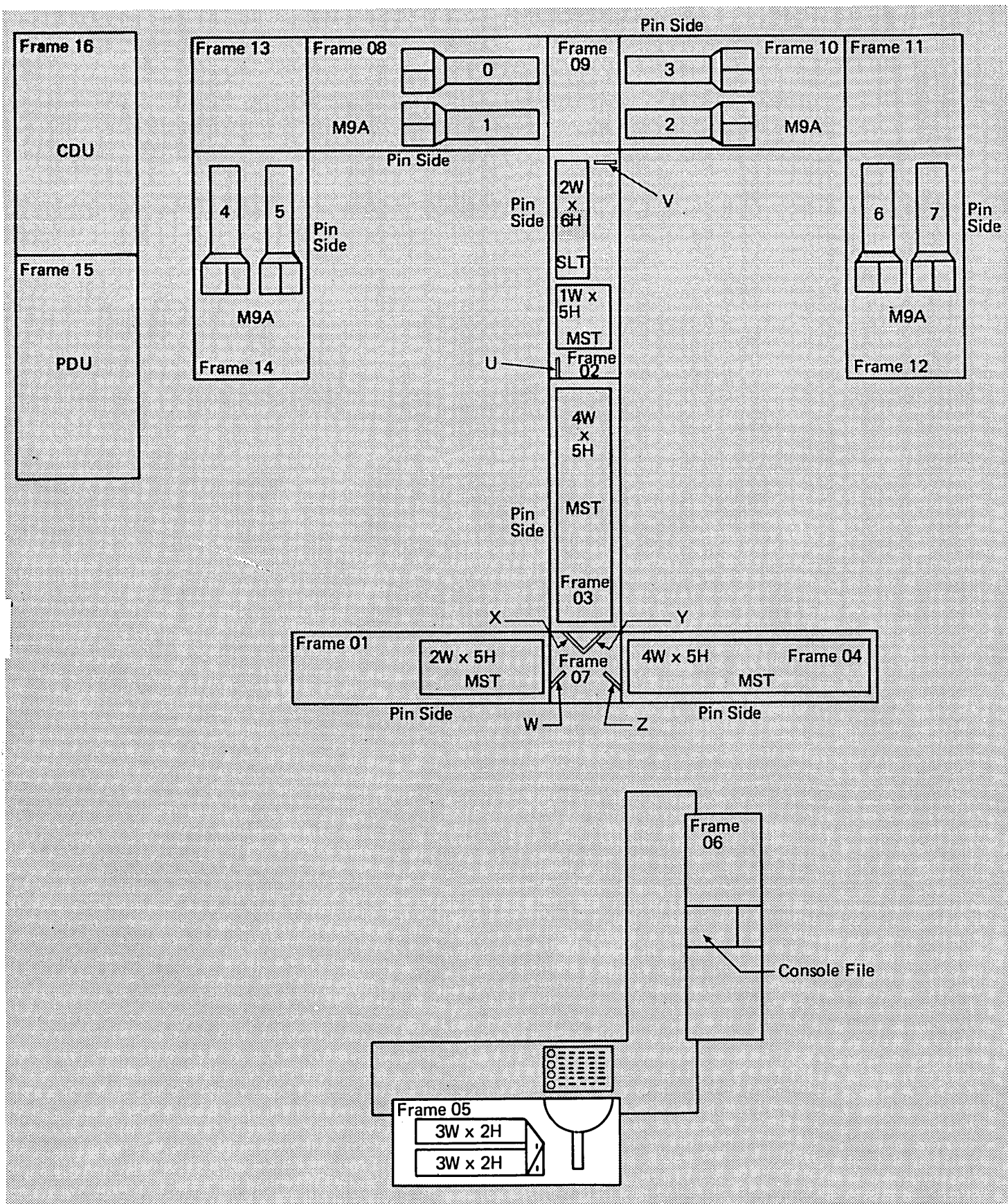


Figure 2-37 - Frame 5

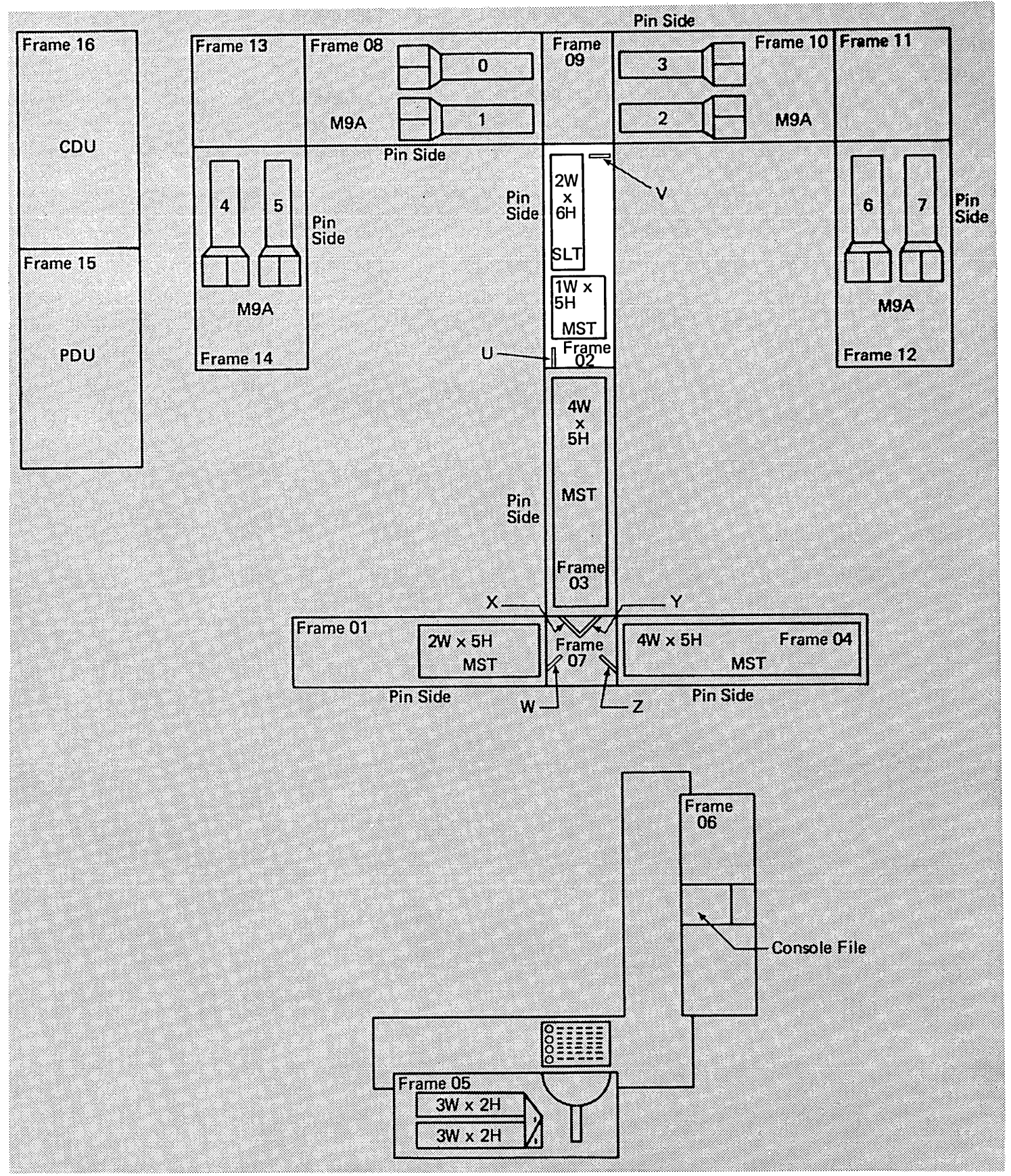
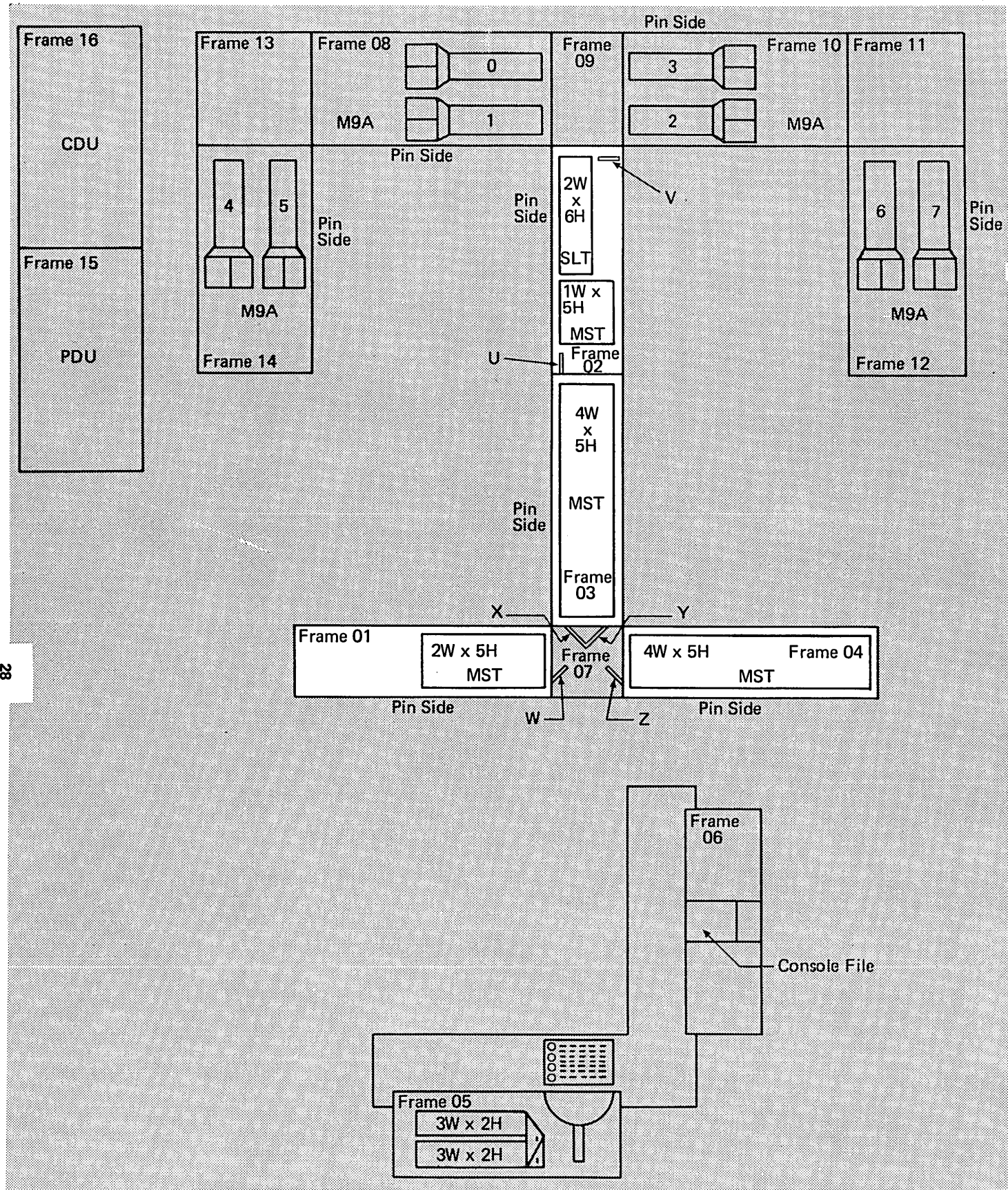


Figure 2-38 - Frame 02



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Figure 2-39 - CPU Frames

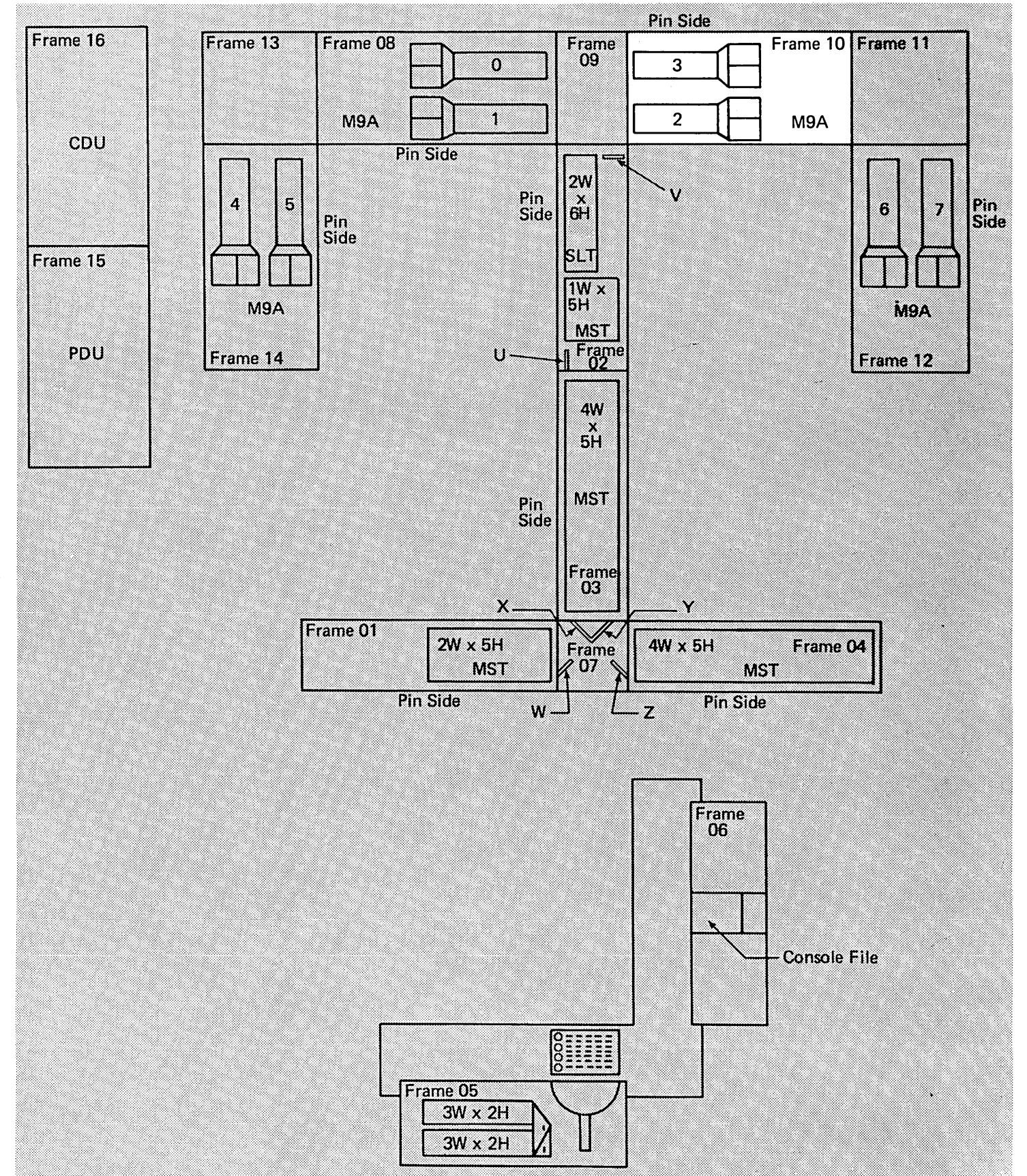


Figure 2-40 - Frame 10

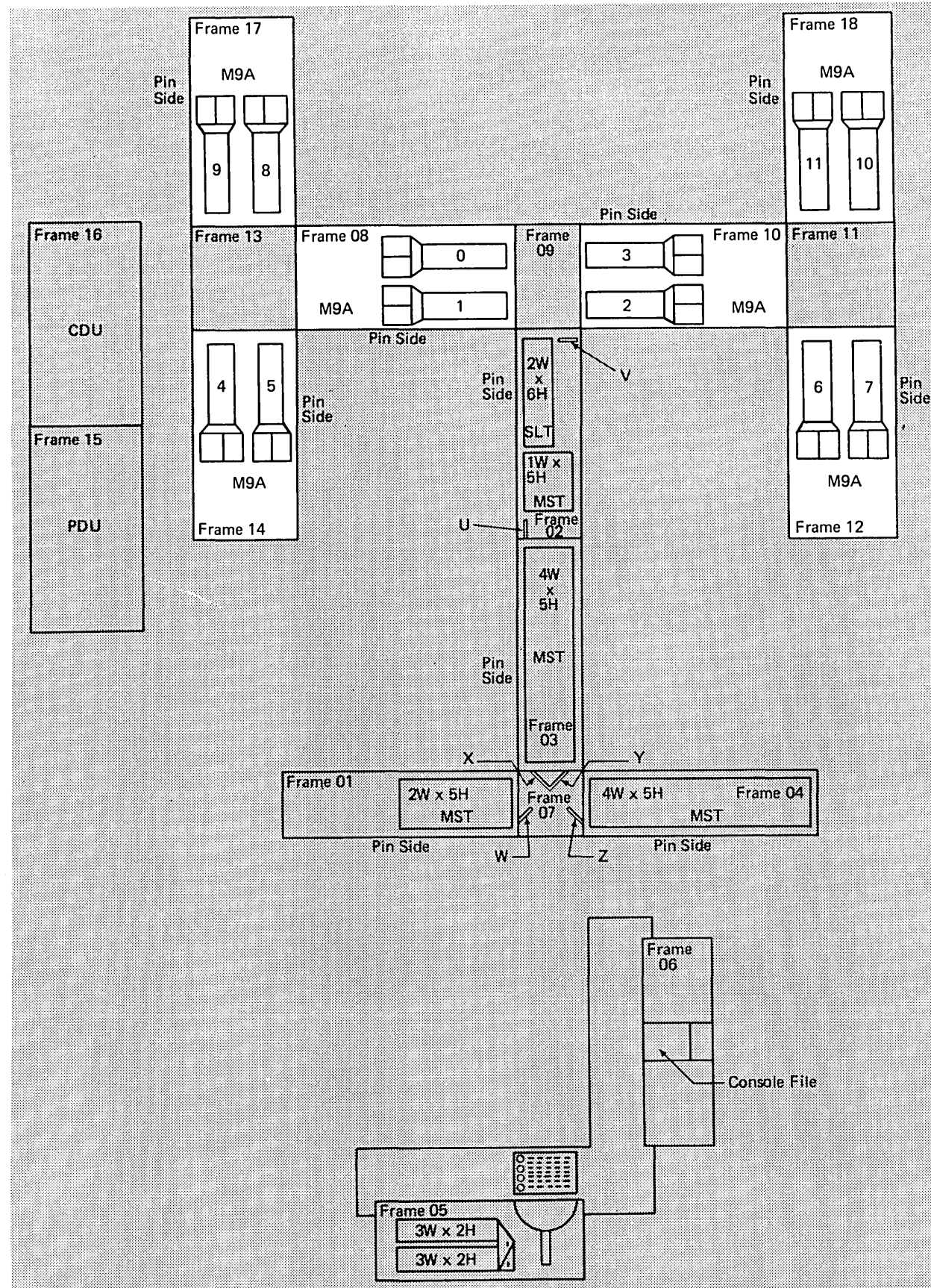


Figure 2-41 - Main Storage Frames

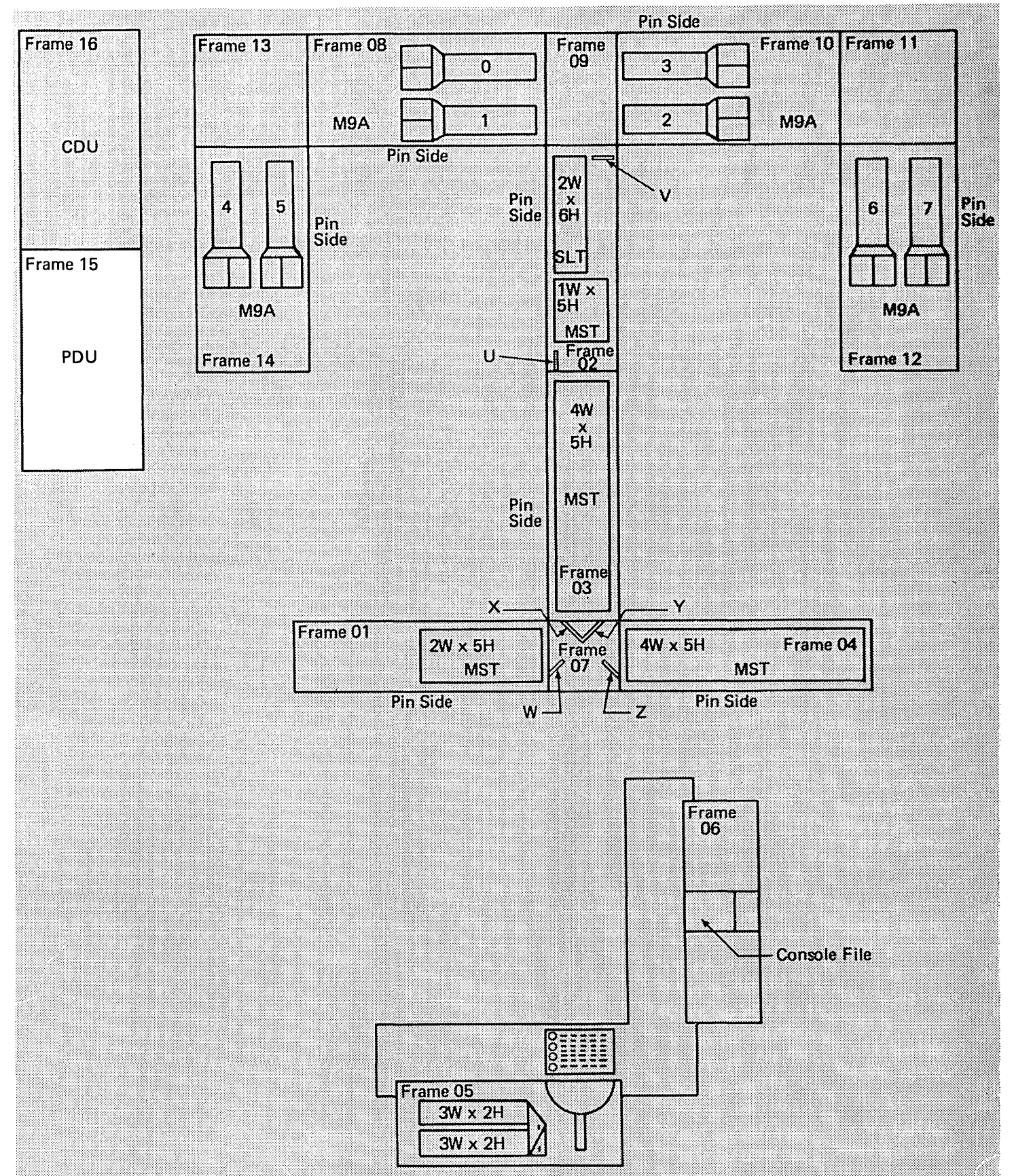
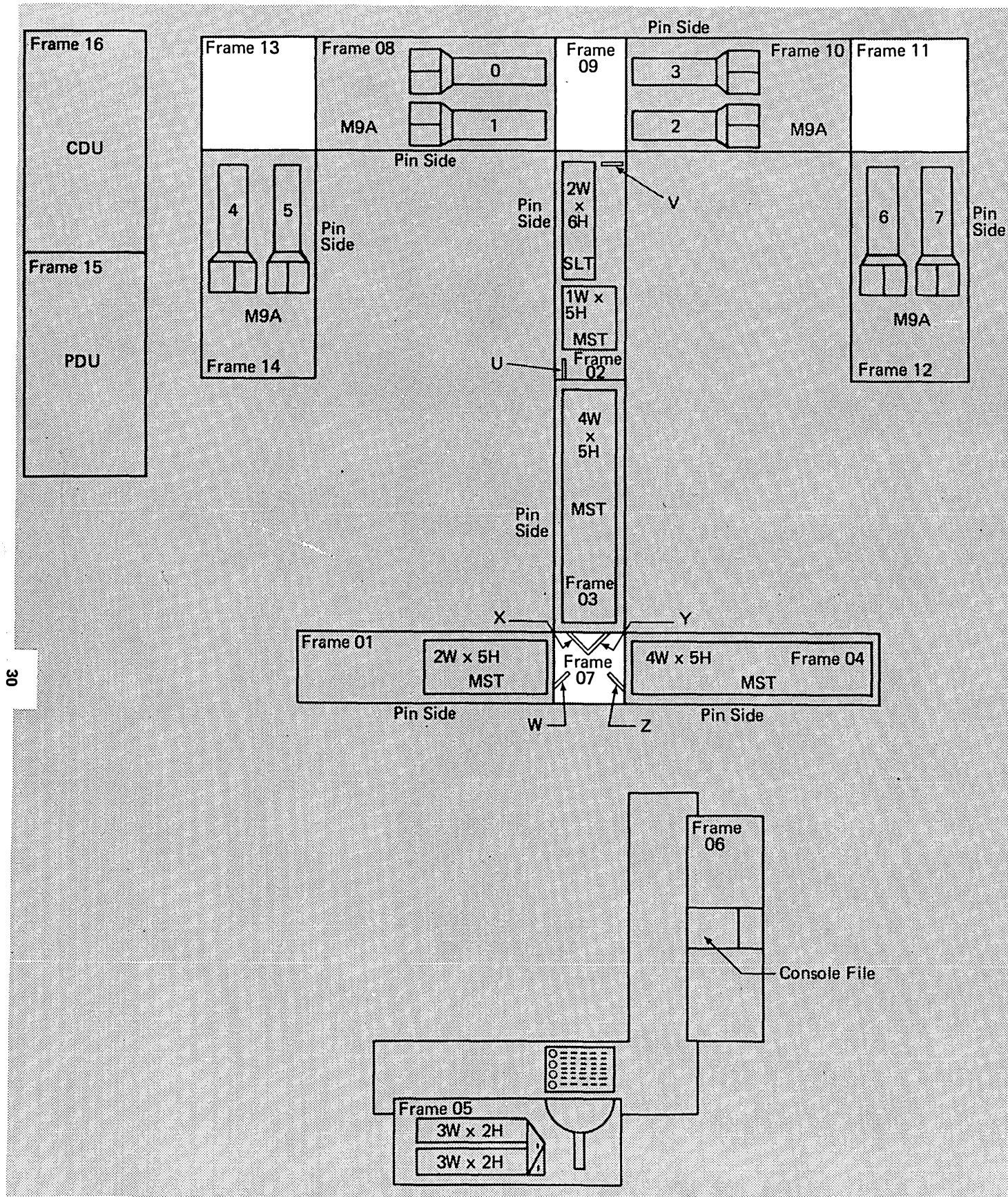


Figure 2-42 - Power Distribution Unit



30

Figure 2-43 - Dummy Frames

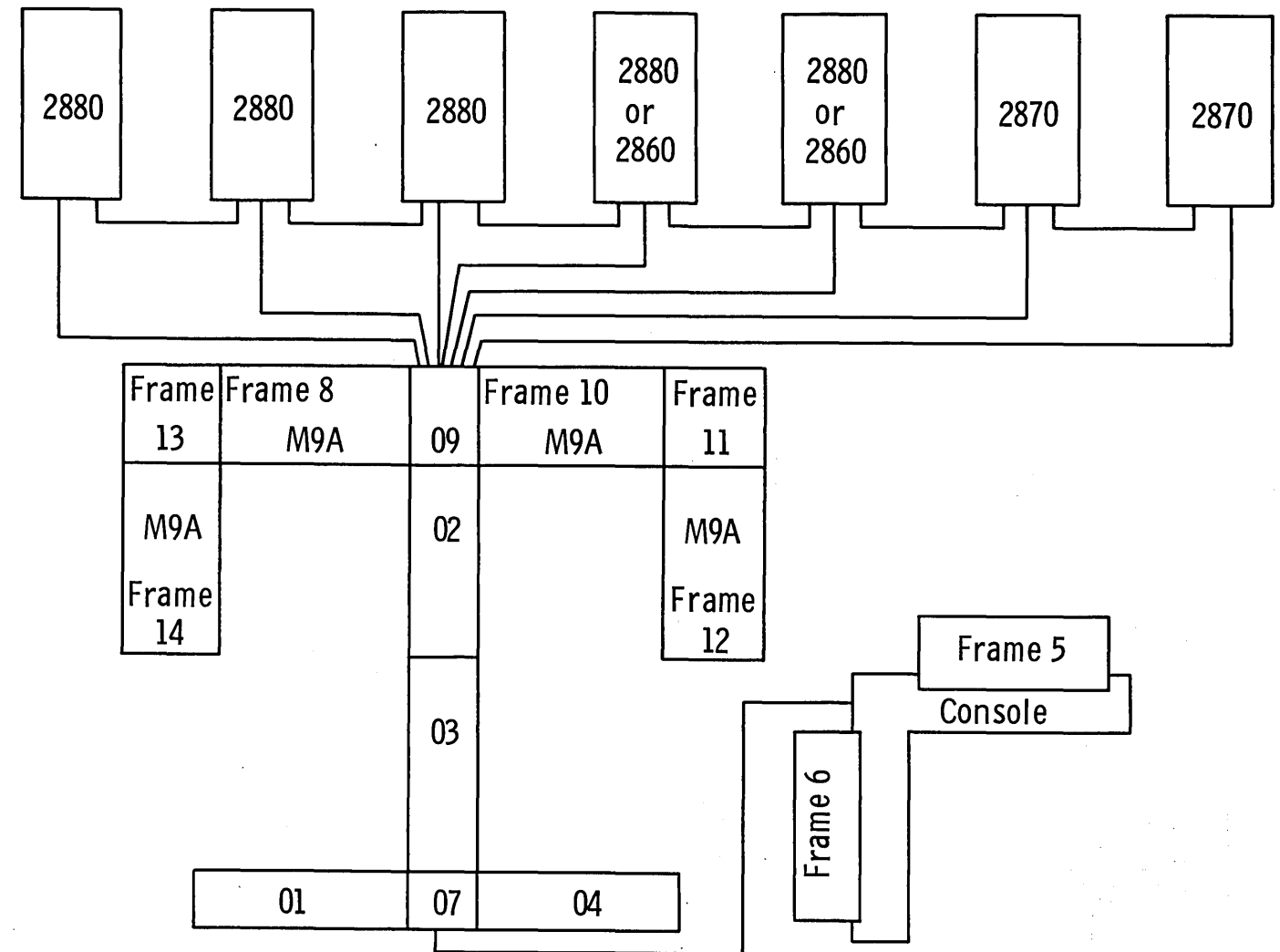


Figure 2-44 - Cabling

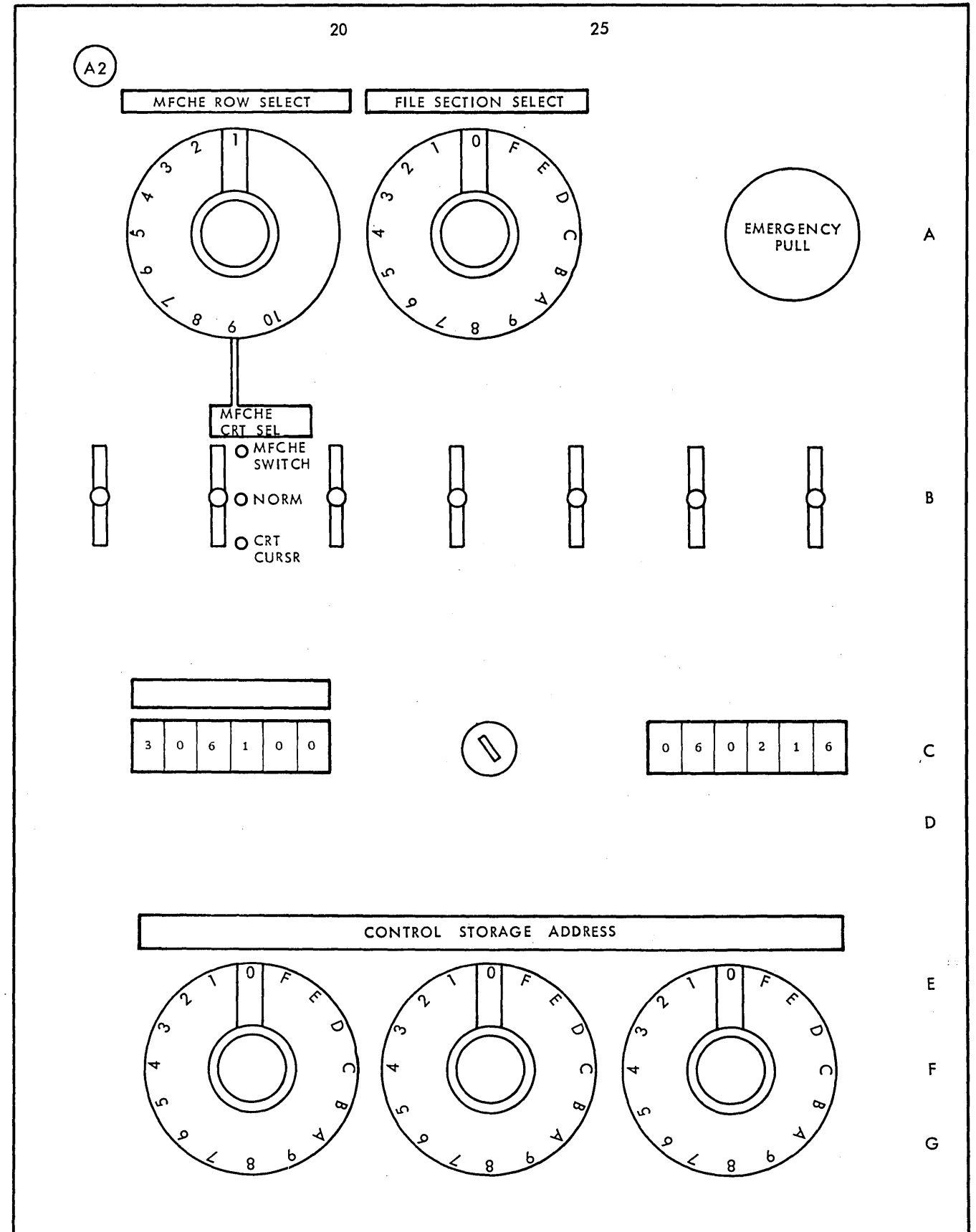
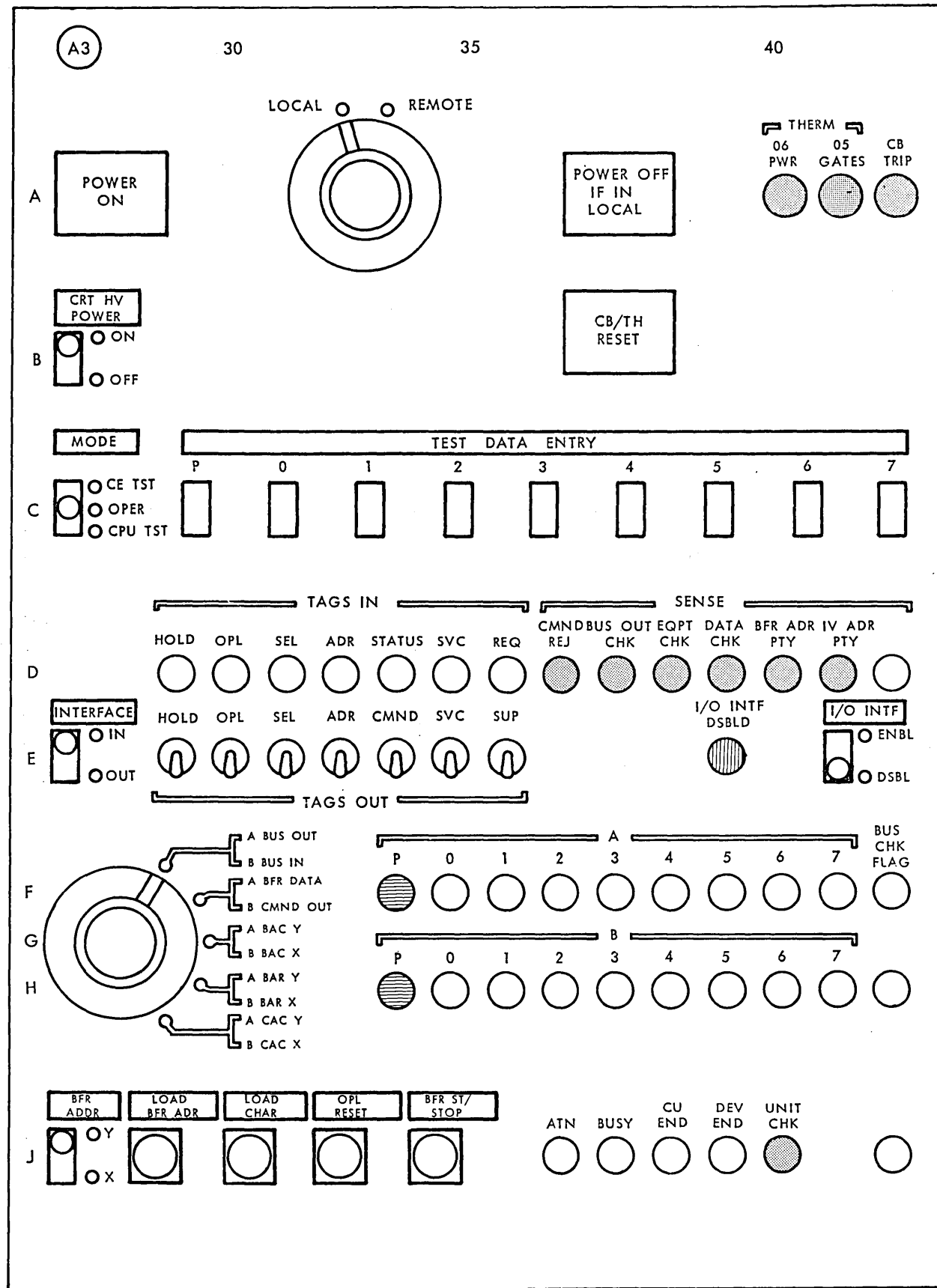


Figure 3-1 - Session 3 Question 1

Figure 3-2 - Session 3 Question 2

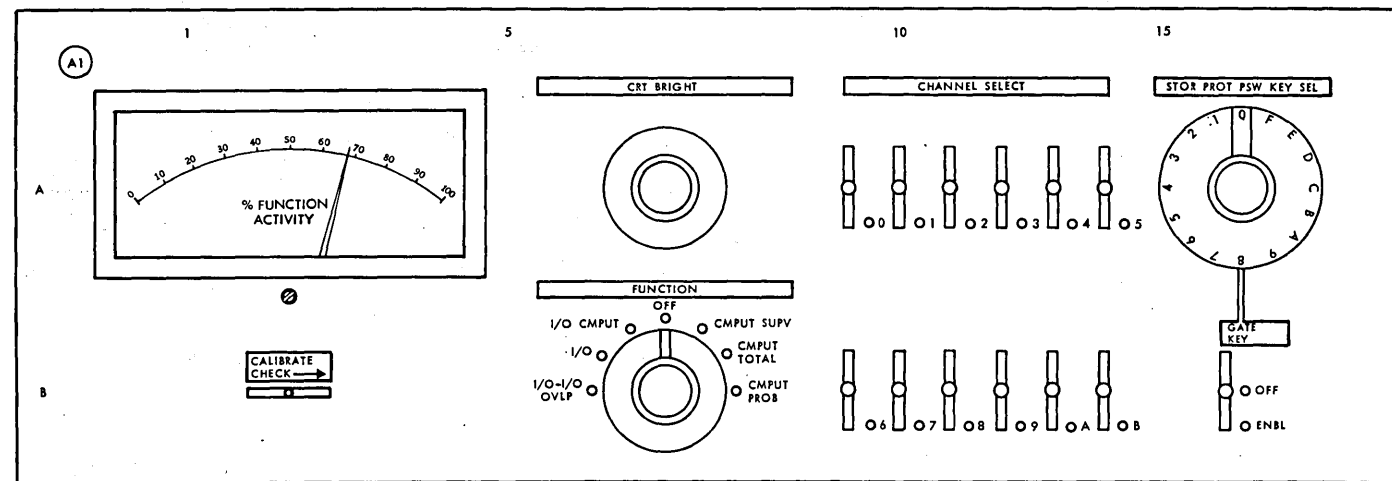


Figure 3-3 - Session 3 Question 3

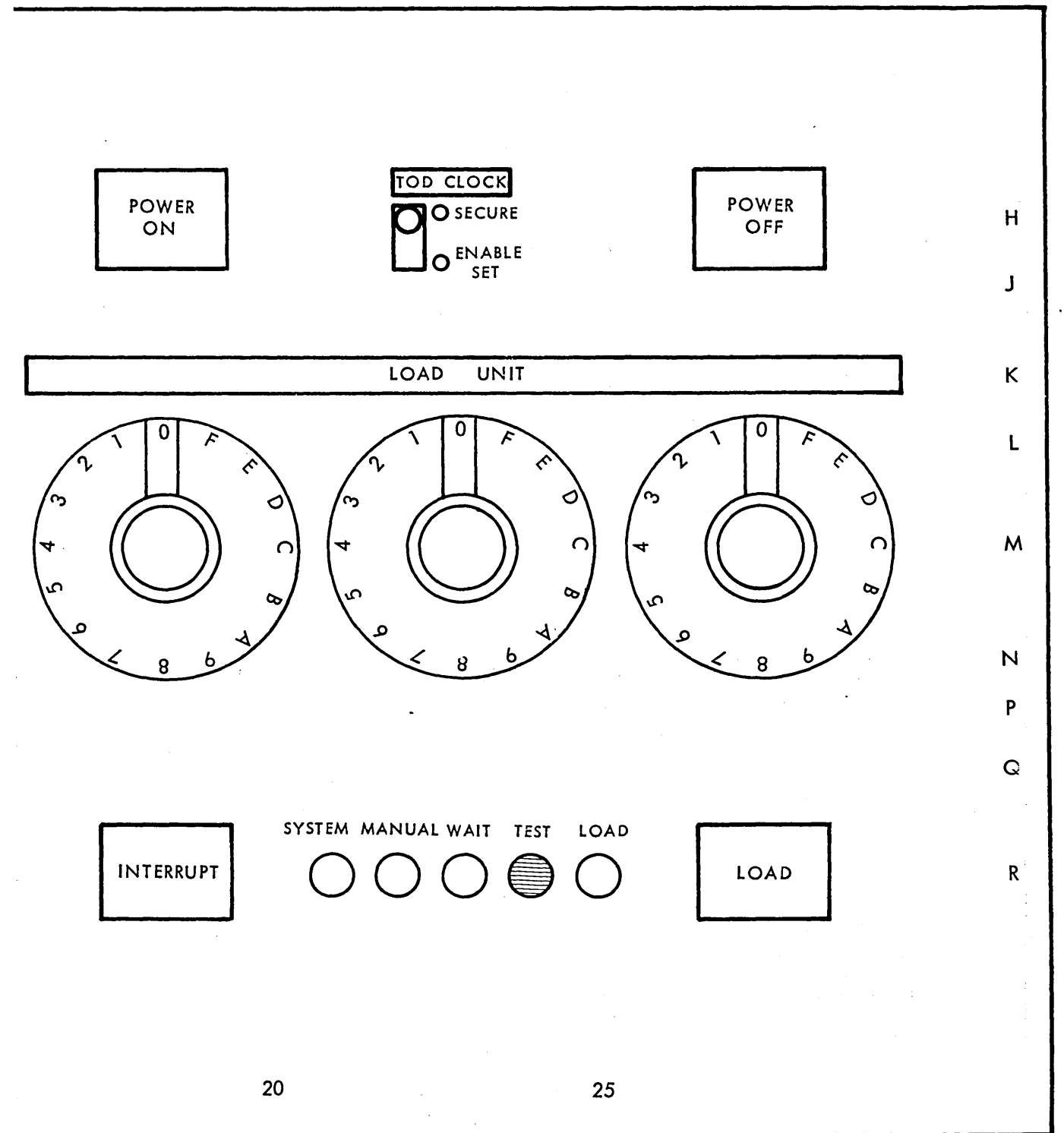


Figure 3-4 - Session 3 Question 4

H
J
K
L
M
N
P
Q
R

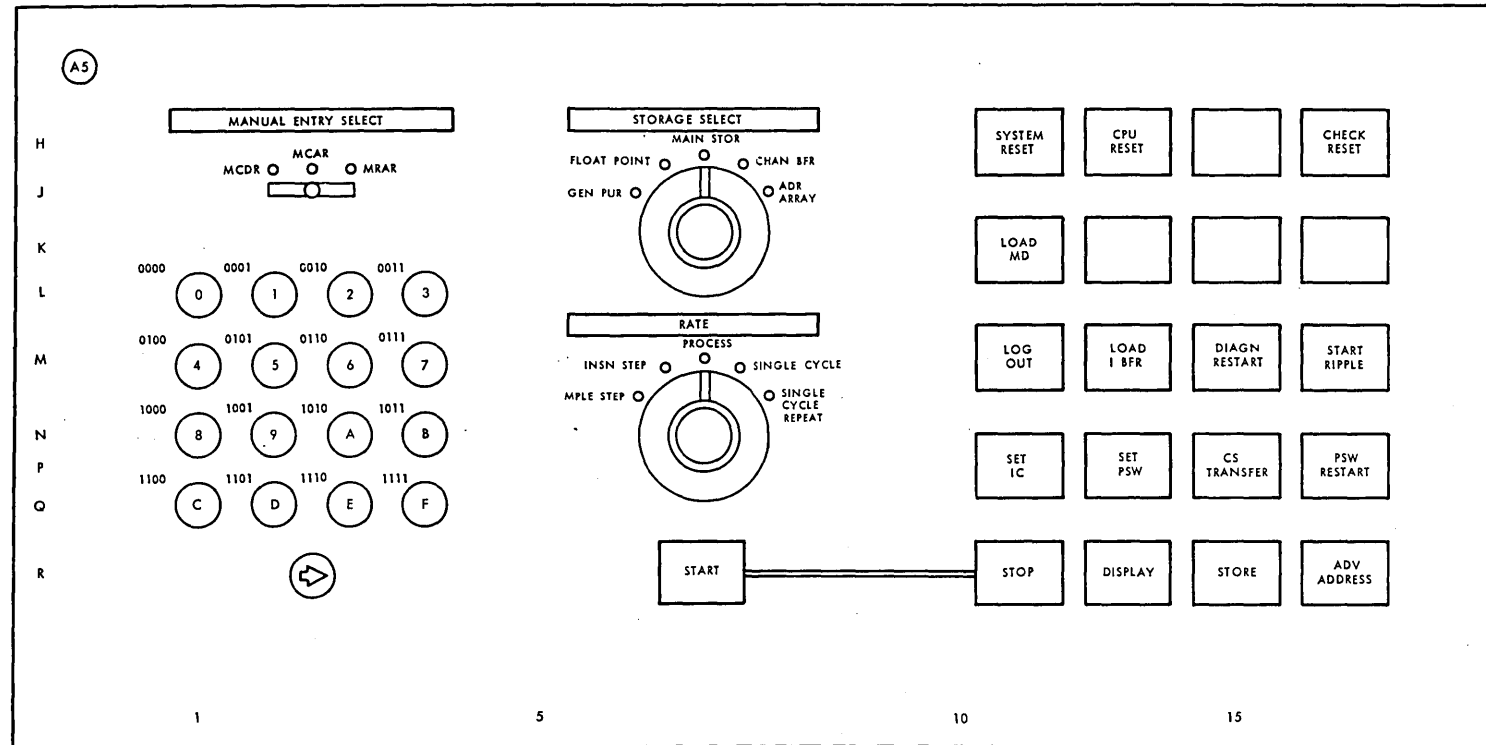


Figure 3-5 - Session 3 Question 5

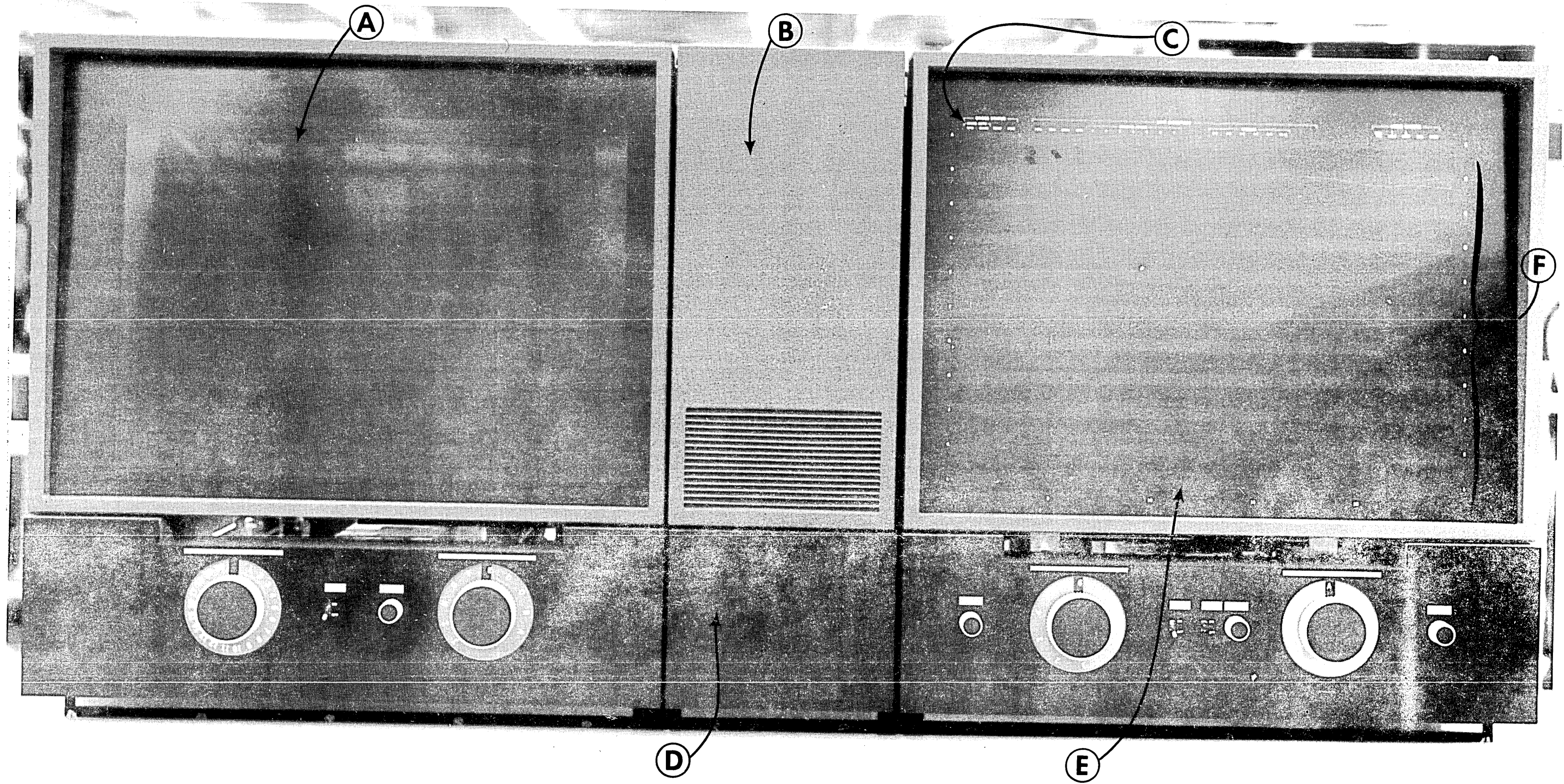


Figure 3-6 - Session 3 Questions 6-11

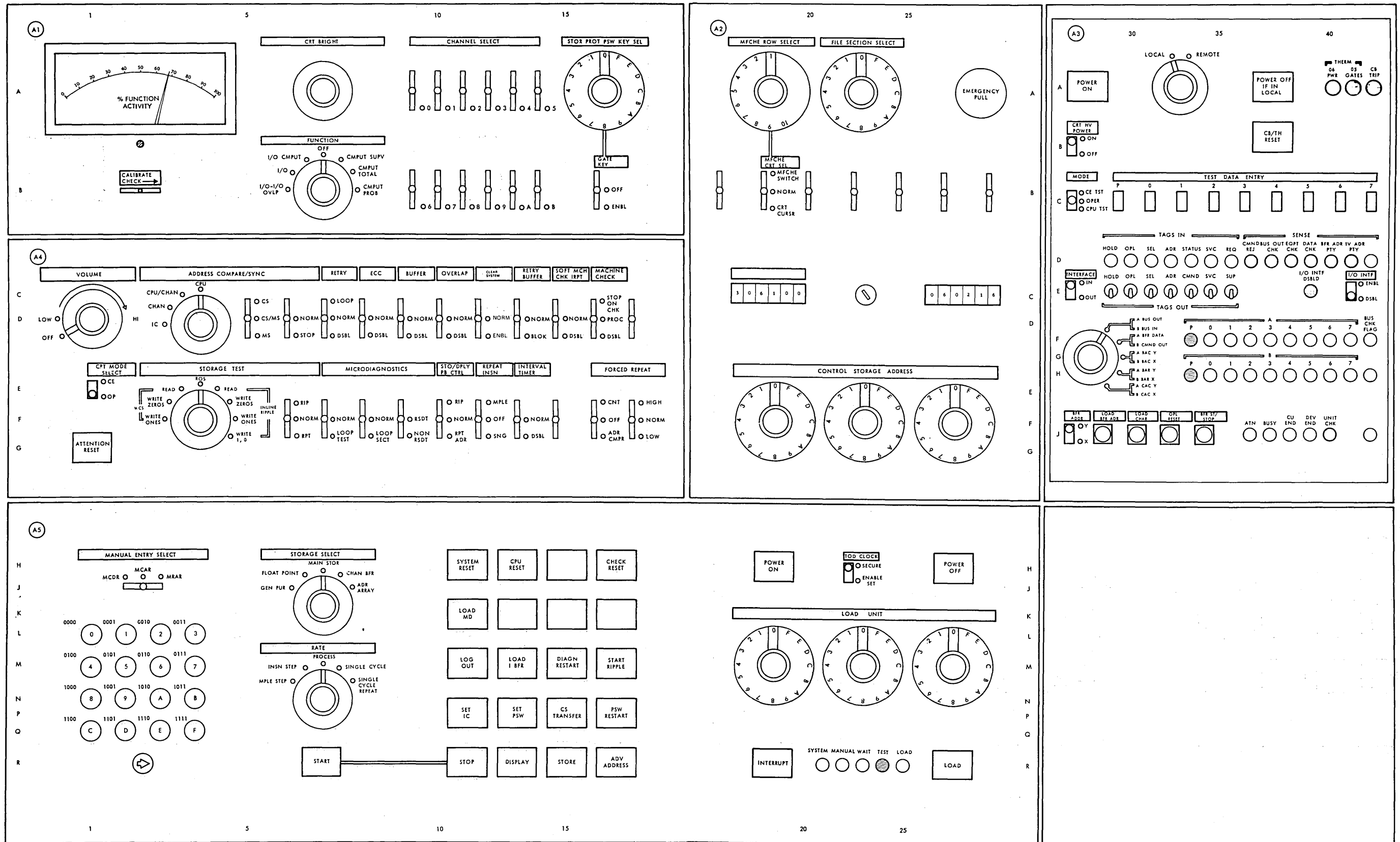
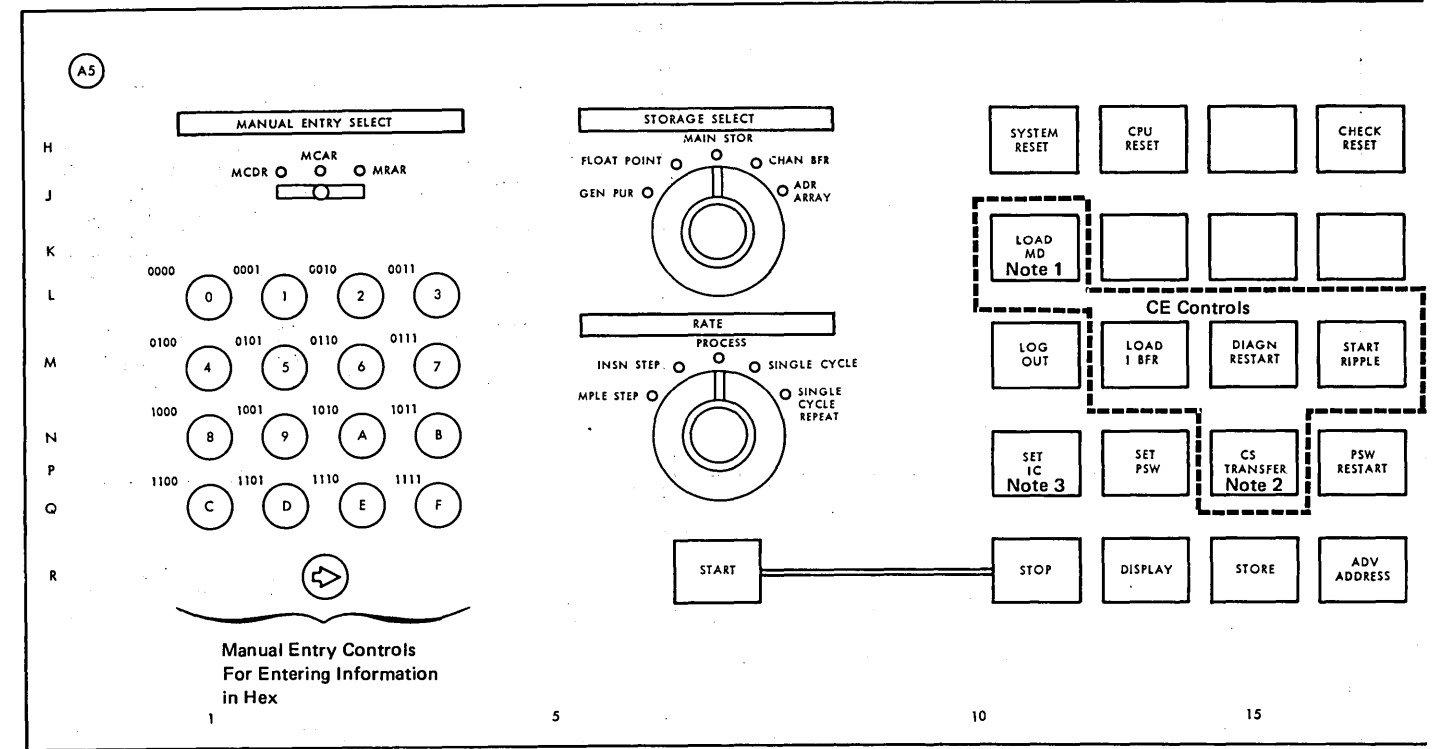
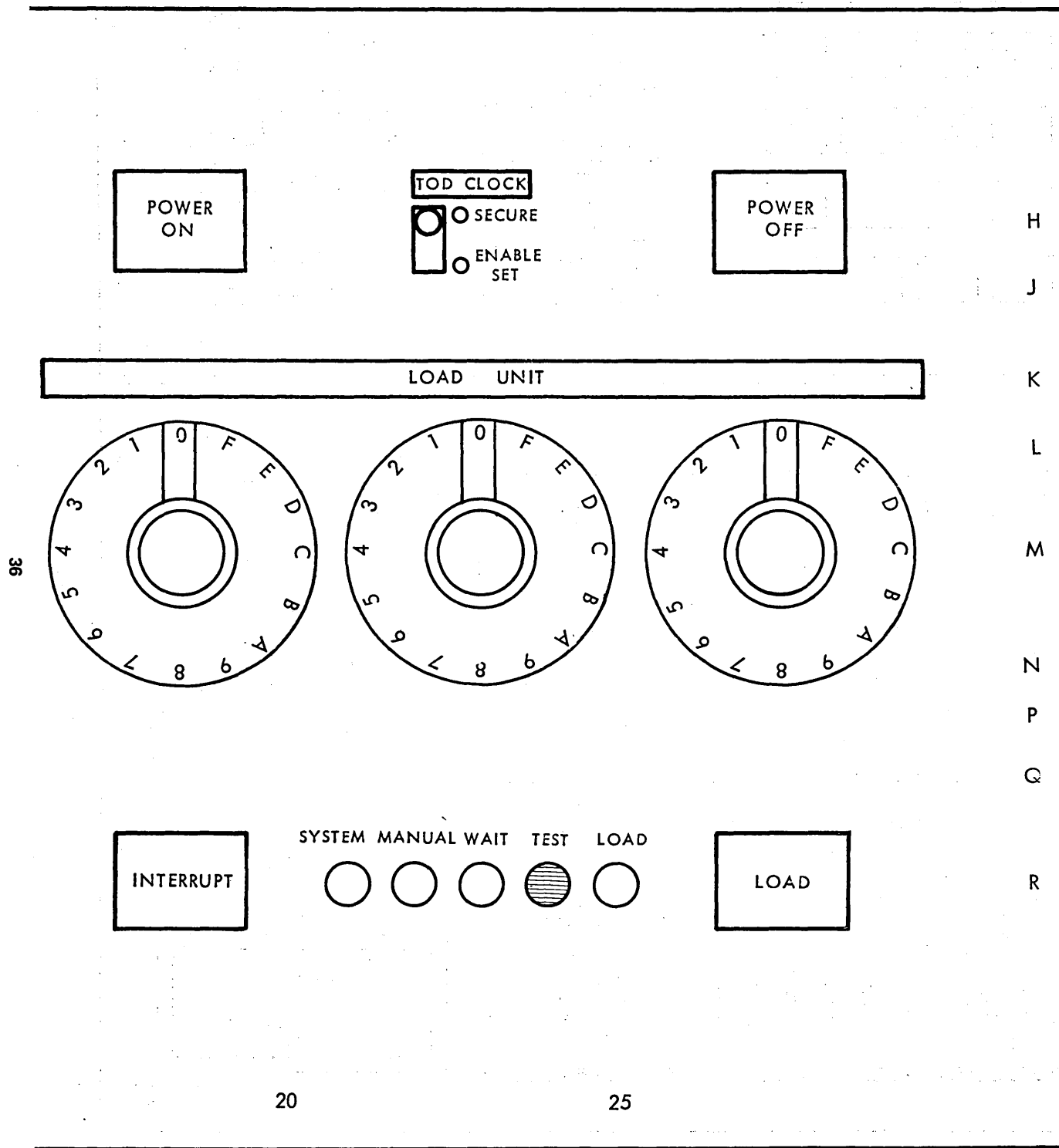


Figure 3-7 - Control Panel



Note 1 MD = Microdiagnostics
 Note 2 CS = Control Storage
 Note 3 IC = Instruction Counter

Figure 3-8 - Operator Controls

Figure 3-9 - Intervention Controls

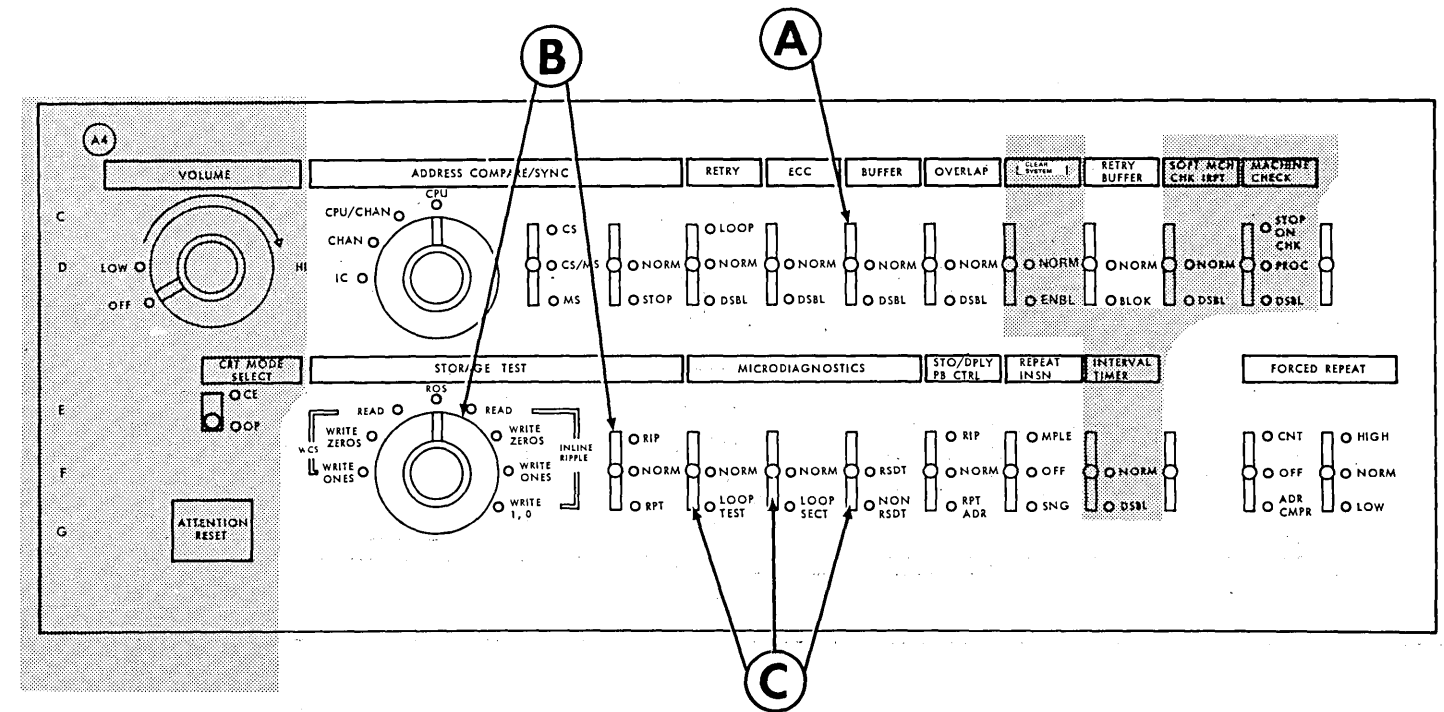
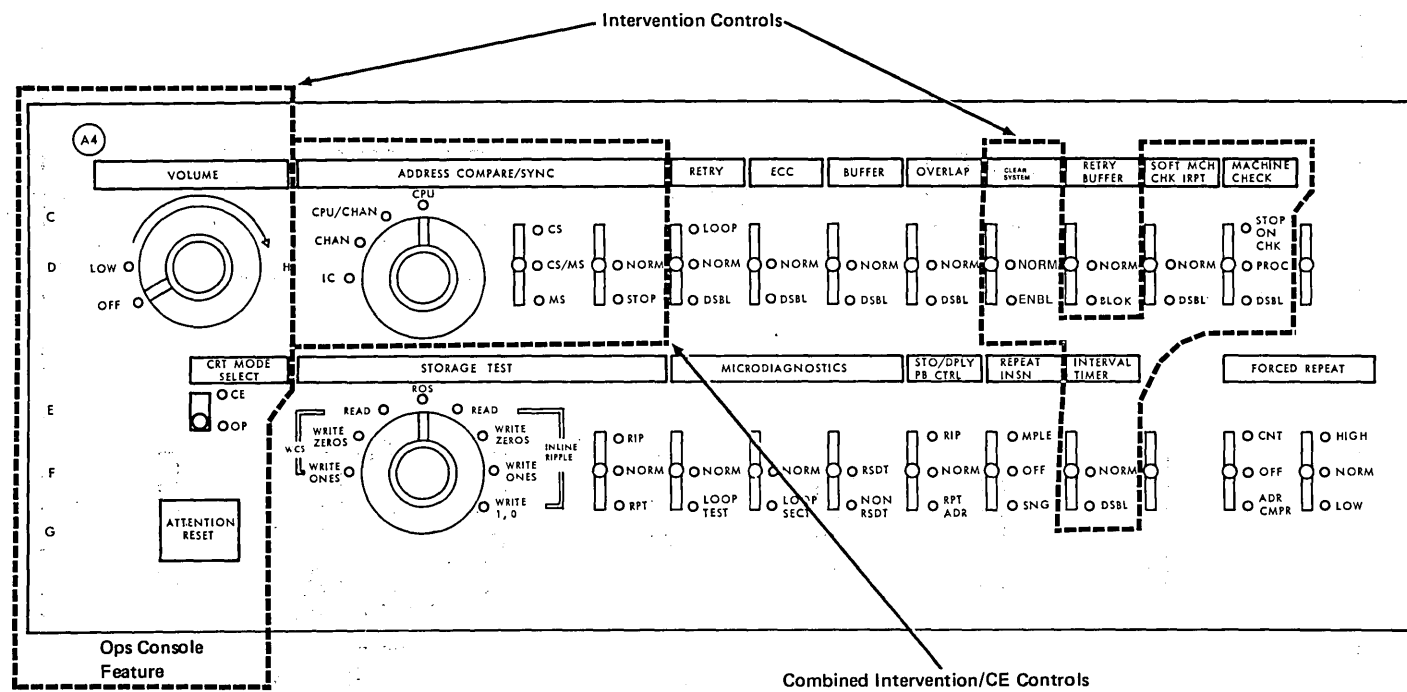


Figure 3-10 - CE/Intervention Controls

Figure 3-11 - CE Controls

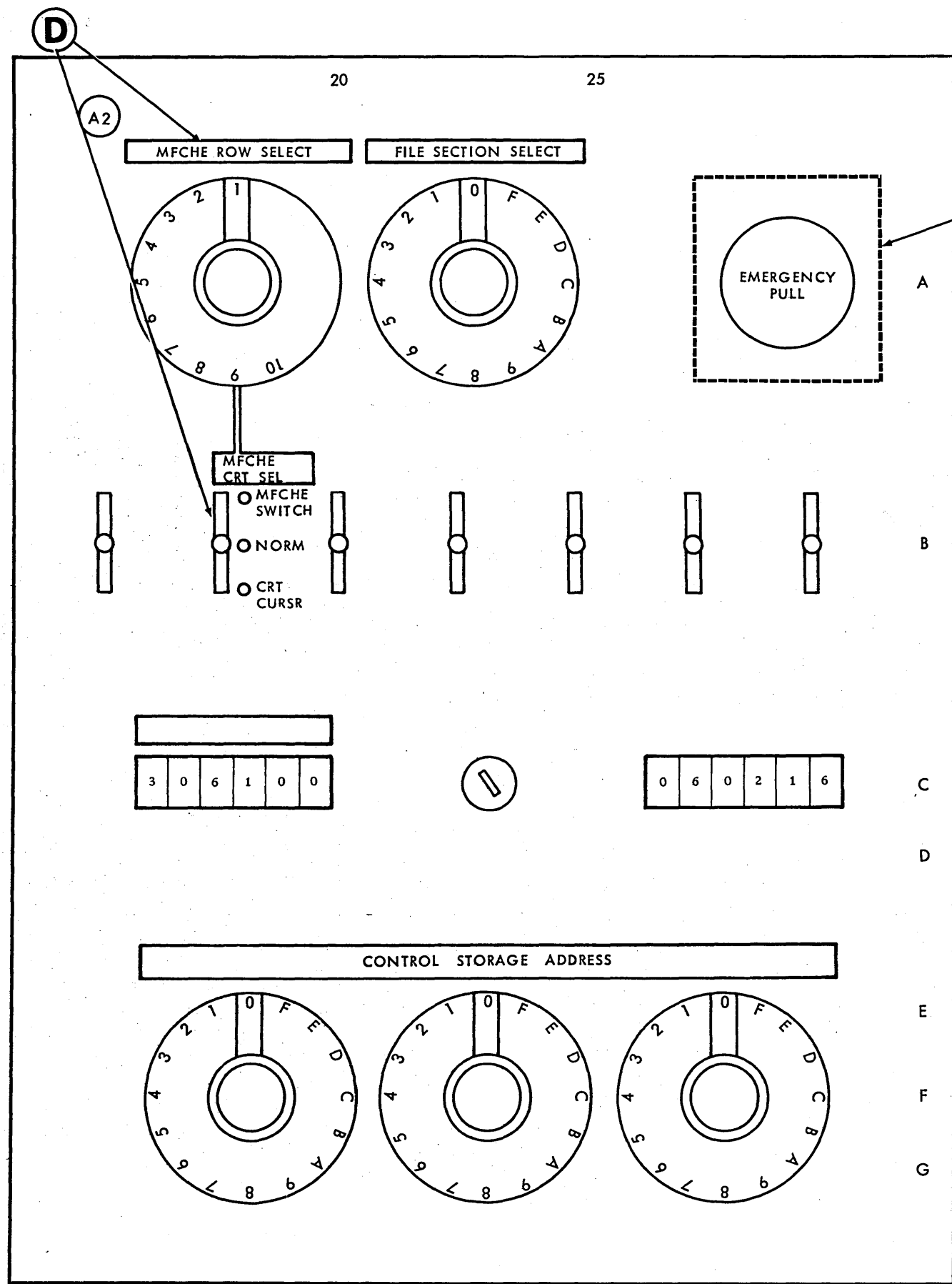


Figure 3-12 - CE Controls

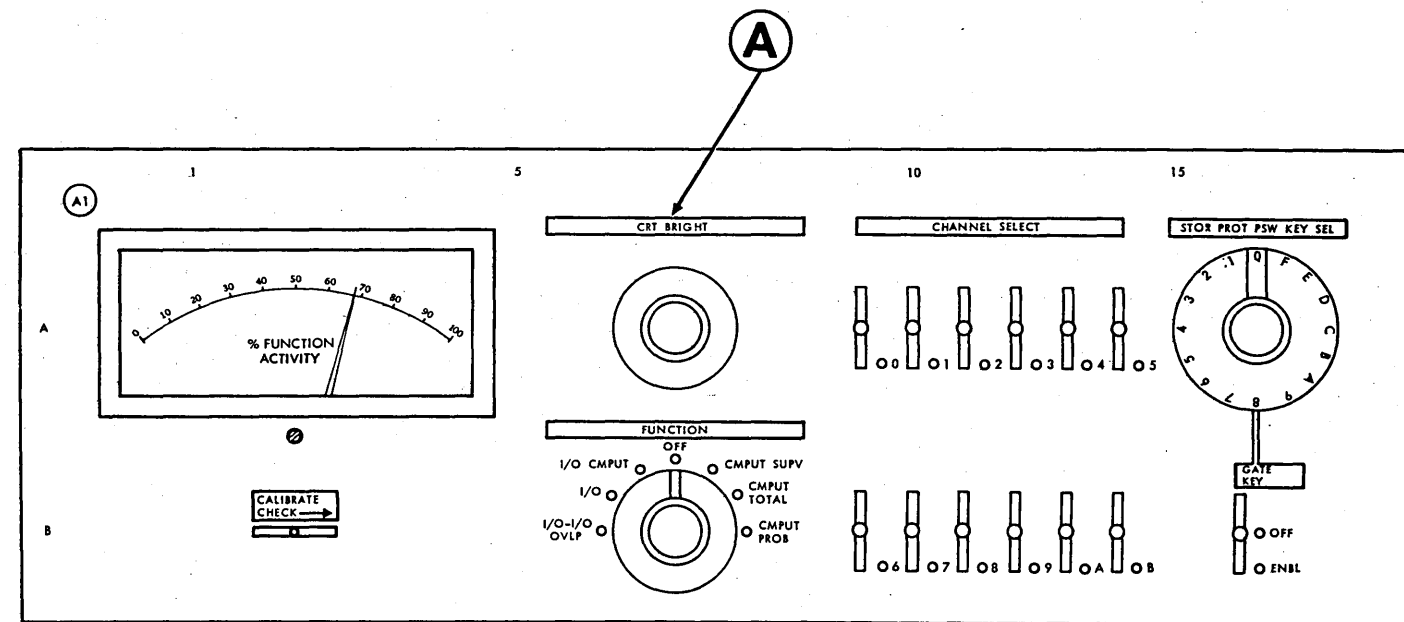
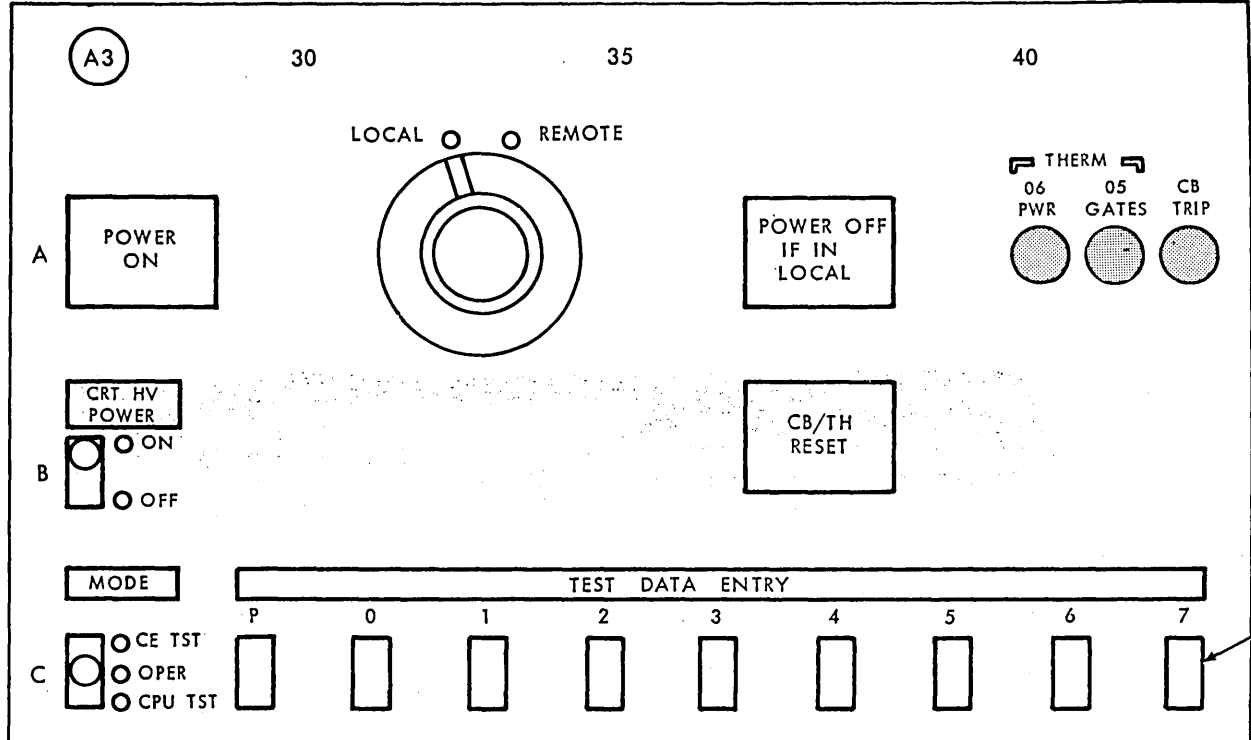


Figure 3-13 - SAM



Bit Entry Toggle Switches

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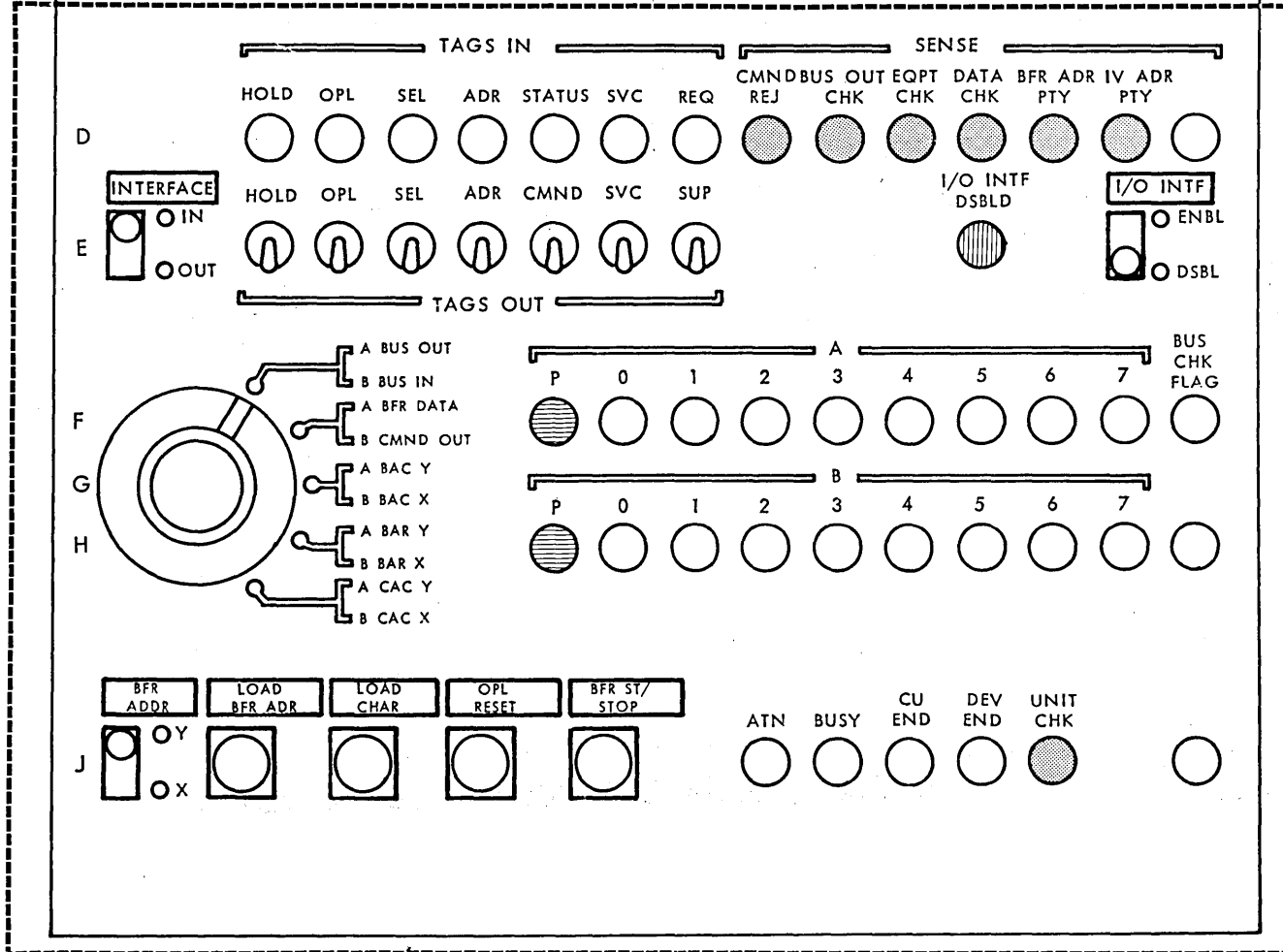


Figure 3-14 - CE Panel for Maintenance Console and Ops Console Feature

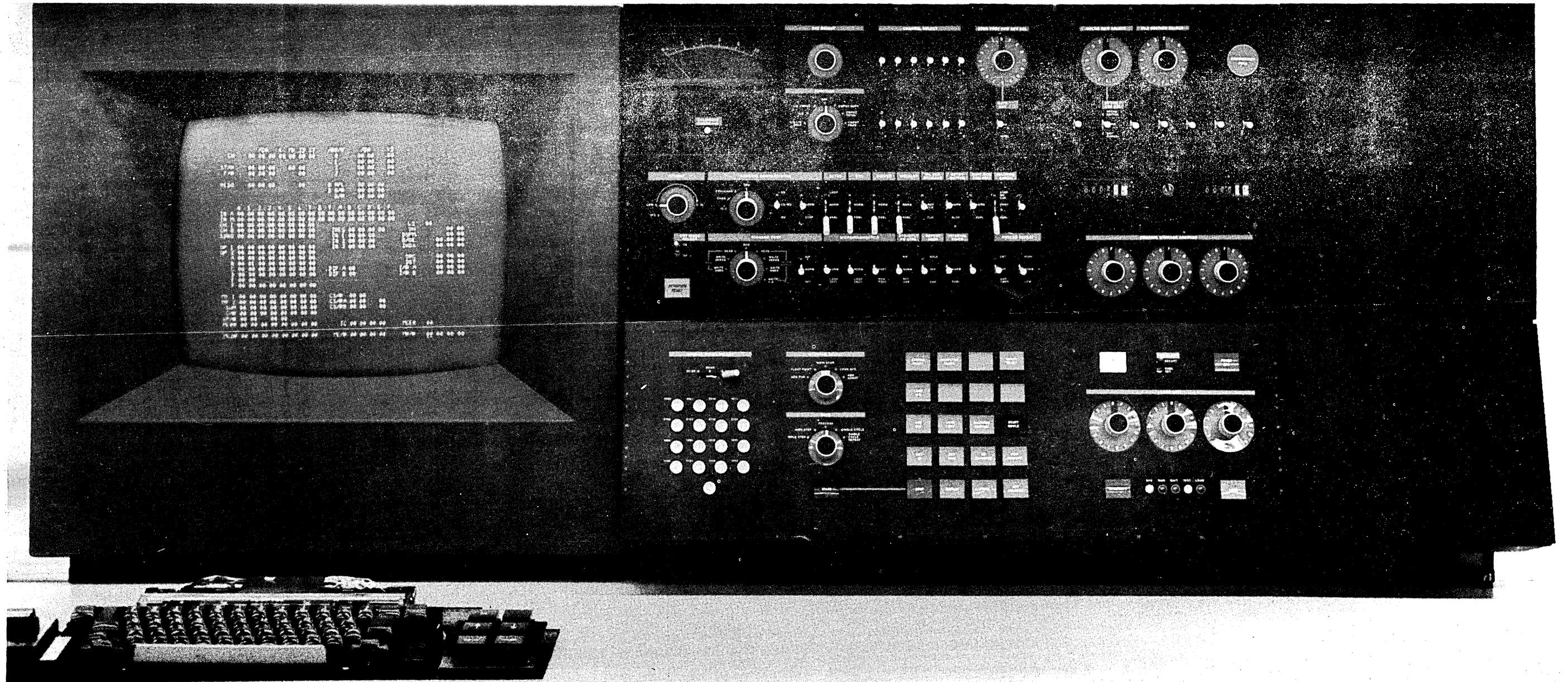


Figure 3-15 -System Control Panel

CH	ADR	K	MK	ID	ST	ARRAY	ADR	VD
	XX XX XX	0X	XX XX	0X		0	XX XX	XX
STAR	XX XX XX		0X	XX		1	XX XX	XX
FAR	XX XX XX			XX		2	XX XX	XX
REDO	XX XX XX			XX		3	XX XX	XX
						B RPL	XX XX XX	
						D BAR	XX XX XX	
						BAR	XX XX XX	

	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
IB A	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX
IB M	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX
CH I	XX	XX	XX	XX	XX	XX	XX	XX							
CH O	XX	XX	XX	XX	XX	XX	XX	XX							
SDBO	XX	XX	XX	XX	XX	XX	XX	XX							
OP 1	XX	XX	XX	XX	XX	XX	XX	XX							
OP 2	XX	XX	XX	XX	XX	XX	XX	XX							
A	XX	XX	XX	XX	XX	XX	XX	XX							
B	XX	XX	XX	XX	XX	XX	XX	XX							
C	XX	XX	XX	XX	XX	XX	XX	XX							
D	XX	XX	XX	XX	XX	XX	XX	XX							
E	XX	XX													
F	XX	XX	XX	XX	XX	XX	XX	XX							

	L2	XX		
	SH		XX	XX
	DSPM		0X	XX
	BASE		XX	XX
	INDX		XX	XX
	SRC		XX	XX
	DST		XX	XX
	IAR A		XX	XX
	IAR B		XX	XX
	DIF A	XX		
	DIF B	XX		
	CSAR	0X	XX	
	CSARA	0X	XX	0X
	CSARB	0X	XX	0X

MCRR	XX	XX	XX	XX	XX	XX	XX	XX	XX		IC	XX	XX	XX	XX	MCER	XX			
MCDR	XX	XX	XX	XX	XX	XX	XX	XX	XX		MCAR	XX	XX	XX	XX	MRAR	XX	XX	XX	XX

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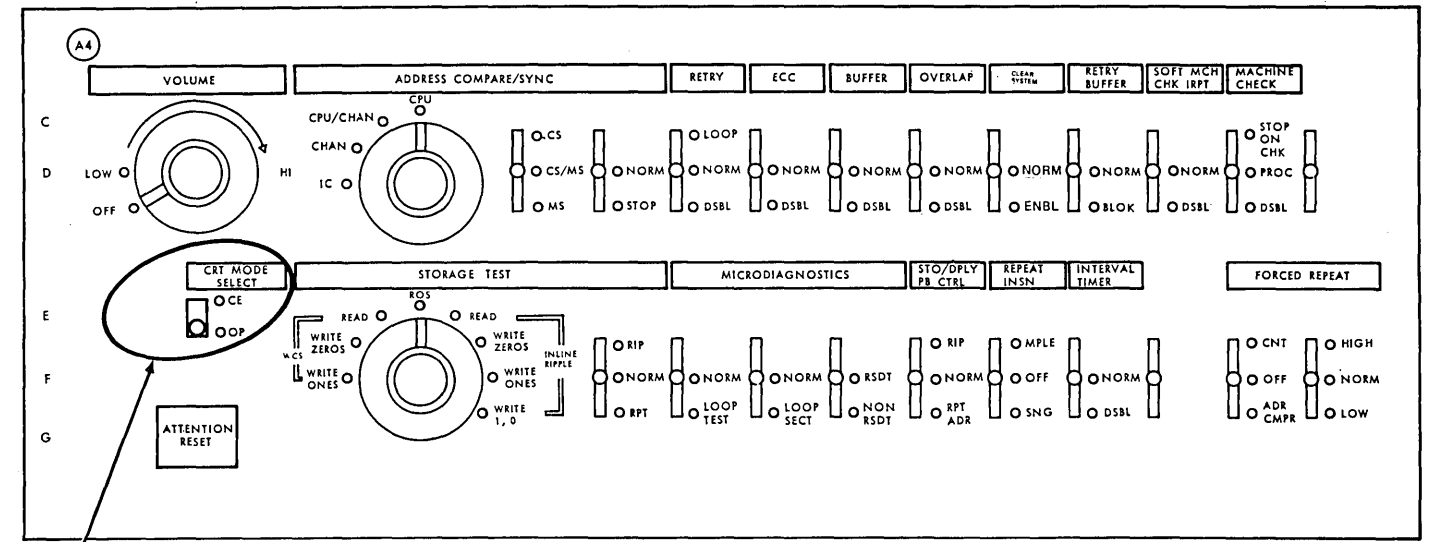


Figure 3-17 - CRT Mode Select Switch

Figure 3-16 - CRT Display

```

      ADR  K  MK  ID  ST  ARRAY  ADR  VD
CH    XX XX XX 0X XX XX 0X    0    XX XX  XX
      XX XX XX    0X XX    1    XX XX  XX
STAR  XX XX XX    XX    2    XX XX  XX
FAR   XX XX XX    XX    3    XX XX  XX

REDO  XX XX XX    XX    B RPL  XX XX XX
      D BAR  XX XX XX
      BAR   XX XX XX

      1  2  3  4  5  6  7  8  9  A  B  C  D  E  F
IB A  XX XX XX XX XX XX XX XX XX XX XX XX XX XX XX
IB M  XX XX XX XX XX XX XX XX XX XX XX XX XX XX XX
CH I  XX XX XX XX XX XX XX XX    L2  XX
CH O  XX XX XX XX XX XX XX XX    IREG XX XX XX XX  SH  XX XX
SDBO  XX XX XX XX XX XX XX XX    IQ 1 XX XX XX  DSPM  0X XX
      IQ 2 XX XX XX    BASE  XX XX XX
      IQ 3 XX XX XX    INDX  XX XX XX

OP 1  XX XX XX XX XX XX XX XX
OP 2  XX XX XX XX XX XX XX XX
  A  XX XX XX XX XX XX XX XX
  B  XX XX XX XX XX XX XX XX
  C  XX XX XX XX XX XX XX XX
  D  XX XX XX XX XX XX XX XX
  E  XX XX
  F  XX XX XX XX XX XX XX XX

      CSAR  0X XX
      CSARA 0X XX  0X
      CSARB 0X XX  0X

MCCR  XX XX XX XX XX XX XX XX    IC  XX XX XX XX  MCER  XX
MCDR  XX XX XX XX XX XX XX XX    MCAR  XX XX XX XX  MRAR  XX XX XX XX

```

Figure 3-18 - CRT Displayed I-Unit Registers

```

      ADR  K  MK  ID  ST  ARRAY  ADR  VD
CH    XX XX XX 0X XX XX 0X    0    XX XX  XX
      1    XX XX  XX
STAR  XX XX XX    0X XX    2    XX XX  XX
FAR   XX XX XX    XX    3    XX XX  XX

REDO  XX XX XX    XX    B RPL  XX XX XX
      D BAR  XX XX XX
      BAR   XX XX XX

      1  2  3  4  5  6  7  8  9  A  B  C  D  E  F
IB A  XX XX XX XX XX XX XX XX XX XX XX XX XX XX
IB M  XX XX XX XX XX XX XX XX XX XX XX XX XX XX
CH I  XX XX XX XX XX XX XX XX
CH O  XX XX XX XX XX XX XX XX
SDBO  XX XX XX XX XX XX XX XX

OP 1  XX XX XX XX XX XX XX XX
OP 2  XX XX XX XX XX XX XX XX
A  XX XX XX XX XX XX XX XX
B  XX XX XX XX XX XX XX XX
C  XX XX XX XX XX XX XX XX
D  XX XX XX XX XX XX XX XX
E  XX XX
F  XX XX XX XX XX XX XX XX

      IREG XX XX XX XX
      IQ 1  XX XX XX
      IQ 2  XX XX XX
      IQ 3  XX XX XX

      L2  XX
      SH  XX XX
      DSPM 0X XX
      BASE XX XX XX
      INDX  XX XX XX

      SRC  XX XX XX
      DST  XX XX XX
      IAR A XX XX XX
      IAR B XX XX XX

      DIF A XX
      DIF B XX

      CSAR 0X XX
      CSARA 0X XX 0X
      CSARB 0X XX 0X

MCRR  XX XX XX XX XX XX XX XX    IC XX XX XX XX    MCER  XX
MCDR  XX XX XX XX XX XX XX XX    MCAR XX XX XX XX    MRAR  XX XX XX XX

```

Figure 3-19 CRT Displayed E-Unit Registers

```

      ADR  K  MK  ID  ST  ARRAY  ADR  VD
CH    XX XX XX 0X XX XX 0X    0    XX XX  XX
      1    XX XX  XX
STAR  XX XX XX    0X XX    2    XX XX  XX
FAR   XX XX XX    XX    3    XX XX  XX

REDO  XX XX XX    XX    B RPL  XX XX XX
      D BAR  XX XX XX
      BAR   XX XX XX

      1  2  3  4  5  6  7  8  9  A  B  C  D  E  F
IB A  XX XX XX XX XX XX XX XX XX XX XX XX XX XX
IB M  XX XX XX XX XX XX XX XX XX XX XX XX XX XX
CH I  XX XX XX XX XX XX XX XX
CH O  XX XX XX XX XX XX XX XX
SDBO  XX XX XX XX XX XX XX XX

OP 1  XX XX XX XX XX XX XX XX
OP 2  XX XX XX XX XX XX XX XX
A  XX XX XX XX XX XX XX XX
B  XX XX XX XX XX XX XX XX
C  XX XX XX XX XX XX XX XX
D  XX XX XX XX XX XX XX XX
E  XX XX
F  XX XX XX XX XX XX XX XX

      IREG XX XX XX XX
      IQ 1  XX XX XX
      IQ 2  XX XX XX
      IQ 3  XX XX XX

      L2  XX
      SH  XX XX
      DSPM 0X XX
      BASE XX XX XX
      INDX  XX XX XX

      SRC  XX XX XX
      DST  XX XX XX
      IAR A XX XX XX
      IAR B XX XX XX

      DIF A XX
      DIF B XX

      CSAR 0X XX
      CSARA 0X XX 0X
      CSARB 0X XX 0X

MCRR  XX XX XX XX XX XX XX XX    IC XX XX XX XX    MCER  XX
MCDR  XX XX XX XX XX XX XX XX    MCAR XX XX XX XX    MRAR  XX XX XX XX

```

Figure 3-20 CRT Displayed SCU Registers

```

      ADR  K  MK  ID  ST  ARRAY  ADR  VD
CH    XX XX XX 0X XX XX 0X    0    XX XX  XX
STAR  XX XX XX    0X XX    1    XX XX  XX
FAR   XX XX XX    XX    2    XX XX  XX
REDO  XX XX XX    XX    3    XX XX  XX
      B RPL  XX XX XX
      D BAR  XX XX XX
      BAR   XX XX XX

      1  2  3  4  5  6  7  8  9  A  B  C  D  E  F
IB A  XX XX XX XX XX XX XX XX XX XX XX XX XX XX
IB M  XX XX XX XX XX XX XX XX XX XX XX XX XX XX
CH I  XX XX XX XX XX XX XX XX
CH O  XX XX XX XX XX XX XX XX    IREG XX XX XX XX
SDBO  XX XX XX XX XX XX XX XX    IQ 1 XX XX XX
OP 1  XX XX XX XX XX XX XX XX    IQ 2 XX XX XX
OP 2  XX XX XX XX XX XX XX XX    IQ 3 XX XX XX
A    XX XX XX XX XX XX XX XX    SRC   XX XX XX
B    XX XX XX XX XX XX XX XX    DST   XX XX XX
C    XX XX XX XX XX XX XX XX    DIF A XX
D    XX XX XX XX XX XX XX XX    DIF B XX
E    XX XX
F    XX XX XX XX XX XX XX XX    IAR A XX XX XX
                                      IAR B XX XX XX

      CSAR  0X XX
      CSARA 0X XX  0X
      CSARB 0X XX  0X

MCRR XX XX XX XX XX XX XX XX    IC XX XX XX XX    MCER  XX
MCDR XX XX XX XX XX XX XX XX    MCAR XX XX XX XX    MRAR  XX XX XX XX

```

```

      ADR  K  MK  ID  ST  ARRAY  ADR  VD
CH    XX XX XX 0X XX XX 0X    0    XX XX  XX
STAR  XX XX XX    0X XX    1    XX XX  XX
FAR   XX XX XX    XX    2    XX XX  XX
REDO  XX XX XX    XX    3    XX XX  XX
      B RPL  XX XX XX
      D BAR  XX XX XX
      BAR   XX XX XX

      1  2  3  4  5  6  7  8  9  A  B  C  D  E  F
IB A  XX XX XX XX XX XX XX XX XX XX XX XX XX XX
IB M  XX XX XX XX XX XX XX XX XX XX XX XX XX XX
CH I  XX XX XX XX XX XX XX XX
CH O  XX XX XX XX XX XX XX XX    IREG XX XX XX XX
SDBO  XX XX XX XX XX XX XX XX    IQ 1 XX XX XX
OP 1  XX XX XX XX XX XX XX XX    IQ 2 XX XX XX
OP 2  XX XX XX XX XX XX XX XX    IQ 3 XX XX XX
A    XX XX XX XX XX XX XX XX    SRC   XX XX XX
B    XX XX XX XX XX XX XX XX    DST   XX XX XX
C    XX XX XX XX XX XX XX XX    DIF A XX
D    XX XX XX XX XX XX XX XX    DIF B XX
E    XX XX
F    XX XX XX XX XX XX XX XX    IAR A XX XX XX
                                      IAR B XX XX XX

      CSAR  0X XX
      CSARA 0X XX  0X
      CSARB 0X XX  0X

MY 1  XX XX XX XX XX XX XX XX    IC XX XX XX XX    MCER  XX
MY 2  XX XX XX XX XX XX XX XX    MCAR XX XX XX XX    MRAR  XX XX XX XX
SUM  XX XX XX XX XX XX XX XX
CAR  XX XX XX XX XX XX XX XX
SPAR XX XX  XX XX
MCRR XX XX XX XX XX XX XX XX    IAR A XX XX XX
MCDR XX XX XX XX XX XX XX XX    IAR B XX XX XX

```

Figure 3-21 CRT Displayed Maint Control Registers

Figure 3-22 CRT Displayed HSM Registers

CH	ADR	K	MK	ID	ST	ARRAY	ADR	VD									
	90 10 00	00	00	00	00	0	90 10	00									
STAR	90 10 00		00	00		1	90 10	00									
FAR	90 10 00			00		2	90 10	00									
						3	90 10	00									
REDO	90 10 00			00		B RPL	90 10 00										
						D BAR	90 10 00										
						BAR	90 10 00										
	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	
IB A	10	90	10	00	00	00	00	00	10	90	10	00	00	00	00	00	
IB M	10	90	10	00	00	00	00	00	10	90	10	00	00	00	00	00	
CH I	10	90	10	00	00	00	00	00									L2
CH O	10	90	10	00	00	00	00	00									00
SDBO	10	90	10	00	00	00	00	00		IREG	10	90	10	00			SH
										IQ 1	10	90	10				00
OP 1	10	90	10	00	00	00	00	00		IQ 2	10	90	10				00
OP 2	10	90	10	00	00	00	00	00		IQ 3	10	90	10				00
A	10	90	10	00	00	00	00	00									BASE
B	10	90	10	00	00	00	00	00									00
C	10	90	10	00	00	00	00	00									00
D	10	90	10	00	00	00	00	00		DIF A	10						00
E	10	90								DIF B	10						00
F	10	90	10	00	00	00	00	00									00
MY 1	10	90	10	00	00	00	00	00		CSAR	10	90					
MY 2	10	90	10	00	00	00	00	00		CSARA	10	90		00			
SUM	10	90	10	00	00	00	00	00		CSARB	10	90		00			
CAR	10	90	10	00	00	00	00	00									
SPAR	10	90		00	00												
MCRR	10	90	10	00	00	00	00	00		IC	10	90	10	00			MCER
																	00
MCDR	10	90	10	00	00	00	00	00		MCAR	10	90	10	00			MRAR
																	00

Figure 3-23 CRT CE Mode

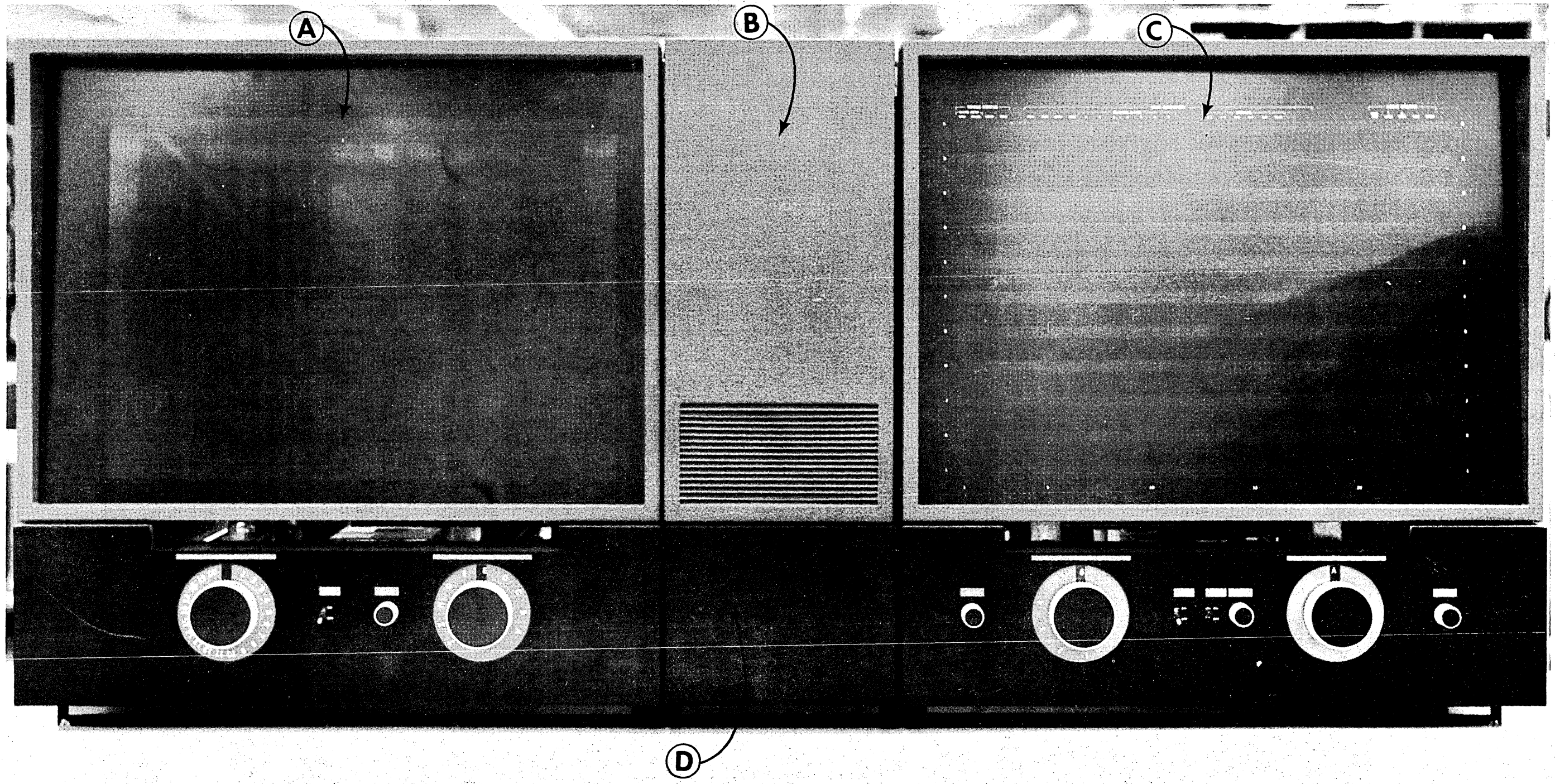
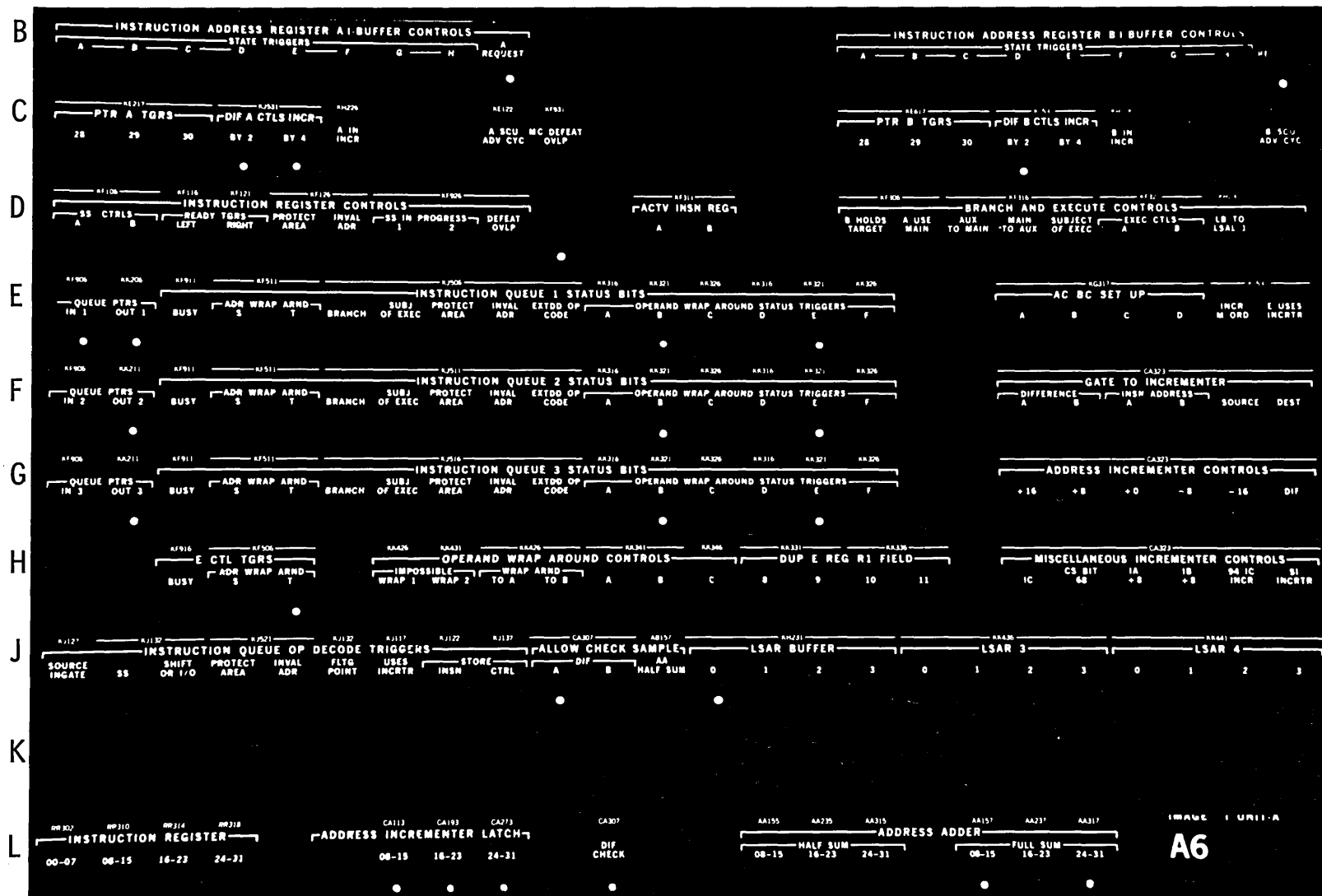


Figure 3-24 Microfiche Console

Row



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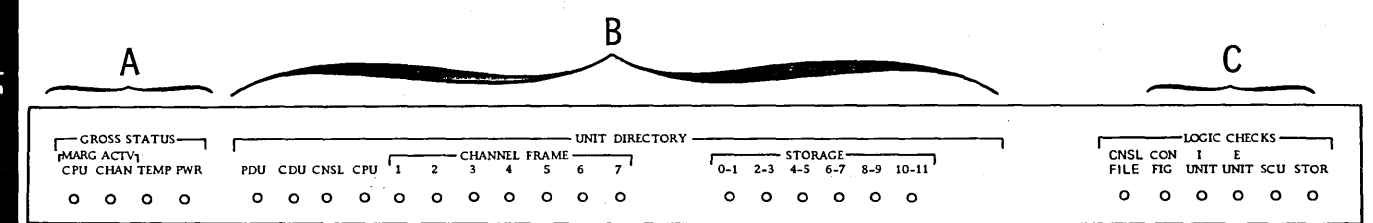


Figure 3-25 Indicator Display

Figure 3-26 Row A Indicators

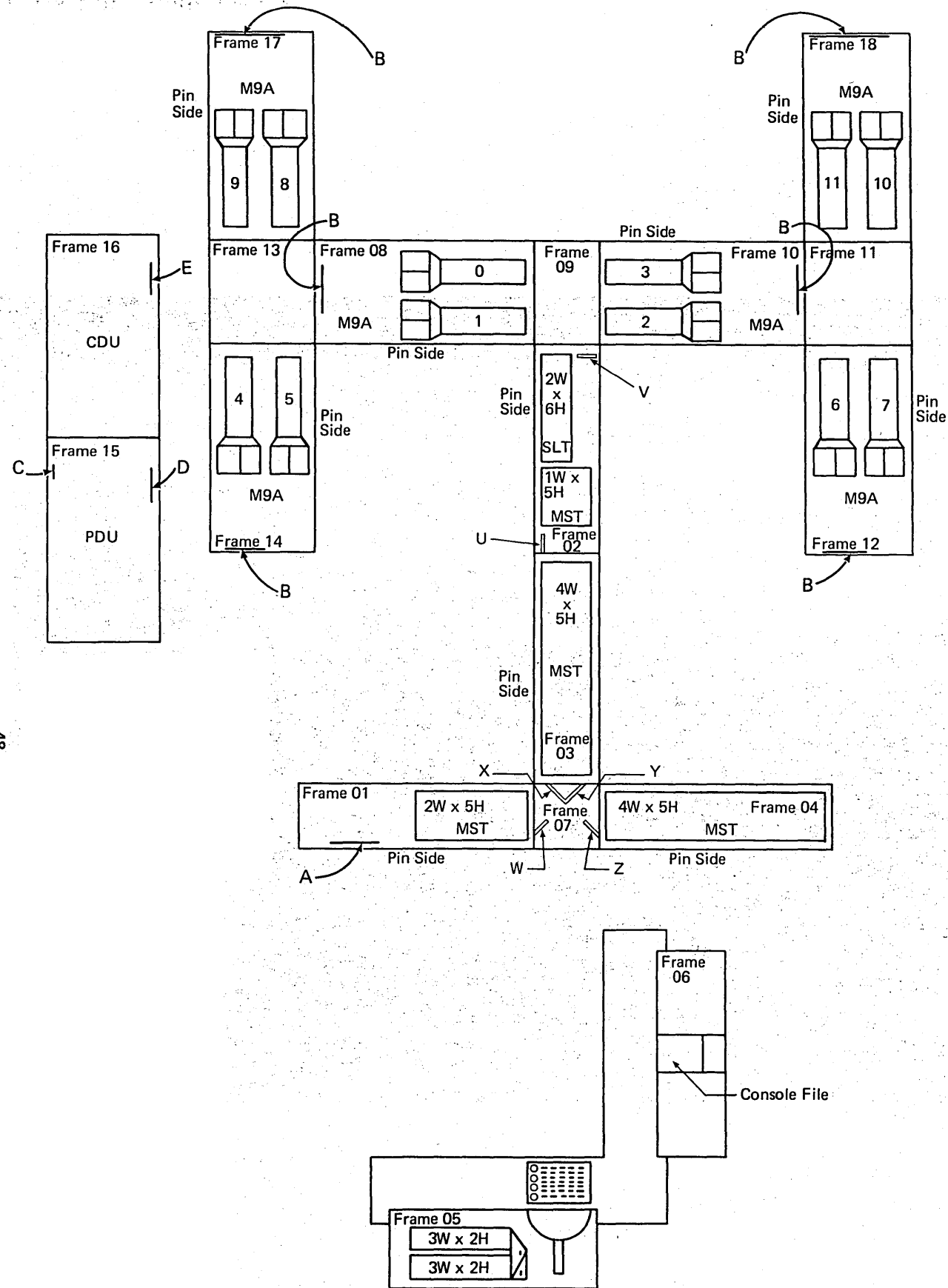


Figure 3-27 CE Panels

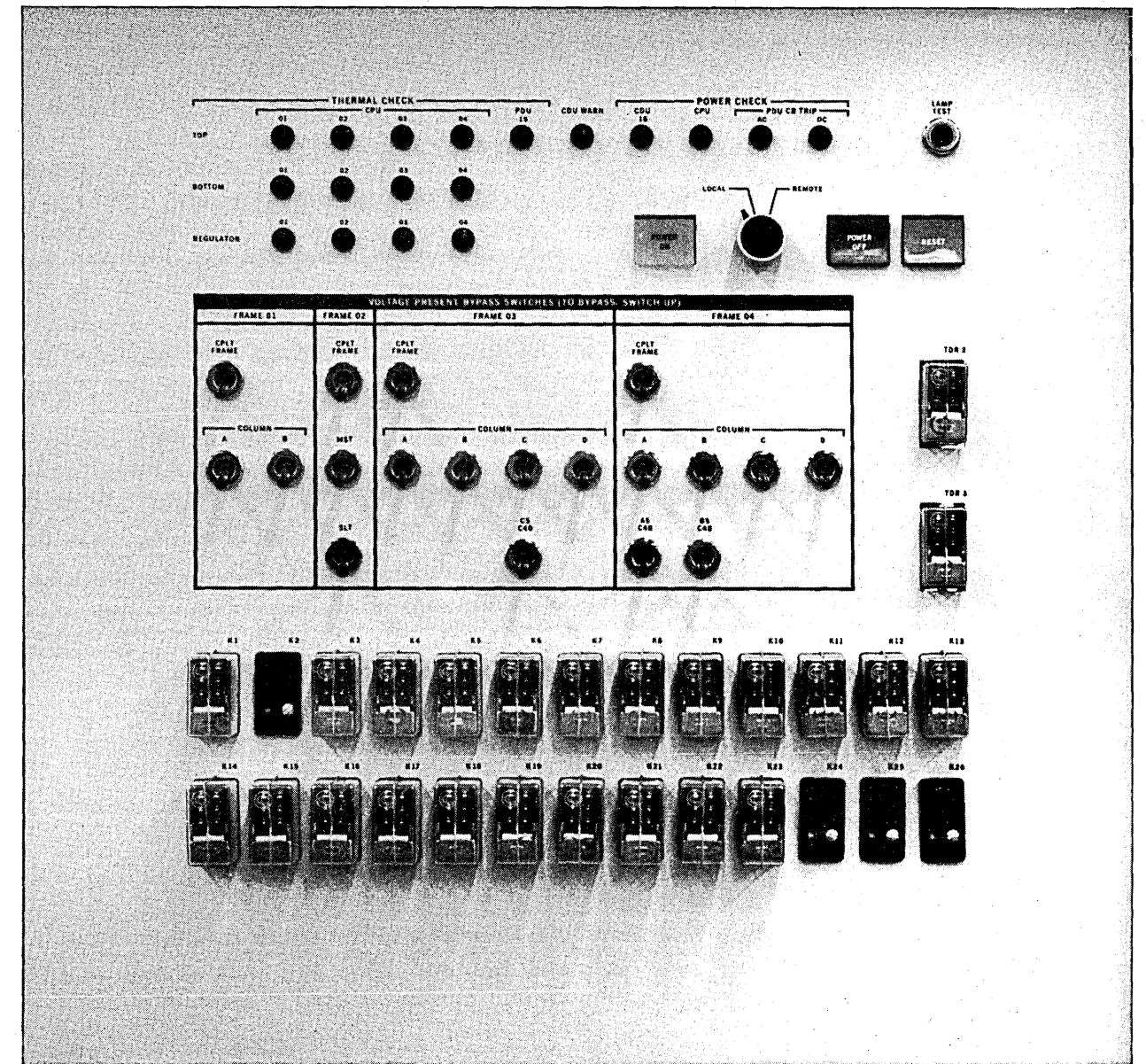


Figure 3-28 Frame 01 CE Panel

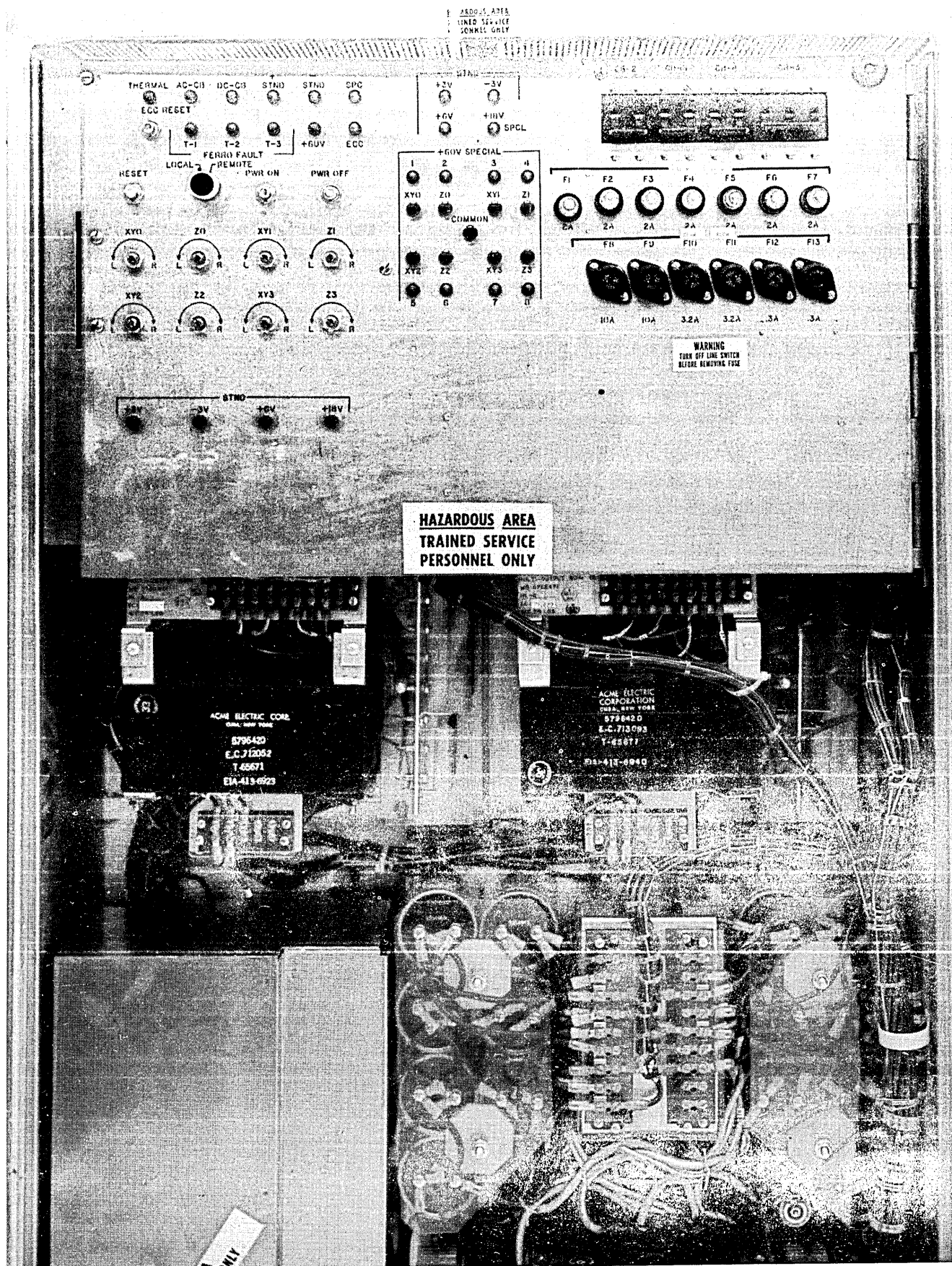


Figure 3-29 | M9A CE Panel

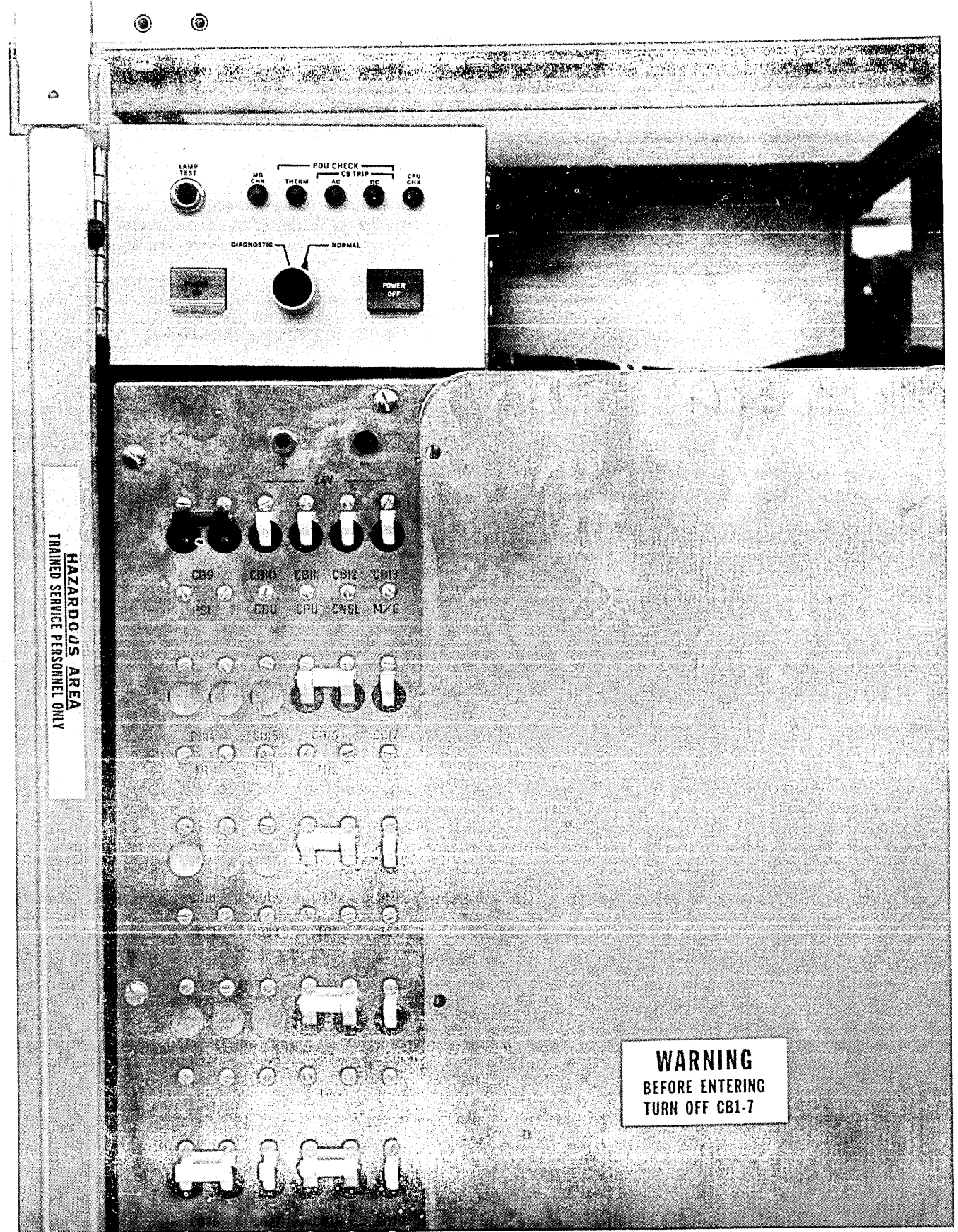


Figure 3-30 | PDU CE Panel

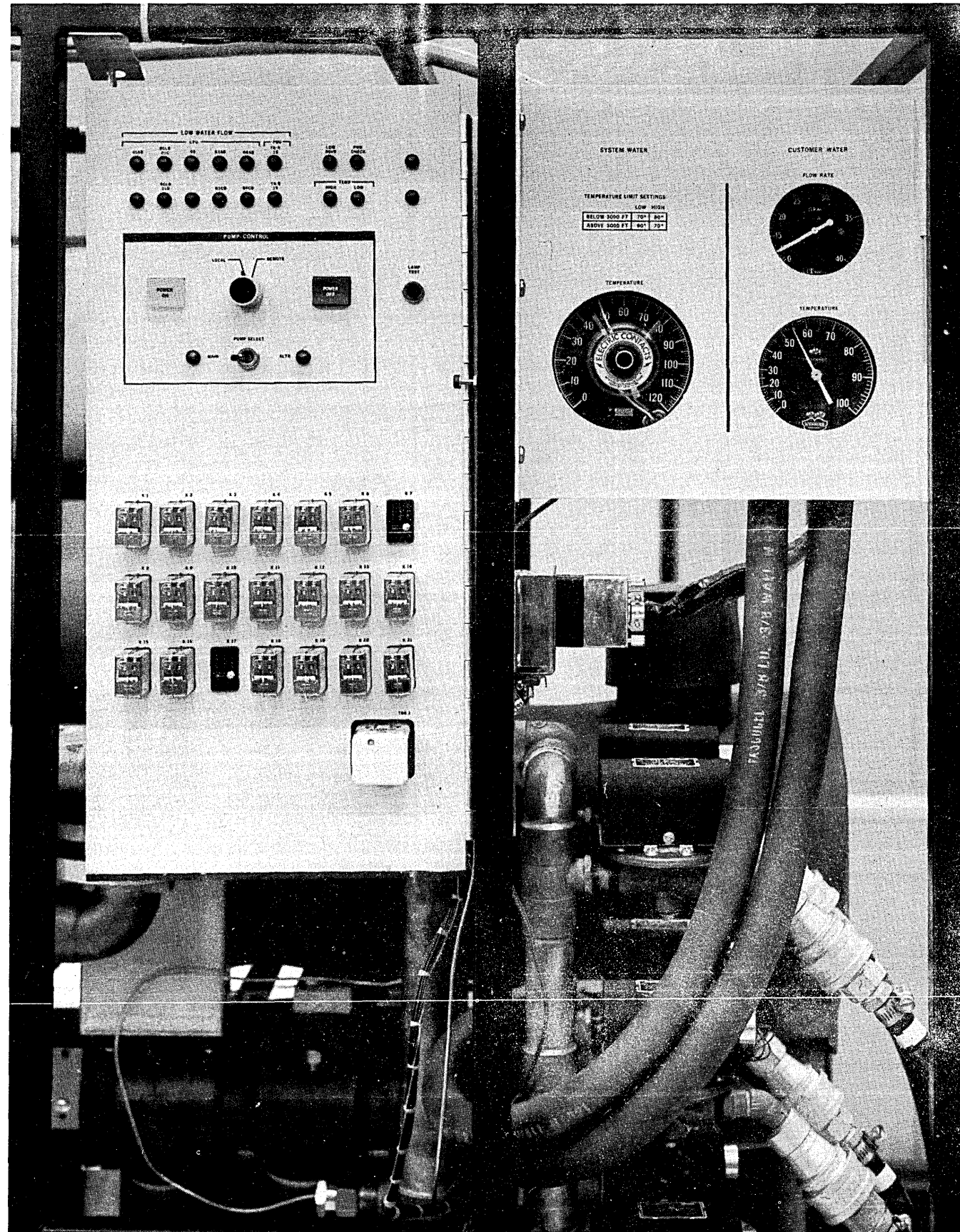


Figure 3-31 CDU CE Panel

- 10 FE Theory of Operation Manual (FETOM)
 - Introduction and Timing
 - I-Unit Operations
 - E-Unit Operations, Volume 1
 - E-Unit Operations, Volume 2
 - SCU, SCLU, and Main Storage
 - Features, 7094 Emulator
 - Features, 7074 Emulator
 - Features, 7080 Emulator
 - Power and Cooling
 - Console and Maintenance Facilities

- 6 FE Maintenance Diagrams - Manuals (FEMDMs)
 - *Volume 1 Base Machine - Diagnostic Diagrams
 - Volume 2 Base Machine - Clocks, I-Unit Operations, E-Unit Operations
 - Volume 3 Base Machine - Storage and Storage Control, Power and Cooling, Console
 - Volume 4 Features - 7094 Emulator
 - Volume 5 Features - 7074 Emulator
 - Volume 6 Features - 7080 Emulator

- FE Maintenance Manual (FEMM)
- FE Installation Manual (FEIM)
- *Microdiagnostic Program User's Guide
- FE Automated Logic Diagrams (FEALDs)
- *DME User's Guide
- *Model 165 Handbook

Figure 3-32 Manuals

Machine Check Interrupts (MCI)
Program Interrupt
Supervisor Call Interrupt
External Interrupt
Input/Output Interrupt

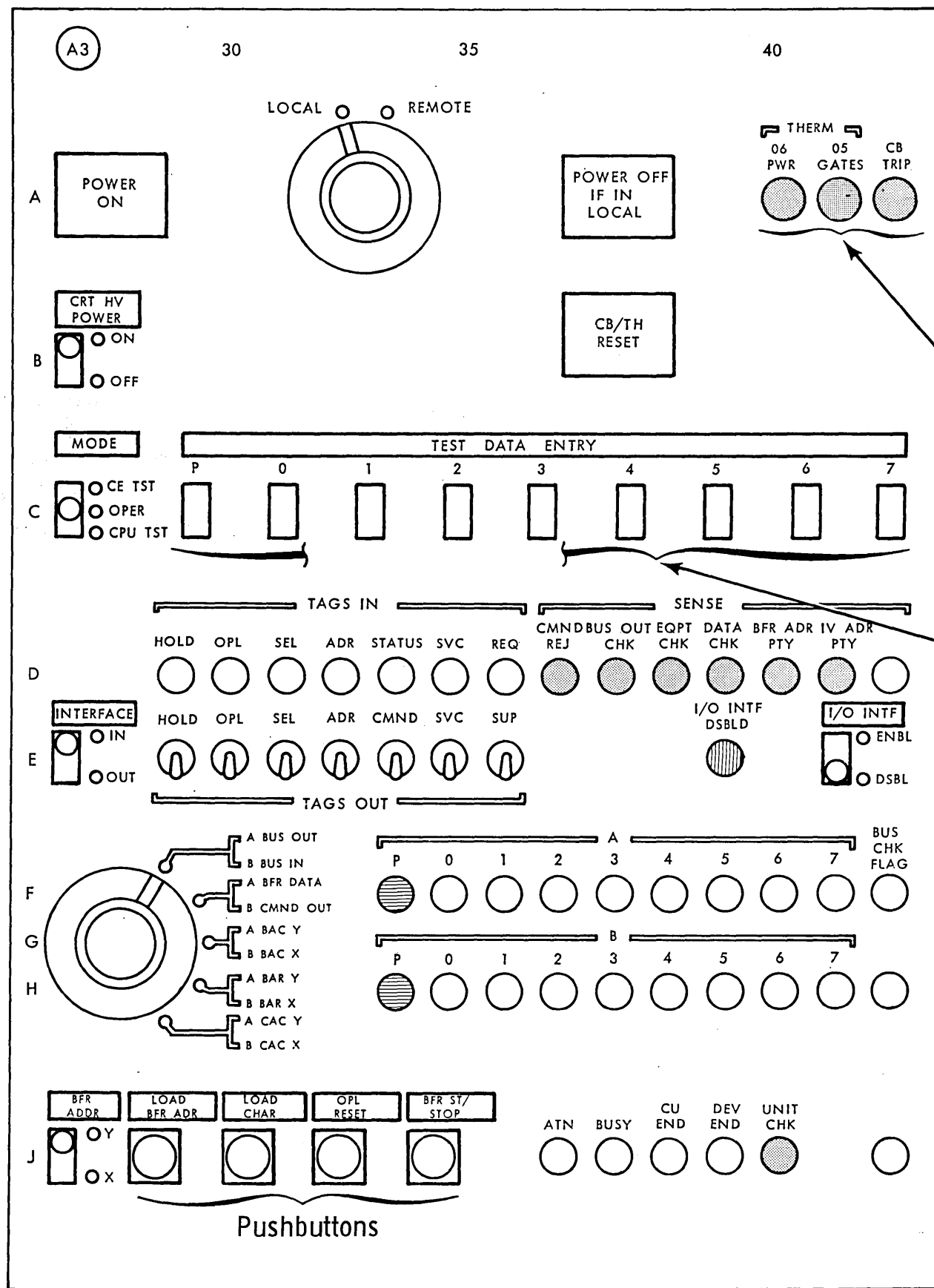
Figure 3-33 System/360 Interrupts

1. Hard Machine Check Interrupt
2. Program Interrupt
3. Supervisor Call Interrupt
4. Soft Machine Check Interrupt
5. External Interrupt
6. Input/Output

Figure 3-34 Model 165 Interrupt Priority

System Control Panel CE Controls

Operators Console CE Controls



Power/Thermal Check Indicators

Toggle Switches

Pushbuttons

Figure 3-35 Section A3

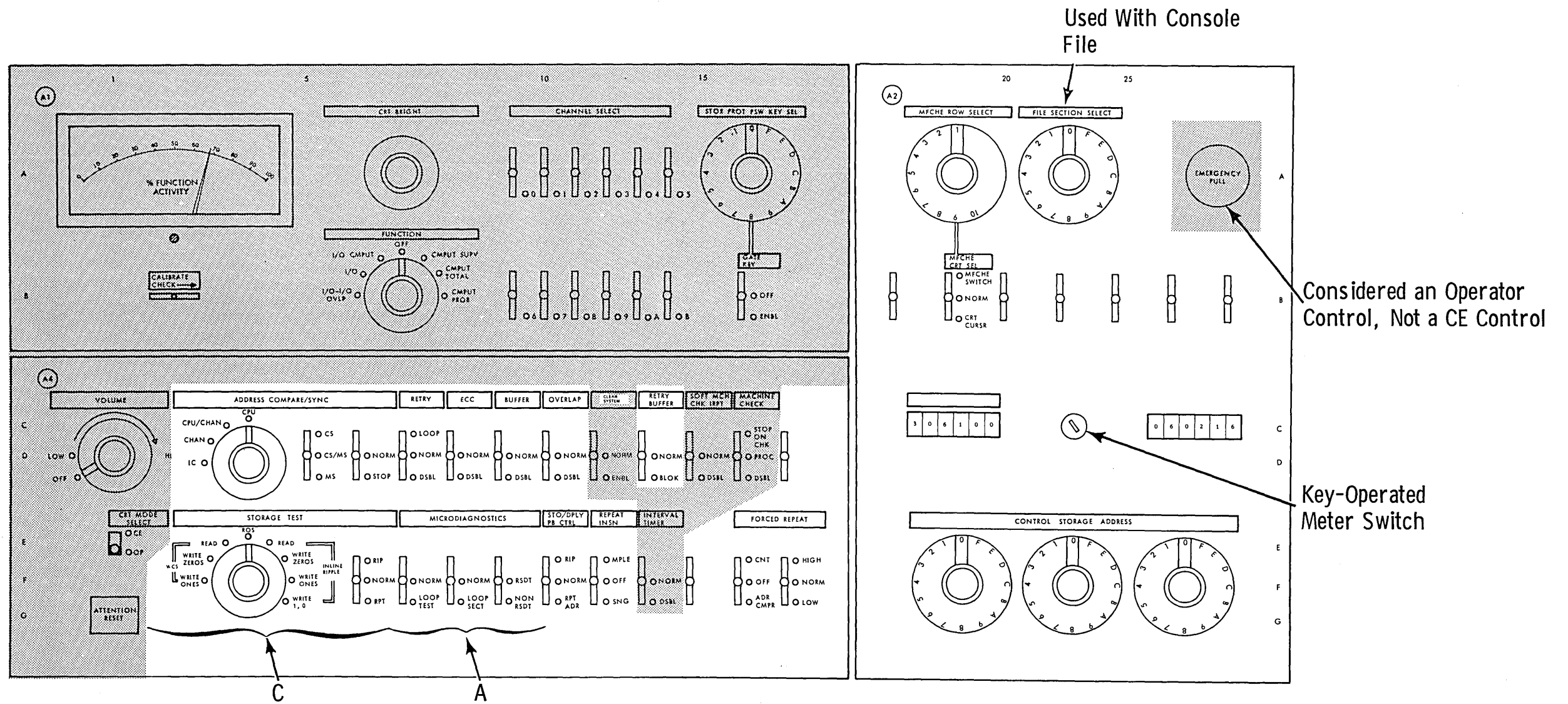


Figure 3-36 CE Controls

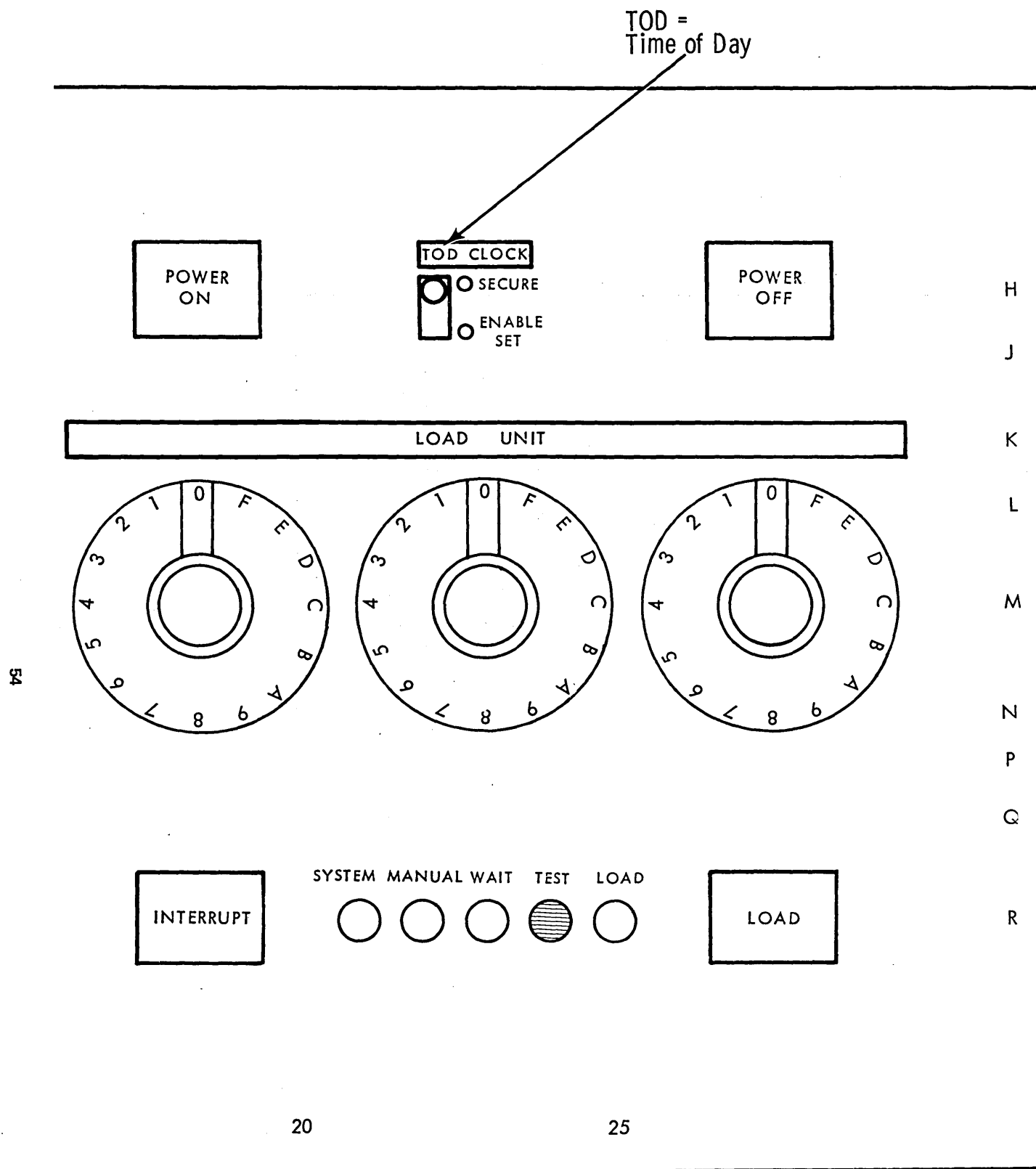


Figure 3-37 Operator Controls

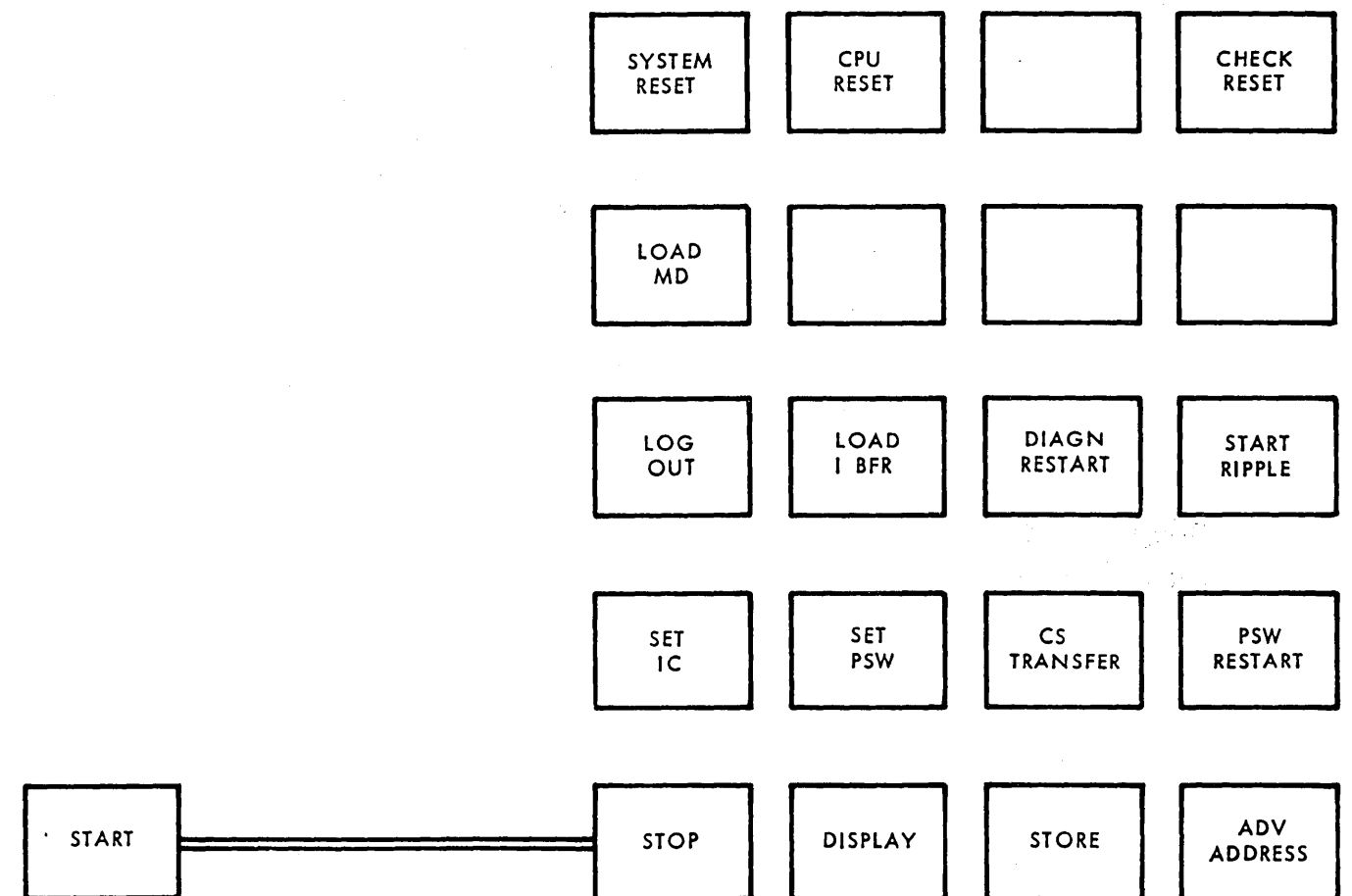


Figure 3-38 Pushbuttons

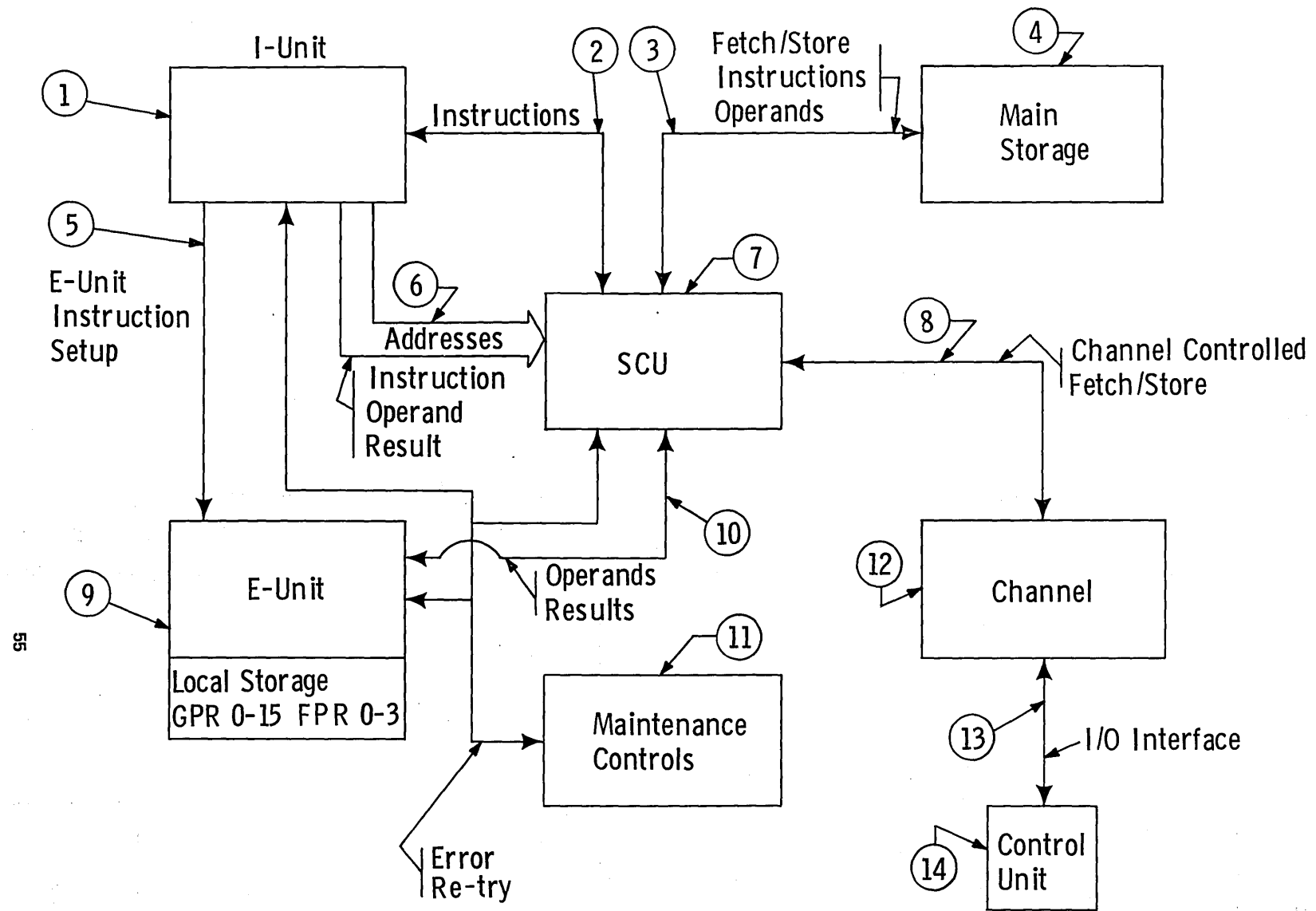


Figure 4-1 Questions 9-12

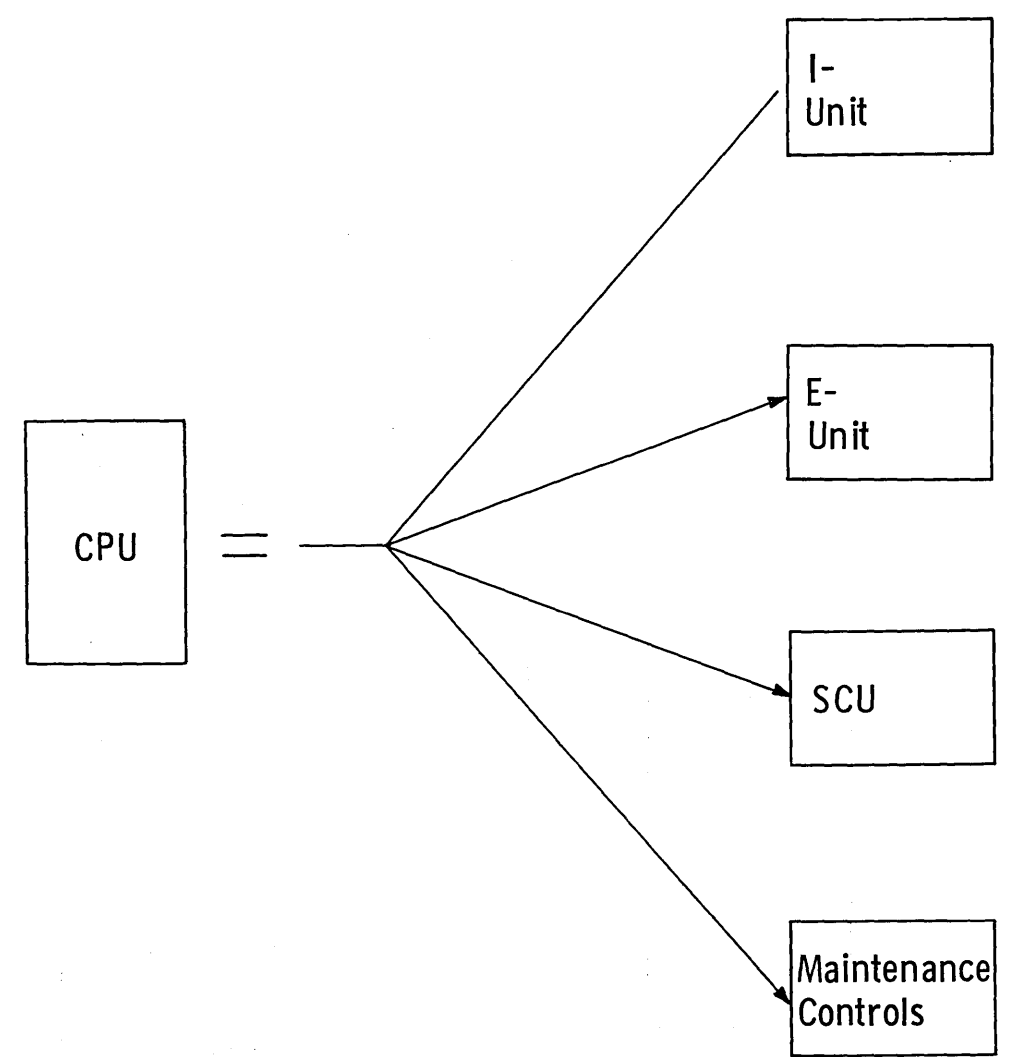
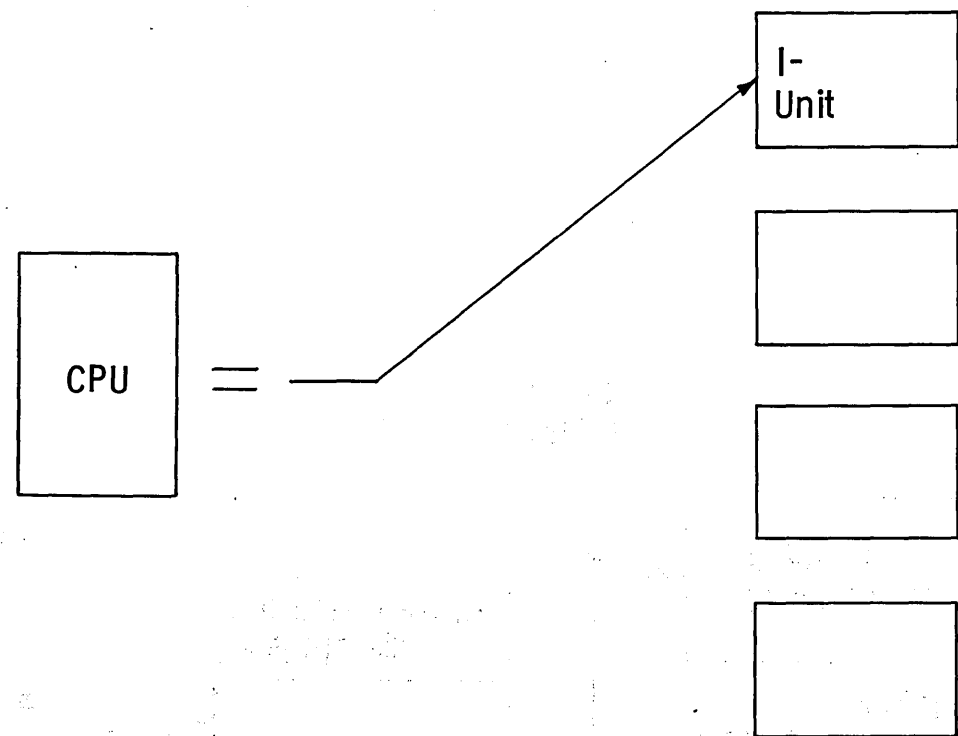


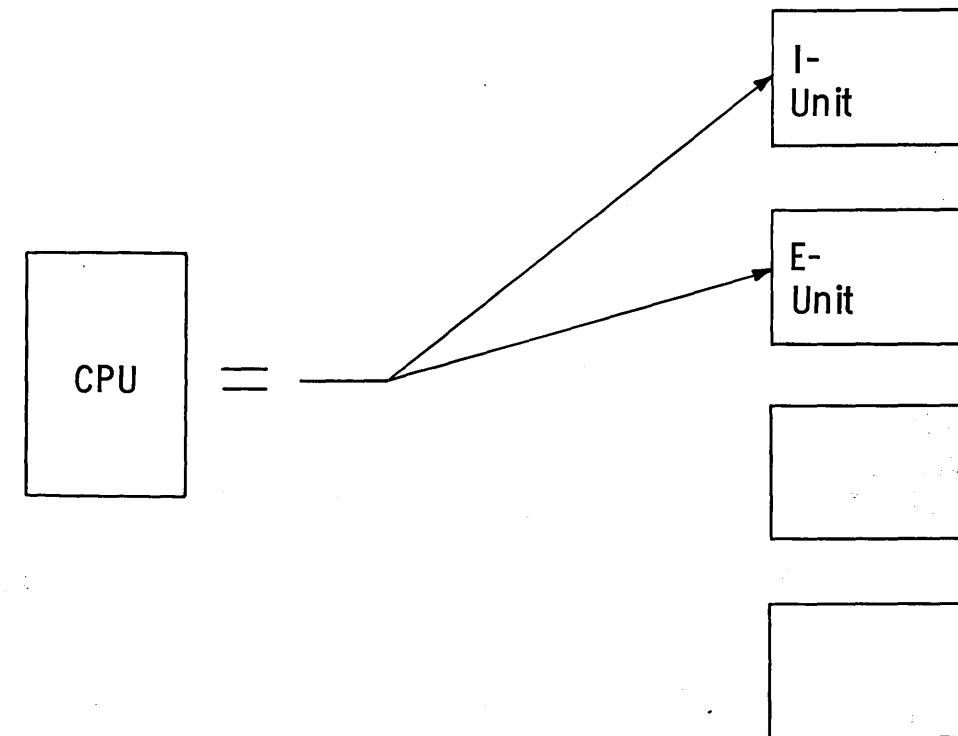
Figure 4-2 CPU Operational Units



Instruction Unit

- * **Fetch Instructions**
Requests "blocks" of instructions from storage via the storage control unit.
- * **Buffer Instructions**
Has buffers/registers for the temporary storage of instructions both as they enter and after they are decoded and are ready to be transferred to the E-unit.
- * **Decodes Instructions**
Instruction is identified and the availability of the facilities needed for further processing is checked.
- * **Calculates effective storage addresses**
A three input adder for determining address for branches, stores, fetches, I/O operations, and shift instructions.
- * **Fetches Operands**
Operands (data the program is operating upon) to be used by the E-unit are prefetched from storage by the I-unit, and loaded into the buffers in the E-unit.
- * **E-Unit Setup**
Establishes the initial conditions for instruction execution.

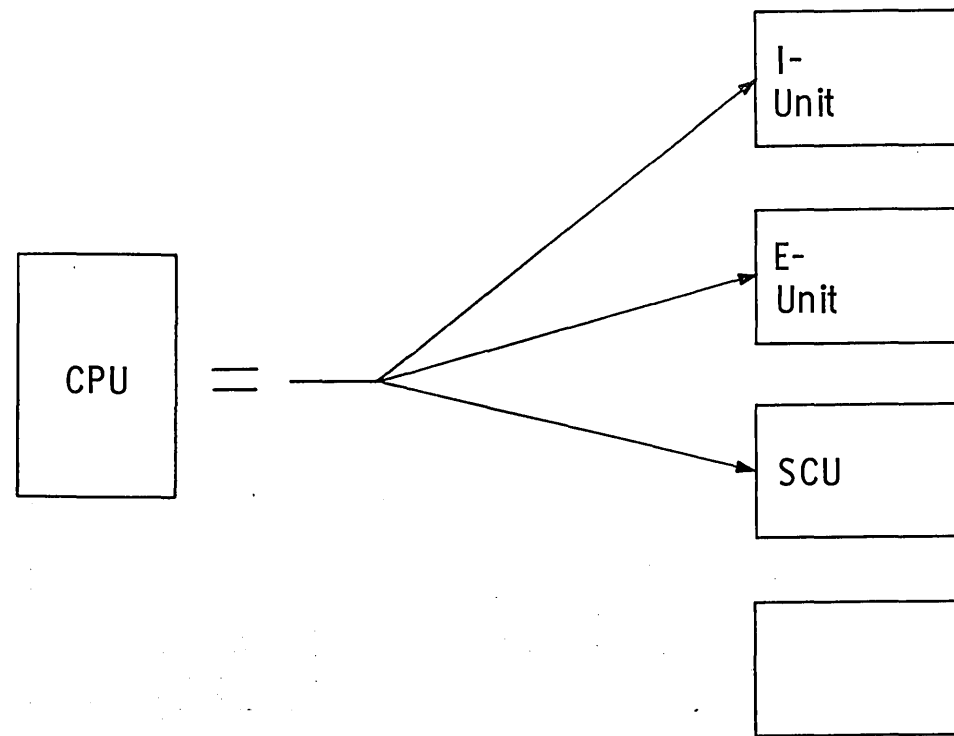
Figure 4-3 I-Unit Operations



Execution Unit

- * **Processes the instructions fetched and readied by the I-unit.**
- * **Except for the portions needed by the I-unit to set up initial conditions, the E-unit is controlled by a microprogram.**
- * **Local storage, consisting of 20-latch registers and associated address registers, are located in the E-unit.**
 - a. The 20 latch registers are used for the 16 GPRs and four FPRs that make up local storage.
 - b. Having the GPRs and FPRs in the E-unit reduces the number of processor storage references required by the CPU during each operation.

Figure 4-4 E-Unit Operations

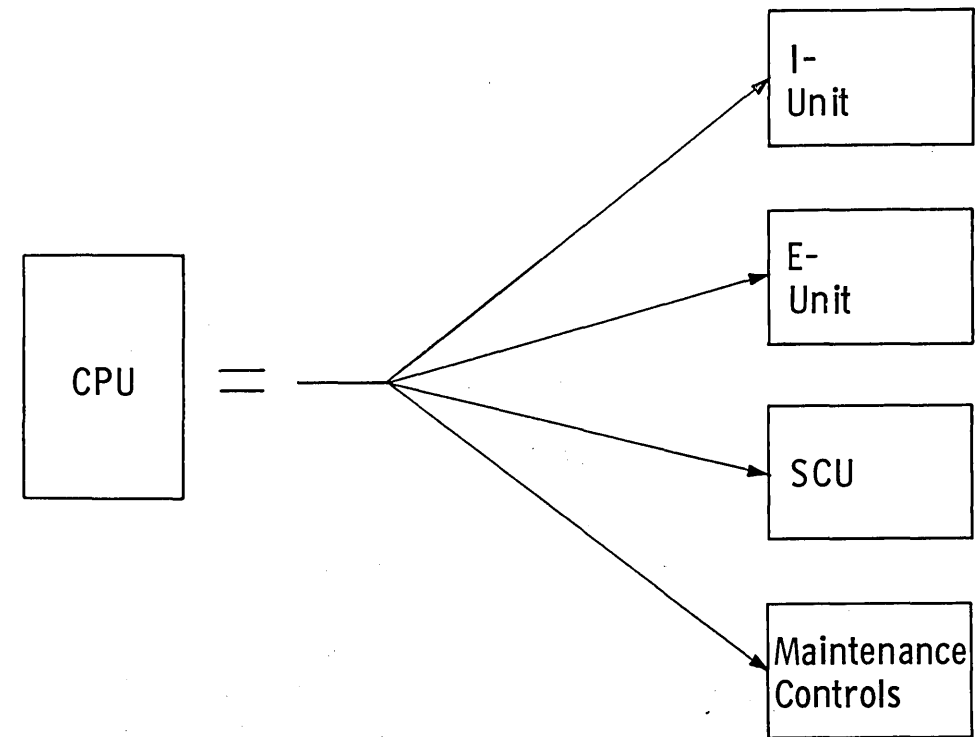


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Storage Control Unit

- *Functionally connects all system units to processor storage.
- *Controls all references to storage from the CPU (I- and E-units), channels, and the maintenance controls.
 - a. Resolves priority between requests.
 - b. Checks the validity of each request.
- *Controls the operation of the high-speed buffer located in the SCU.
- *Contains the Error Checking and Correction (ECC) logic.

Figure 4-5 SCU Operations



Maintenance Controls

- * Executes the functions provided by the system control panel controls, provides diagnostic capabilities for the system, and contains logic required to buffer the needed information to execute the system portion of instruction re-try.

Figure 4-6 Maintenance Control Operation

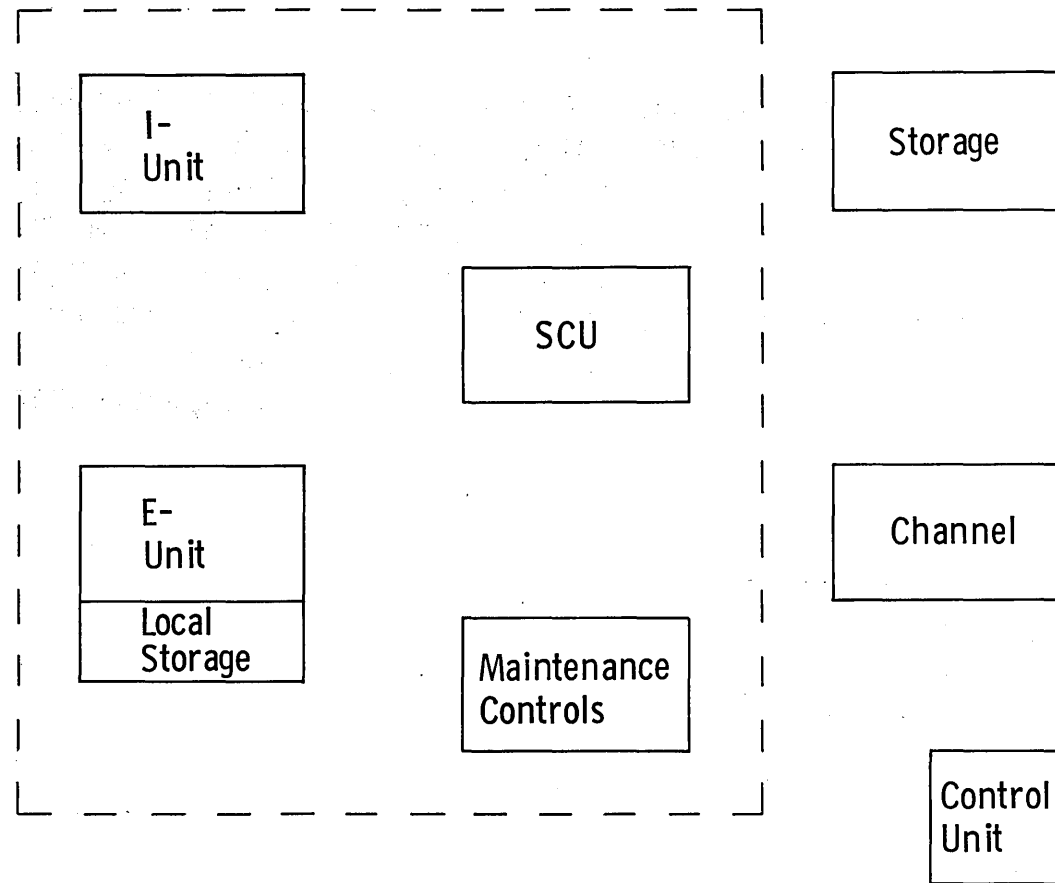


Figure 4-7 Basic Logic Flow

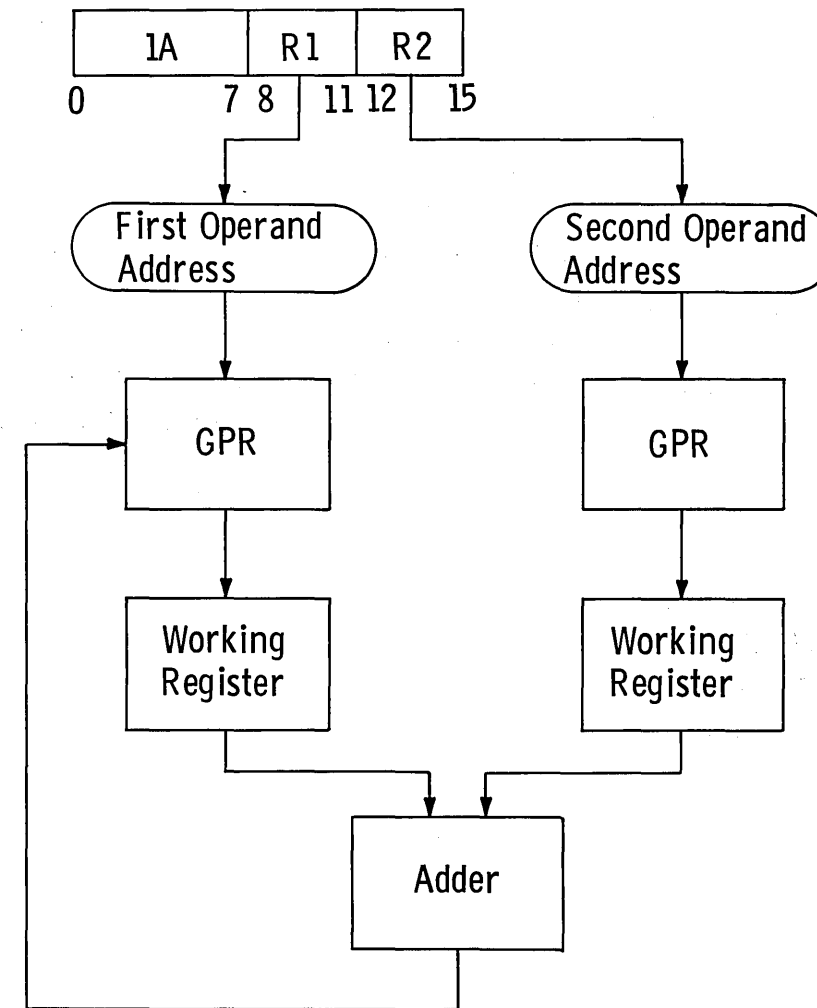


Figure 4-8 RR Instruction

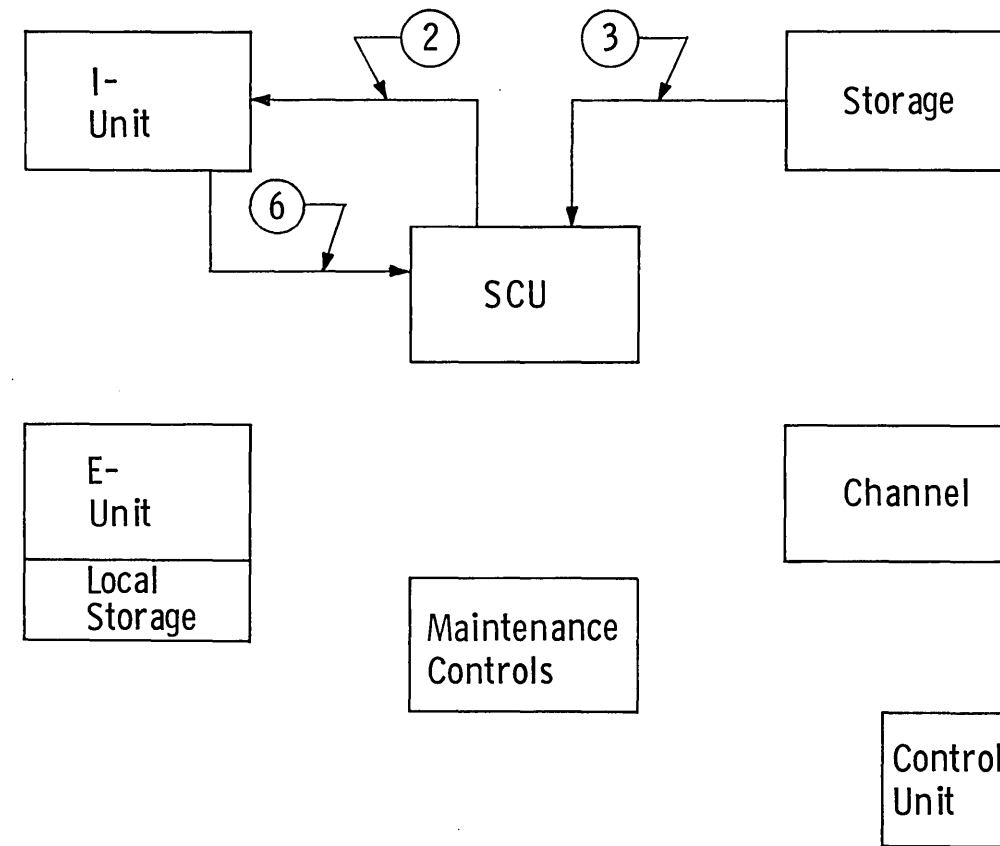
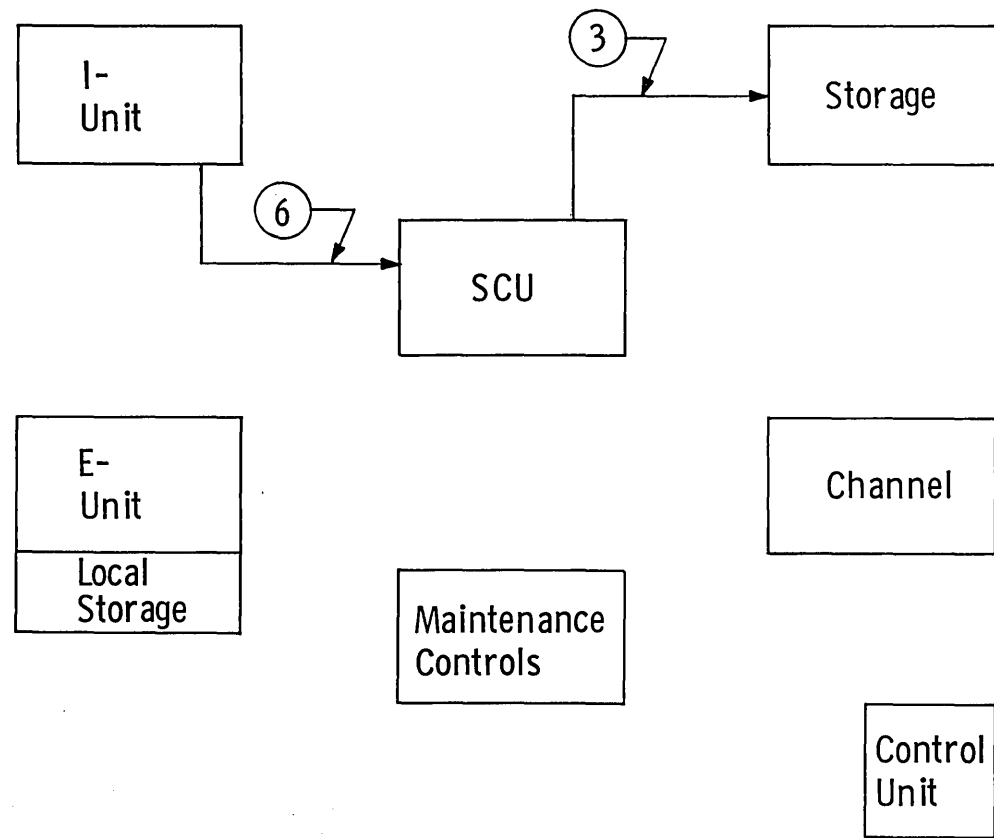


Figure 4-9 RR Basic Logic Flow 1

Figure 4-10 RR Basic Logic Flow 2

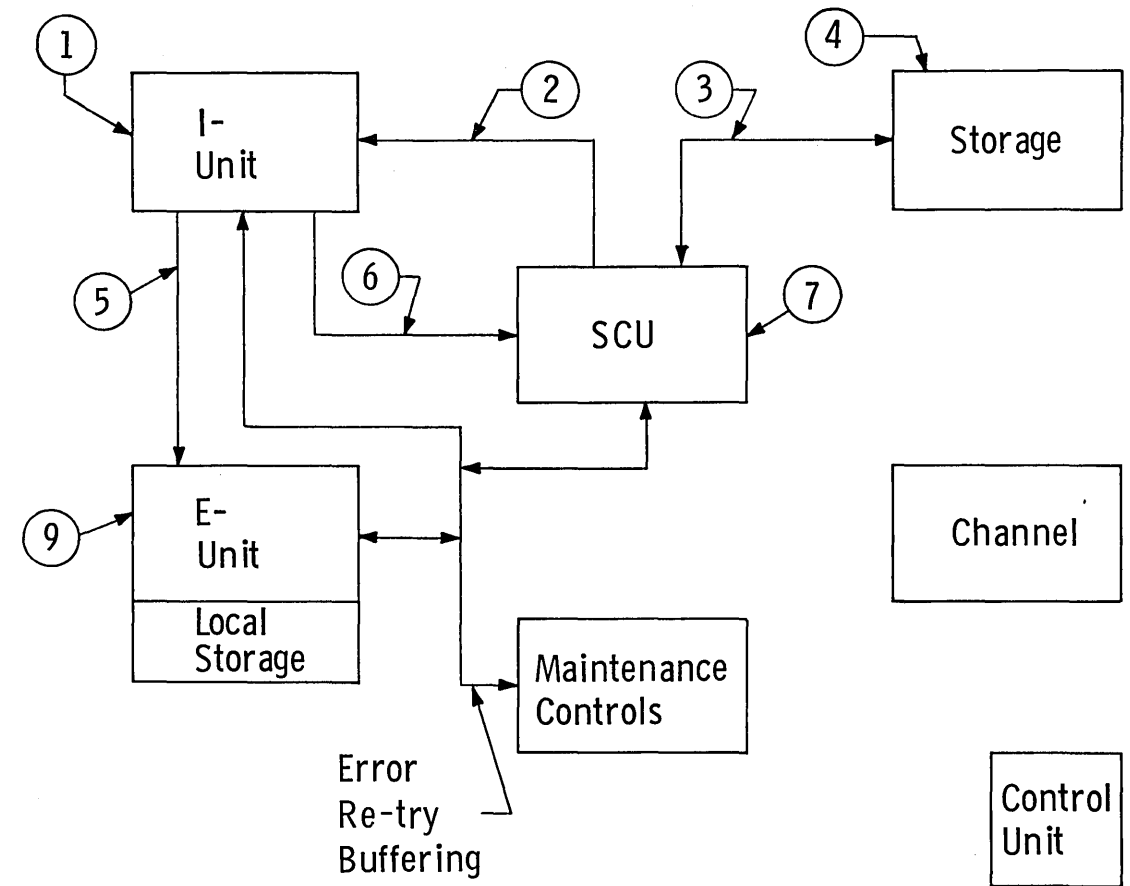
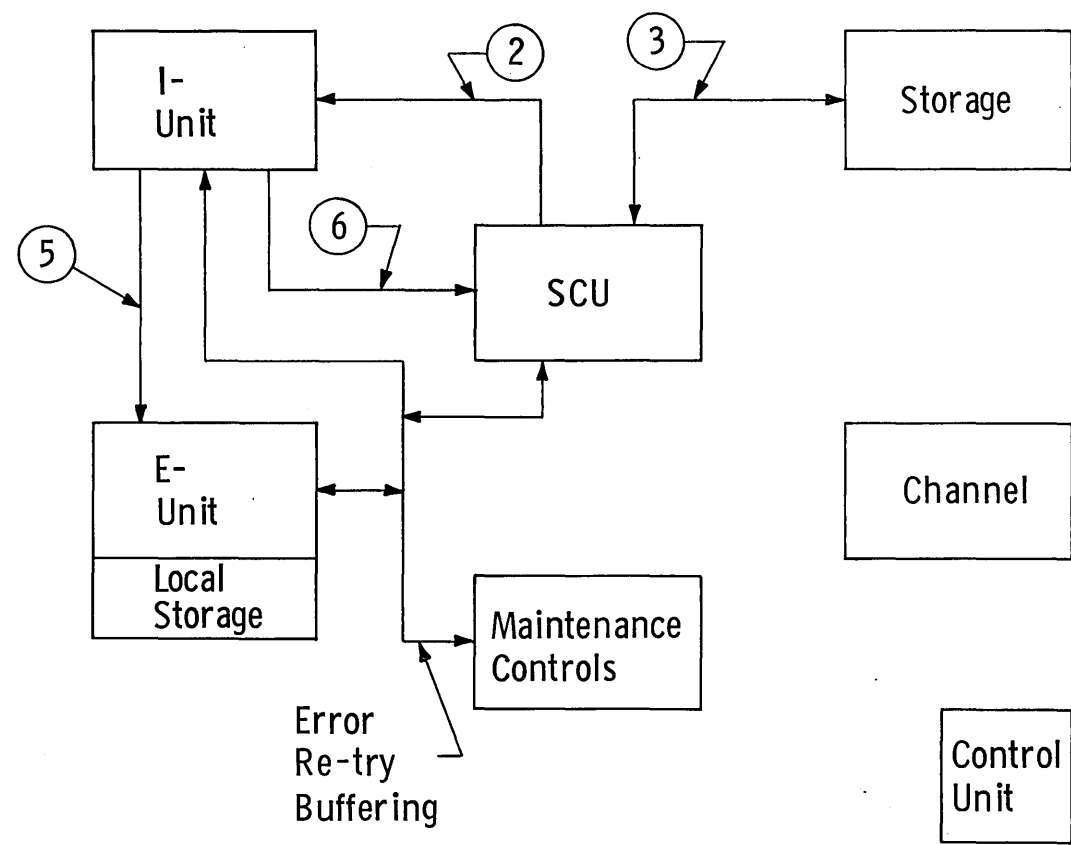


Figure 4-11 RR Basic Logic Flow 3

Figure 4-12 RR Question on Basic Logic Flow

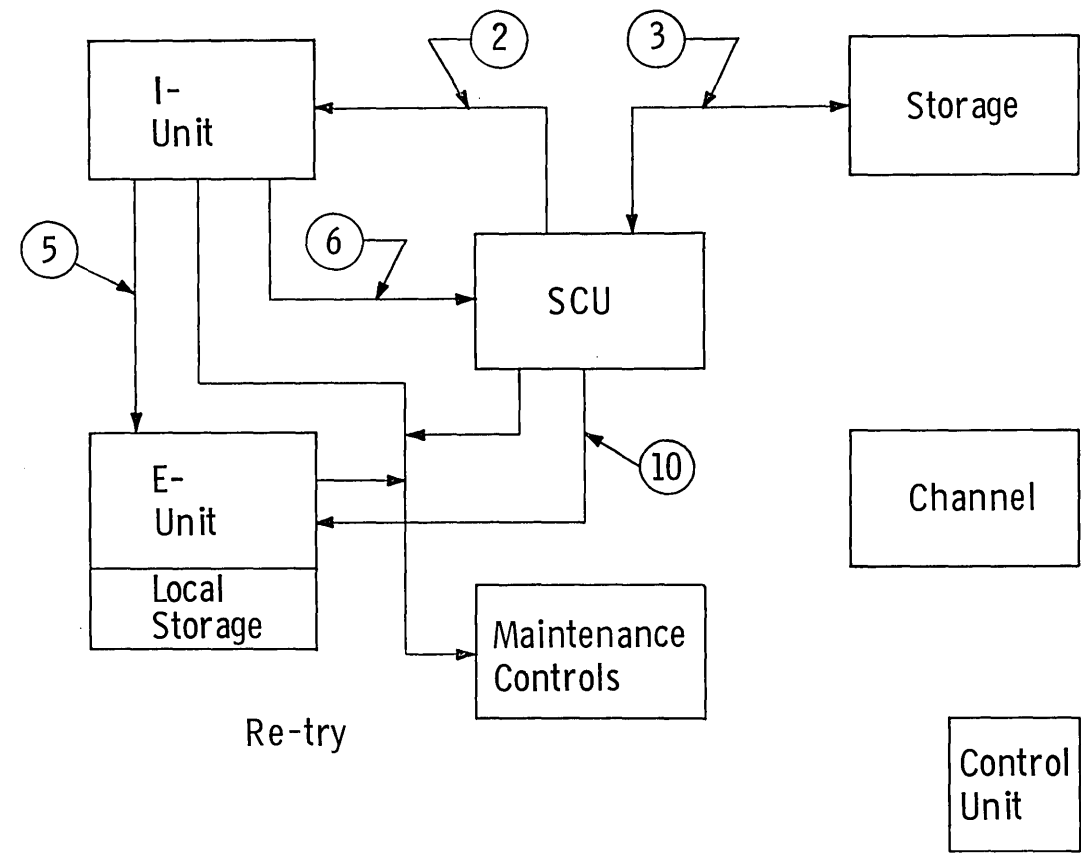
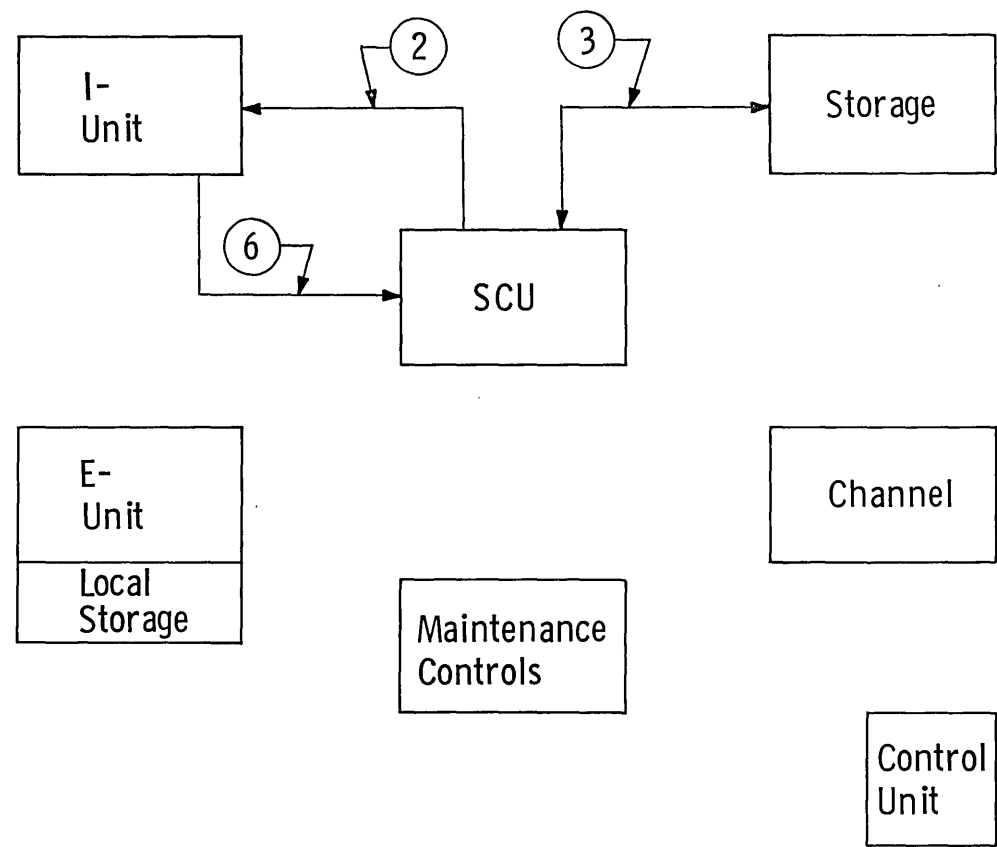


Figure 4-13 RX Basic Logic Flow 1

Figure 4-14 RX Basic Logic Flow 2

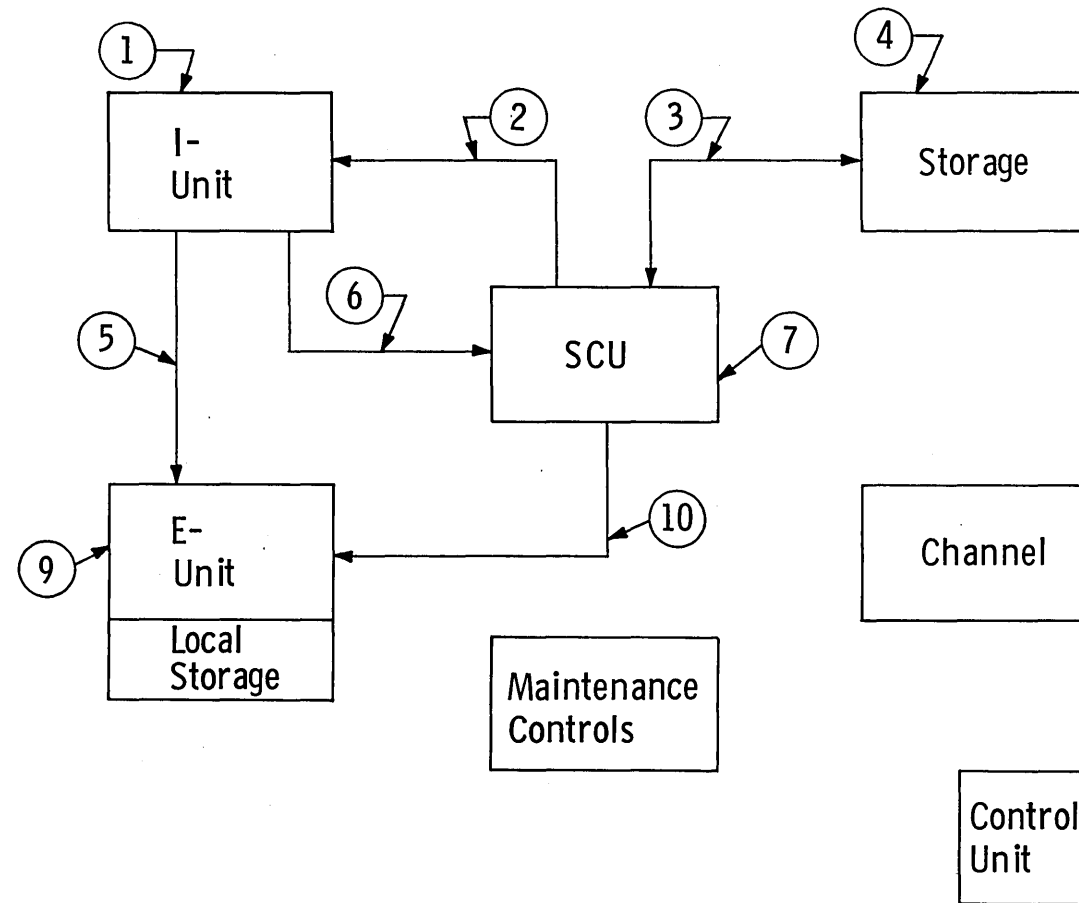


Figure 4-15 RX Question on Basic Logic Flow

Op Code	R1	R2
---------	----	----

- 1A Add
- 1E Add Logical
- 19 Compare
- 15 Compare Logical
- 1B Subtract
- 1F Subtract Logical

Op Code	R1	X2	B2	D2
---------	----	----	----	----

- 5A Add
- 4A Add Halfword
- 5E Add Logical
- 59 Compare
- 49 Compare Halfword
- 55 Compare Logical
- 5B Subtract
- 4B Subtract Halfword
- 5F Subtract Logical

Figure 4-16 RR-RX Instructions

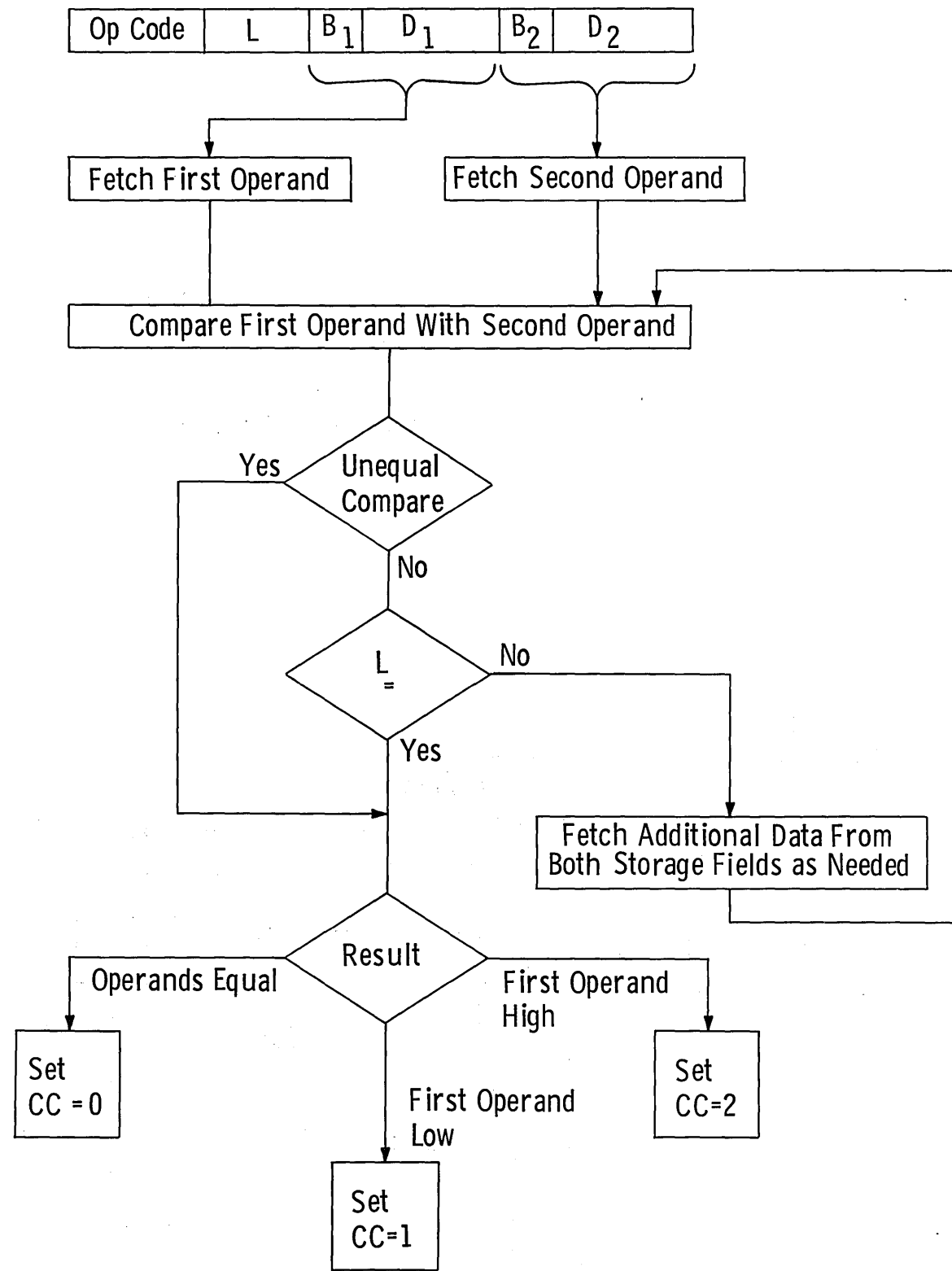


Figure 4-17 SS Compare Flowchart

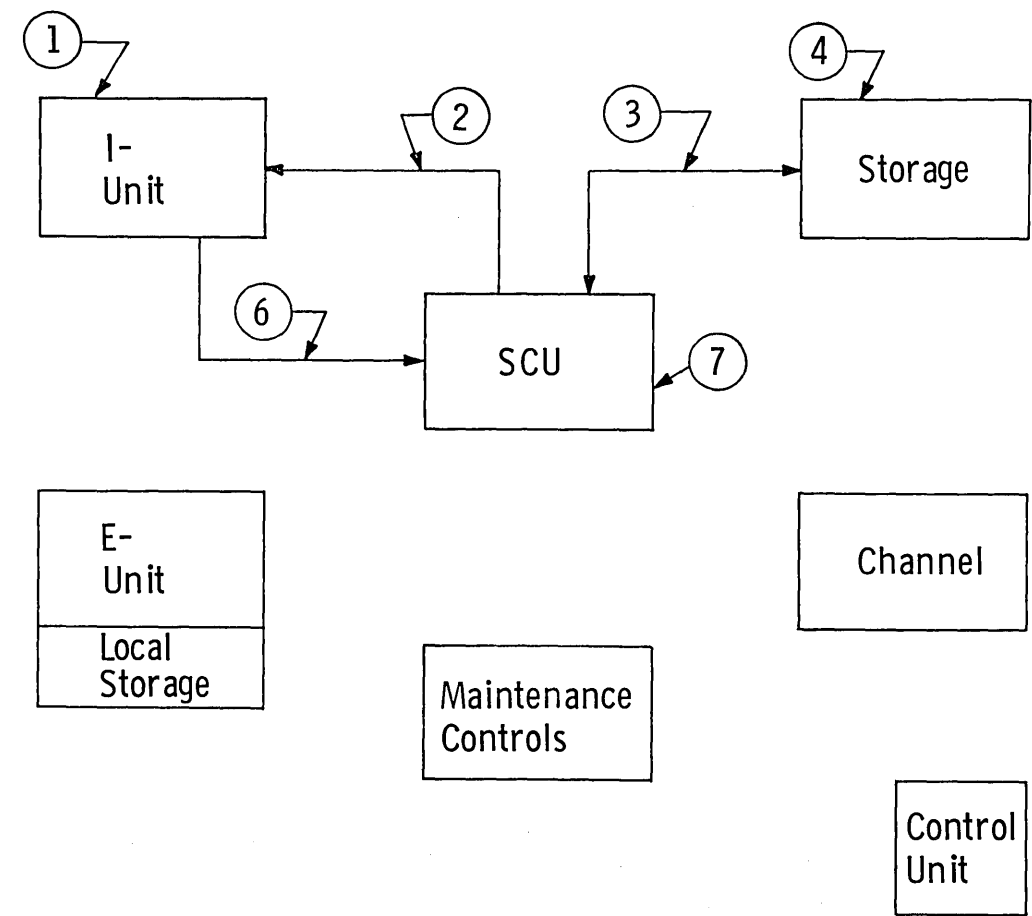
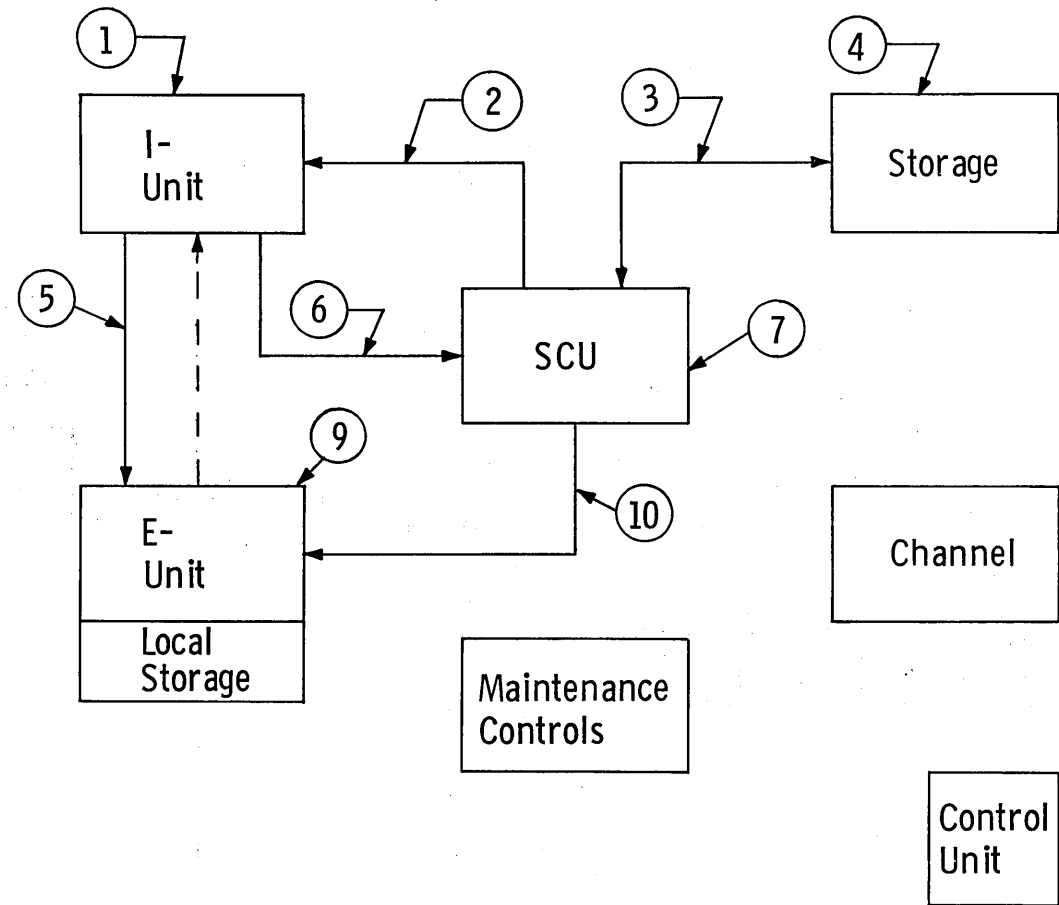


Figure 4-18 SS Basic Logic Flow 1



----- E-Unit Control of I-Unit
For Operand Fetches

Note: Re-try Paths Omitted for
Clarity

Figure 4-19 SS Basic Logic Flow 2

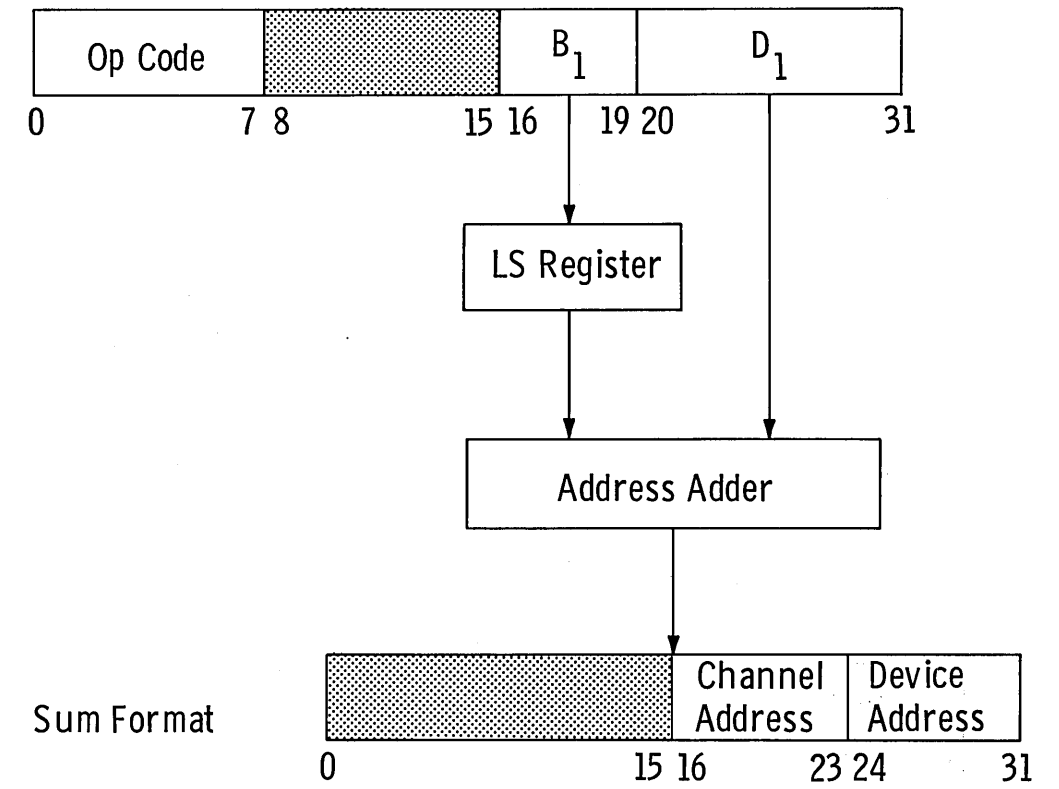


Figure 4-20 I/O Instructions

Partial List of System Logic Units

1. D BAR
2. Address Adder
3. LAR Buffer Latch
4. ACAL
5. MCDR
6. Buffer Bypass Latch
7. L2 Register
8. Parallel Adder
9. Channel Data-Out Buffer
10. A-Register
11. Shift Control Triggers
12. Destination Register
13. Main I-Buffer
14. A-Pointer
15. C-Register
16. STAR
17. FAR
18. Source Register
19. LAL 5
20. F-Register
21. Instruction Queues
22. Serial Adder
23. MCWR
24. Difference Register B
25. CSAR
26. B-Register

		ADR	K	MK	ID	ST	ARRAY	ADR	VD
aa → CH	XX	XX	XX	0X	XX	XX	0	XX	XX
ab → STAR	XX	XX	XX		0X	XX	1	XX	XX
ac → FAR	XX	XX	XX			XX	2	XX	XX
ad → REDO	XX	XX	XX			XX	3	XX	XX
							be → B RPL	XX	XX
							bf → D BAR	XX	XX
							bg → BAR	XX	XX

		1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
ae → IB A	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX
af → IB M	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX
ag → CH I	XX	XX	XX	XX	XX	XX	XX	XX								
ah → CH O	XX	XX	XX	XX	XX	XX	XX	XX	bh → IREG	XX	XX	XX	XX	by → L2	XX	
aj → SDBO	XX	XX	XX	XX	XX	XX	XX	XX	bj → IQ 1	XX	XX	XX	XX	bx → DSMP	0X	XX
ak → OP 1	XX	XX	XX	XX	XX	XX	XX	XX	bk → IQ 2	XX	XX	XX	XX	by → BASE	XX	XX
am → OP 2	XX	XX	XX	XX	XX	XX	XX	XX	bm → IQ 3	XX	XX	XX	XX	bz → INDX	XX	XX
an → A	XX	XX	XX	XX	XX	XX	XX	XX						ca → SRC	XX	XX
ap → B	XX	XX	XX	XX	XX	XX	XX	XX						cb → DST	XX	XX
aq → C	XX	XX	XX	XX	XX	XX	XX	XX	bp → DIF A	XX				cd → IAR A	XX	XX
ar → D	XX	XX	XX	XX	XX	XX	XX	XX	bq → DIF B	XX				ce → IAR B	XX	XX
as → E	XX	XX														
at → F	XX	XX	XX	XX	XX	XX	XX	XX								

au → MY 1	XX	XX	XX	XX	XX	XX	XX	XX	br → CSAR	0X	XX					
av → MY 2	XX	XX	XX	XX	XX	XX	XX	XX	bs → CSARA	0X	XX	0X	← cf			
aw → SUM	XX	XX	XX	XX	XX	XX	XX	XX	bt → CSARB	0X	XX	0X	← cg			
ax → CAR	XX	XX	XX	XX	XX	XX	XX	XX								
ay → SPAR	XX	XX		XX	XX											
az → MCRR	XX	XX	XX	XX	XX	XX	XX	XX	bn → IC	XX	XX	XX	XX	ch → MCER	XX	
ba → MCDR	XX	XX	XX	XX	XX	XX	XX	XX	bu → MCAR	XX	XX	XX	XX	cj → MRAR	XX	XX

Figure 5-1 Partial List of System Logic Units

Figure 5-2 Session 5 Question 12-17

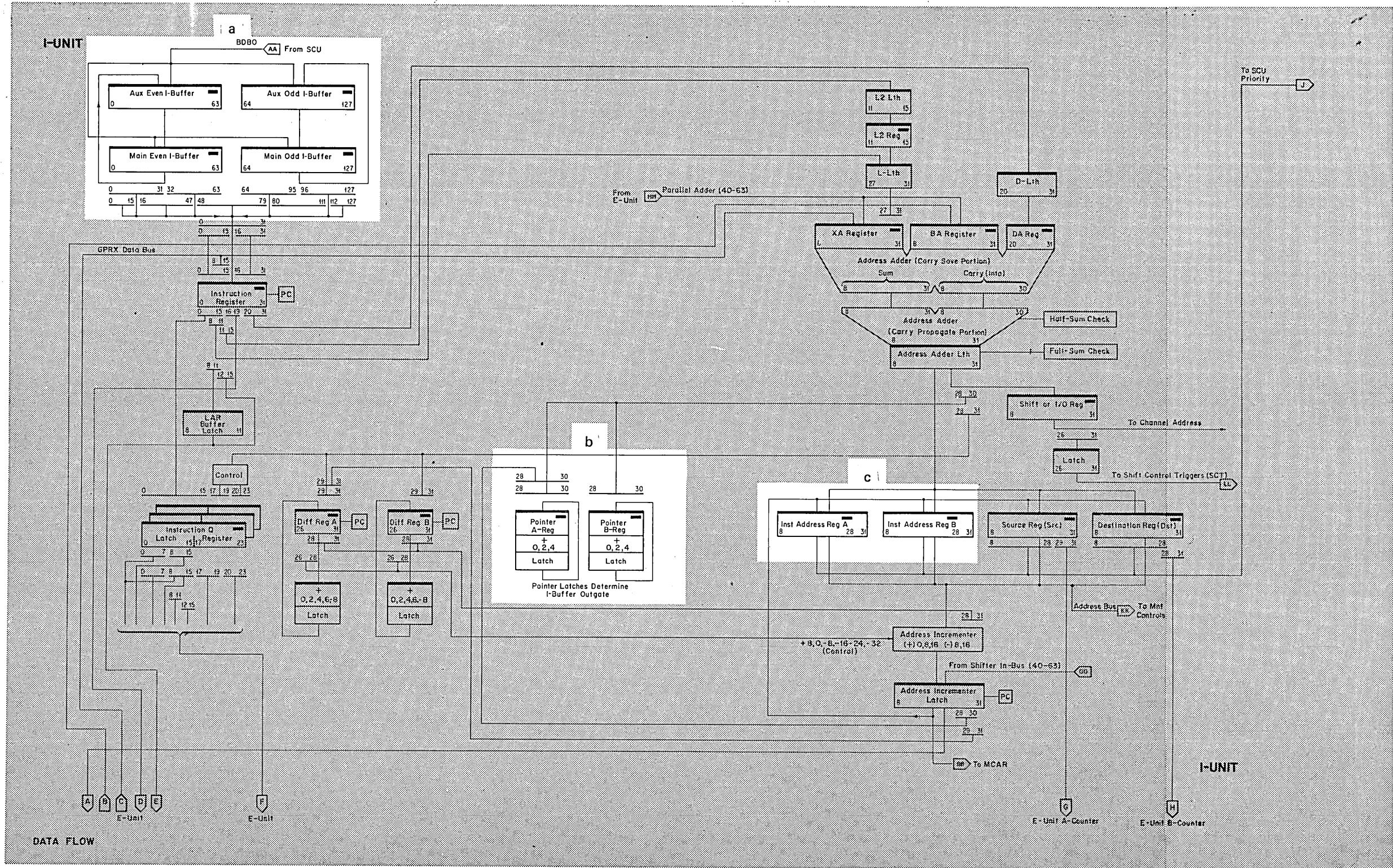


Figure 5-3 I Buffers

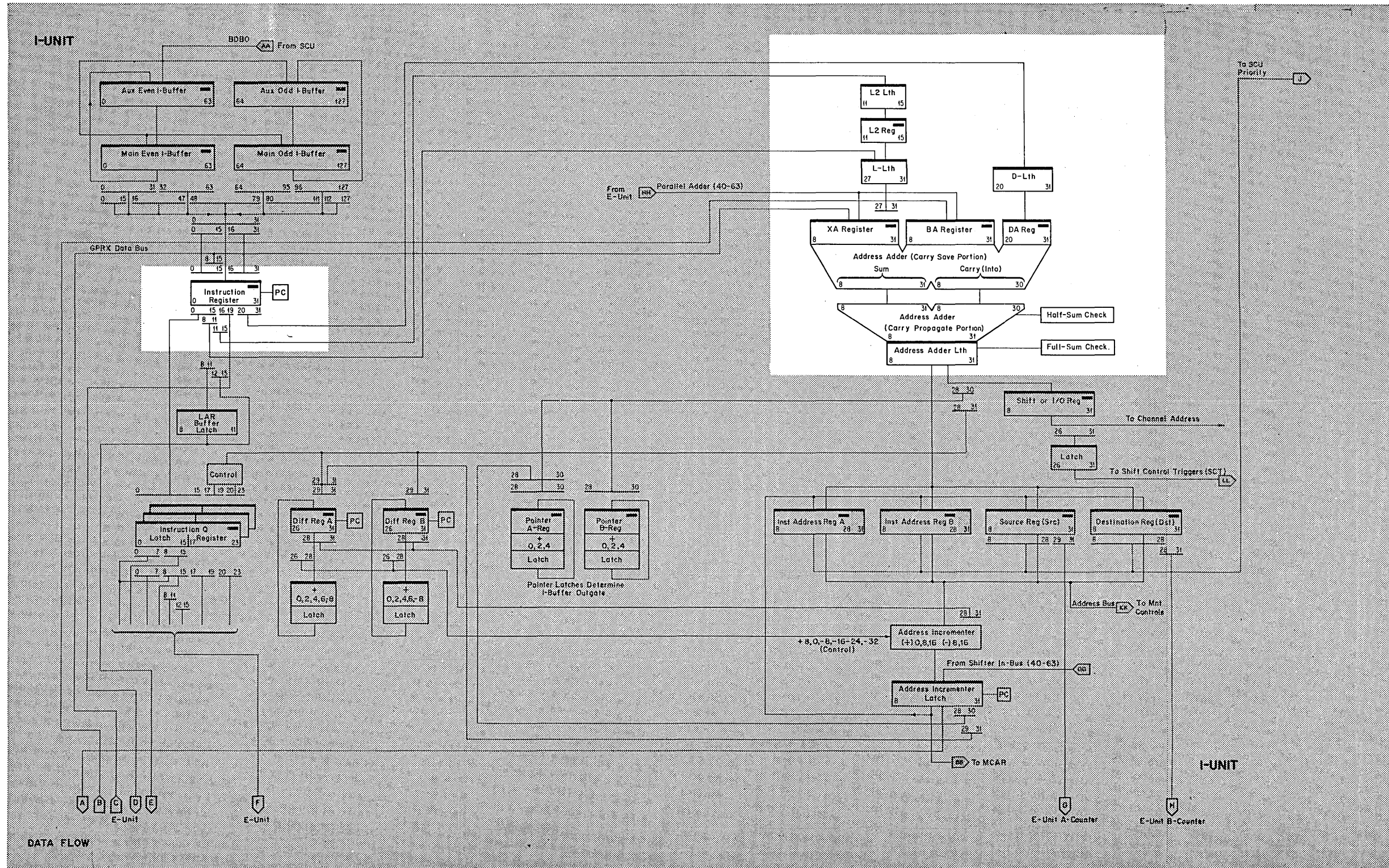


Figure 5-4 | I-Register

Address Adder

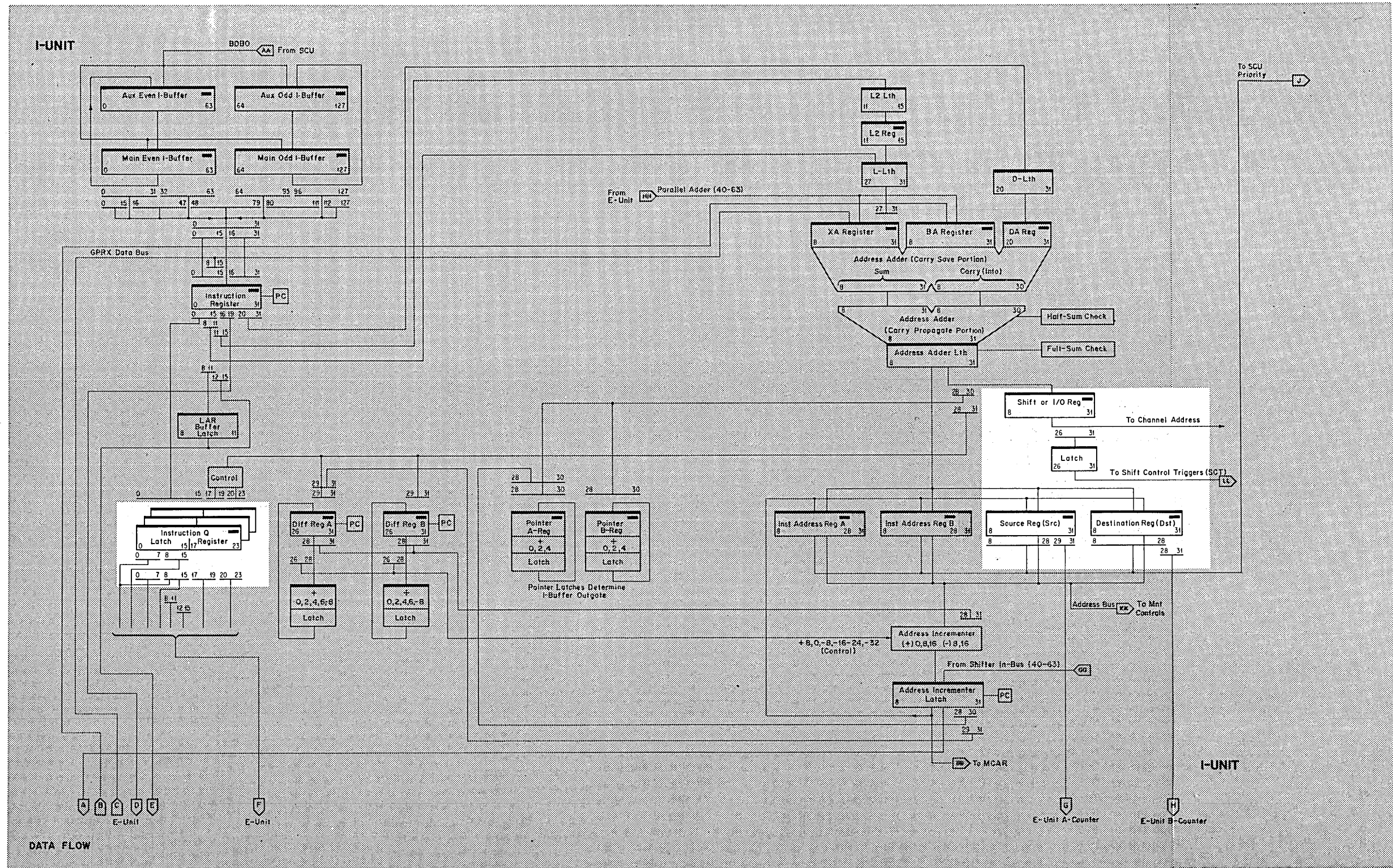


Figure 5-5 Instruction Queues

Address Registers

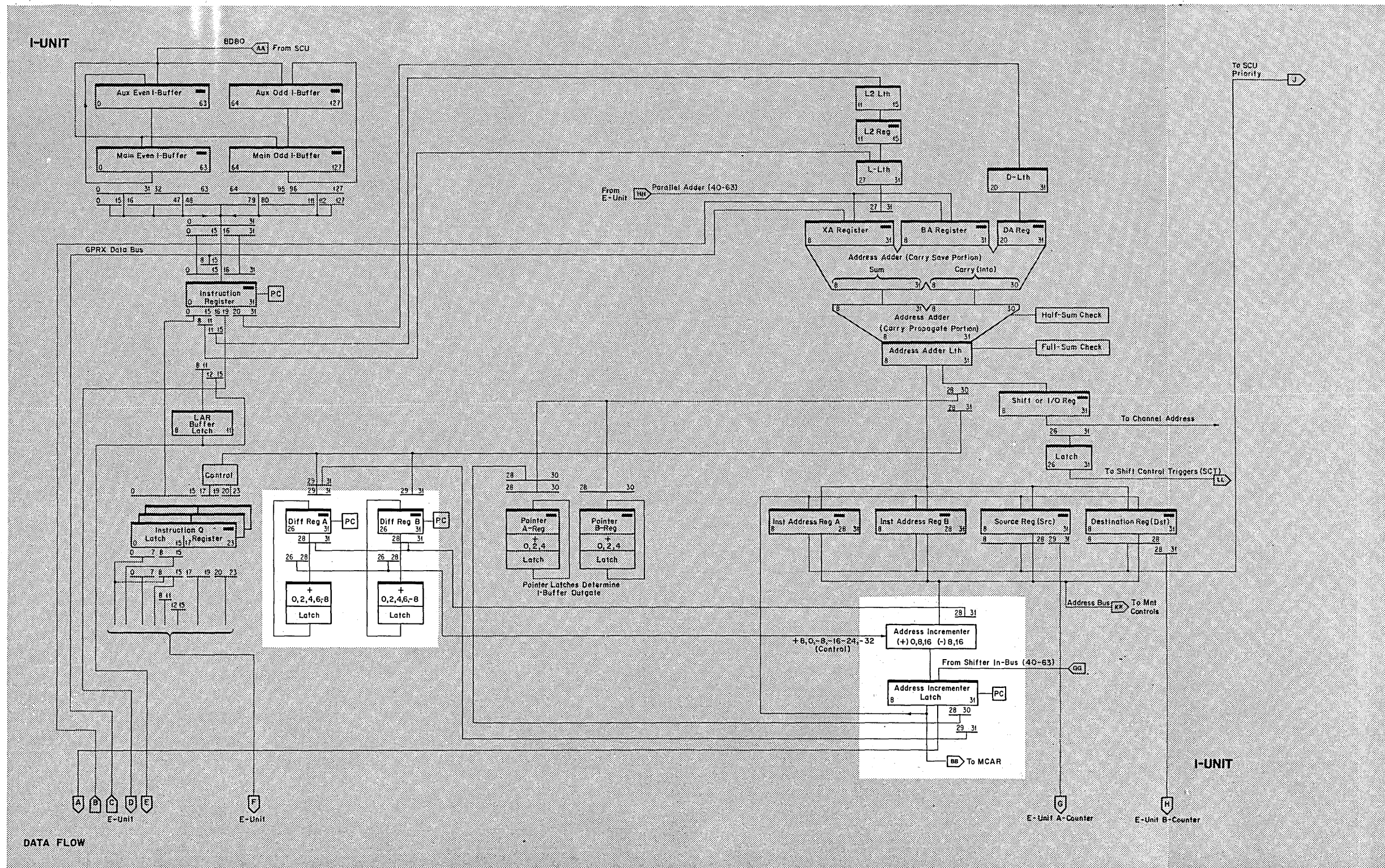


Figure 5-6 Difference Register

Address Incrementer

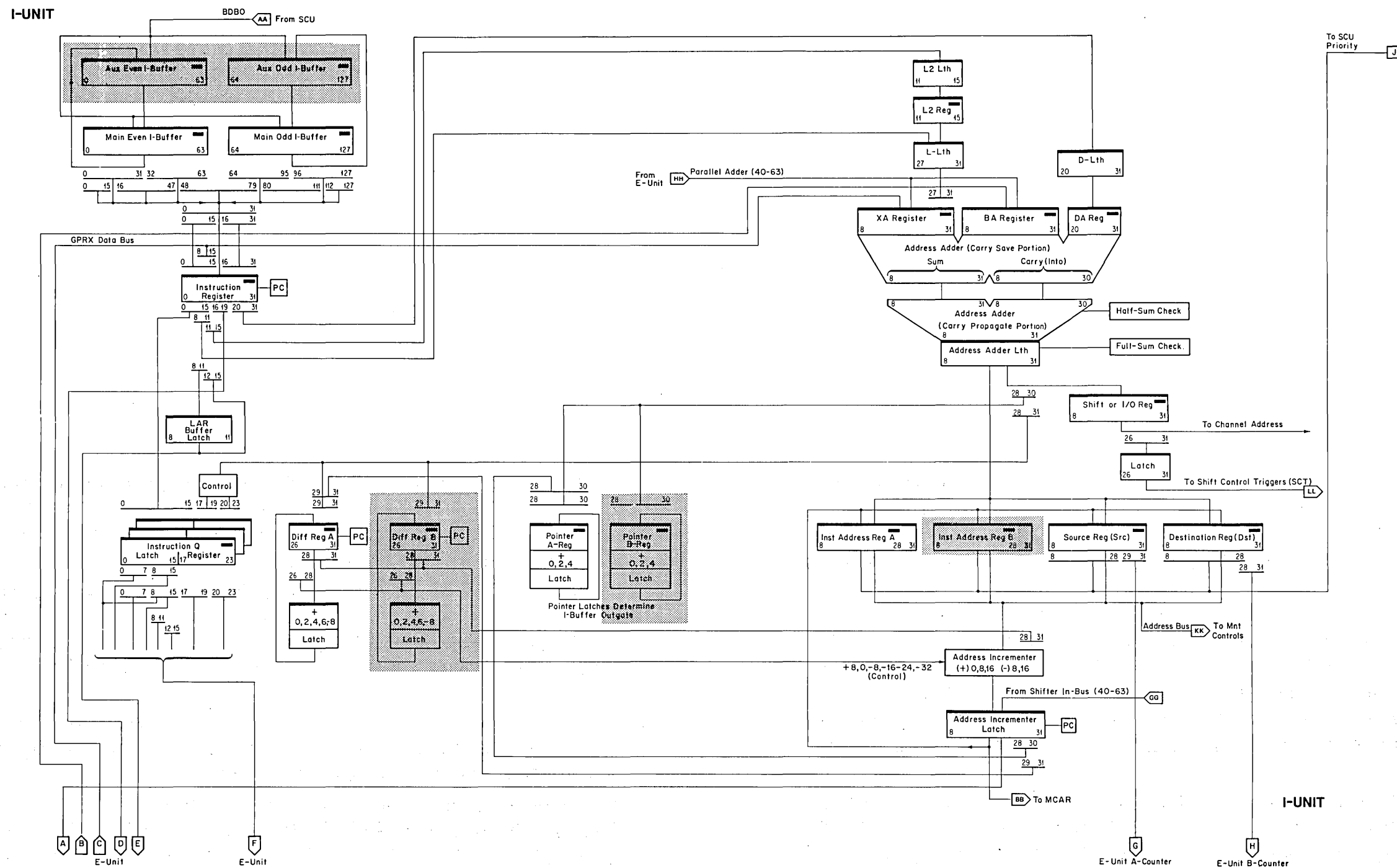


Figure 5-7 Revised Data Flow

INSTRUCTION BUFFER

To accelerate preprocessing of instructions, the main instruction buffer stores up to one quadword of the current instruction stream in the I-unit to provide extremely rapid access to consecutive instructions for preprocessing. A doubleword of the "instruction stream" is fetched from main storage and placed on a bus called "Buffer Data Bus-Out" (BDBO) by the Storage Control Unit (SCU). From BDBO the instructions can then be ingated to either half of the instruction buffer. A fetch to main storage is initiated immediately when either half of the I-buffer is depleted, to keep the contents of the I-buffer as current and as far ahead of the I-unit processing as possible.

Instructions are outgated one-at-a-time from the main instruction buffer to the instruction register under the control of the pointer A-register. Four bytes, starting with an even byte, are sent to the instruction register. If the left two bytes contain an RR instruction, the right-most two bytes are ignored. After an instruction is outgated from the I-buffer, the pointer is updated by the length of the instruction to keep track of which byte is the beginning of the next instruction. The pointer is also instrumental in determining when a new main storage fetch must be initiated to refill each half of the instruction buffer as soon as it is emptied.

ADDRESS REGISTERS

The four 24-bit address registers used to make storage requests are: instruction address register A (IARA), instruction address register B (IARB), source (src) address register, and destination (dst) address register. Instruction address registers A and B are used exclusively for fetching instructions. The source address register is used only for fetching operands from main storage. The destination address register is used for storing operands into main storage.

For instructions requiring operands of eight bytes or less, the source address register is controlled only by the I-unit. For instructions requiring longer operands (load multiple and SS format), the initial fetch request is made by the I-unit, and control then passes to the E-unit for subsequent requests. The destination address register is used to hold the address during store requests, which are always made by the E-unit.

Any of the four registers can be ingated from the address-adder latch or the address-incrementer latch. The contents of any of the four registers can be transferred to the address-incrementer for incrementing or the SCU address latches for accessing main storage.

POINTERS

A special type of functional unit associated with the I-unit is the "pointer." Pointers keep track of individual instructions in the instruction buffers and the queue registers. Because the I-unit handles several instructions at a time, they are needed to ensure that instructions are processed in the proper sequence.

Address Register Pointers (Pointer A-Register and Pointer B-Register)

Two pointers, one associated with each of the two instruction address registers, select the word that is to be transferred from an instruction buffer to the instruction register. As instructions are transferred from the instruction register to the instruction queues, the contents of the pointer register are incremented according to the instruction length and are transferred to the pointer latch. The contents of the pointer latch then select the next word that is to be transferred from the instruction buffer to the instruction register.

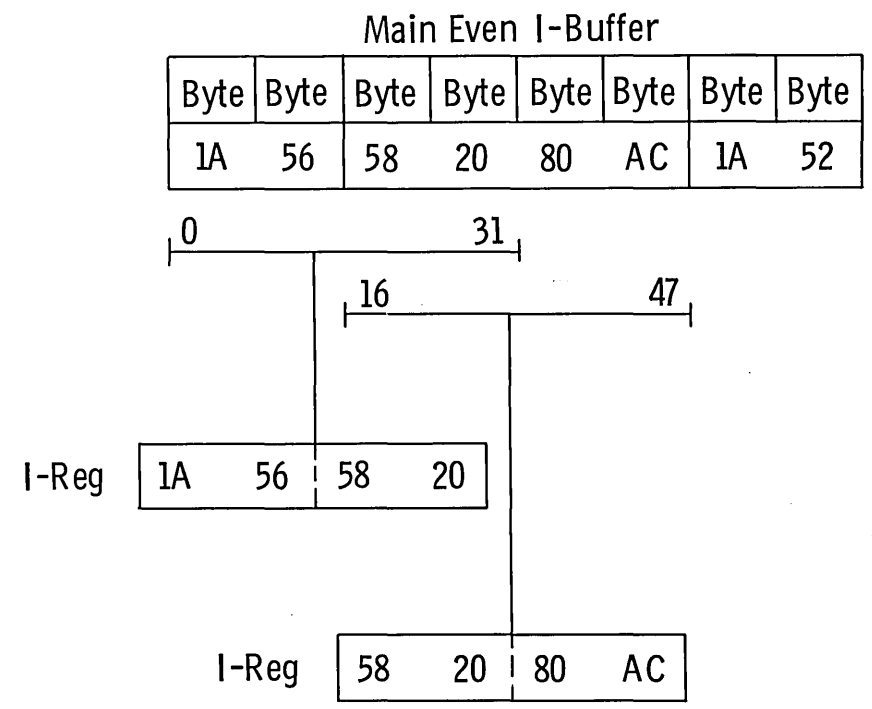


Figure 5-10 Address Register Pointers

Figure 5-11 I-Reg Ingate

INSTRUCTION REGISTERS

The four-byte instruction register holds each instruction during a decode cycle. Ingating from the main instruction buffer is determined by pointer A-register, and by the format of the instruction itself (RR, RX, RS, SI, or SS). Each half of the instruction register can be ingated separately. Parity is checked on a byte basis.

Each instruction processed by the I-unit remains in the instruction register for at least one machine cycle for decoding. During this time, the instruction is decoded to determine all the information concerning the instruction that the I-unit requires to preprocess it. If all interlocking conditions are not satisfied, or if any I-unit facility (eg, the address adder or an address register) is busy with an earlier instruction, the decode cycle is delayed until all interlocking conflicts are resolved or the required facilities become available. The following conditions must be satisfied for an instruction to be decoded:

1. A queue register must be available (not busy) to receive the instruction.
2. Required general purpose registers in the E-unit, and the address adder must be available if an address calculation is required.
3. If an SS format instruction is being processed in the I-unit or the E-unit, only branch and RR format instructions are decoded.
4. If a defeat I-unit/E-unit overlap condition exists, no instruction can be decoded until all instructions preceding it complete their execution cycle. A defeat I-unit/E-unit overlap condition occurs when the overlap switch is set at the DSBL position, or when an instruction that required I-unit/E-unit overlap to be defeated is decoded in the I-register.
5. If the instruction to be decoded is a branch, no other branch instruction can be in progress in the I-unit or E-unit.

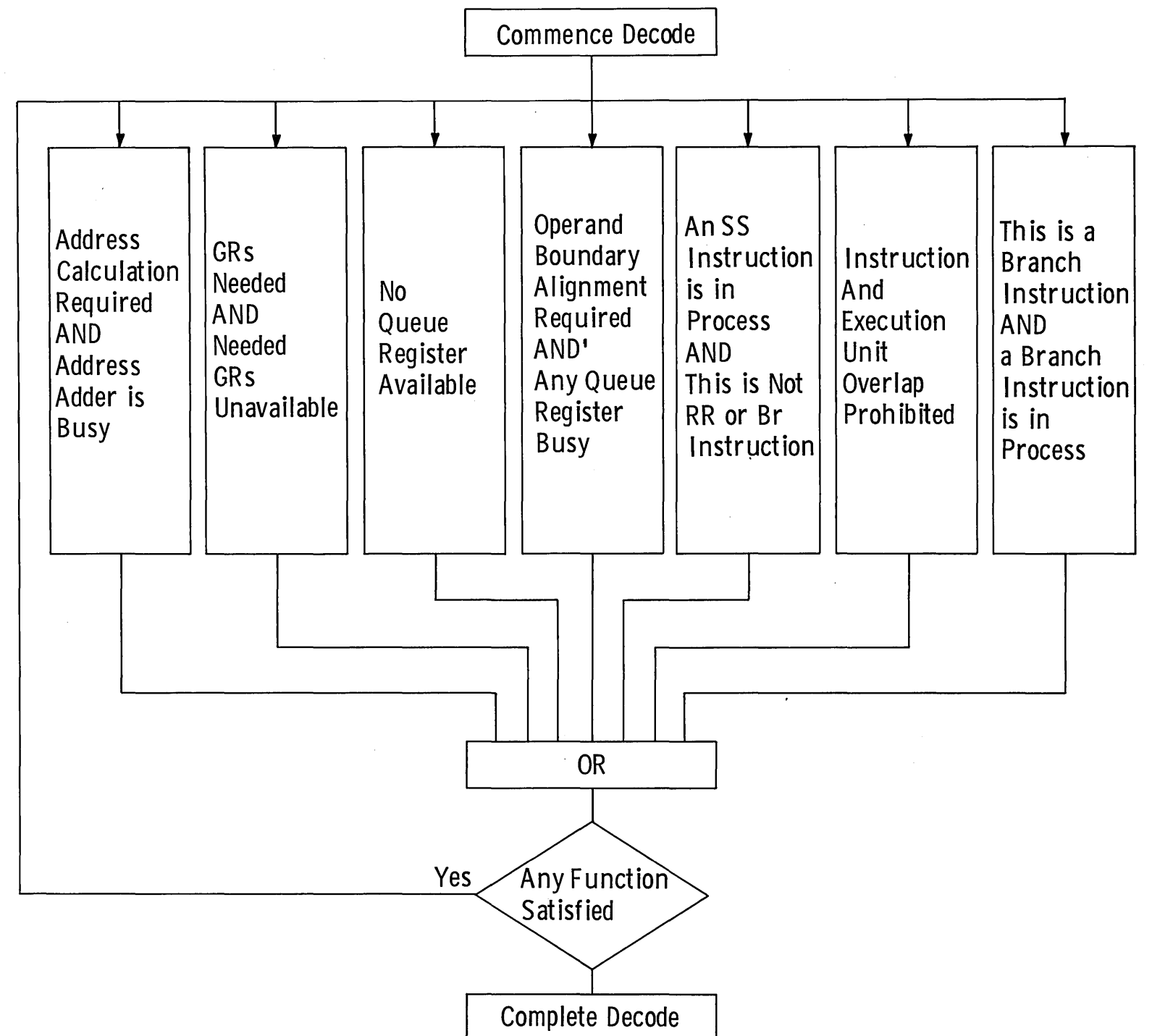


Figure 5-12 Instruction Register

Figure 5-13 Instruction Decode

ADDRESS ADDER

Instructions that reference main storage for operands or that require address-type operands (shift and I/O instructions) must have addresses or shift amounts calculated for them using information supplied by the X, B, and D fields of the instruction format. These calculations are performed by the I-unit address adder prior to E-unit execution using base address (B), index (X), and displacement (D) components specified by the instruction.

To briefly review System/360 Principles of Operation on these address components they are defined as follows:

1. The base address is a 24-bit number in a GPR specified by the B-field.
2. The index is a 24-bit number in a GPR specified by the X-field.
3. The displacement is a 12-bit number in the instruction format.

In forming the address, the base address and index are treated as unsigned 24-bit positive binary integers (whole numbers). The displacement is treated as a 12-bit positive integer. The three are added as 24-bit binary numbers, ignoring overflow. Because every address includes a base, the sum is always 24-bits long. The address bits are numbered 8-31 corresponding to the numbering of the base address and index bits in the GPR. The instruction may have zeros in the base address, index, or displacement fields. A zero means that there is no corresponding address component. A base or index of zero implies that a zero quantity is to be used in forming the address, regardless of the contents of GPR0.

Because the 24-bit (plus 3 parity bits) address adder performs the additions involved in these address calculations, it has three input registers: DA, BA, and XA. Up to three address components (displacement, base address, and index) can be added and checked in one machine cycle.

The principal inputs to the adder input registers are two local storage buses (GPR X data bus and GPR B data bus) and the D-latches (which receives its input from the instruction register) During the instruction decode cycle, the required GPRs are read from local storage, and the D-field is set up. When the decode cycle is successful, the quantities are ingated to the adder input registers and then added in the next cycle.

When an instruction requires a store request, the result of the address calculation is put into the destination address register (dst). If dst is busy, the contents of the adder input registers are held until the destination register becomes not busy.

When an instruction requires a fetch request, the result of the address calculations is sent to the source address register (src) and a request is made during the same cycle in which the address is calculated. If src or both the operand buffers are busy, the contents of the adder input registers are held. The address components are retained in the XA, BA, and DA registers and re-added each cycle until the busy condition is cleared.

For shift and I/O instructions, the calculated address-type operand is put into the shift or I/O register. As in other instructions, the contents of the adder input registers are held until the receiving register is available.

INSTRUCTION QUEUE REGISTERS

The three instruction queue (IQ) registers allow up to three instructions to be preprocessed in the I-unit ahead of actual E-unit execution. The instructions are stacked in the IQ-registers until needed by the E-unit. Each IQ-register consists of two sections. Refer to the system data flow in Volume 1 of the FEMDM. Note that bits 0-15, which are timed as latches, hold the first two bytes of the instruction. Bits 17-23, which are timed as triggers, hold the initial values for the A-counter adder latches (ACAL) and B-counter adder latches (BCAL). (Note that there is no bit 16 in the queues.)

The IQ-registers are ingated and outgated in a 1, 2, 3, 1... cycle sequence. Two pointers are provided: The inpointer indicates which IQ-register is next to be loaded from the I-register, and the outpointer indicates which IQ-register contains the next instruction to be sent to the E-unit for execution. These pointers are not shown on the data flow.

Instruction Queue Pointers

Two three-bit pointers are associated with the instruction queues: an inpointer that indicates which queue is next to be loaded from the instruction register, and an outpointer that indicates which queue's contents are to be used next by the E-unit. This pointer is not shown on the data flow. The IQ-inpointer steps 1, 2, 3, 1 ... etc, and works with busy triggers associated with each queue. Every cycle the contents of the instruction register are gated to all nonbusy queues. When conditions are present to allow the instruction to be released from the instruction register, the queue pointed to by the INPOINTER is loaded, made busy, and the inpointer is stepped to point to the next queue.

The instruction sent to the E-unit for execution is always from the queue pointed to by the outpointer. At the same time, the queue whose contents were outgated is made not busy and the outpointer is stepped to point to the next queue. The outpointer steps 1, 2, 3, 1... just as the inpointer does.

These pointers ensure that the instructions are kept in sequence as they are transferred to the E-unit.

Shift or I/O Register

The address adder generates shift counts and I/O addresses as if a main storage address were being generated. When operands for shift and I/O instructions are being prefetched, the I-unit transfers the contents of address-adder latches to the "shift I/O" register. The address adder can then be reused without waiting for execution of the shift or I/O instruction. Because shifting is performed by the E-unit's shifter, the shift-count bit positions of the "shift or I/O" register are transferred to a six-bit shift latch to preserve trigger-latch timing relationship. This latch is shown under the shift or I/O register on the data flow. Its output goes to the shift control triggers, which are part of the shifter, located in the E-unit.

During the execution of I/O instructions, the shift or I/O register contents are gated to the channel-selection logic.

Difference Registers

Two difference registers, each associated with an instruction address register, permit calculations of the true instruction count (IC) when needed. Because the I-unit prefetches instructions up to two doublewords ahead of the instruction being executed, neither instruction address register contains the actual instruction counter value of the instruction in the E-unit. Two registers (difference registers A and B) contain in two's complement form the difference between the instruction counter (IC) value and the corresponding instruction address register. The IC value can be obtained when needed by adding the active IAR and its corresponding difference register.

The difference register (A when using IAR A) keeps track of how far ahead I-unit instruction processing is with respect to the E-unit. An incrementer associated with each difference register can increment or decrement the contents of the difference register or can do both. When an instruction address register is set to a new value, the four low-order bits are transferred to the four low-order bits of the difference register; the remaining two bits of the difference register are reset to zeros. As instruction processing progresses, the contents of the difference register are changed such that at any point the sum of the instruction address and the difference equals the current IC. To keep the difference register value correct, the difference register is decremented by 8 each time the I-unit increments the instruction address by 8.

Address incrementer bits 29-31 are always transferred to difference register A after the E-unit or the I-unit calculates the IC transfer into instruction address register B because the I-unit always restarts with IARA active after an operation that requires IC to be calculated.

Figure 5-17 Shift or I/O Register

Figure 5-18 Difference Register

Address Incrementer

The 24-bit address incrementer can increment or decrement the contents of the four address registers and can be used as a path between the I-unit and the E-unit. The I-unit uses the incrementer for:

1. Adding 8 to the appropriate instruction address register A or B, when updating to the address of the next doubleword of instructions.
2. Calculating the instruction-counter (IC) value from the appropriate instruction address and difference register and transferring the result to instruction address register A. This calculation is part of the program store compare recovery operation.

The E-unit also has access, and can use, the incrementer.

1. The E-unit uses the incrementer to add or subtract from the contents of the source register and destination registers.
2. Transfer main storage addresses from the shifter in-bus to the appropriate address register. The transferred address is neither shifted nor incremented.
3. Transfer the contents of an address register or the value of the IC to the maintenance controls address register.

Note: If a conflict exists between the I-unit and the E-unit for usage of the incrementer, the I-unit waits.

		ADR	K	MK	ID	ST	ARRAY	ADR	VD	
CH	XX	XX	XX	0X	XX	XX	0	XX	XX	
STAR	XX	XX	XX		0X	XX	1	XX	XX	
FAR	XX	XX	XX			XX	2	XX	XX	
REDO	XX	XX	XX			XX	3	XX	XX	
							B RPL	XX	XX	XX
							D BAR	XX	XX	XX
							BAR	XX	XX	XX

		1	2	3	4	5	6	7	8	9	A	B	C	D	E	F						
IB A	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX						
IB M	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX	XX						
CH I	XX	XX	XX	XX	XX	XX	XX	XX	XX									L2	XX			
CH O	XX	XX	XX	XX	XX	XX	XX	XX	XX	I REG	XX	XX	XX	XX				SH	XX	XX		
SDBO	XX	XX	XX	XX	XX	XX	XX	XX	XX	IQ 1	XX	XX	XX					DSPM	0X	XX		
										IQ 2	XX	XX	XX					BASE	XX	XX	XX	
OP 1	XX	XX	XX	XX	XX	XX	XX	XX	XX	IQ 3	XX	XX	XX					INDX	XX	XX	XX	
OP 2	XX	XX	XX	XX	XX	XX	XX	XX	XX													
A	XX	XX	XX	XX	XX	XX	XX	XX	XX										SRC	XX	XX	XX
B	XX	XX	XX	XX	XX	XX	XX	XX	XX										DST	XX	XX	XX
C	XX	XX	XX	XX	XX	XX	XX	XX	XX	DIF A	XX								IAR A	XX	XX	XX
D	XX	XX	XX	XX	XX	XX	XX	XX	XX	DIF B	XX								IAR B	XX	XX	XX
E	XX	XX																				
F	XX	XX	XX	XX	XX	XX	XX	XX	XX													

CSAR	0X	XX		
CSARA	0X	XX		0X
CSARB	0X	XX		0X

MCRR	XX	XX	XX	XX	XX	XX	XX	XX	XX	IC	XX	XX	XX	XX	MCER	XX			
MCDR	XX	XX	XX	XX	XX	XX	XX	XX	XX	MCAR	XX	XX	XX	XX	MRAR	XX	XX	XX	XX

Figure 5-19 Address Incrementer

Figure 5-20 CRT Display

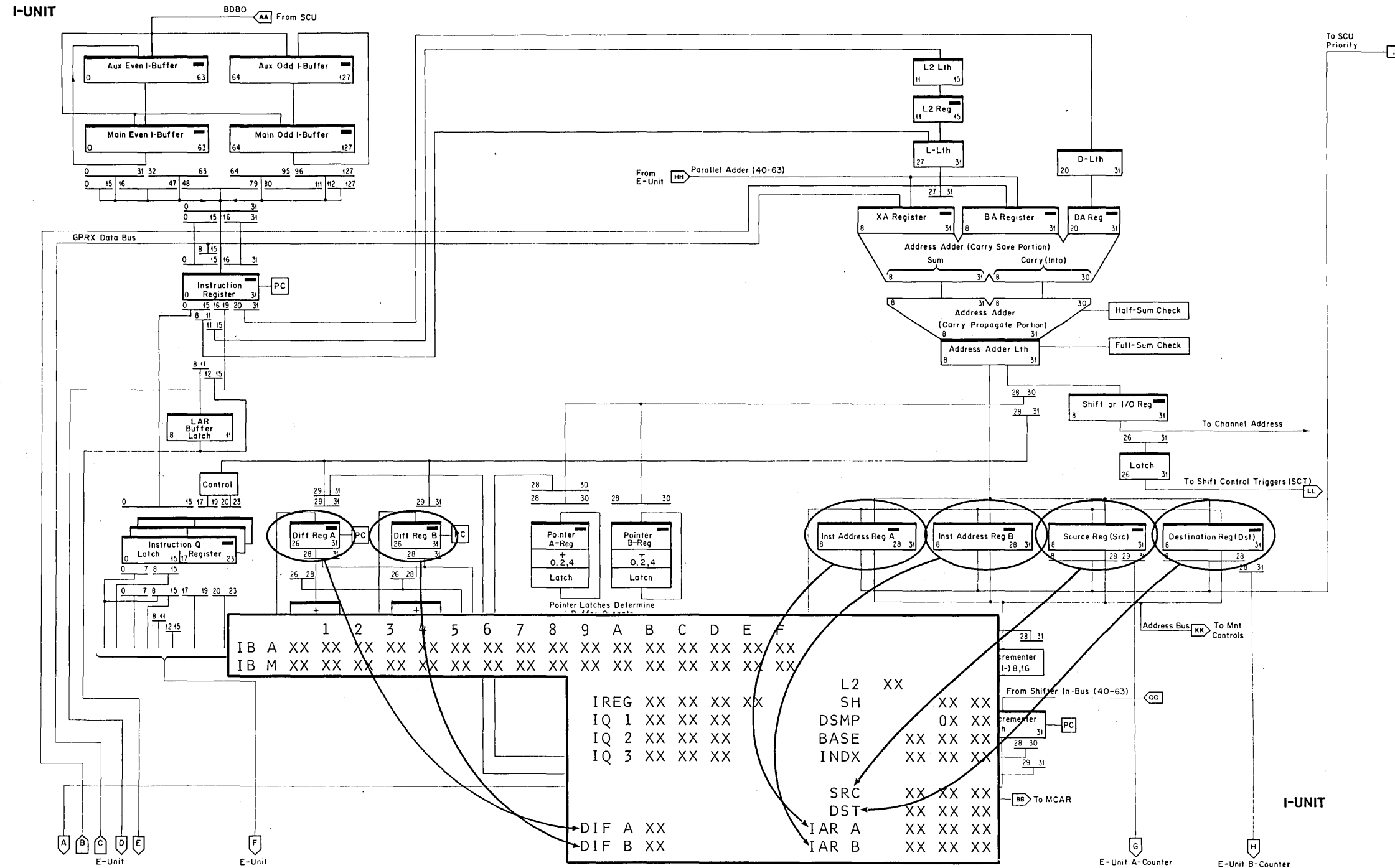


Figure 5-21 Difference Register Displays

Address Register Displays

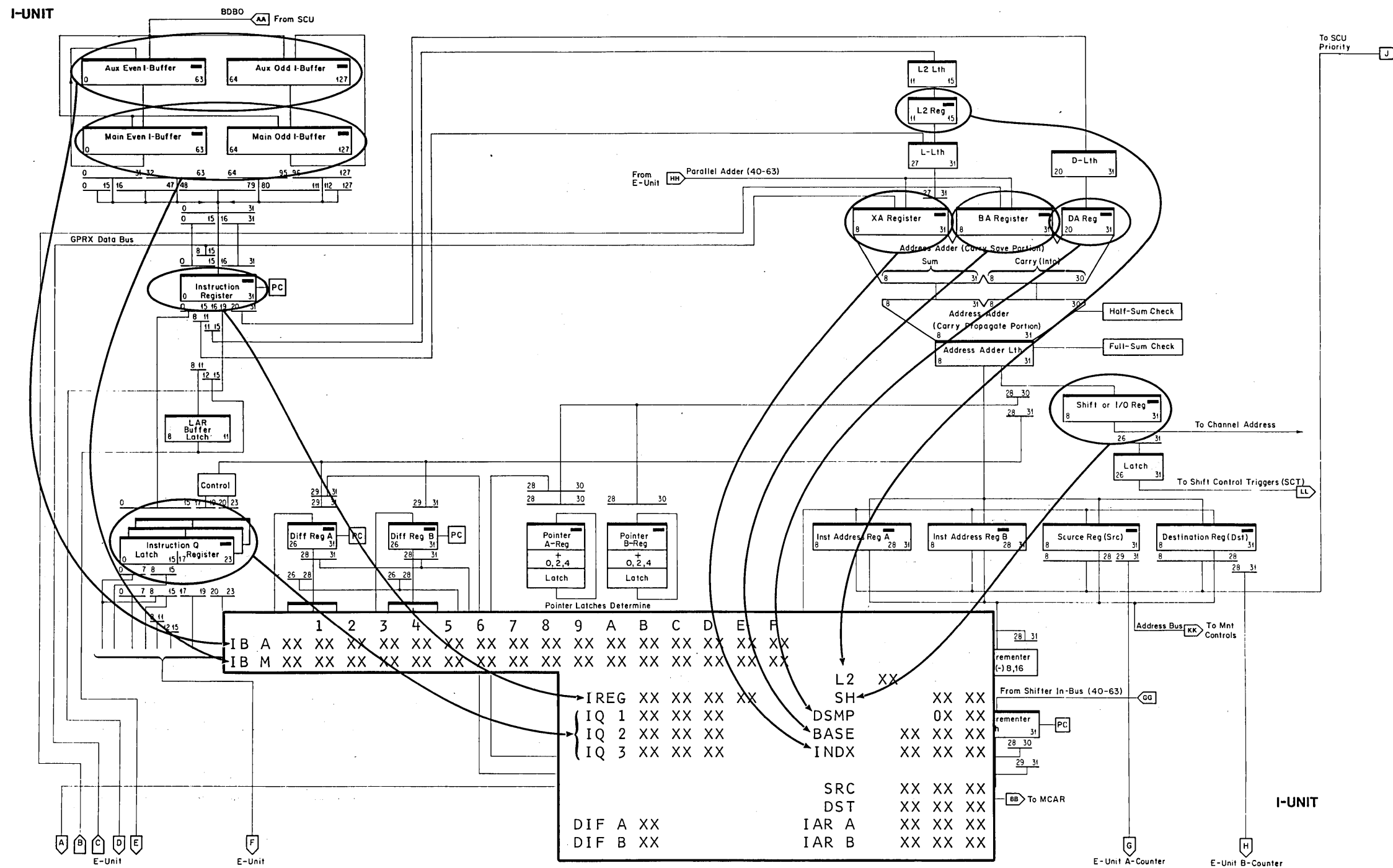


Figure 5-22 I-Buffer, I-Register, I-Q Display

Shifter Inputs and I/O Reg Display

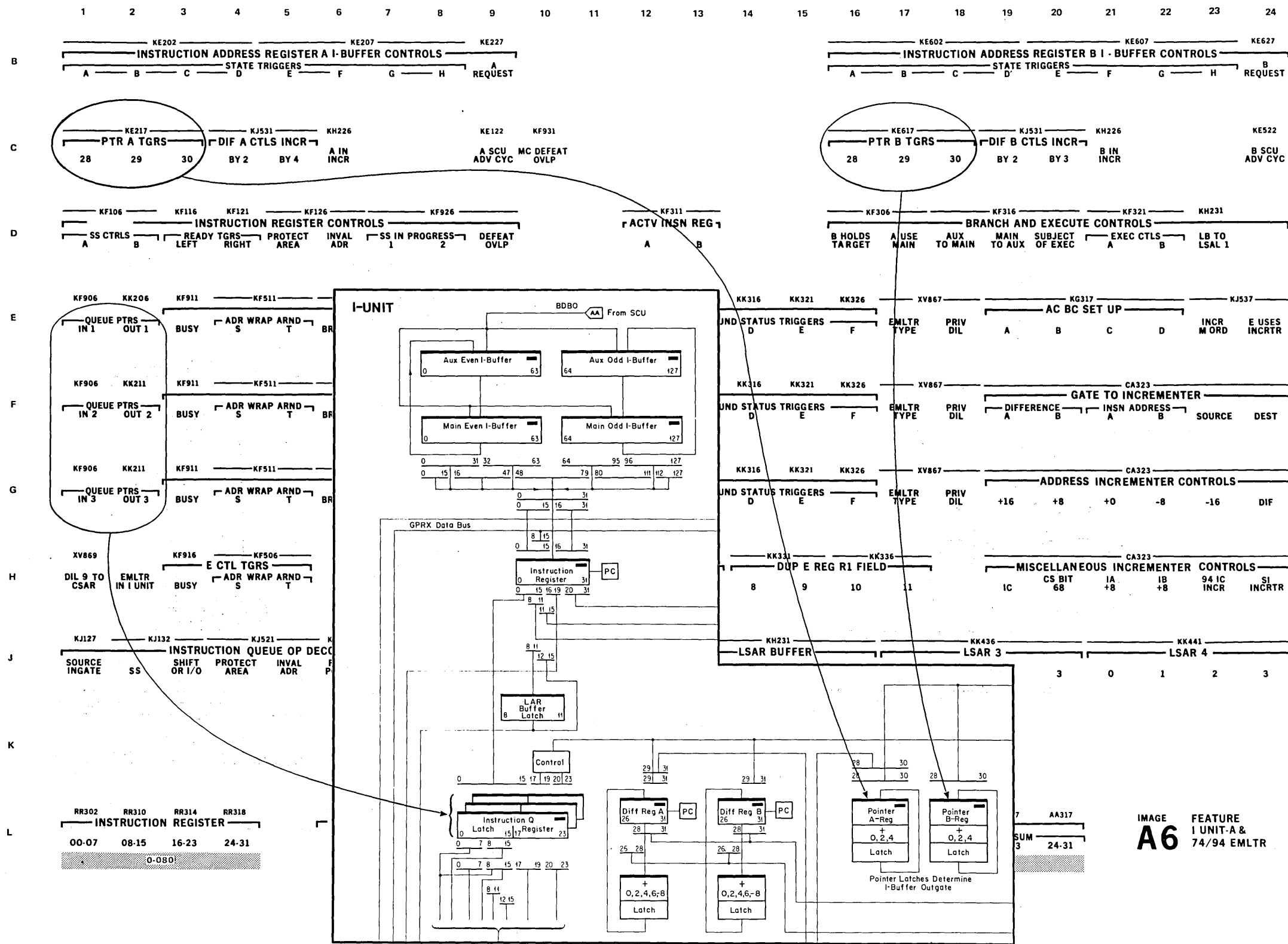


IMAGE FEATURE
A6 I UNIT-A &
 74/94 EMLTR

Figure 5-23 Pointer Displays

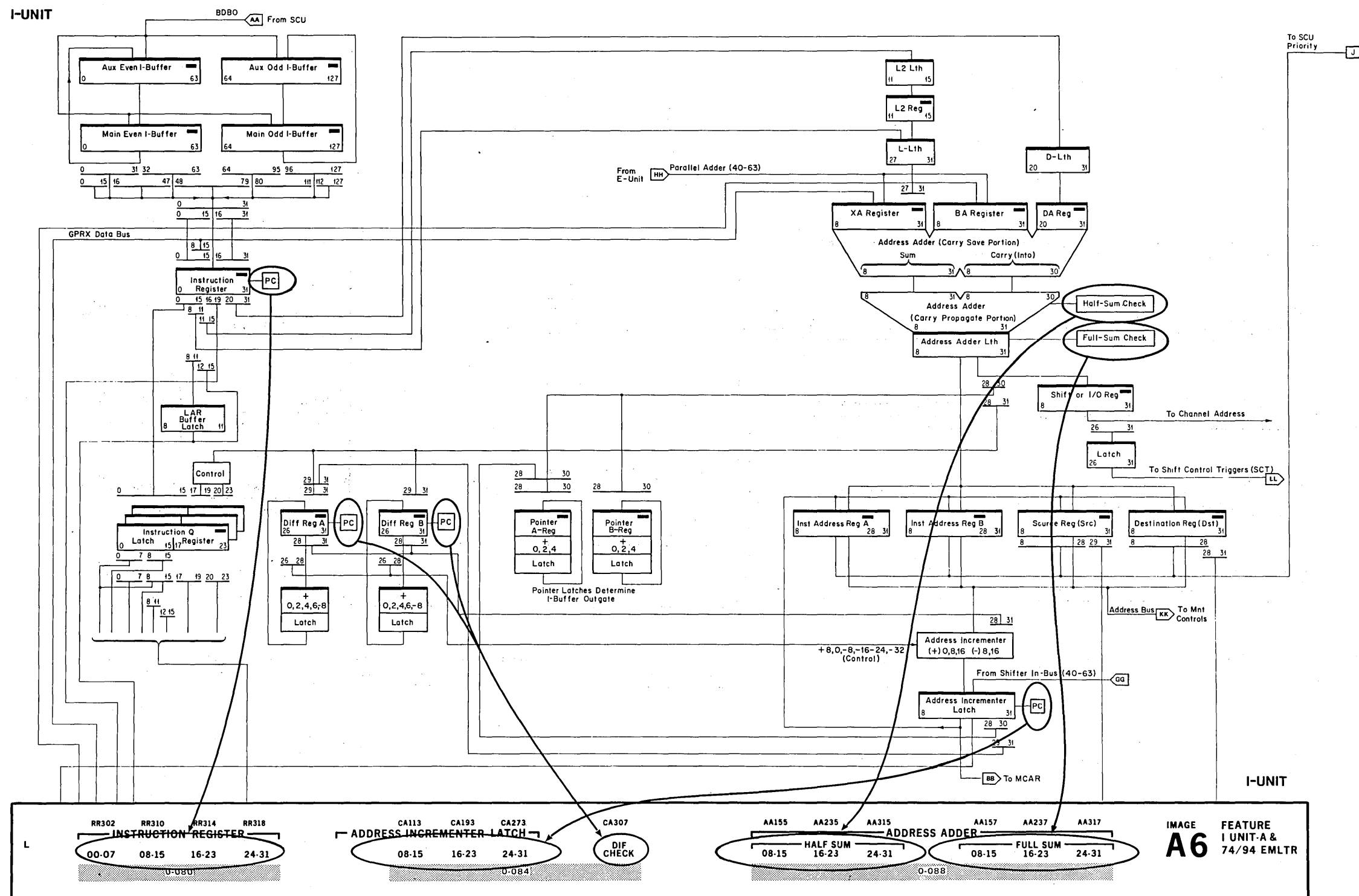


Figure 5-24 I-Unit Errors

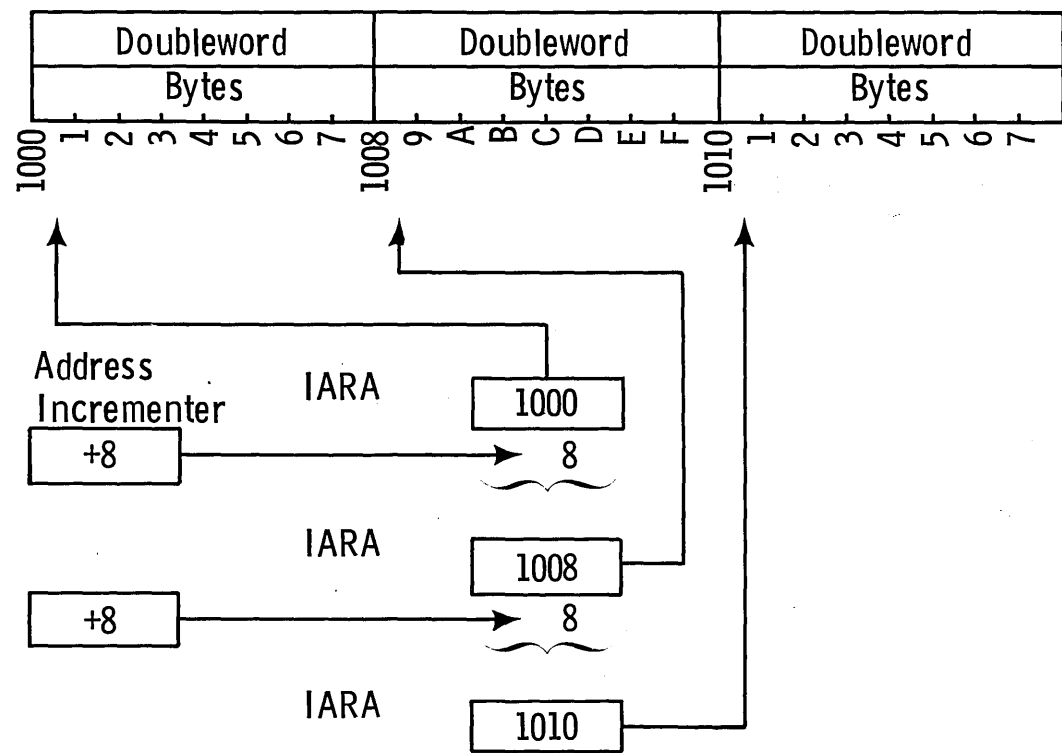


Figure 5-25. Address Update

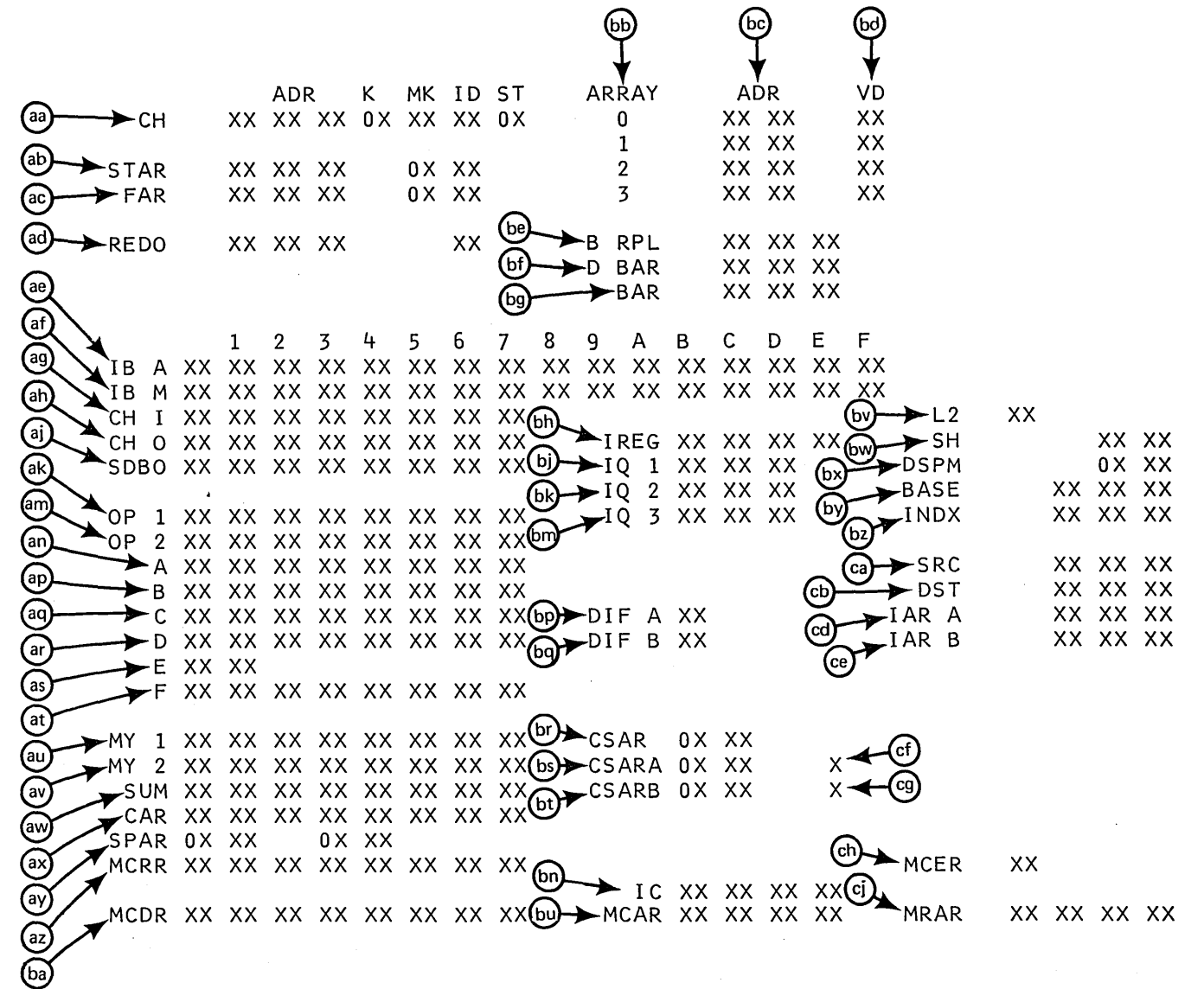


Figure 5-26. Questions 12-17 Remedial

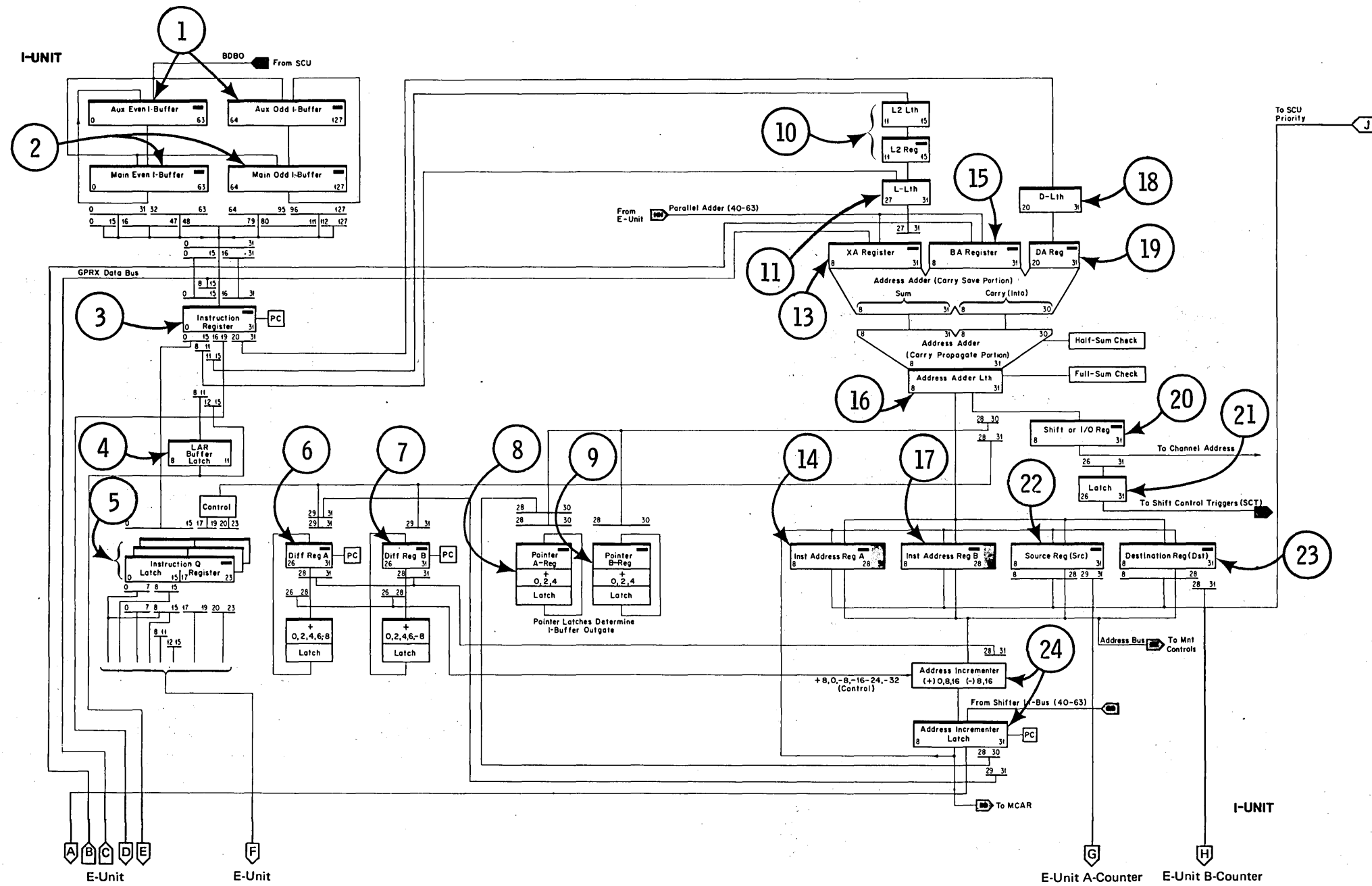


Figure 6-1. Session 6, Questions 10-15

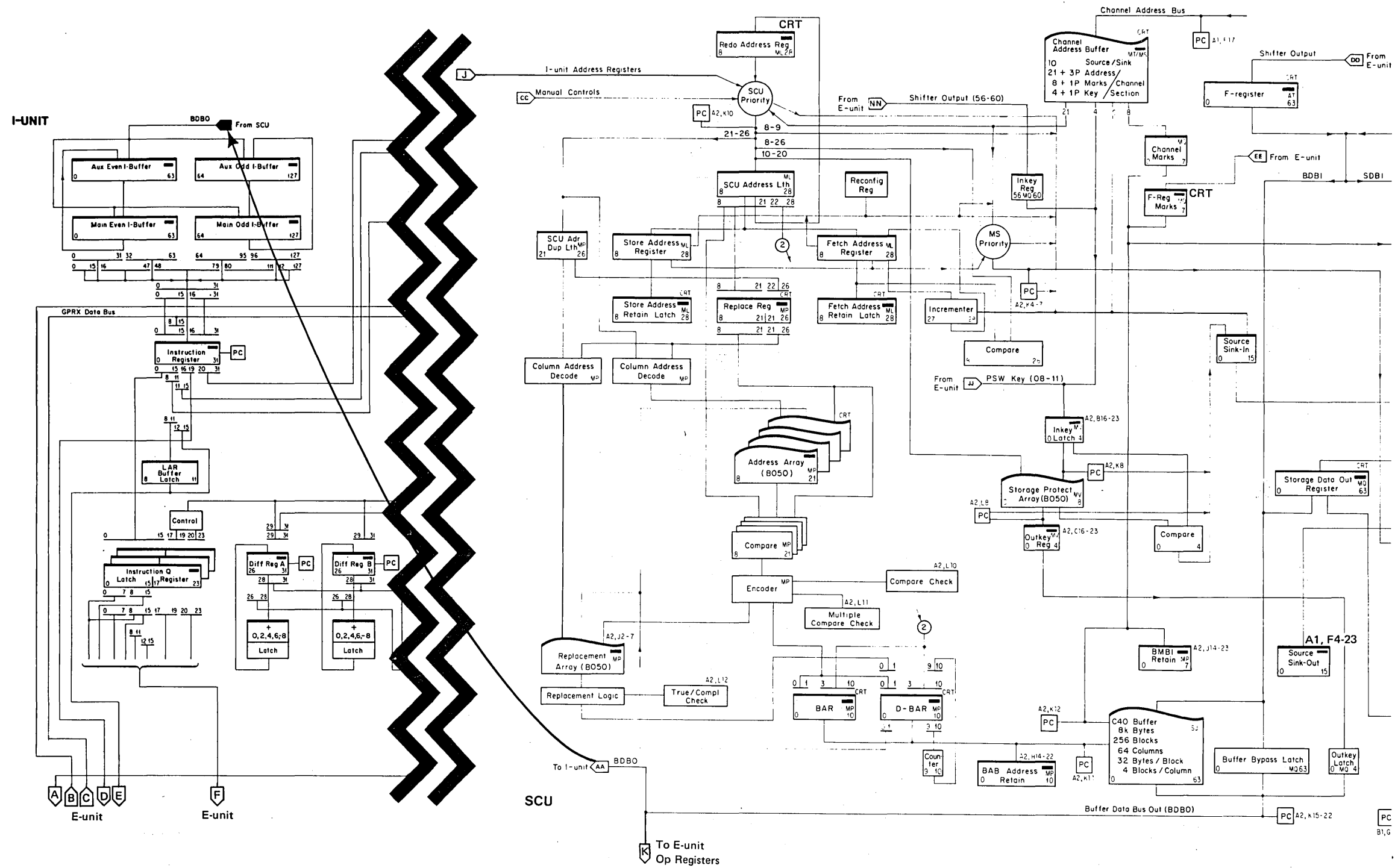


Figure 6-2. BDBO

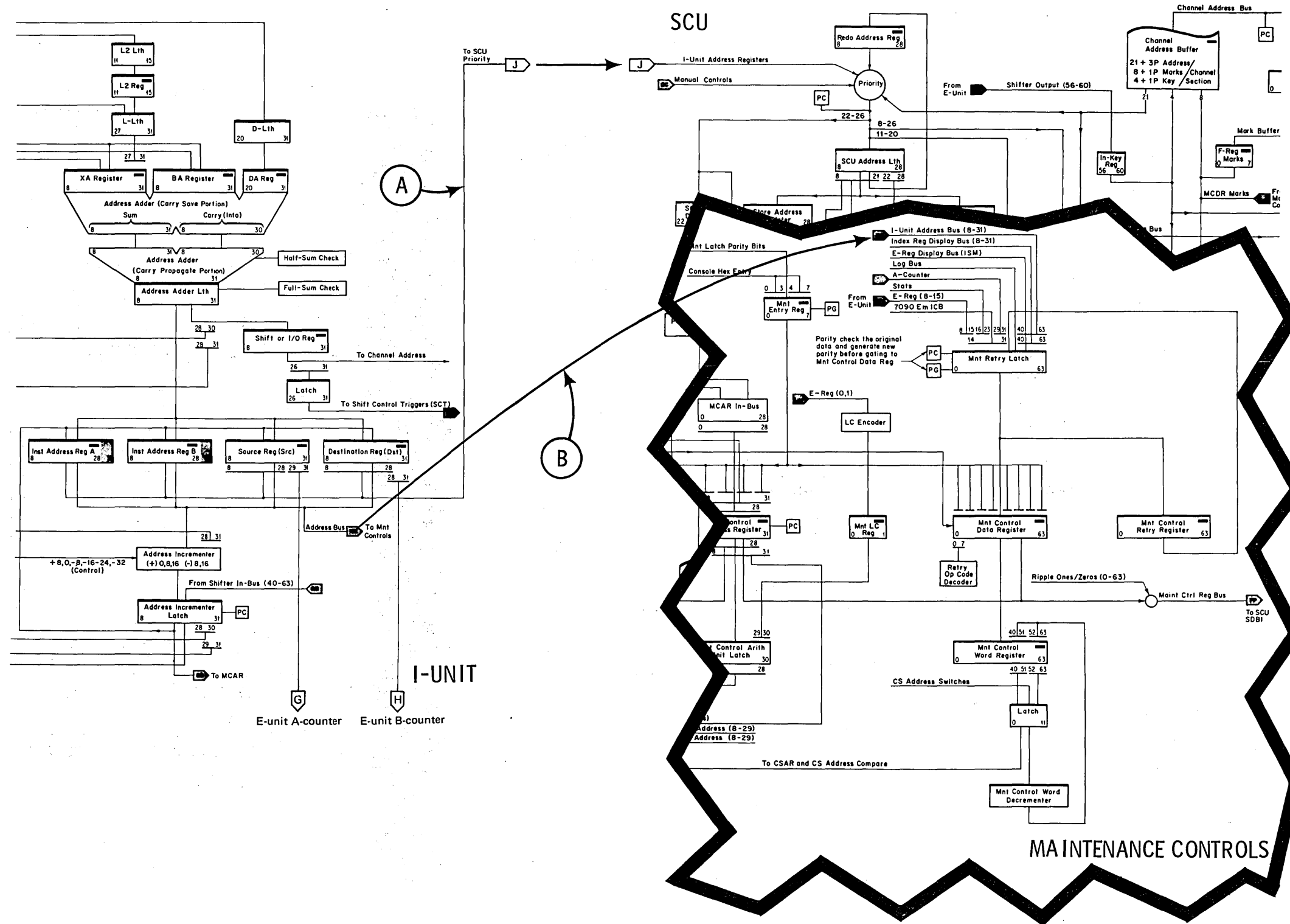


Figure 6-3. Address Register Bus

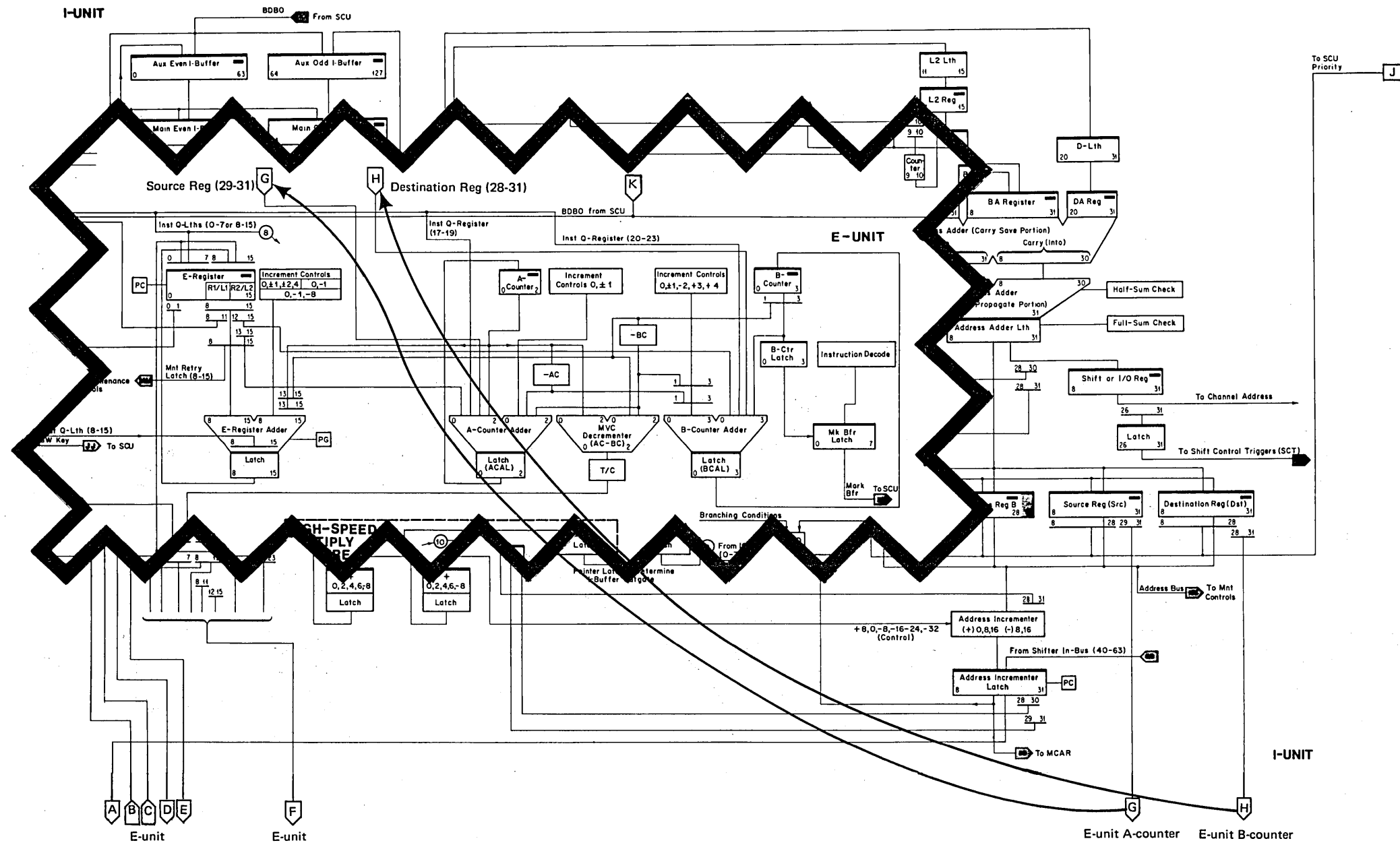


Figure 6-4. Address Register To E-Unit

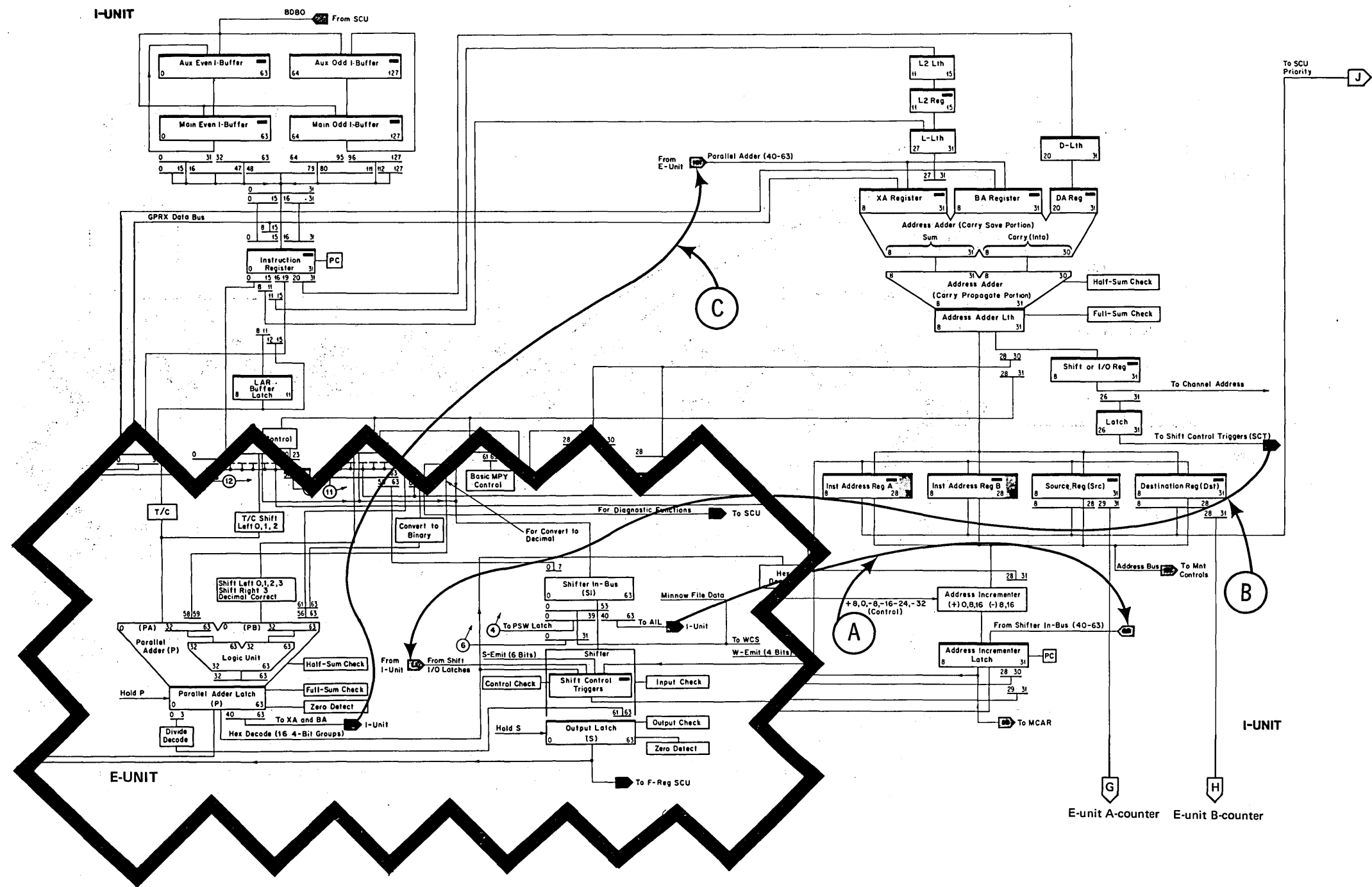


Figure 6-5. PAL, AIL, SCT

Because the I-unit preprocesses instructions, the need for a GPR in the I-unit can arise before that GPR is updated and available. For example, if the I-register contains an RX instruction, the address adder is not busy, the E-unit is executing an add instruction (RR) with an R1 field addressing GPR5, and the RX instruction X-field is also addressing GPR5, a GPR conflict condition exists. The RX instruction in this case must not be decoded until the needed GPR (5) has been changed by the E-unit. Otherwise, the wrong value will be obtained from GPR5. The needed delay is produced by blocking 'I is go'. The RX instruction remains in the I-register until the GPR is updated and a GPR conflict no longer exists.

When a GPR conflict delays the decoding of an instruction in the I-register, the total delay time can sometimes be reduced by one cycle by taking the address component from the parallel adder output during the GPR put-away cycle instead of waiting one more cycle for the information to be written in the GPR and read out again.

The normal sequence for the E-unit is to complete an execution, activate "end op," and then to write the result into the GPR for the specified R1 field on the following cycle. This sequence is not altered; but, by first detecting the GPR conflict and then waiting for "end op," the unavailable GPR contents will be available at the parallel adder during the "end op" cycle. Detection and obtaining the updated GPR contents from the parallel adder latch during the pre-fetching cycle is called address wraparound.

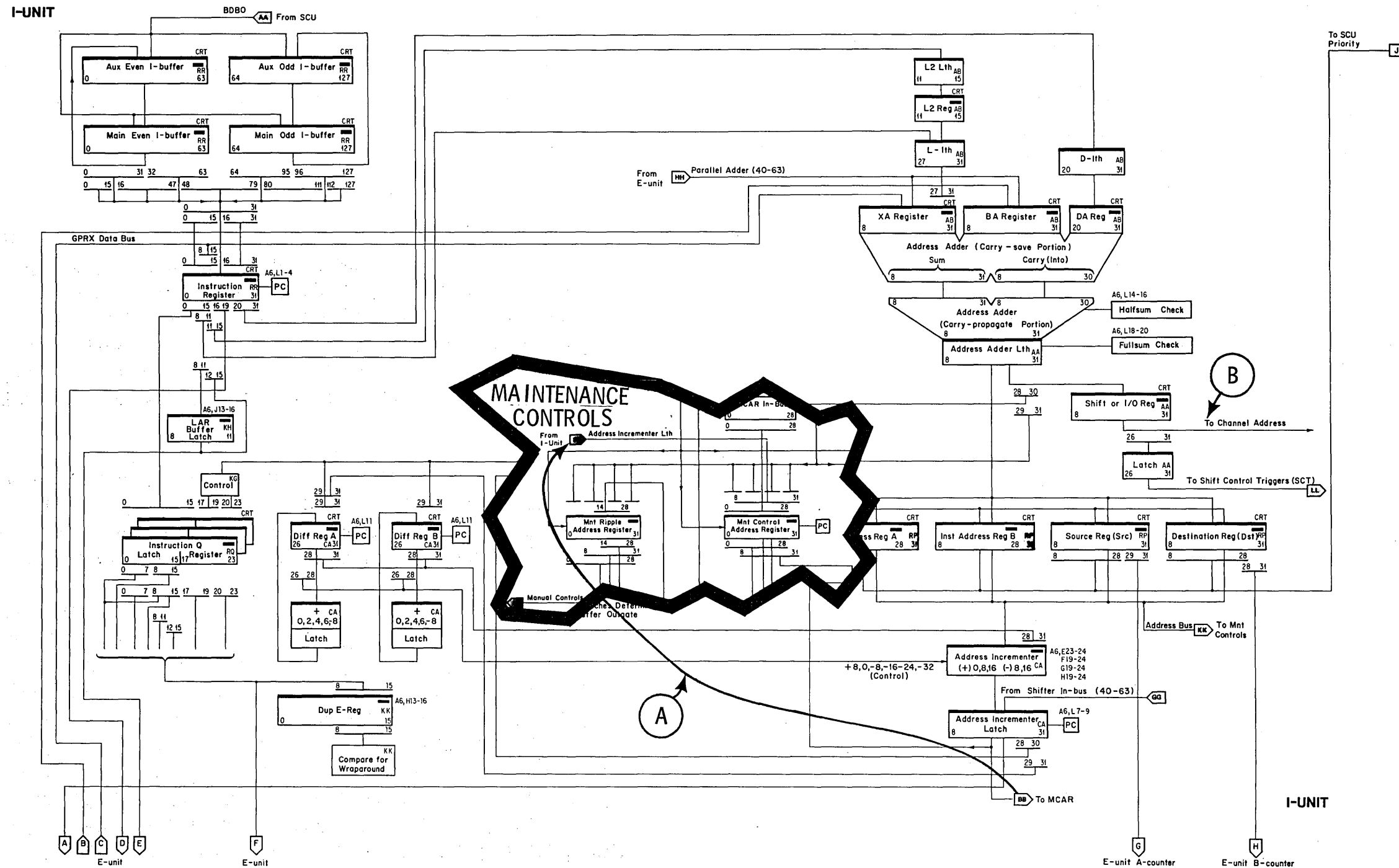


Figure 6-7. AIL To MCAR

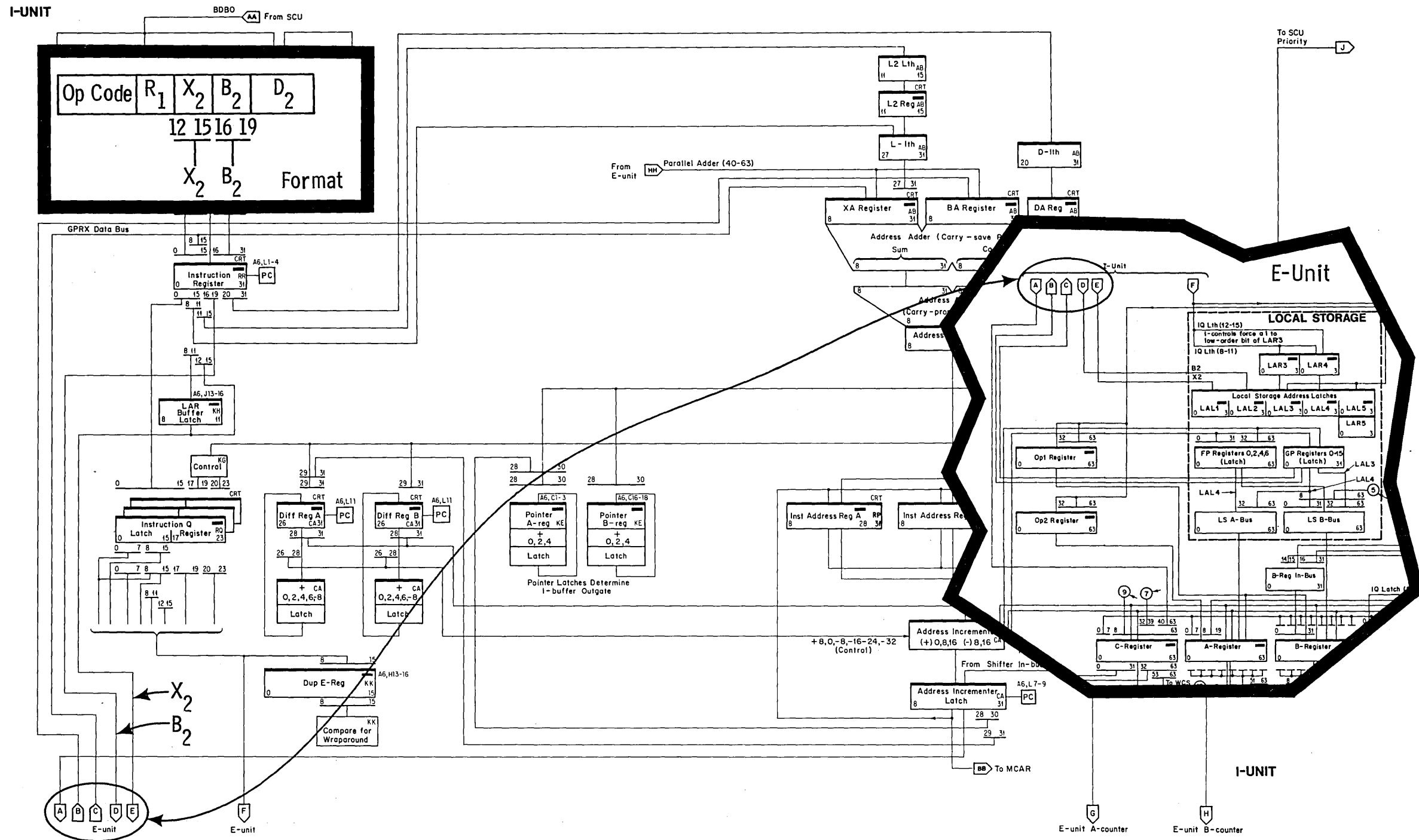


Figure 6-8. Local Store

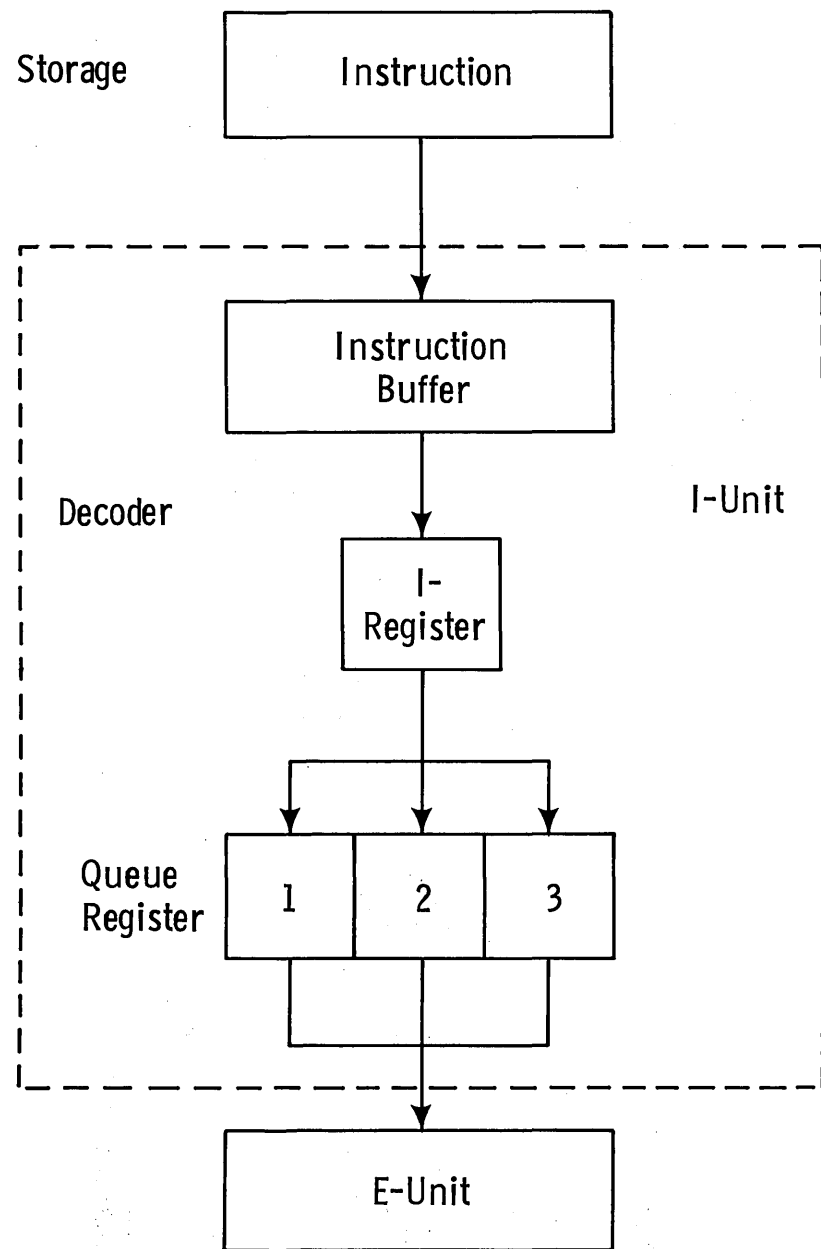


Figure 6-9. Simple I-Unit Data Flow

The 128-bit I-buffer temporarily stores instructions so that the I-register can have a supply of instructions to decode without having to wait for storage fetch operations. This is accomplished by fetching 16 bytes of instructions and gating them into the I-buffer. All requests are for doublewords (eight bytes) and the doubleword can be gated to either half, even or odd, of the I-buffer. An attempt is made to keep the I-buffer ahead of instruction processing. Therefore, when half of an I-buffer is emptied by having all of its contents moved to the I-register, a storage request for more instruction stream data is initiated. A pointer register, in addition to controlling the gating of instructions from the I-buffer to the I-register, also indicates when a buffer half is empty.

The instruction address register contains the storage address of the instruction stream being fetched. The instruction address register is updated by the address incrementer.

Figure 6-10. I-Fetch Review

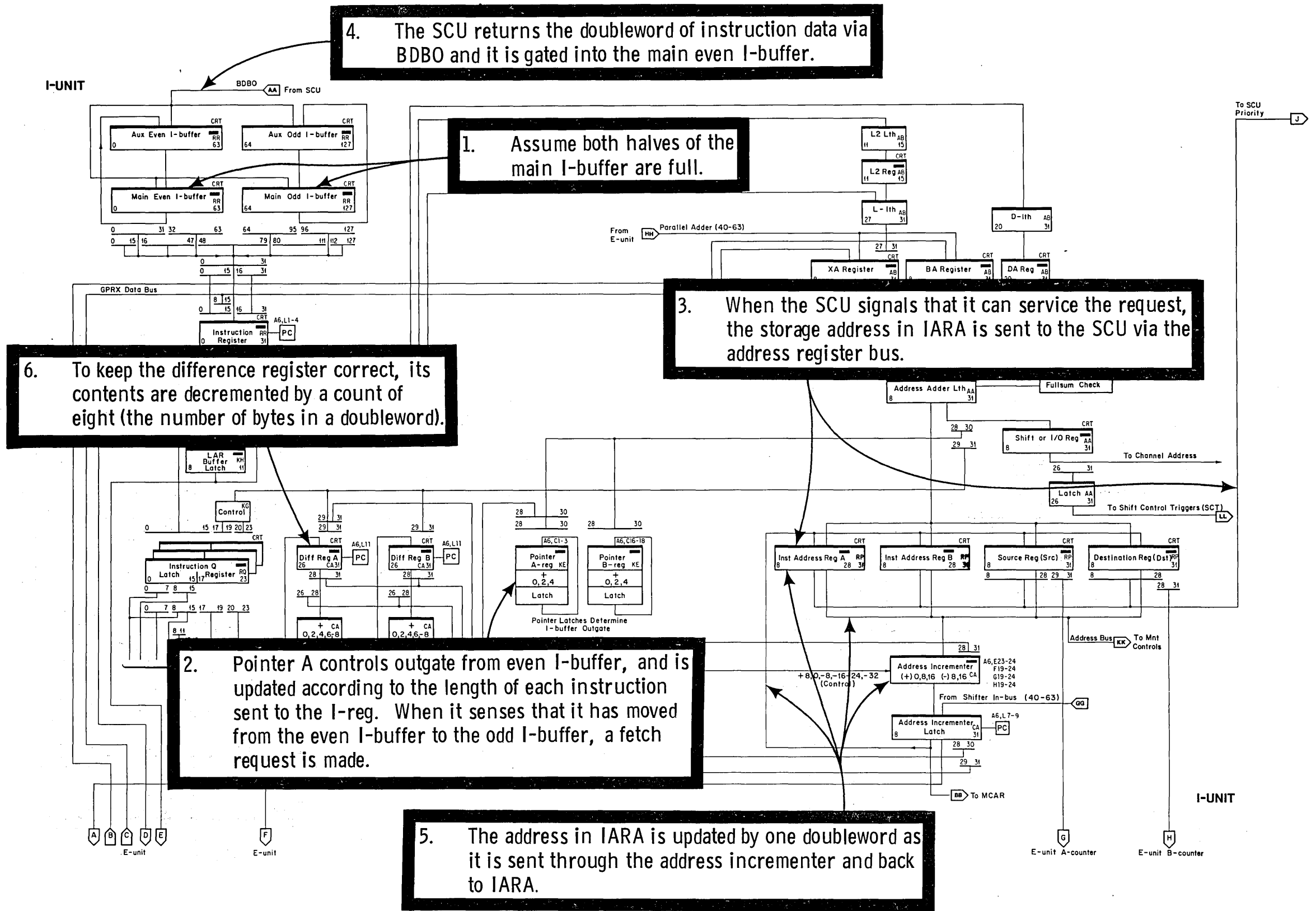


Figure 6-11. I-Fetch

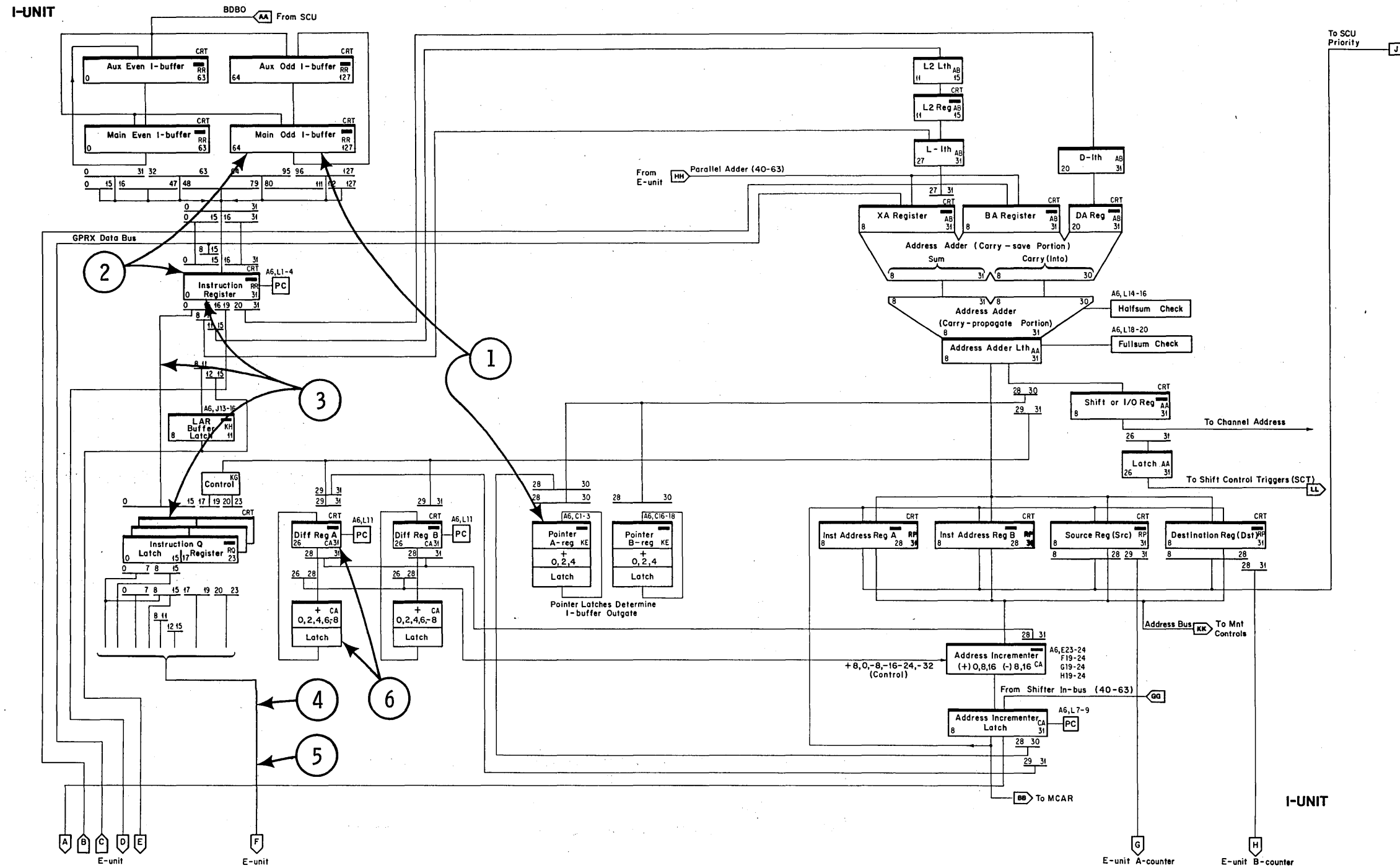


Figure 6-12. RR Add

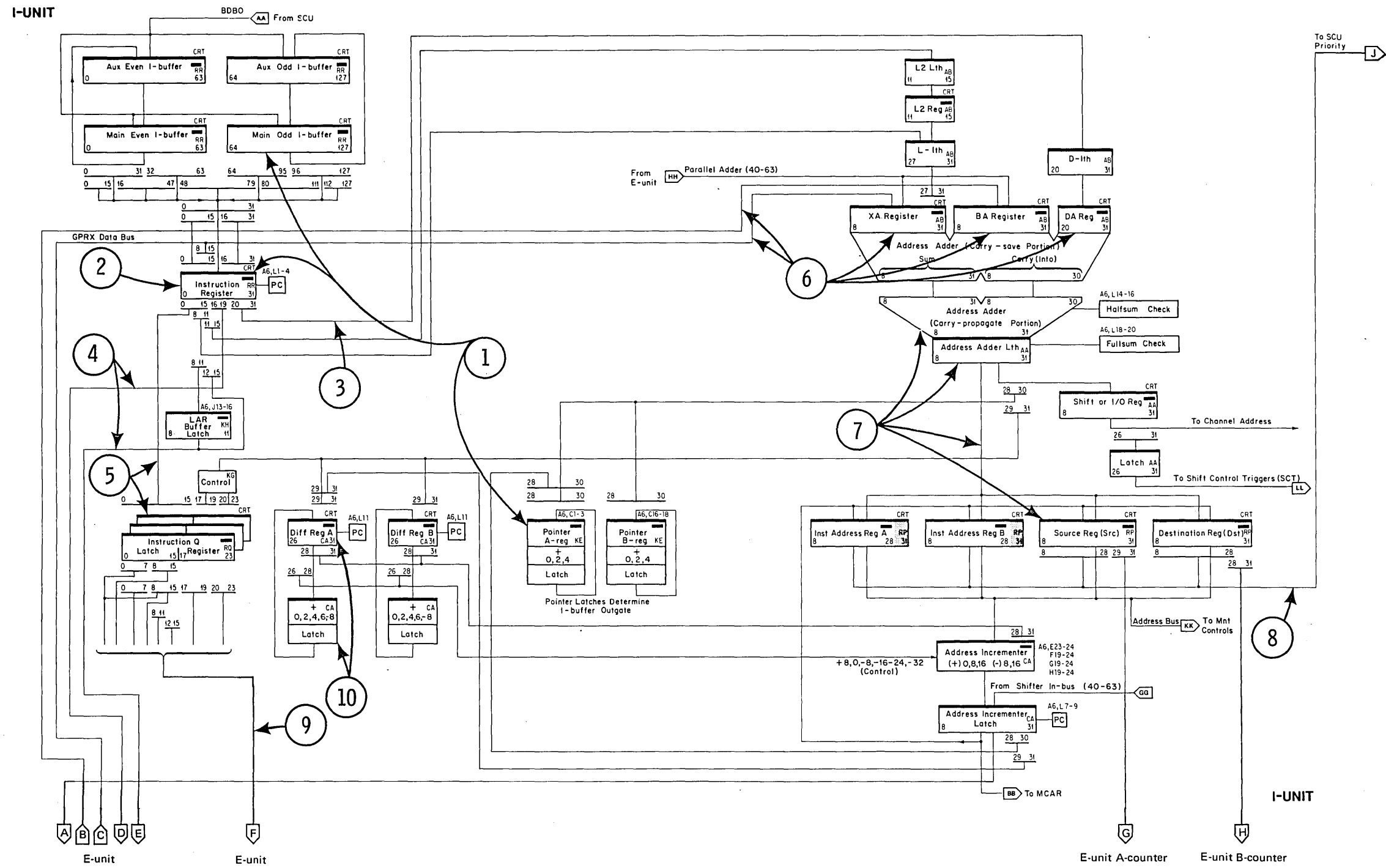


Figure 6-13. RX Add

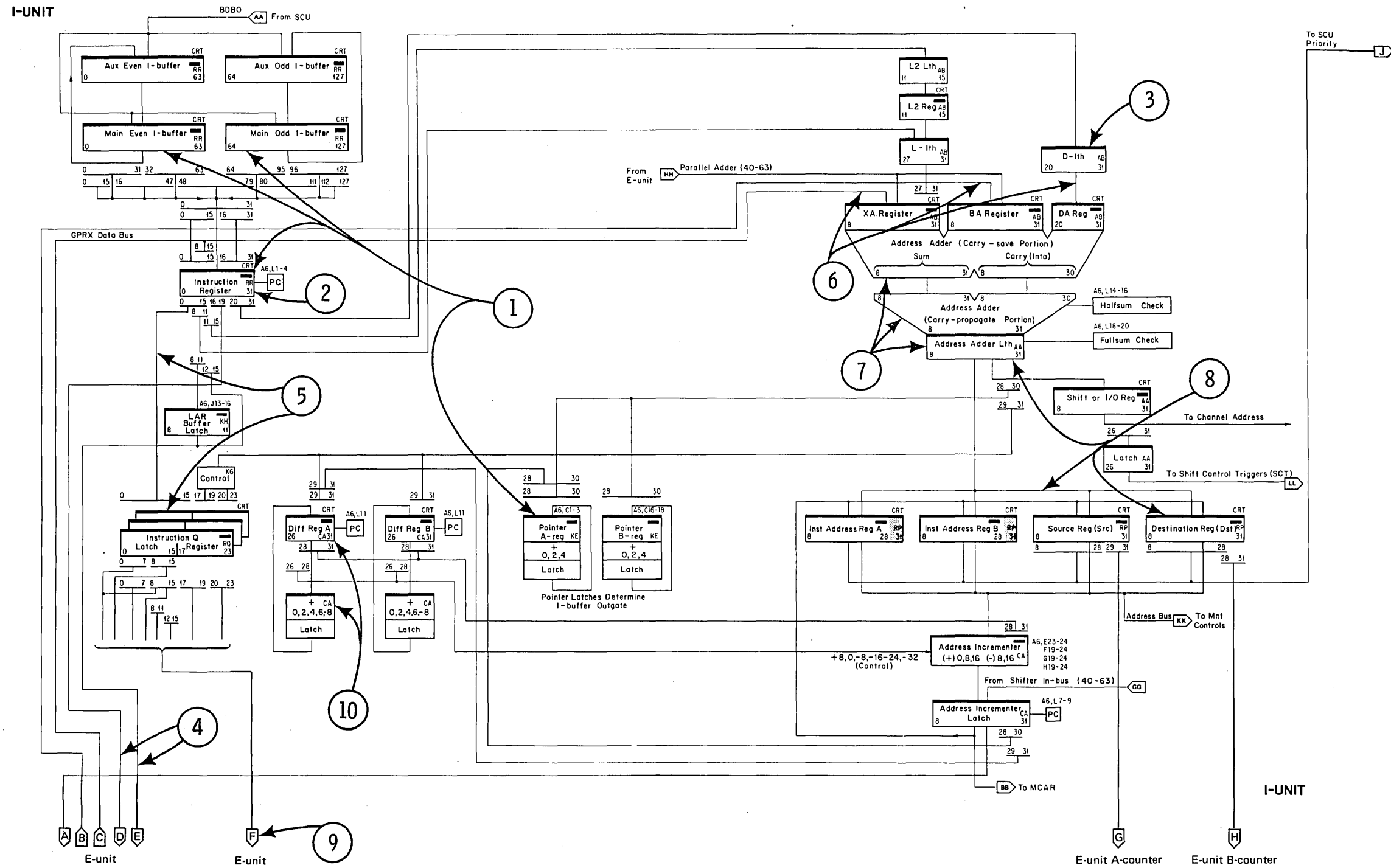


Figure 6-14. RX Store

Operand Store Compare

An operand store compare condition exists when a fetch instruction is decoded before a store instruction is completed. A store fetch sequence can cause a problem because of the way the I-unit processes fetch instructions and the way that the E-unit processes store instructions.

For example, if a fetch follows closely behind a store, it is possible for the fetch to be processed out of program sequence before the store. This can happen because the I-unit generates the address for a store but the E-unit initiates the request to SCU when the data is ready to be stored. While the E-unit is processing previously decoded instructions, the I-unit could decode a fetch instruction. Because the request to the SCU for a fetch instruction is made at the beginning of the address calculation cycle, the fetch request to the SCU could be processed before the store request. This does not cause any problem except when the fetch and store requests are made to the same main storage address. Then special action is needed.

Because this condition can exist, the source and destination registers are compared each time a fetch instruction is decoded before a store instruction is completed. If fetch address equals the store address, the fetch instruction is ignored until the store instruction has been completed. After the store is finished, a new request is made for the fetch.

The I-unit controls check for this condition and provide the control necessary to prevent a fetch instruction from receiving old information.

Figure 6-15. Operand Store Compare

PROGRAM STORE COMPARE

Because the I-unit preprocesses instructions, a store instruction could alter an instruction that the I-unit has already fetched. This situation could cause incorrect program execution. Therefore, to prevent the E-unit from receiving the wrong instruction, a test is made by the I-unit controls. The controls cause a compare circuit to compare the address in the destination register with the instruction address register (IARA). If the destination register equals IARA or IARA + 16 or IARA + 32, a program store compare condition is signaled.

A program store compare condition (PSC) causes all further processing of instructions to stop until the store instruction has finished. The I-unit is reset, the address of the instruction immediately following the store is calculated, and then instruction processing is restarted.

Figure 6-16. Program Store Compare

SS FORMAT INSTRUCTIONS

Multiple decode and address calculations cycles are needed. For decoding and address calculations, the I-unit handles an SS format instructions as two or three instructions with multiple decode cycles (three for logical and two for decimal) and multiple address calculation cycles. The I-unit generates both initial operand addresses and fetches a doubleword operand from each address. For logical instructions, base and displacement are added to produce an address that points to the leftmost byte of the field.

WORD OVERLAP TEST (WOT)

I-unit tests for word overlap condition for SS logical instruction. The I-unit also tests logical instructions to determine whether the E-unit is to use an alternate execution microprogram routine because of overlapping operand fields. An overlapped operand field exists when all or a portion of the first and second operands reside in the same address in main storage. For example, if an SS logical instruction specifies address 1005 for the first operand, a length field of five, and an address of 1009 for the second operand, there is an overlap of one byte in address 1009.

Figure 6-17. SS Instruction

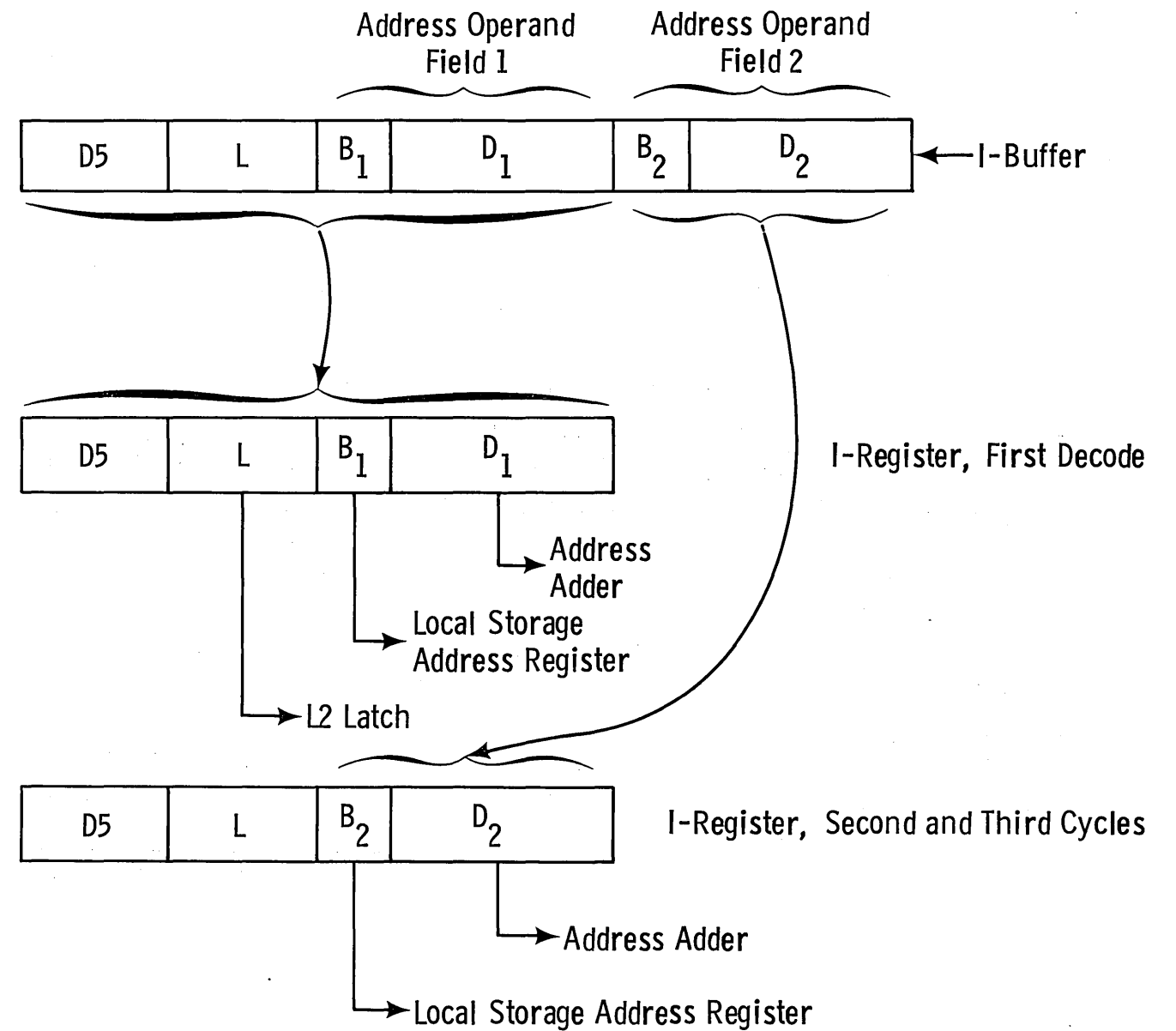


Figure 6-18. I-Register

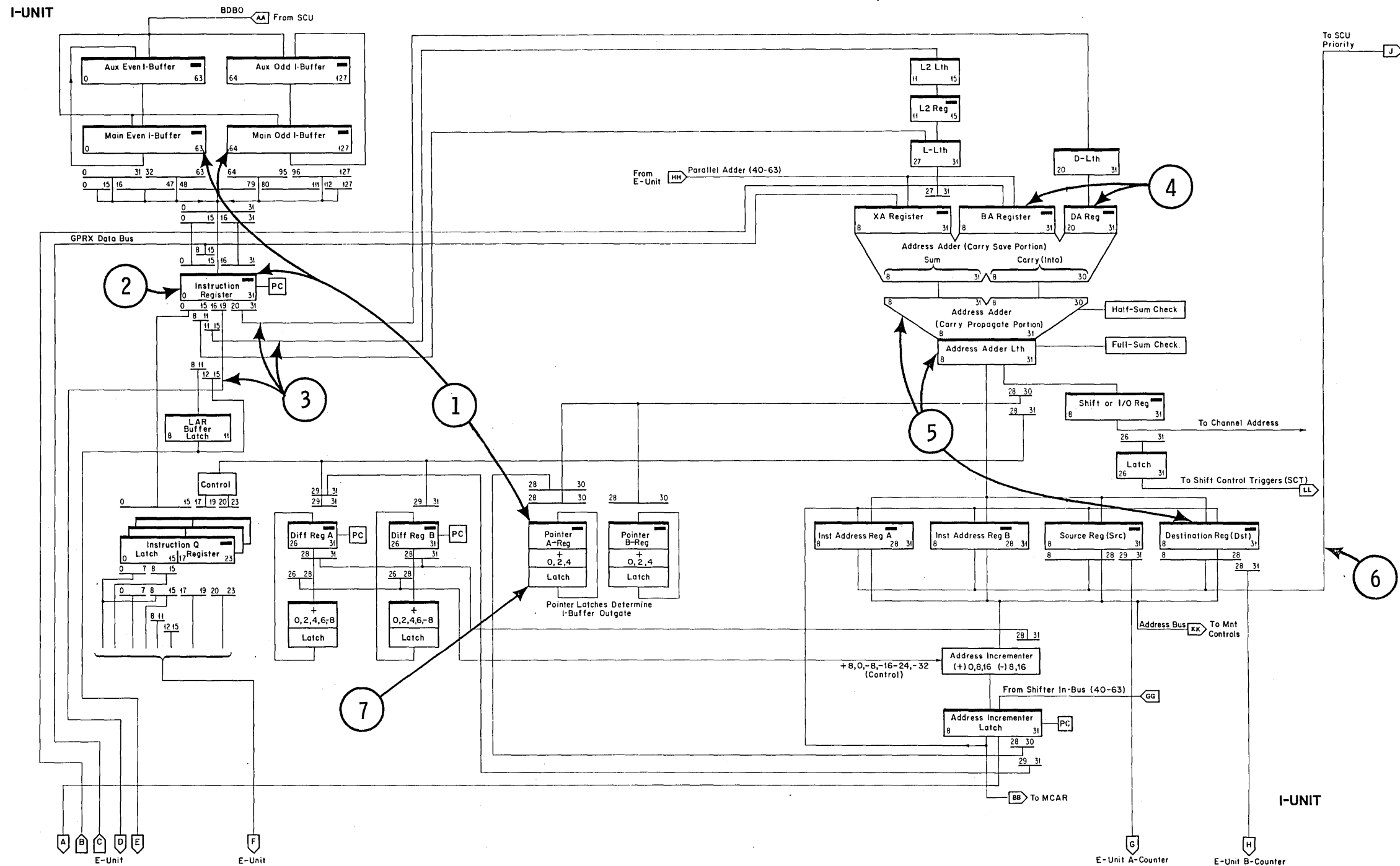


Figure 6-19. First Cycle, SS Instruction

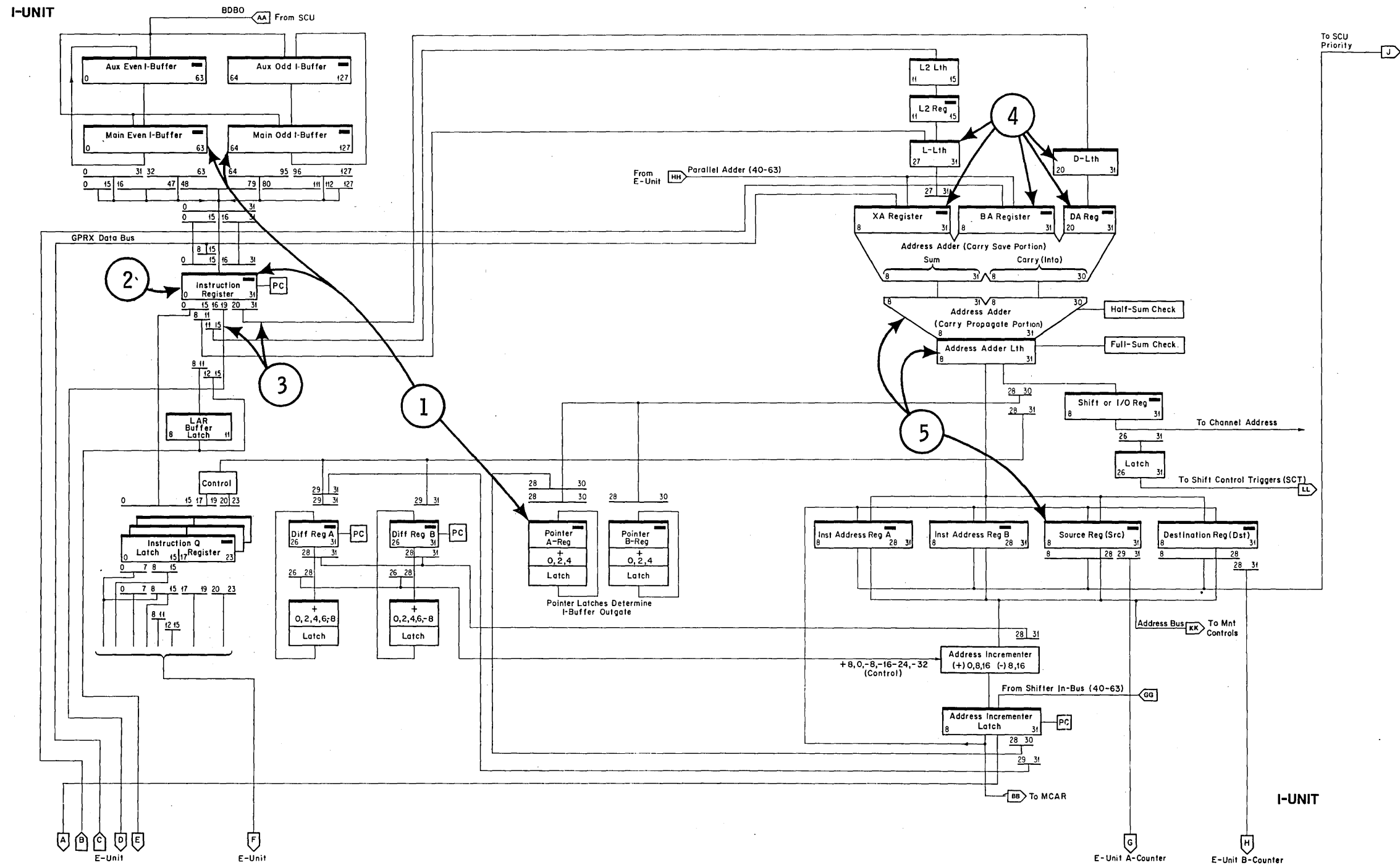


Figure 6-20. 2nd Cycle, SS Instruction

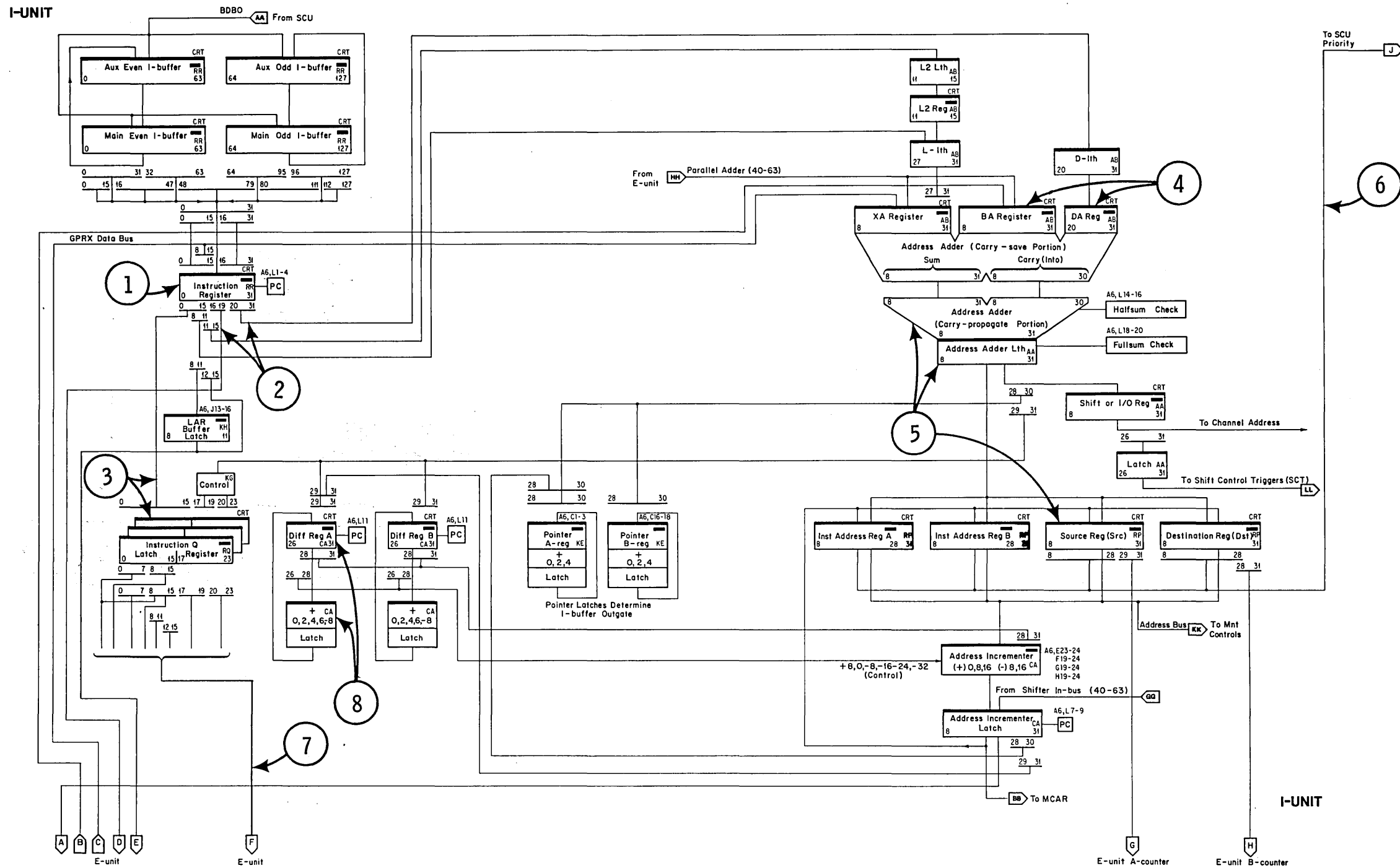


Figure 6-21. 3rd Cycle, SS Instruction

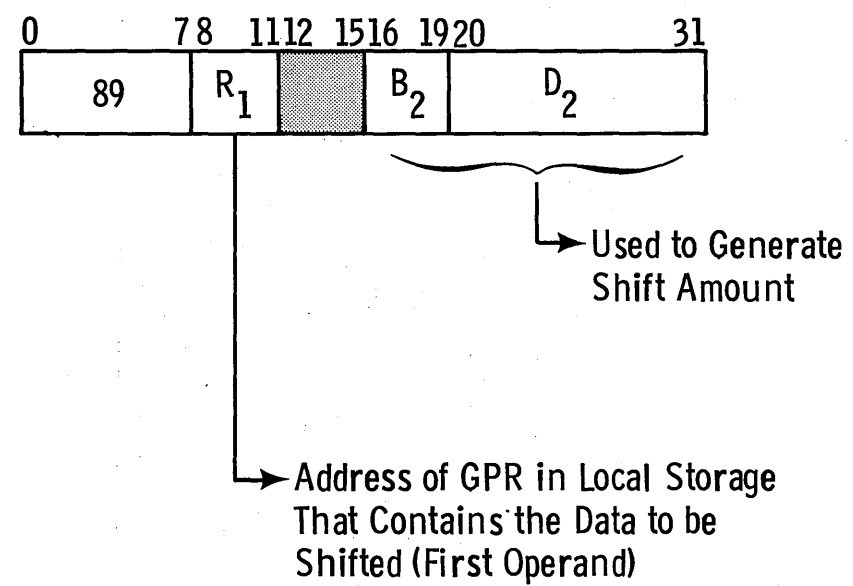


Figure 6-22. RS Shift Format (SLL)

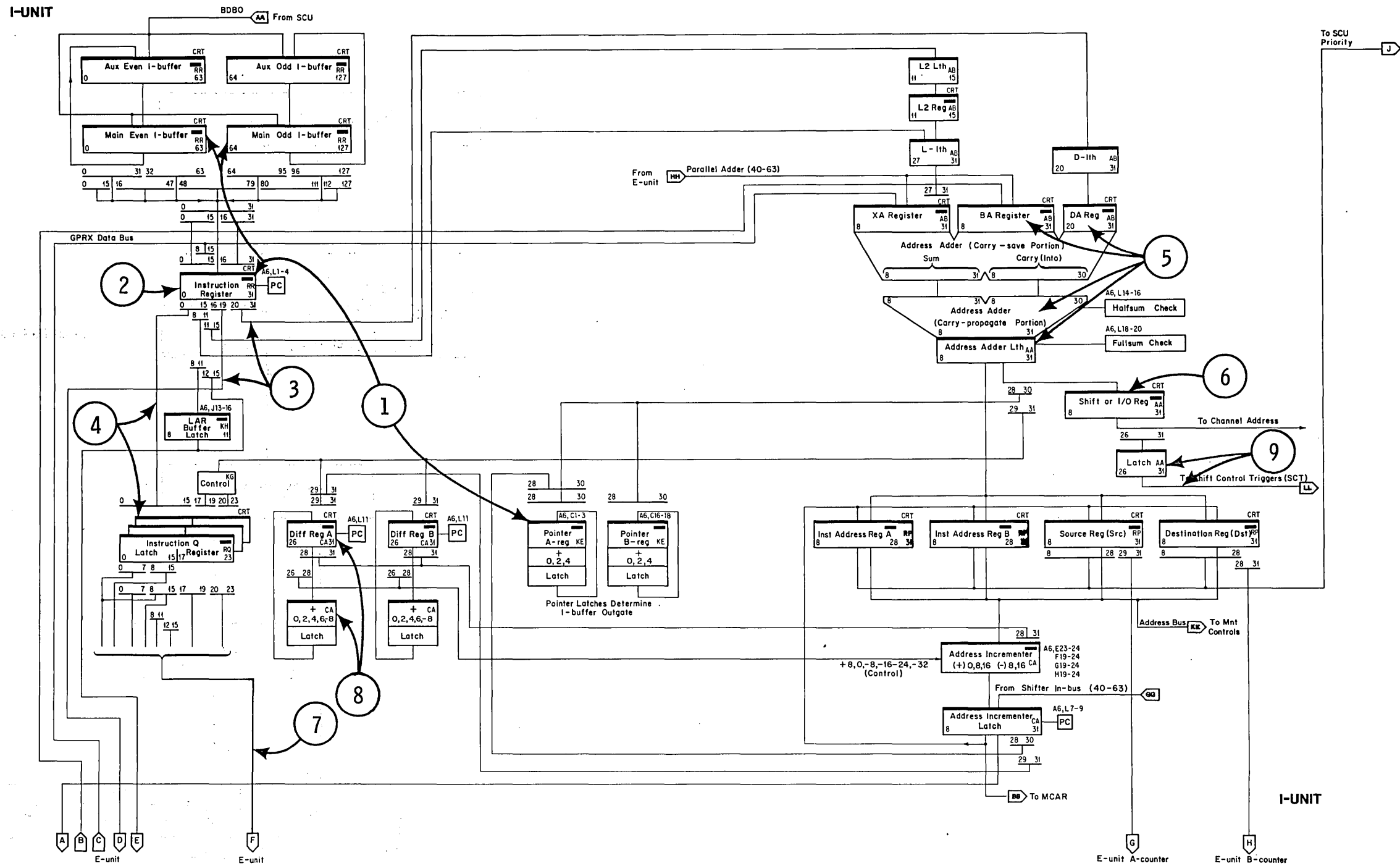


Figure 6-23. RS Shift

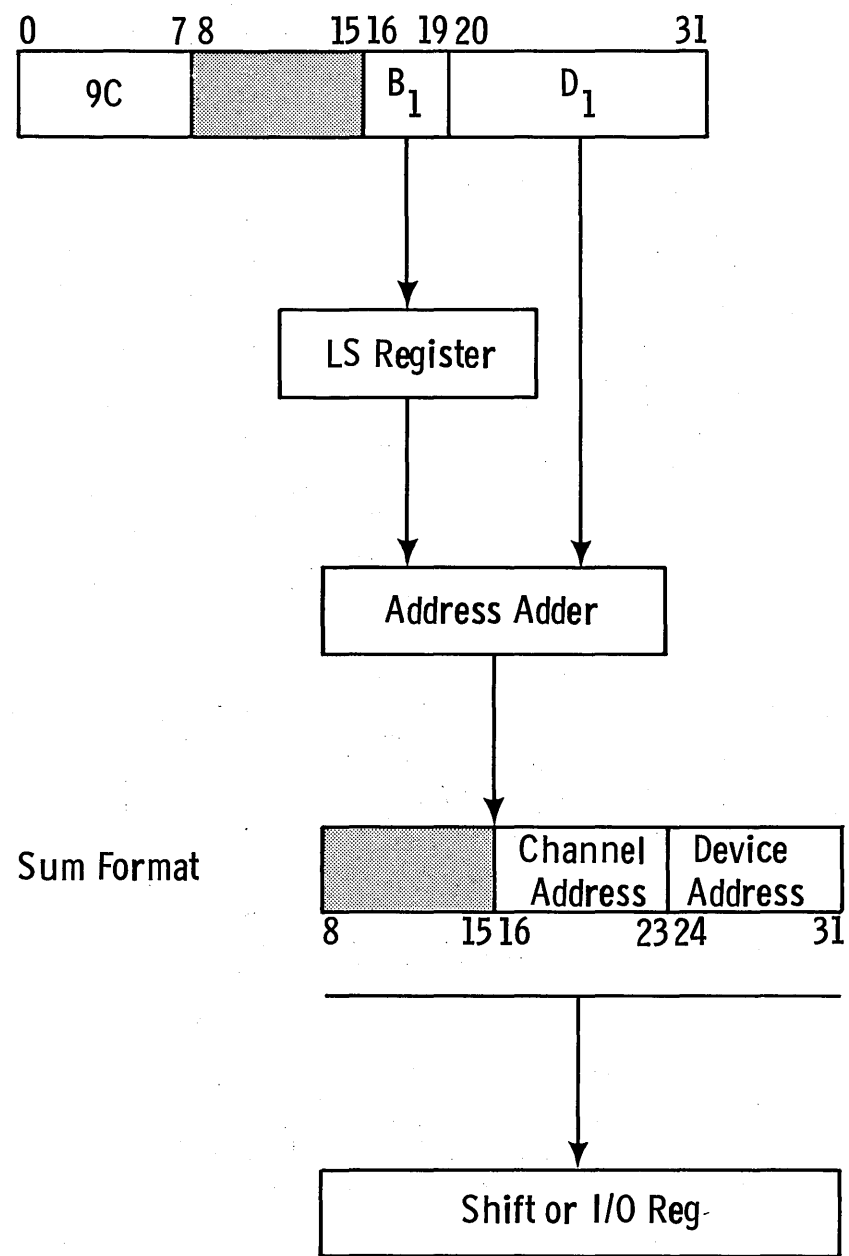


Figure 6-24. Start I/O

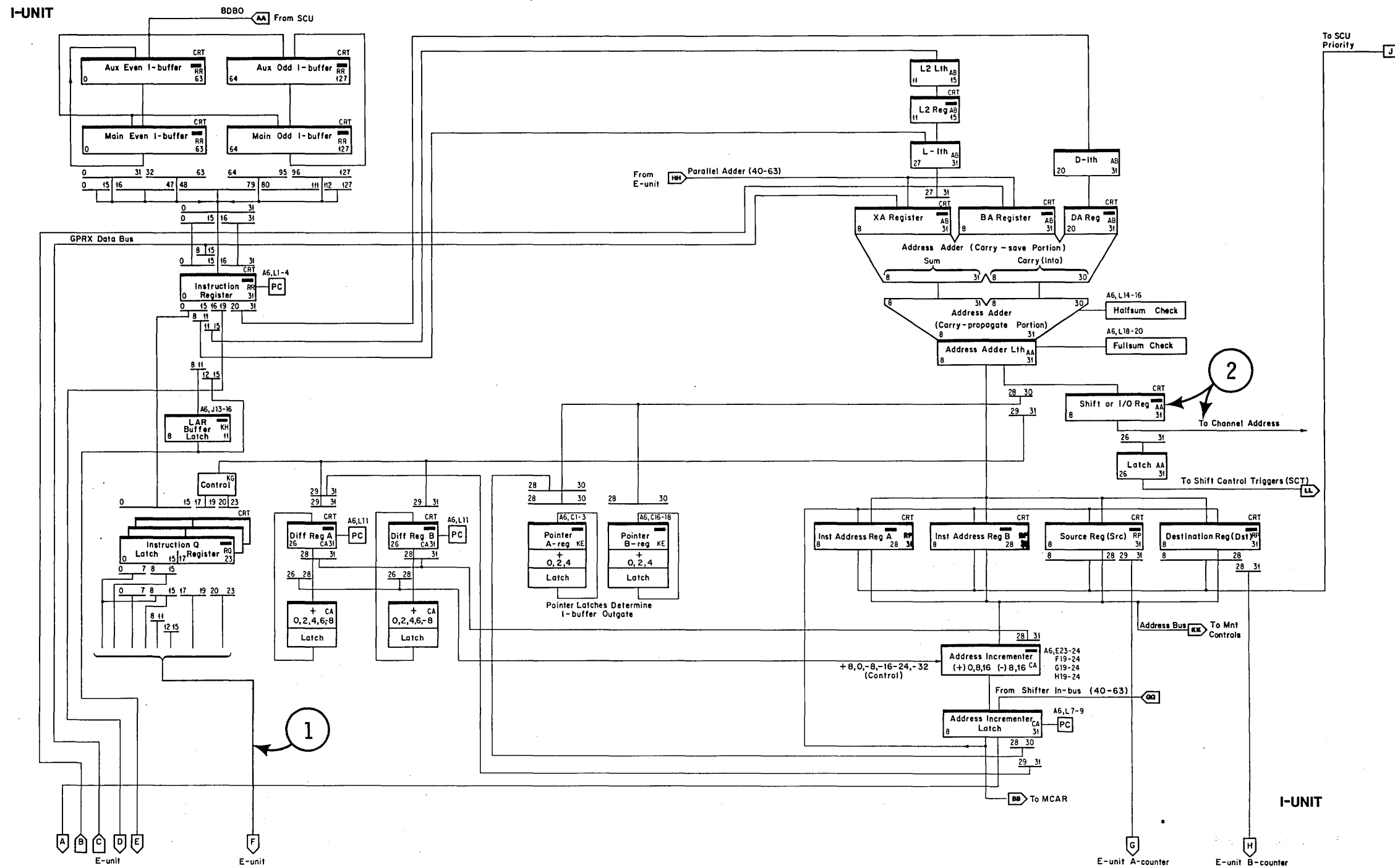


Figure 6-25. Start I/O

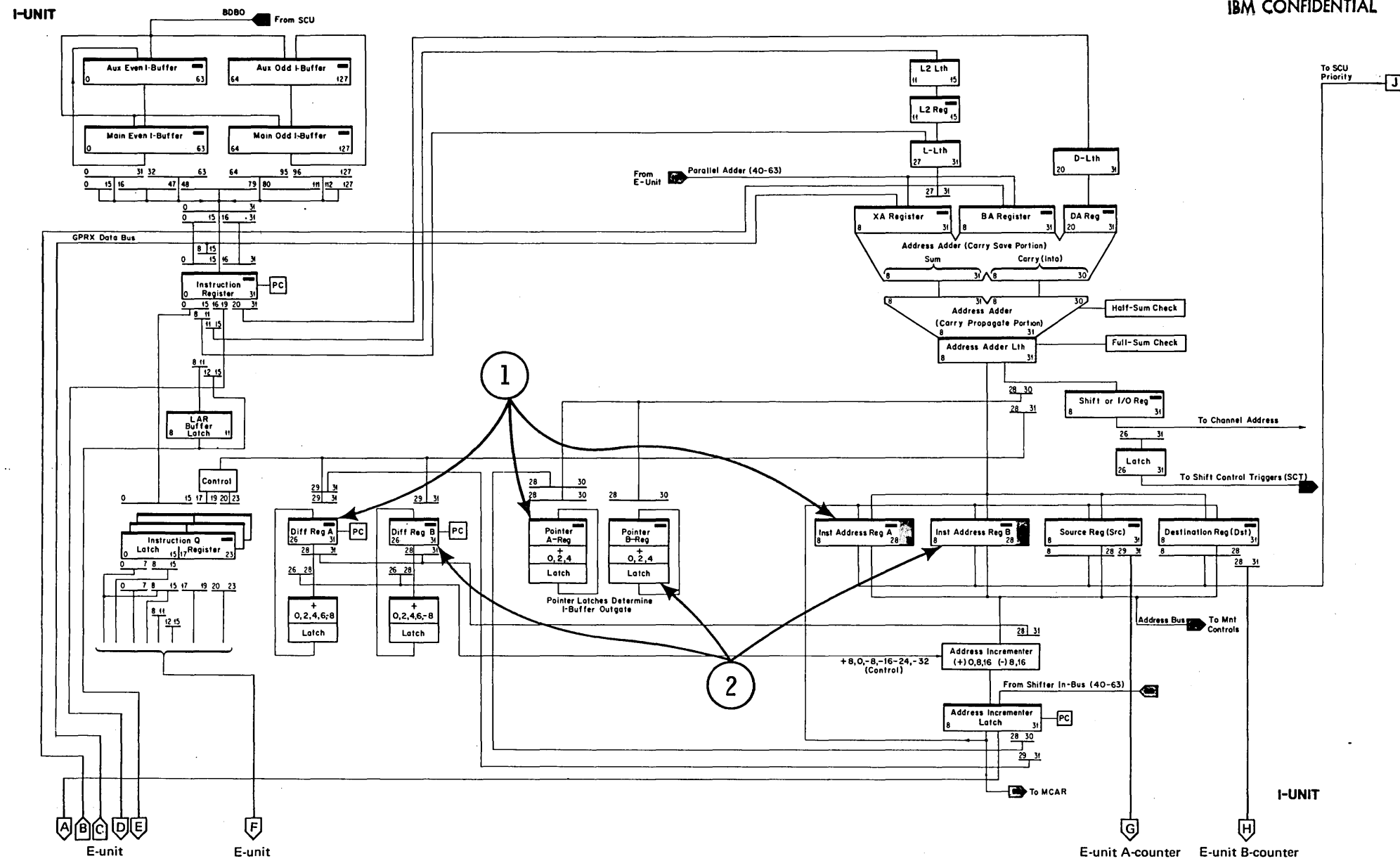


Figure 6-26. IARA And IARB

I-UNIT BRANCH INSTRUCTION PROCESSING

Special action is required when a branch instruction is decoded in the I-unit. When the address is calculated for a branch instruction, it is put into the instruction address register that is not currently active. For example, if IAR A is currently being used to fetch instructions for the main instruction buffer, the branch target address is put IAR B. An instruction fetch is then made per IAR B. The doubleword of instructions obtained by this fetch is part of the target instruction stream. Conversely the instructions obtained by a fetch per the instruction address register currently being used are part of the normal instruction stream. The I-unit makes an estimate as to the probable success of the branch by decoding the branch instruction op code, the branch mask, and the R2 field of the instruction, if applicable. (A successful branch is one in which the branch actually takes place during E-unit execution; conversely, an unsuccessful branch is one in which the branch does not occur when the branch is executed.)

BRANCH ESTIMATES

Unsuccessful branch estimates are made for:

Branch on condition (BC) when the mask bit is not equal to 0 or 15.
Branch on condition (BCR) when the mask bit is not equal to 0 or 15 and R2 is not equal to 0.

Successful branch estimates are made for:

Branch on condition (BC) when the mask bit equals 15.
Branch on condition (BCR) when the mask bit equals 15 and R2 is not equal to 0.
Branch and link (BAL).
Branch and link (BALR) when R2 is not equal to 0.
Branch on count (BCT)
Branch on count (BCTR) when R2 is not equal to 0.
Branch on index low or equal (BXLE).
Branch on index high (BXH).

The following instructions are not regarded as branch instructions by branch controls.

Branch on condition (BC) when the mask bit equals 0.
Branch on condition (BCR) when the mask bit or R2 equals 0.
Branch and link (BALR) when R2 equals 0.
Branch on count (BCTR) when R2 equals 0.

Figure 6-27. I-Unit Branch Instruction Processing

Figure 6-28. Branch Estimates

UNSUCCESSFUL BRANCH ESTIMATES

When a branch instruction is decoded that requires an unsuccessful branch estimate, the I-unit generates the target address and initiates a fetch request for the target stream of instructions. When the target fetch returns, the I-unit places the target instructions in the auxiliary buffer. Also, the I-unit continues processing the instructions following the branch instruction in the old instruction path without stopping.

Sometime later, the E-unit sends the result of the branch instruction back to the I-unit. If the decision is not to branch (I-unit estimate was correct), it is only necessary to rescind any outstanding requests for the target stream and to continue processing.

However, if the E-unit determines that a branch is necessary (I-unit estimate was incorrect), the I-unit must back up and process the target stream instead of the old instruction stream. The I-unit is reset to cancel any instructions that may have already been sent to a Q-register and the target instruction stream that was fetched and placed in the auxiliary buffer is moved to the main buffer. Instruction processing then resumes in the target stream.

SUCCESSFUL BRANCH ESTIMATES

When a branch instruction is estimated to be successful, the target address is generated and a fetch request is initiated in the same manner as for unsuccessful estimates. I-unit instruction processing must wait until the target stream is actually available. The old instruction stream of instructions is moved to the auxiliary buffer. When the target stream instructions return, they are placed in the main buffer and instruction processing continues.

Sometime later, the E-unit advises the I-unit of the outcome of the branch instruction. If the estimate was correct, the I-unit has correctly started processing in the target stream and it is only necessary to rescind any outstanding request for the old instruction stream.

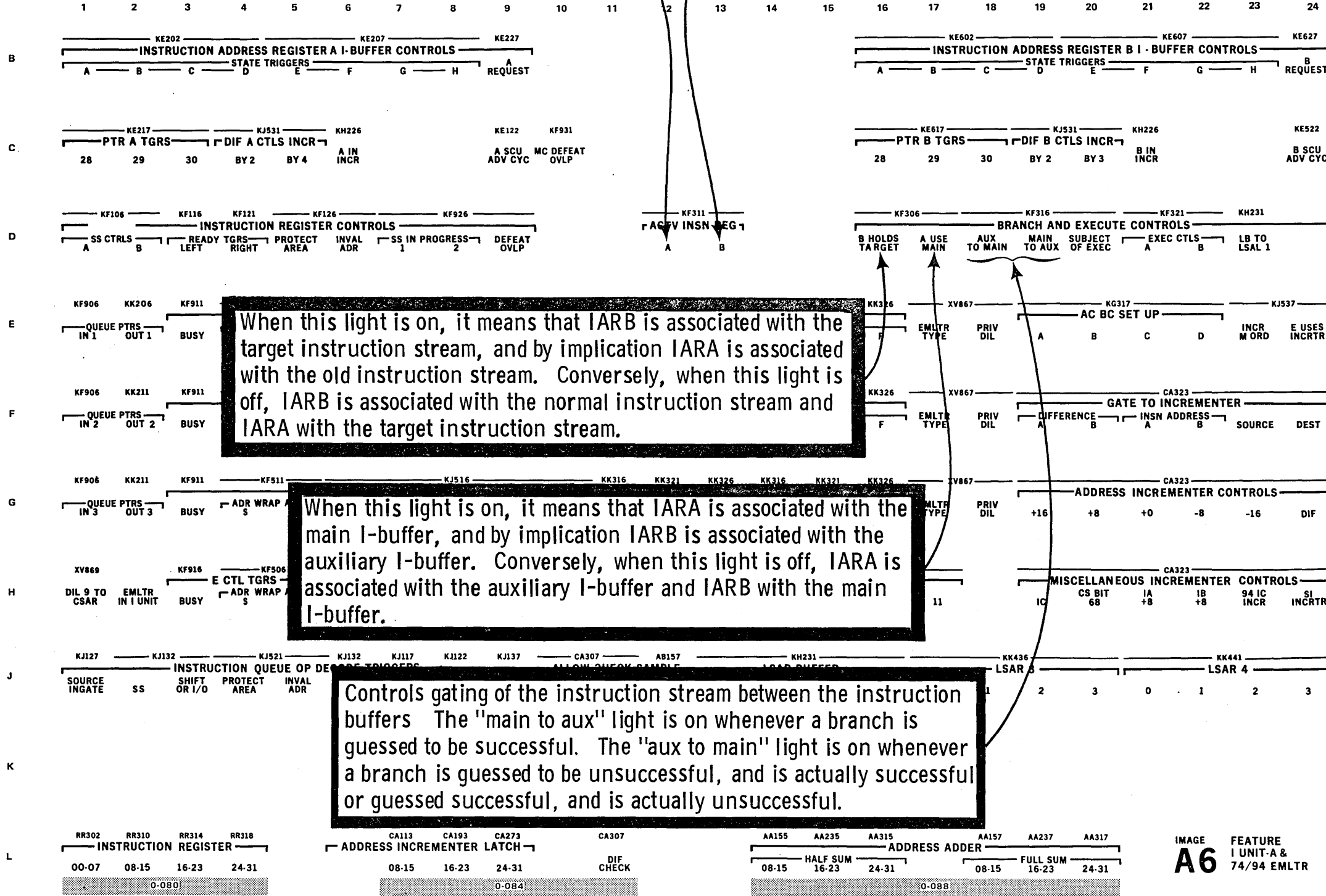
However, if a successful estimate branch is actually unsuccessful, then the I-unit must be reset to cancel any instructions processed in the target stream. The old instruction stream must be returned to the main buffer from the auxiliary buffer and then processing is resumed in the old instruction stream.

Figure 6-29. Unsuccessful Estimate

Figure 6-30. Successful Estimates

When this light is on, it means that IARA is being used to fetch instructions. Conversely, when this light is off, fetch requests are blocked, and any fetch request previously issued by IARA is rescinded. Any time the I-unit is restarted, this light will come on and remain on until a successful branch is executed.

When this light is on, it means that IARB is being used to fetch instructions. Conversely, when this light is off, fetch requests are blocked, and any fetch request previously issued by IARB is rescinded. This light is not affected by restarting the I-unit.



When this light is on, it means that IARB is associated with the target instruction stream, and by implication IARA is associated with the old instruction stream. Conversely, when this light is off, IARB is associated with the normal instruction stream and IARA with the target instruction stream.

When this light is on, it means that IARA is associated with the main I-buffer, and by implication IARB is associated with the auxiliary I-buffer. Conversely, when this light is off, IARA is associated with the auxiliary I-buffer and IARB with the main I-buffer.

Controls gating of the instruction stream between the instruction buffers. The "main to aux" light is on whenever a branch is guessed to be successful. The "aux to main" light is on whenever a branch is guessed to be unsuccessful, and is actually successful or guessed successful, and is actually unsuccessful.

Figure 6-31. MFI Branch Indicators

E-UNIT SETUP

When an instruction is transferred from the I-unit to the E-unit, the E-unit registers must be set up with the values needed to begin the execution of that instruction. Setup includes placing the instruction in the E-register, fetching operands from local storage, ingating operands from the operand buffers (the operand buffers hold the operands fetched from storage by the I-unit), and sending starting values to ACAL and BCAL. Also, the op code must be put into the control storage address register (CSAR to cause a CS branch to the first word of the microprogram routine that will control the E-unit during the execution of this instruction. The instruction queue register in the I-unit must be released for use by another instruction.

The conditions for transferring a new instruction to the E-unit are:

1. The I-unit has an instruction ready.
2. The E-unit has completed execution of the last instruction.

When the I-unit has an instruction ready for the E-unit, the queue out-pointer gates the op code to the CSAR in-bus, and the 'instruction ready' line is turned on. When the end-op bit and "instruction ready" line are both on, the op code (Q-register bits 0-7) is ingated to CSAR, and the 'op branch taken' trigger is turned on. The "op branch taken" trigger causes most of the setup information to be transferred from the I-unit to the E-unit.

110

CH	XX XX XX	0X	XX XX	0X	ARRAY	ADR	VD									
					0	XX XX	XX									
STAR	XX XX XX		0X XX		1	XX XX	XX									
FAR	XX XX XX		XX		2	XX XX	XX									
REDO	XX XX XX		XX		3	XX XX	XX									
					B RPL	XX XX XX										
					D BAR	XX XX XX										
					BAR	XX XX XX										
		1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
IB A	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX
IB M	B0 06	43 80	80 7C	54 80	B0 92	59 80	B0 9A	47 80								
CH I	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX								
CH O	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX								
SDBO	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	IREG	59 80	B0	8A		L2	XX	
									IQ 1	XX XX	XX			SH		XX XX
									IQ 2	XX XX	XX			DSPM		0X XX
									IQ 3	XX XX	XX			BASE		XX XX XX
OP 1	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX							INDX		XX XX XX
OP 2	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX									XX XX XX
A	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX							SRC		XX XX XX
B	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX							DST		XX XX XX
C	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX		DIF A	XX				IAR A		XX XX XX
D	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX		DIF B	XX				IAR B		XX XX XX
E	XX XX															
F	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX									
**MY 1	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX		CSAR	0X XX						
**MY 2	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX		CSARA	0X XX	0X					
**SUM	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX		CSARB	0X XX	0X					
**CAR	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX									
**SPAR	0X XX		0X XX													
MCRR	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX		IC	XX XX	XX XX		M CER		XX	
MCDR	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX	XX XX		M CAR	XX XX	XX XX		MR AR		XX XX	XX XX

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Figure 6-32. E-Unit Setup

Figure 7-1. CRT For Session 7, Question 1

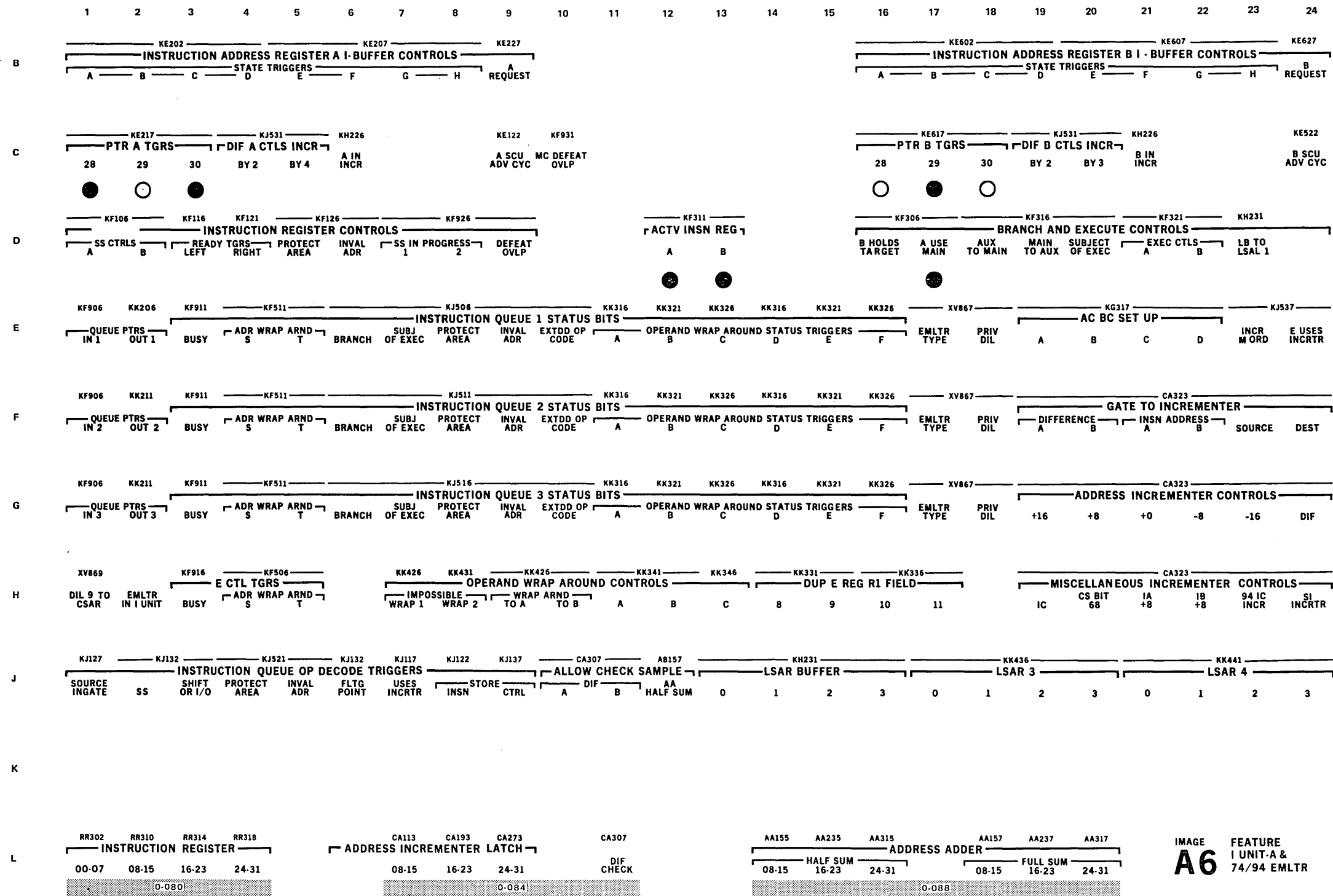


Figure 7-2. Image A6 For Session 7, Question 1

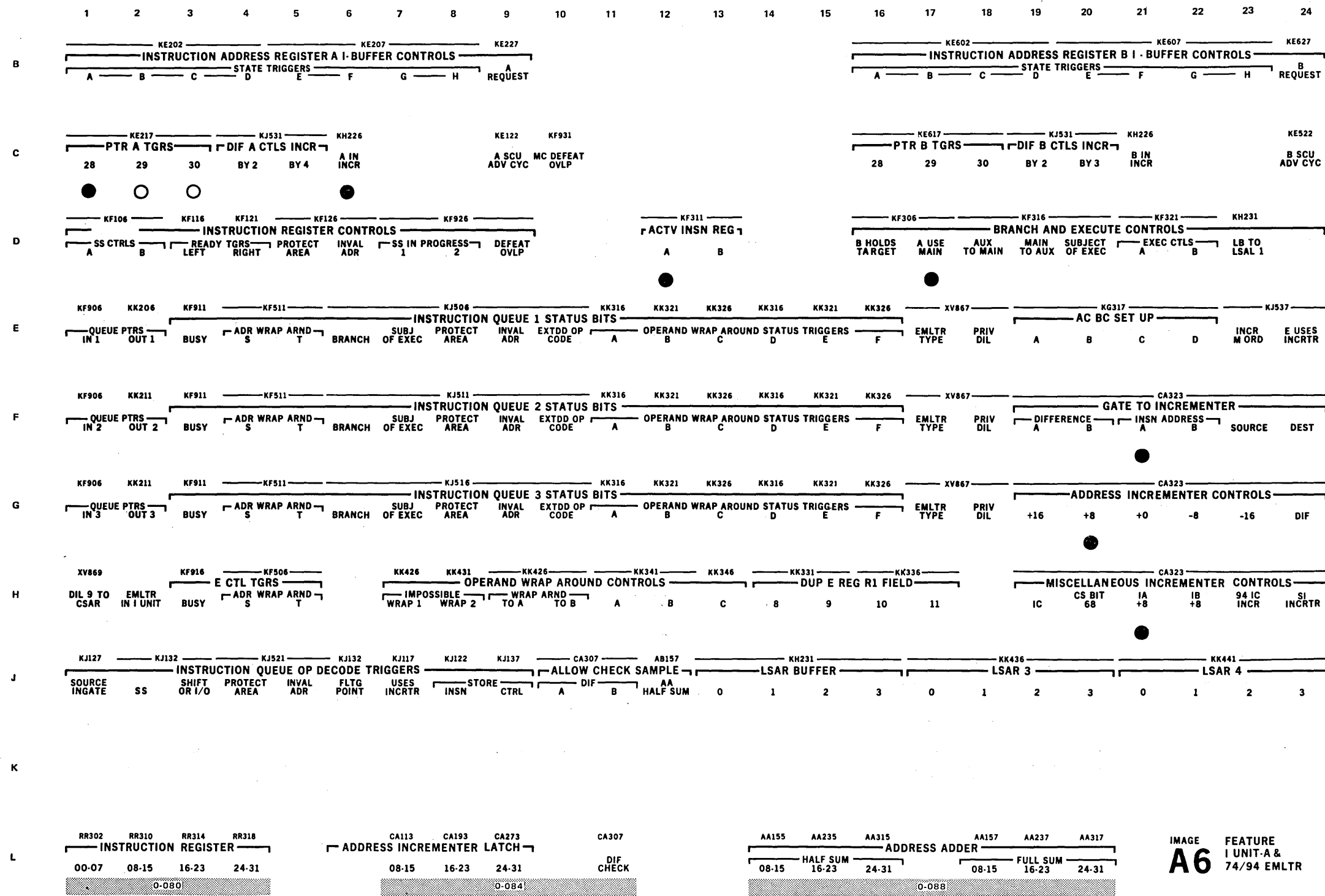


Figure 7-3. Image A6 For Session 7, Question 2

```

CH      ADR  K  MK ID ST  ARRAY  ADR  VD
      XX XX XX 0X XX XX 0X    0    XX XX  XX
      1    XX XX  XX
STAR   XX XX XX    0X XX    2    XX XX  XX
FAR    XX XX XX          XX    3    XX XX  XX

REDO   XX XX XX          XX    B RPL  XX XX XX
      D BAR  XX XX XX
      BAR    XX XX XX

      1  2  3  4  5  6  7  8  9  A  B  C  D  E  F
IB A XX XX XX XX XX XX XX XX XX XX XX XX XX XX
IB M XX XX XX XX XX XX XX XX XX XX XX XX XX XX
CH I XX XX XX XX XX XX XX XX          L2  XX
CH O XX XX XX XX XX XX XX XX          IREG XX XX XX XX  SH  XX XX
SDBO XX XX XX XX XX XX XX XX          IQ 1 XX XX XX  DSPM  0X XX
      IQ 2 XX XX XX          BASE  XX XX XX
      IQ 3 XX XX XX          INDX  XX XX XX

OP 1 XX XX XX XX XX XX XX XX          SRC  XX XX XX
OP 2 XX XX XX XX XX XX XX XX          DST  XX XX XX
  A XX XX XX XX XX XX XX XX          IAR A  XX XX XX
  B XX XX XX XX XX XX XX XX          IAR B  XX XX XX
  C XX XX XX XX XX XX XX XX          DIF A XX
  D XX XX XX XX XX XX XX XX          DIF B XX
  E XX XX
  F XX XX XX XX XX XX XX XX

**MY 1 XX XX XX XX XX XX XX XX          CSAR  0X XX
**MY 2 XX XX XX XX XX XX XX XX          CSARA 0X XX  0X
** SUM XX XX XX XX XX XX XX XX          CSARB 0X XX  0X
** CAR XX XX XX XX XX XX XX XX
**SPAR 0X XX  0X XX
MCRR XX XX XX XX XX XX XX XX          IC  XX XX XX XX  MCER  XX
MCDR XX XX XX XX XX XX XX XX          MCAR XX XX XX XX  MRAR  XX XX XX XX

```

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Figure 7-4. CRT For Session 7, Question 2

```

CH      ADR  K  MK ID ST  ARRAY  ADR  VD
      XX XX XX 0X XX XX 0X    0    XX XX  XX
      1    XX XX  XX
STAR   XX XX XX    0X XX    2    XX XX  XX
FAR    XX XX XX          XX    3    XX XX  XX

REDO   XX XX XX          XX    B RPL  XX XX XX
      D BAR  XX XX XX
      BAR    XX XX XX

      1  2  3  4  5  6  7  8  9  A  B  C  D  E  F
IB A XX XX XX XX XX XX XX XX XX XX XX XX XX XX
IB M XX XX XX XX XX XX XX XX XX XX XX XX XX XX
CH I XX XX XX XX XX XX XX XX          L2  XX
CH O XX XX XX XX XX XX XX XX          IREG XX XX XX XX  SH  XX XX
SDBO XX XX XX XX XX XX XX XX          IQ 1 XX XX XX  DSPM  0X XX
      IQ 2 XX XX XX          BASE  XX XX XX
      IQ 3 XX XX XX          INDX  XX XX XX

OP 1 XX XX XX XX XX XX XX XX          SRC  XX XX XX
OP 2 XX XX XX XX XX XX XX XX          DST  XX XX XX
  A XX XX XX XX XX XX XX XX          IAR A  XX XX XX
  B XX XX XX XX XX XX XX XX          IAR B  XX XX XX
  C XX XX XX XX XX XX XX XX          DIF A XX
  D XX XX XX XX XX XX XX XX          DIF B XX
  E XX XX
  F XX XX XX XX XX XX XX XX

**MY 1 XX XX XX XX XX XX XX XX          CSAR  0X XX
**MY 2 XX XX XX XX XX XX XX XX          CSARA 0X XX  0X
** SUM XX XX XX XX XX XX XX XX          CSARB 0X XX  0X
** CAR XX XX XX XX XX XX XX XX
**SPAR 0X XX  0X XX
MCRR XX XX XX XX XX XX XX XX          IC  XX XX XX XX  MCER  XX
MCDR XX XX XX XX XX XX XX XX          MCAR XX XX XX XX  MRAR  XX XX XX XX

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Figure 7-5. CRT For Session 7, Question 3

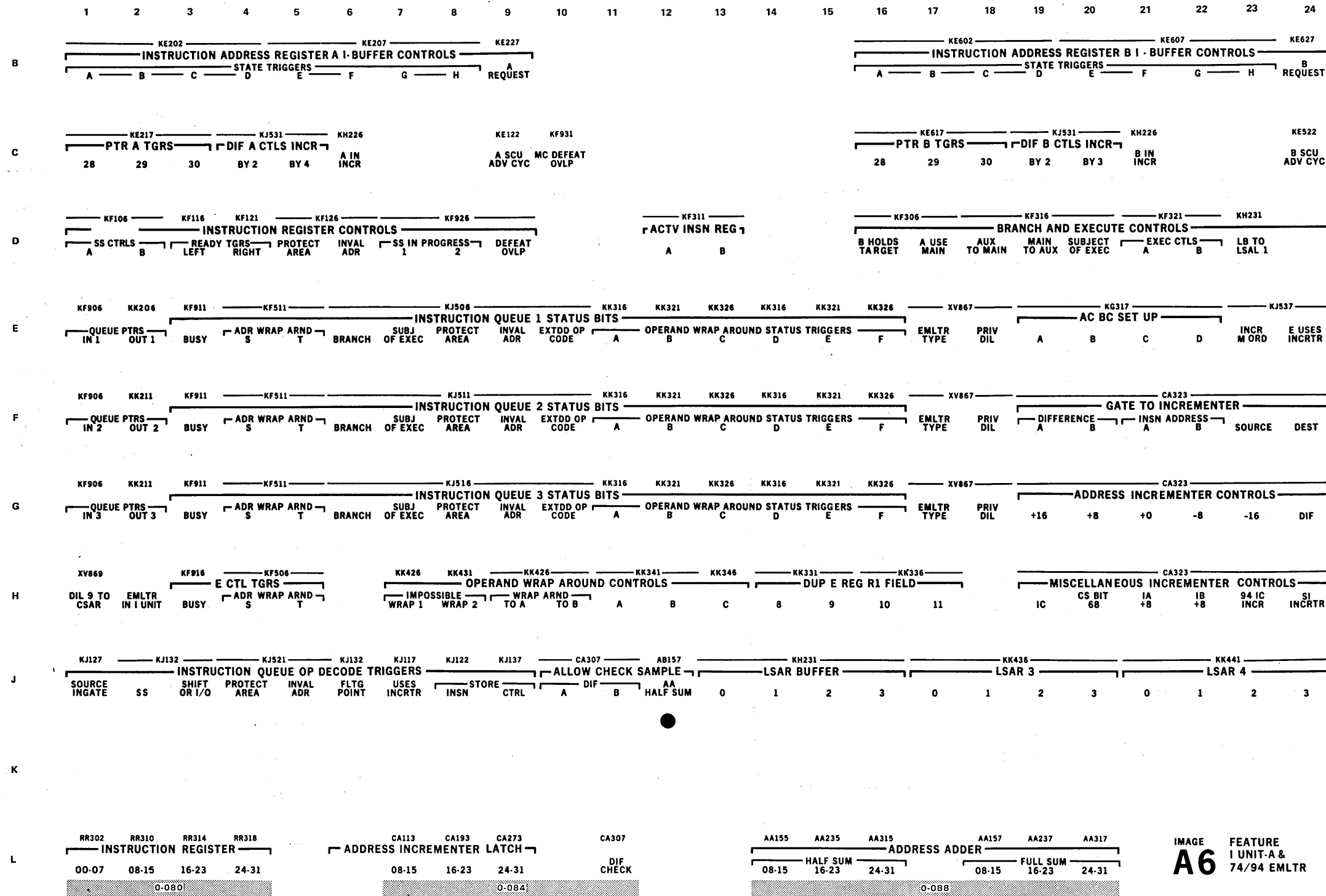


IMAGE FEATURE
A6 I UNIT-A &
74/94 EMLTR

Figure 7-6. Image A6 For Session 7, Question 3

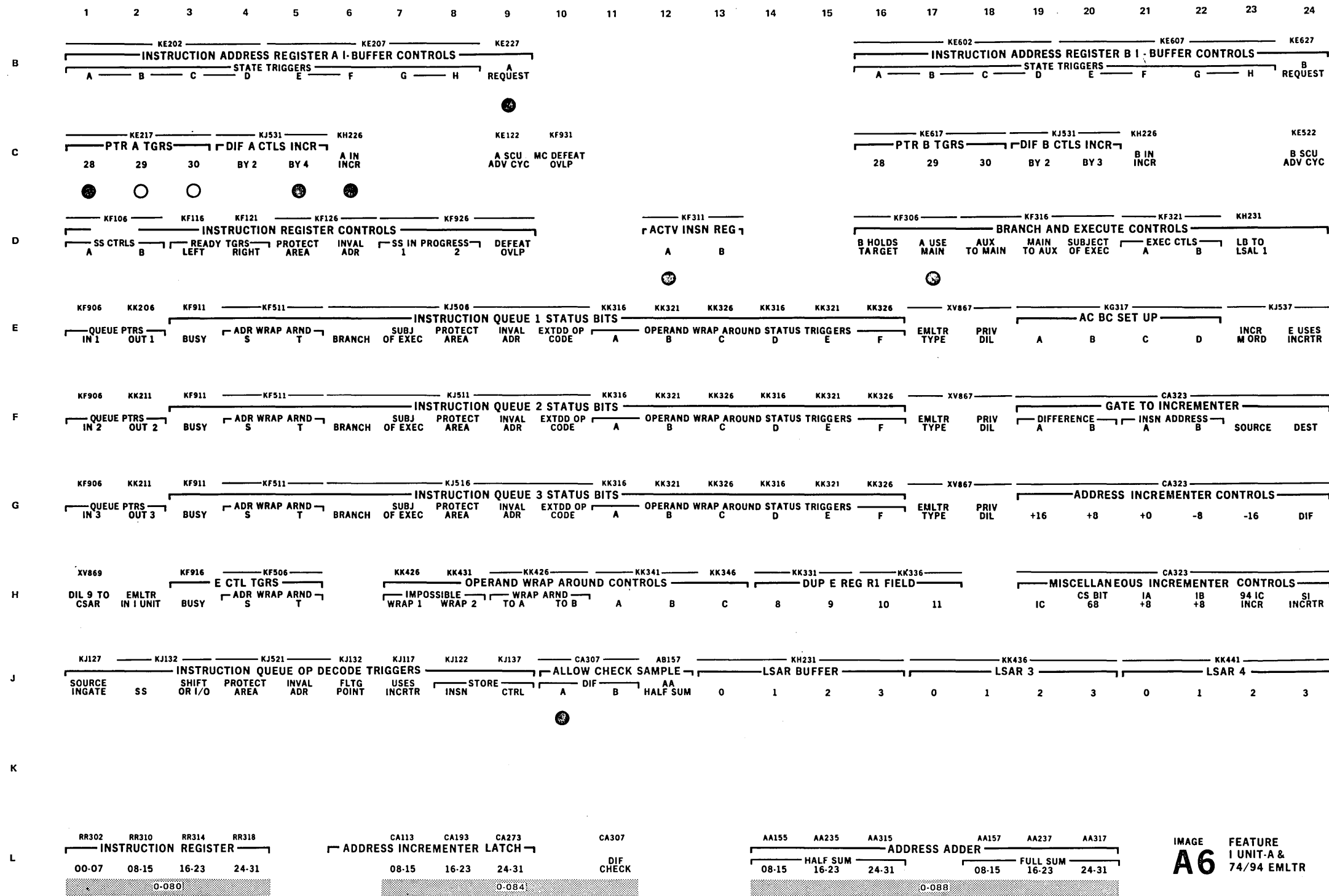


IMAGE A6 FEATURE I UNIT-A & 74/94 EMLTR

Figure 7-7. Image A6 For Session 7, Question 4

CH	ADR	K	MK	ID	ST	ARRAY	ADR	VD
	XX XX XX	0X	XX	XX	0X	0	XX XX	XX
STAR	XX XX XX		0X	XX		1	XX XX	XX
FAR	XX XX XX			XX		2	XX XX	XX
						3	XX XX	XX
REDO	XX XX XX			XX		B RPL	XX XX XX	
						D BAR	XX XX XX	
						BAR	XX XX XX	
	1 2 3 4 5 6 7 8 9	A	B	C	D	E	F	
IB A	XX XX XX XX XX XX XX	XX	XX	XX	XX	XX	XX	
IB M	XX XX XX XX XX XX XX	XX	XX	XX	XX	XX	XX	
CH I	XX XX XX XX XX XX XX							L2 XX
CH O	XX XX XX XX XX XX XX							SH XX XX
SDBO	XX XX XX XX XX XX XX					IREG	XX XX XX	DSPM 0X XX
						IQ 1	XX XX XX	BASE XX XX XX
						IQ 2	XX XX XX	INDX XX XX XX
						IQ 3	XX XX XX	
OP 1	XX XX XX XX XX XX XX							SRC XX XX XX
OP 2	XX XX XX XX XX XX XX							DST XX XX XX
A	XX XX XX XX XX XX XX							IAR A XX XX XX
B	XX XX XX XX XX XX XX							IAR B XX XX XX
C	XX XX XX XX XX XX XX					DIF A	XX	
D	XX XX XX XX XX XX XX					DIF B	XX	
E	XX XX							
F	XX XX XX XX XX XX XX							
*MY 1	XX XX XX XX XX XX XX					CSAR	0X XX	
*MY 2	XX XX XX XX XX XX XX					CSARA	0X XX	0X
*SUM	XX XX XX XX XX XX XX					CSARB	0X XX	0X
*CAR	XX XX XX XX XX XX XX							
*SPAR	0X XX 0X XX							
MCRR	XX XX XX XX XX XX XX					IC	XX XX XX XX	MCER XX
MCDR	XX XX XX XX XX XX XX					MCAR	XX XX XX XX	MRAR XX XX XX XX

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Figure 7-8. CRT For Session 7, Question 4

CH	ADR	K	MK	ID	ST	ARRAY	ADR	VD
	XX XX XX	0X	XX	XX	0X	0	XX XX	XX
STAR	XX XX XX		0X	XX		1	XX XX	XX
FAR	XX XX XX			XX		2	XX XX	XX
						3	XX XX	XX
REDO	XX XX XX			XX		B RPL	XX XX XX	
						D BAR	XX XX XX	
						BAR	XX XX XX	
	1 2 3 4 5 6 7 8 9	A	B	C	D	E	F	
IB A	XX XX XX XX XX XX XX	XX	XX	XX	XX	XX	XX	
IB M	XX XX XX XX XX XX XX	XX	XX	XX	XX	XX	XX	
CH I	XX XX XX XX XX XX XX							L2 XX
CH O	XX XX XX XX XX XX XX							SH XX XX
SDBO	XX XX XX XX XX XX XX					IREG	XX XX XX	DSPM 0X XX
						IQ 1	XX XX XX	BASE XX XX XX
						IQ 2	XX XX XX	INDX XX XX XX
						IQ 3	XX XX XX	
OP 1	XX XX XX XX XX XX XX							SRC XX XX XX
OP 2	XX XX XX XX XX XX XX							DST XX XX XX
A	XX XX XX XX XX XX XX							IAR A XX XX XX
B	XX XX XX XX XX XX XX							IAR B XX XX XX
C	XX XX XX XX XX XX XX					DIF A	XX	
D	XX XX XX XX XX XX XX					DIF B	XX	
E	XX XX							
F	XX XX XX XX XX XX XX							
*MY 1	XX XX XX XX XX XX XX					CSAR	0X XX	
*MY 2	XX XX XX XX XX XX XX					CSARA	0X XX	0X
*SUM	XX XX XX XX XX XX XX					CSARB	0X XX	0X
*CAR	XX XX XX XX XX XX XX							
*SPAR	0X XX 0X XX							
MCRR	XX XX XX XX XX XX XX					IC	XX XX XX XX	MCER XX
MCDR	XX XX XX XX XX XX XX					MCAR	XX XX XX XX	MRAR XX XX XX XX

○ = FLASHING

Figure 7-9. CRT For Session 7, Question 5

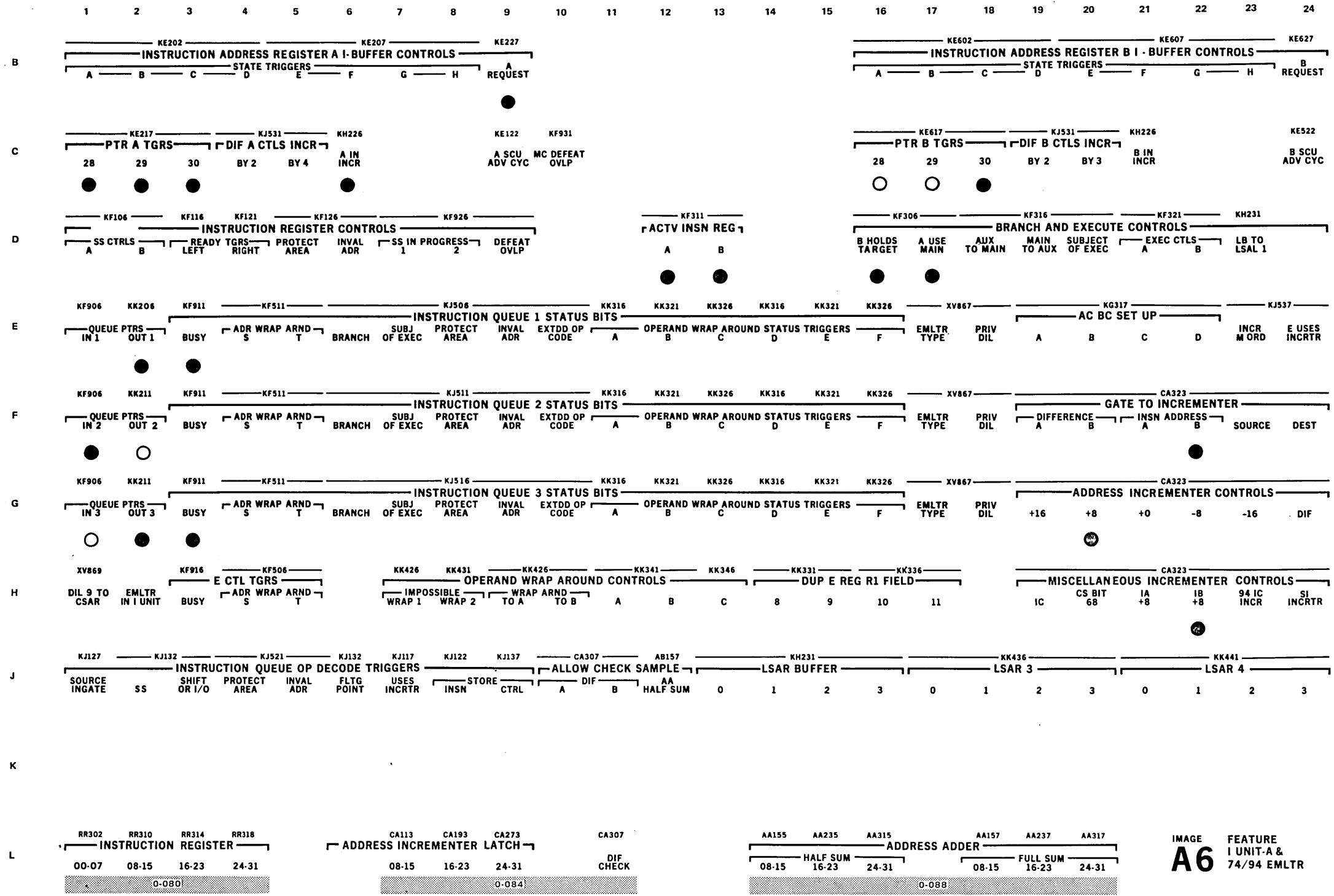


IMAGE A6 FEATURE I UNIT-A & 74/94 EMLTR

Figure 7-10. Image A6 For Session 7, Question 5

PREFACE

This volume of the maintenance diagrams manual contains diagnostic diagrams that can be used by both Phase I and Phase II CEs when analyzing system malfunctions.

There are four sections in this manual.

- The first section (0-XXX numbered diagrams) contains the error check analysis diagrams and the various display formats with descriptions.
- The second section (1-XXX numbered diagrams) covers the control descriptions and operating procedures for the system console.
- The third section (2-XXX numbered diagrams) contains failure analysis diagrams that serve as troubleshooting charts for specific units on the system.
- The fourth section (3-XXX numbered diagrams) contains general reference data in chart form.

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ECAD'S AND DISPLAYS

- ECAD'S
 - ECAD Description 0-002
 - Source/Sink Out Address Check (2 Parts) 0-004
 - Source/Sink, Key, Mark, Data, and Channel Bus Check(2 Parts) 0-008
 - Source/Sink Parity Check (2 Parts) 0-016
 - SDBI Check, Storage Mark Check, and Storage Address Check 0-020
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 - SCU Storage Address Check (2 Parts) 0-032
 - SCU Address Check (2 Parts) 0-036
 - C40 Address and Mark Check (2 Parts) 0-040
 - Buffer Data Bus Out Check (2 Parts) 0-044
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 - Buffer Array Checks (2 Parts) 0-052
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- DISPLAYS
 - Microfiche Indicator Locations
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 - Image A2 0-505
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I-unit ECADs

Alphabetical listing of MFI lamps -- has system page number, and image frame and row location

This page contains the descriptions of the indicators on these pages

SYSTEM CONSOLE

- CONTROL PANEL DESCRIPTIONS
 - Main Control Panel 1-001
 - Panel A1 Controls (2 Parts) 1-003
 - Panel A2 Controls (2 Parts) 1-005
 - Panel A3 Controls (2 Parts) 1-007
 - Panel A4 Controls (3 Parts) 1-009
 - Panel A5 Controls (3 Parts) 1-011
 - Operator's Keyboard 1-013
 - Frame 06 Controls (2 Parts) 1-015

- OPERATING PROCEDURES
 - Console Operating Procedures 1-201

- DIAGNOSTICS
 - Diagnostic Charts 1-401

FAILURE ANALYSIS DIAGRAMS

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 - Console File Maintenance (8 Parts) 2-001

- OPERATOR'S CONSOLE
 - Operator's Console Charts 2-201

- MAIN STORAGE
 - Troubleshooting Guide (5 Parts) 2-401
 - BSM Logic Flow (4 Parts) 2-403
 - Waveforms (2 Parts) 2-405

REFERENCE DATA

- Model 165 Frame Layout 3-001
- CPU Logic Index 3-003
- Permanent Storage and Logout Assignments 3-005
- Model 165 Data Flow Diagram 3-999

C

D

A

B

E

Figure 7-12. Volume 1 Contents

ERROR CHECK ANALYSIS DIAGRAMS (ECADS)

Error check analysis diagrams (ECADs) show line names, card locations, and logic pages for the circuits that activate the microfiche error lights. The ECADs do not necessarily show every logic line in the data flow path related to a given error light. They do, however, show all the cards in the data path. In addition, some control logic is shown. Note that ECADs are applicable only to machine-check type problems.

ECAD DESCRIPTION

Each ECAD is structured so that the user can go back from the microfiche error indicator through the display logic to the error detection point that controls the given indicator. The ECAD then covers the functional logic back to the previous error detection point in the data flow. Included on the ECAD (usually a multi-sheet diagram) is a data flow drawing of the logic area in question. The data flow shows the error checking points.

Additional information found on ECADs:

- Heavy broken lines show error check flow from the error detection logic to the indicator. Although not shown on most ECADs, the machine error check lines also go to the logic that stops the clocks and freezes the maintenance control registers that are buffering retry information.
- Heavy solid lines show the functional flow of data, addresses, marks, keys, etc.
- Normal-weight solid lines show control flow.
- Some ECADs contain a list of suggested microdiagnostic and/or diagnostic programs.
- Where applicable, each ECAD lists related diagrams that are located in volumes 2 through 6 of the FEMDM.

HOW TO LOCATE AN ECAD

To locate an ECAD for a given error light refer to the ECAD Contents list. This list is in order by microfiche frame, row, and column. ECAD numbers are also shown on the microfiche images in diagrams 1-001 through 1-031 in this manual. The ECAD numbers are in the shaded areas directly under the error-light nomenclature.

HOW TO USE AN ECAD

Use an ECAD in the following manner to locate suspect cards.

1. Check the data flow connected by the heavy solid lines. Locate the block closest to the error light. Start at the first card location above the WDxxx logic pages and work back changing one card at a time.
2. Check the control flow (normal-weight solid lines) in the same manner as described above.
3. Check the error detection logic (heavy broken lines).

Figure 7-13. ECAD Information

● Machine Check Switch

The machine check switch is a three position (STOP ON CHK, PROC, DSBL) lever switch that is used to modify the handling of a machine check within the system.

1. Stop On Check: With the switch in this position, all machine checks cause a hard stop. There is no logout and no interrupt is taken. If the switch is moved to the process position and the start switch is pressed, a retry is attempted if the machine is in retry mode. If the machine is not in retry mode, results are unpredictable.
2. Process: With the switch in the process position, all machine checks cause a hard stop, a logout, and (if the retry switch is set to NORM) an instruction retry. If retry is disabled, a logout and machine check interrupt occurs. If retry is in the count mode, a logout and machine check interrupt occurs only on count overflow.
3. Disable: In the disable position, this switch causes all machine checks to turn on the associated check triggers. No other action is taken.

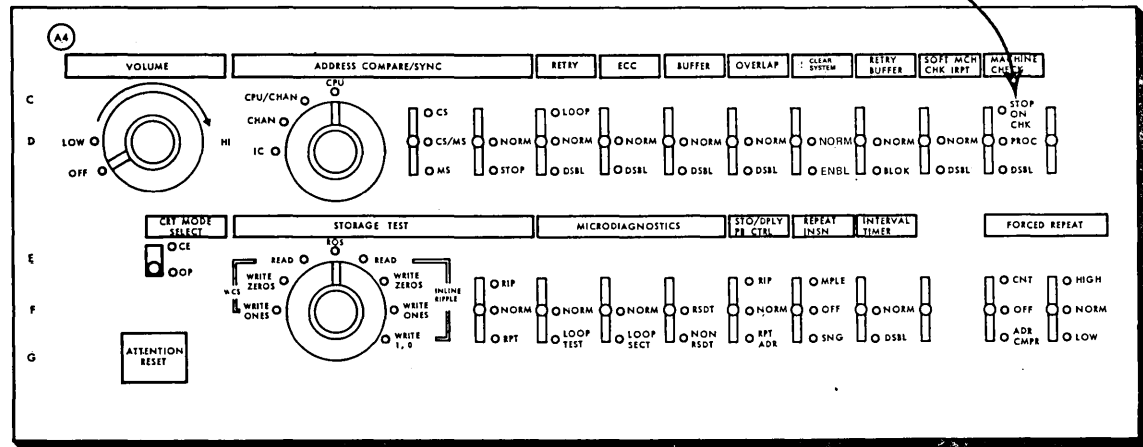
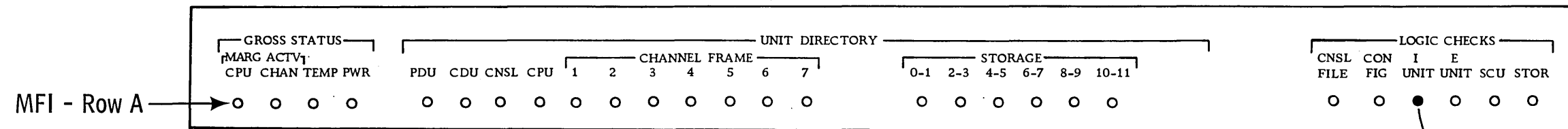


Figure 7-14. Stop On Check



FIXED INDICATORS (MFI DISPLAY)

GROSS STATUS INDICATORS

- Margin Active, CPU -- One of the four margin control switches is not set at the nominal value (1.25V dc).
- Margin Active, Channel -- A margin control on one of the channel frames is not set at the nominal value. (Does not apply to the 2880)
- Temperature -- One of the following coolant conditions exists in the CDU: high temperature, low temperature, low reservoir, or low flow.
- Power -- Power is not up on a unit that has its local/remote switch set to remote. This indicator is also on if the MG detects an over-voltage condition or if the MG is set to the local (voltage sense) mode.

UNIT DIRECTORY INDICATORS

- PDU -- One of the following PDU conditions exists: MG check, PDU thermal check, ac or dc circuit breaker tripped.
- CDU -- One of the following CDU conditions exists: empty reservoir, no 208V ac to the pump, or any of the conditions that turn on the gross status temperature indicator.
- Console -- There is a tripped CB in frame 06 or a thermal indication in frame 05 or 06.
- CPU -- There is a thermal indication in the CPU or PDU or a tripped CB in the PDU.
- Channel Frames 1 through 7 -- Power is not up on the indicated channel frame (local/remote switch set to remote).
- Storage 0, 1 through 10, 11 -- Power is not up on the indicated logical storage unit (local/remote switch set to remote).

LOGIC CHECK INDICATORS

The five logic check indicators are used to indicate a machine check condition. Additional information for a logic check condition is obtained by displaying the appropriate image on the MFI display.

- Configuration check Image A1
- I-Unit Image A6
- E-Unit Image A5
- Storage Control Unit Image A2
- Storage Image A1

Figure 7-15. MFI Row A

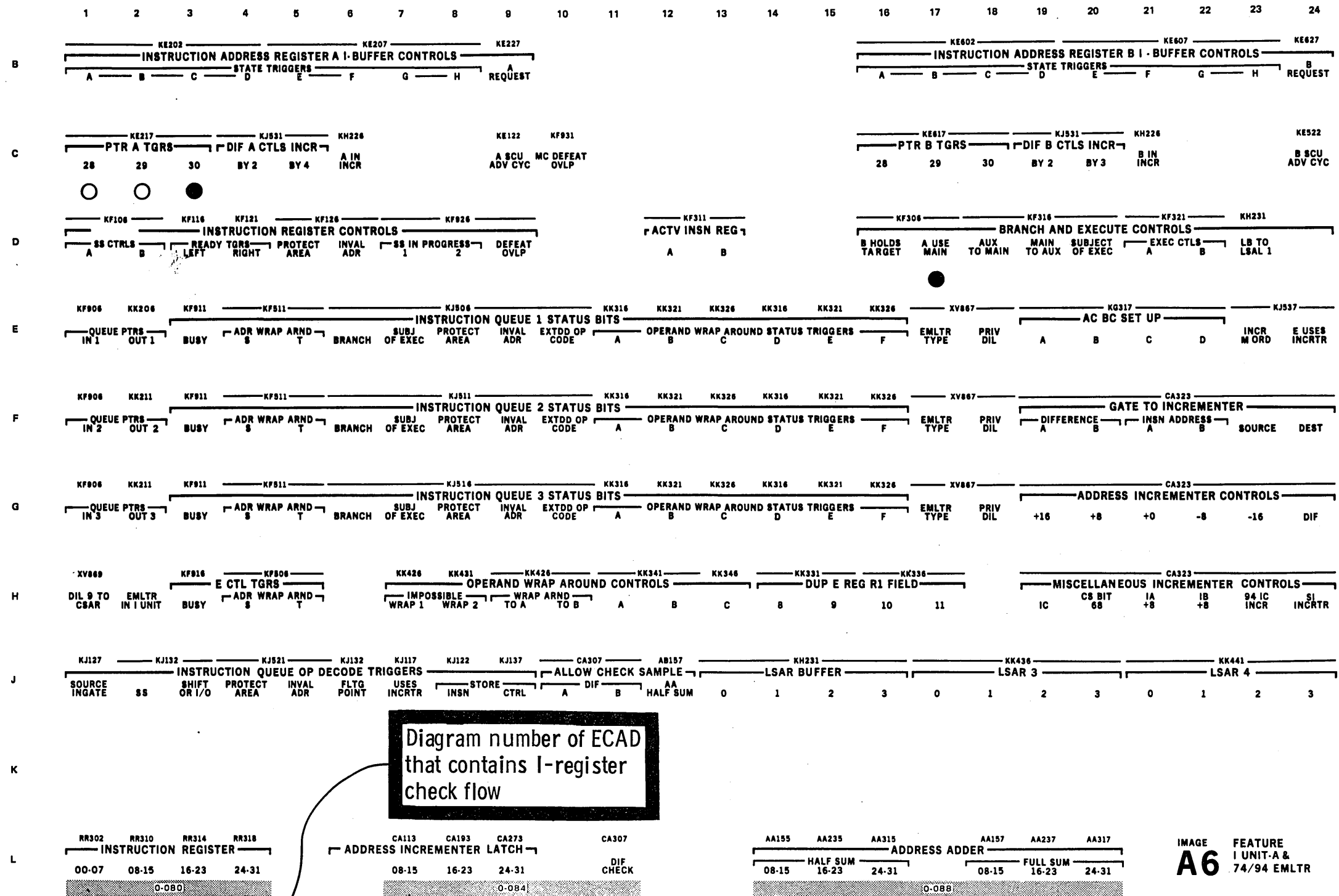


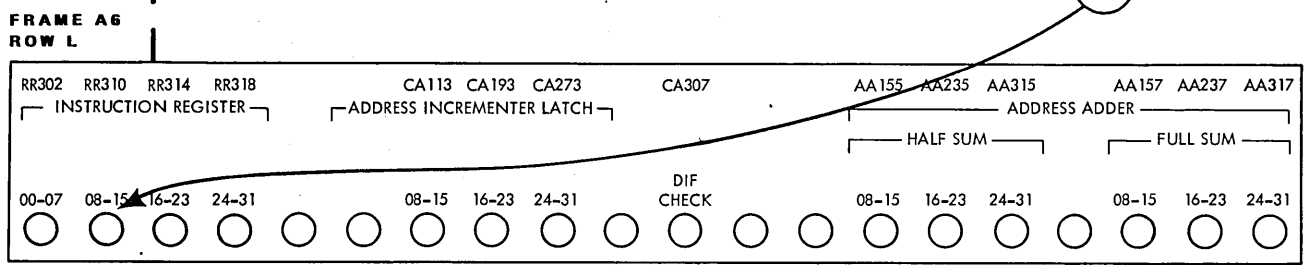
Figure 7-16. Image A6.

Buf Data Bus Out	P0	07	P1	15	P2	23	P3	31	P4	39	P5	47	P6	55	P7	63
Card Location 03C4xx	E2		F2		G2		H2		E2		F2		G2		H2	
ALD Page MQxxx	301-305		307-313		315-321		323-327		331-337		341-347		351-357		361-367	

Instruction Buffers, Any Byte, Any Buffer									
Bit Positions in Byte (Table 1)	00	01	02	03	04	05	06	07	P
Card Location 03Bxxx	4T2	4S2	4R2	4Q2	5T2	5S2	5R2	5Q2	5P2
ALD Page RRxxx									
Aux Even	050	054	058	062	066	070	074	078	082
Aux Odd	086	090	094	098	102	106	110	114	118
Main Even	122	126	130	134	138	142	146	150	154
Main Odd	158	162	166	170	174	178	182	186	190

Instruction Register									
Bit Positions in Byte (Table 1)	00	01	02	03	04	05	06	07	P
Card Location 03Bxxx	4T2	4S2	4R2	4Q2	5T2	5S2	5R2	5Q2	5P2
ALD Page RRxxx									
Bytes 0-1	194	198	202	206	210	214	218	222	226
Bytes 2-3	230	234	238	242	246	250	254	258	262

Line Name	Card Location				ALD Page					
	Bytes	0	1	2	3	Bytes	0	1	2	3
Ind I-reg Error xx	03B5xx	N2	N2	N2	N2	RRxxx	302	310	314	318
Ind A6-A7 Col x	Dor	1	2	3	4	WDxxx	221	221	221	221
Display Fiche Bit xx	01B1xx	G2	H2	J2	K2	WDxxx	007	011	015	019
Display Fiche Bit xx	Exit 01	1	2	3	4	WMxxx	215	215	215	215
Display Fiche Bit xx	Entr 05	1	2	3	4	WL100				
Bus Bit xx MF	05B-A2xx	J6	J6	J6	J6	PA011				
Line 9<>xx	05B-A1xx	D2	E2	F2	G2	PBxxx	001	001	011	011
Ind	06A-A1xx	E2	E2	E4	E4	PBxxx	201	201	211	211



Line Name	Card Location	ALD Page
Ingate to I-buffers	03B5M2	KE906-921

Line Name	Card Location	ALD Page
Pointer A Lths	03B5J2	KE117
Pointer B Lths	03B4J2	KE517
Ingate I-reg 0-15	03B4M2	KF116
Ingate I-reg 16-31	03B4M2	KF121

Table 1

Byte	Position								
	0	1	2	3	4	5	6	7	P
0	00	01	02	03	04	05	06	07	P
1	08	09	10	11	12	13	14	15	P
2	16	17	18	19	20	21	22	23	P
3	24	25	26	27	28	29	30	31	P
4	32	33	34	35	36	37	38	39	P
5	40	41	42	43	44	45	46	47	P
6	48	49	50	51	52	53	54	55	P
7	56	57	58	59	60	61	62	63	P
8	64	65	66	67	68	69	70	71	P
9	72	73	74	75	76	77	78	79	P
10	80	81	82	83	84	85	86	87	P
11	88	89	90	91	92	93	94	95	P
12	96	97	98	99	100	101	102	103	P
13	104	105	106	107	108	109	110	111	P
14	112	113	114	115	116	117	118	119	P
15	120	121	122	123	124	125	126	127	P

Note: This table shows the position within any byte that any bit of a quadword occupies. For example, bit 91 of a quadword is located in byte 11, bit 03, of that quadword.

To determine which word of the main instruction buffer was gated to the instruction register, look at microfiche frame A6. If the A using main indicator (A6, D17) is on, pointer A triggers (A6, C1-C3) show the word outgated from the instruction buffer. If the A using main indicator is off, pointer B triggers (A6, C16-C18) show the word outgated from the instruction buffer. The pointers are coded as follows:

Pointer	Bits Outgated
000	00-31
001	16-47
010	32-63
011	48-79
100	64-95
101	80-111
110	96-127
111	112-127, 00-15

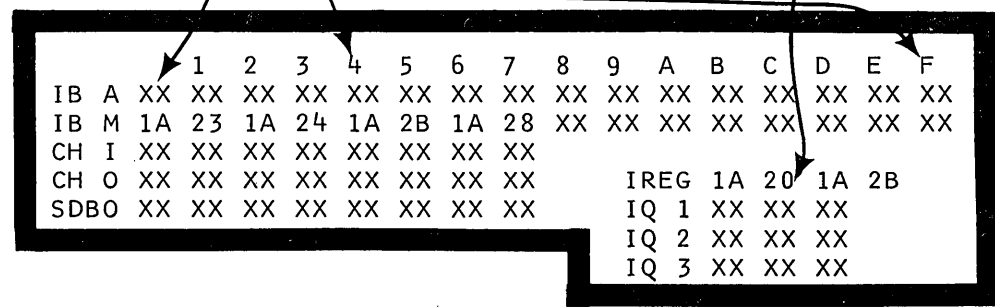


Figure 7-17. I-Register ECAD

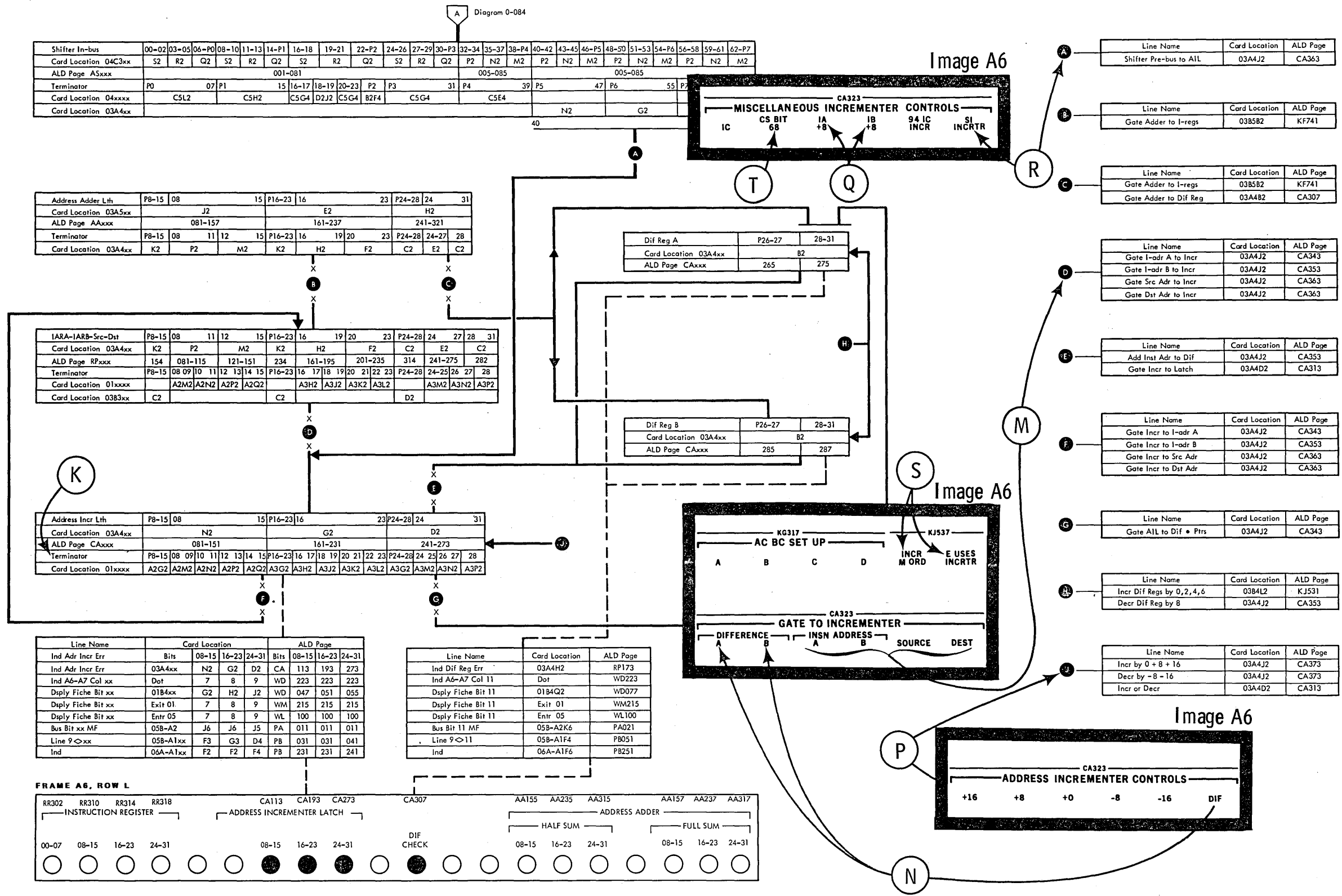


Figure 7-18. Address Incrementer ECAD

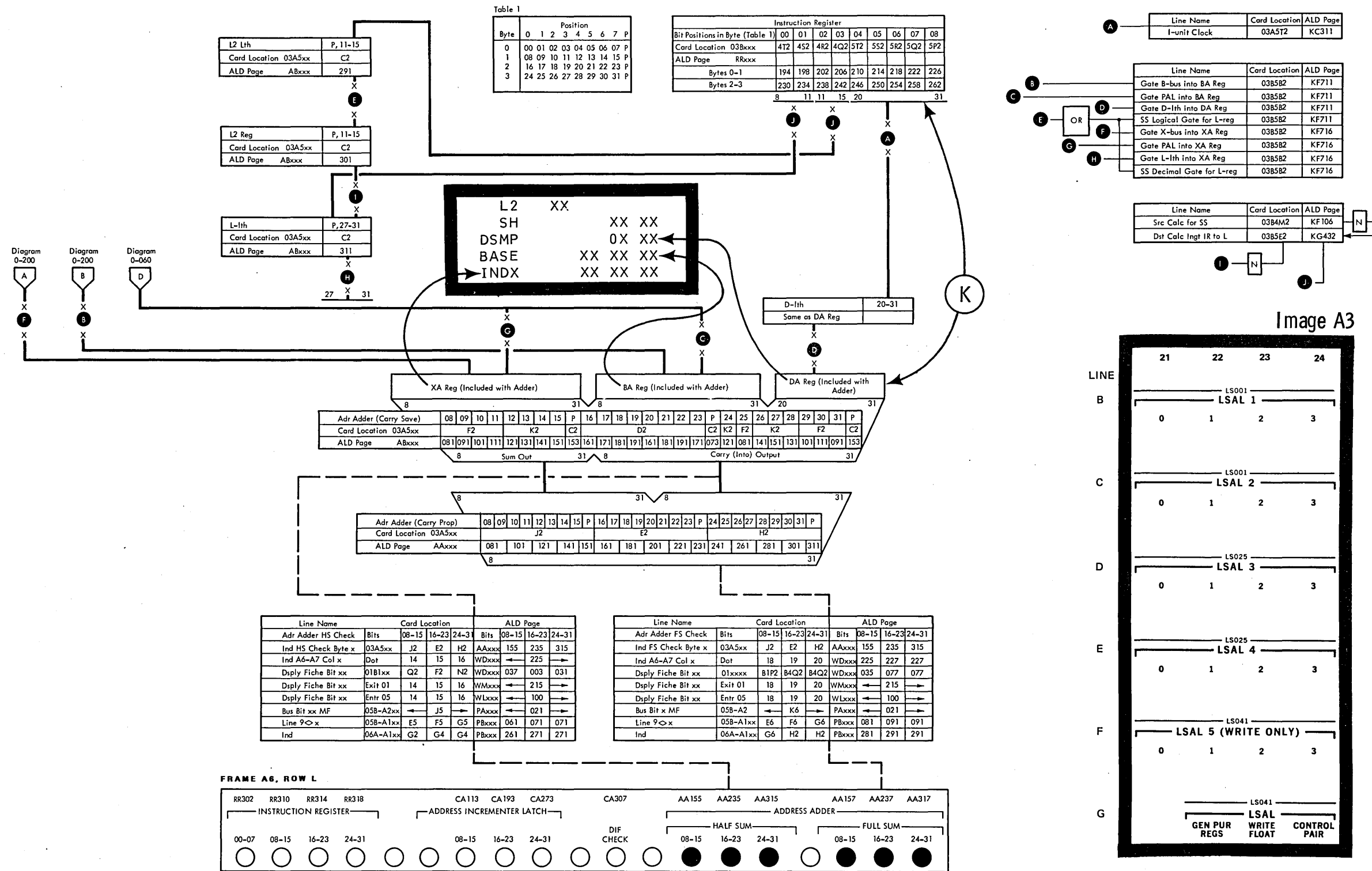


Figure 7-19. Address Adder ECAD

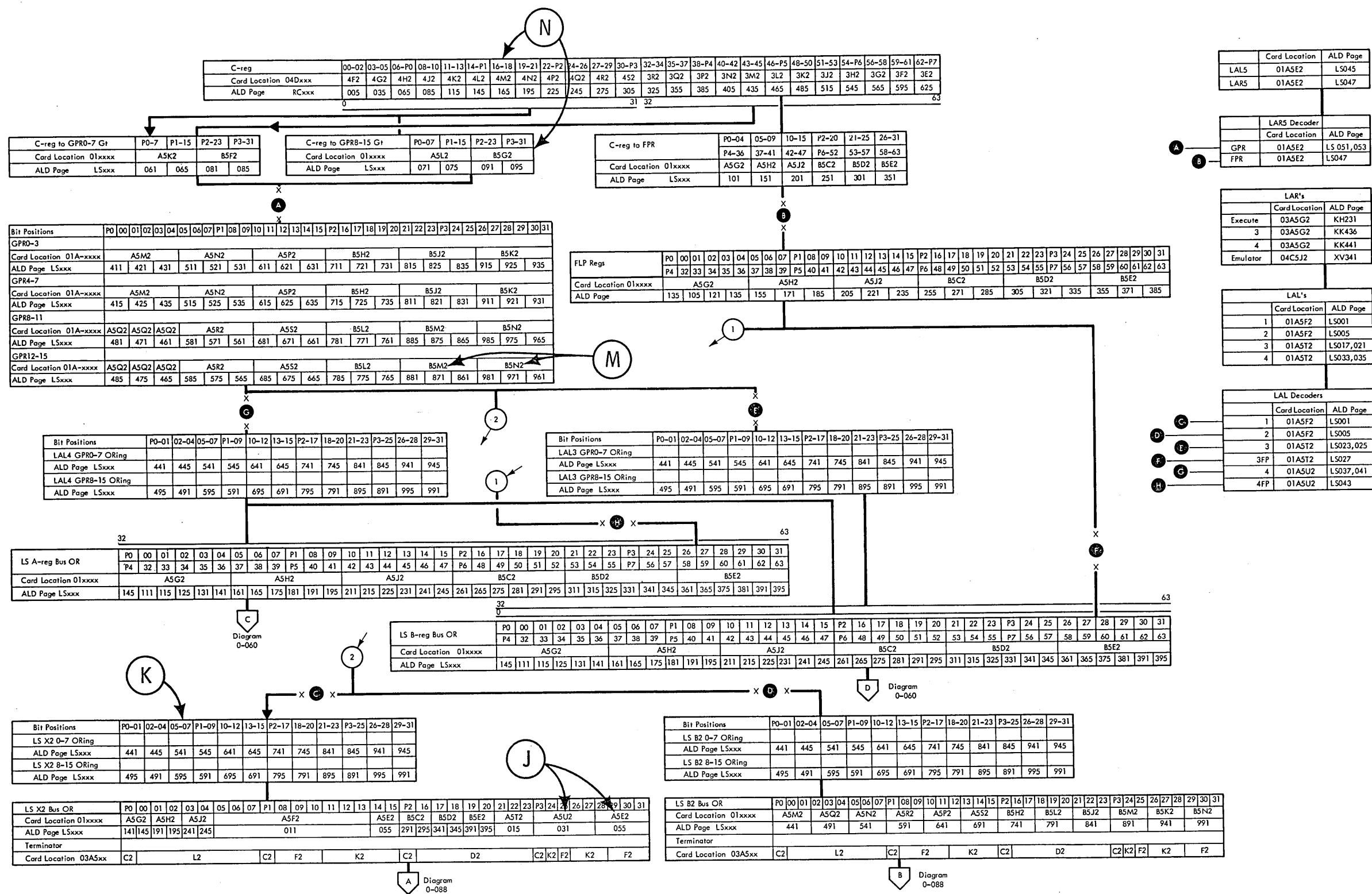


Figure 7-20. LS ECAD

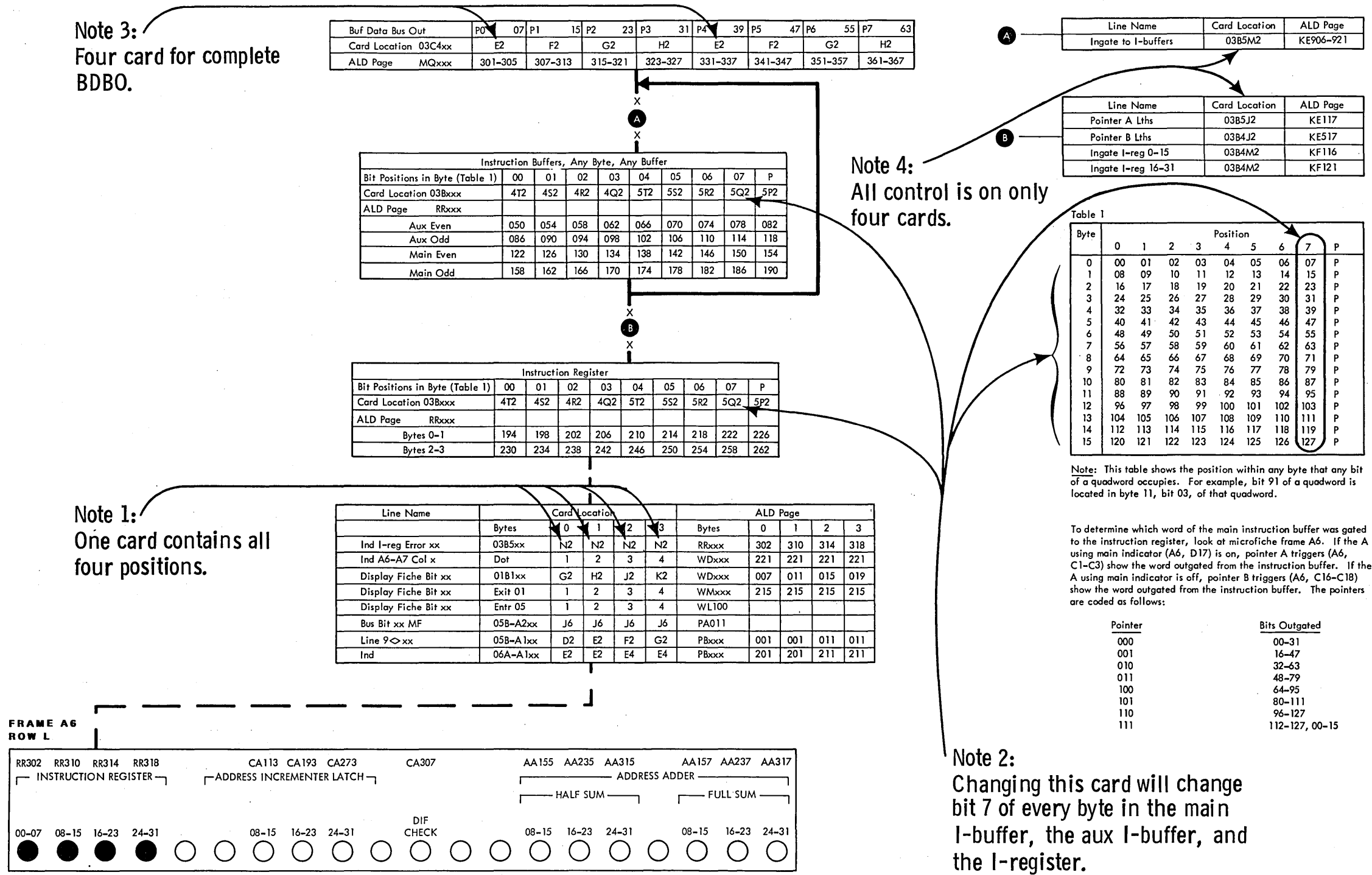


Figure 7-21. I-Buffer Packaging

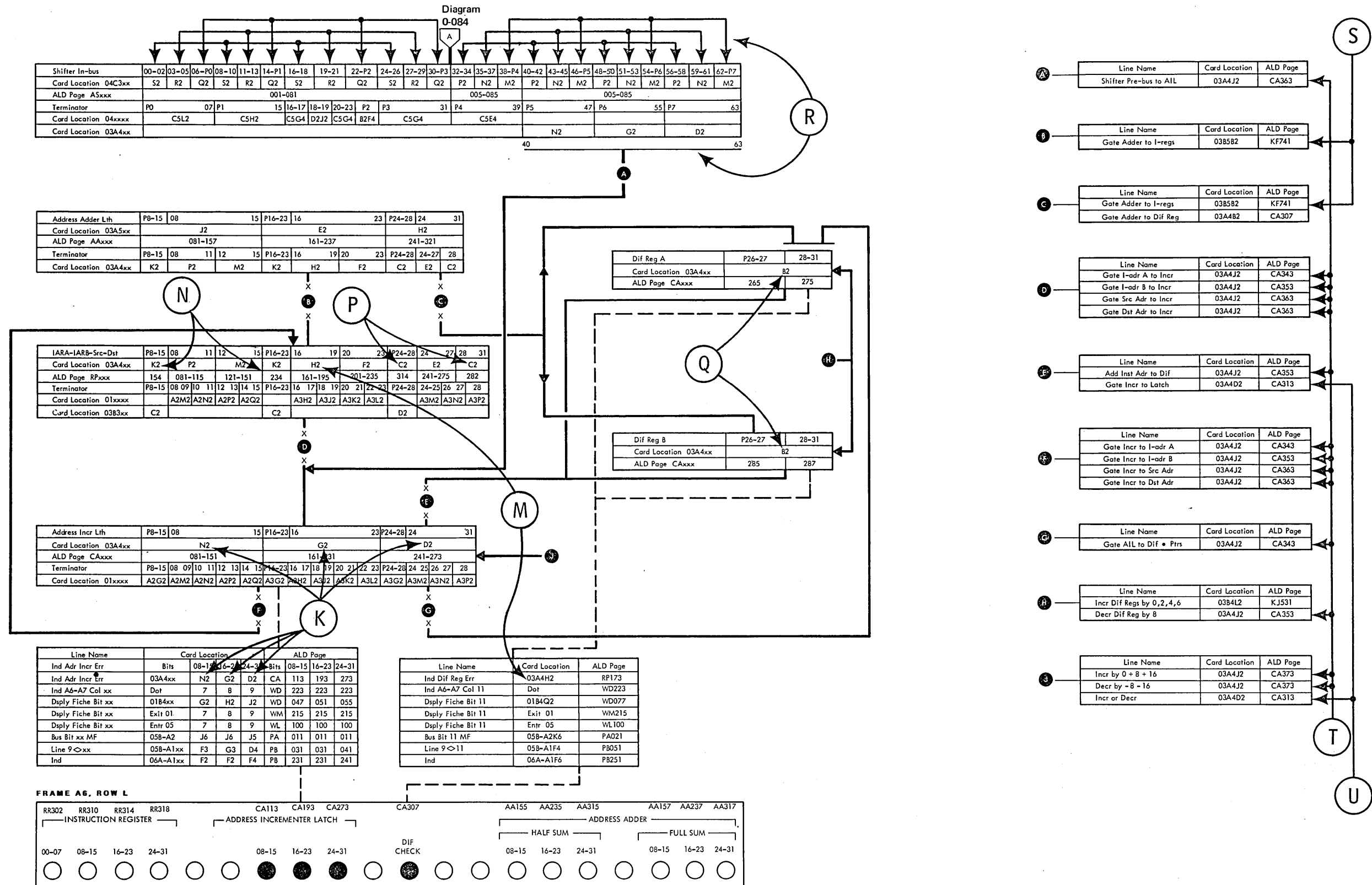


Figure 7-22. Address Incrementer Packaging

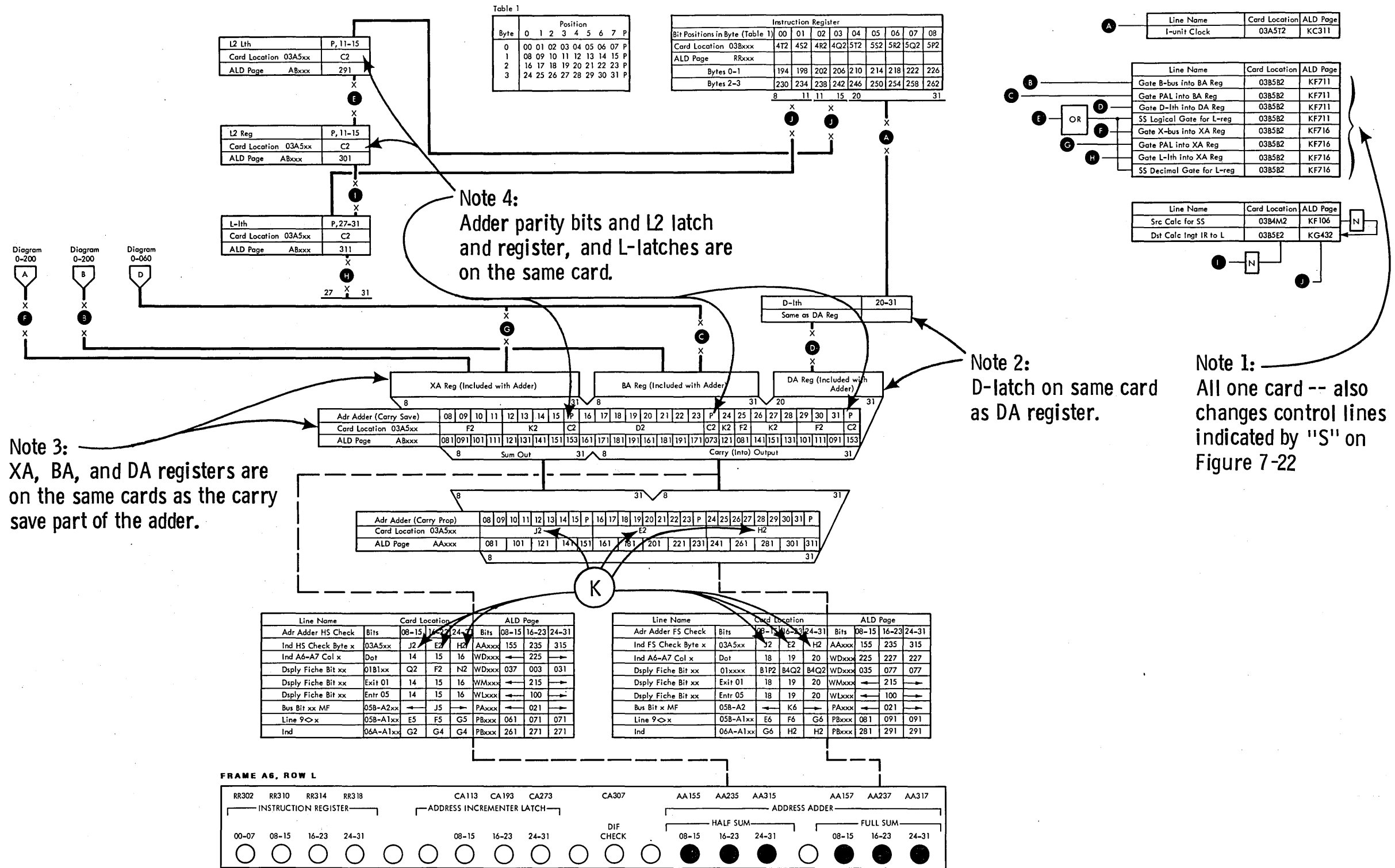


Figure 7-23. Address Adder Packaging

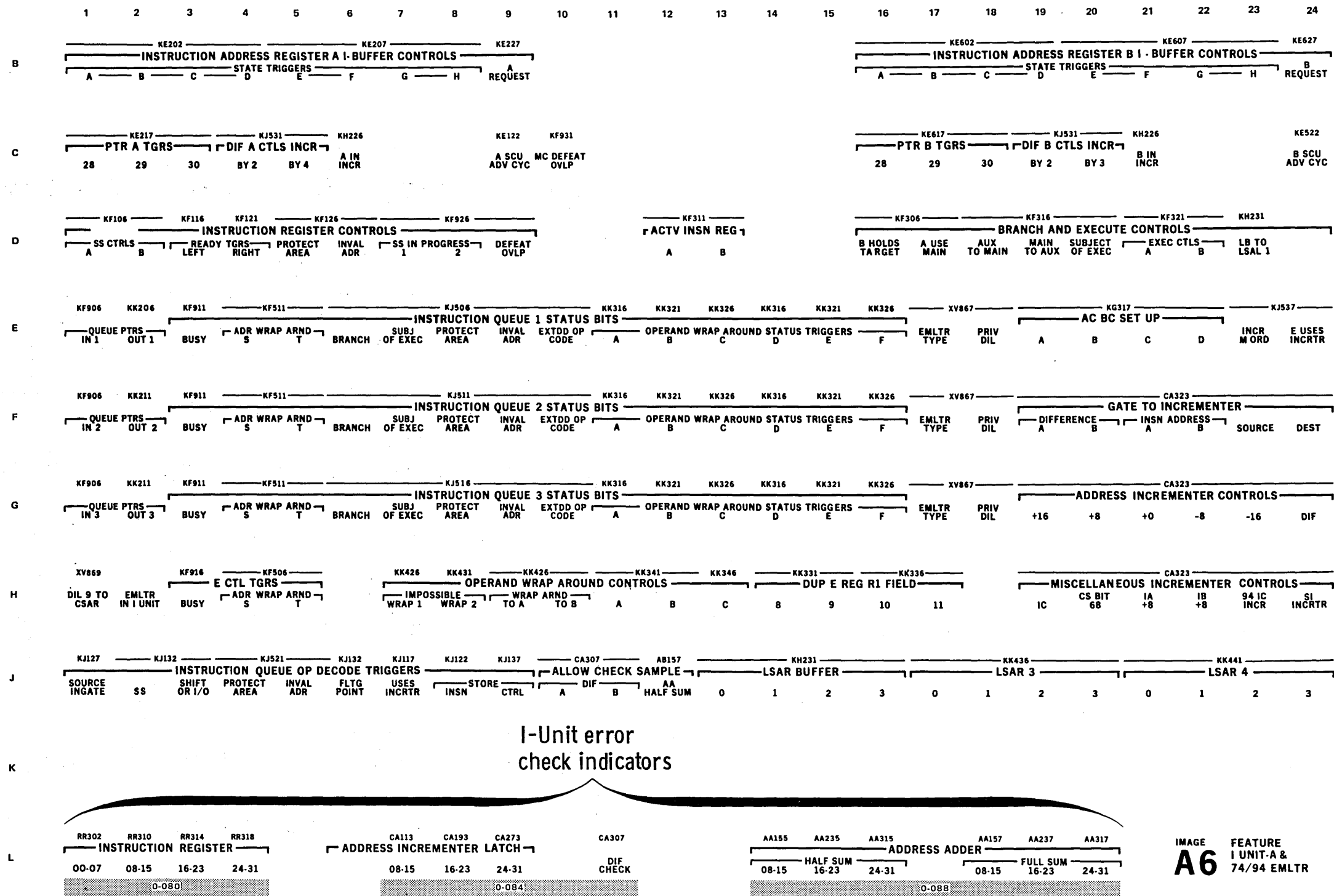


IMAGE FEATURE
A6 I UNIT-A &
 74/94 EMLTR

Figure 7-24. I-Unit Error Lights

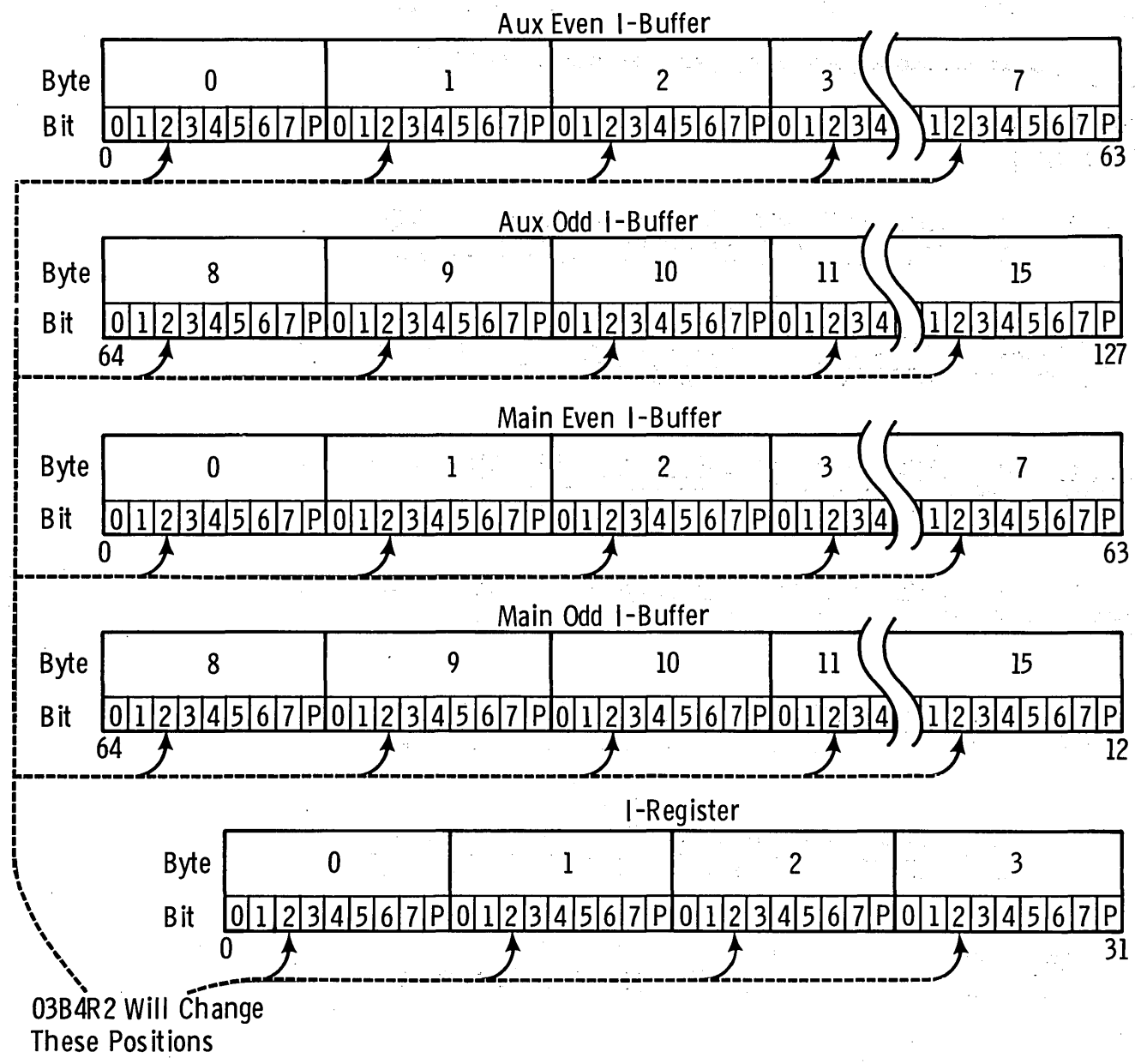


Figure 7-25 I-Buffer Functional Packaging

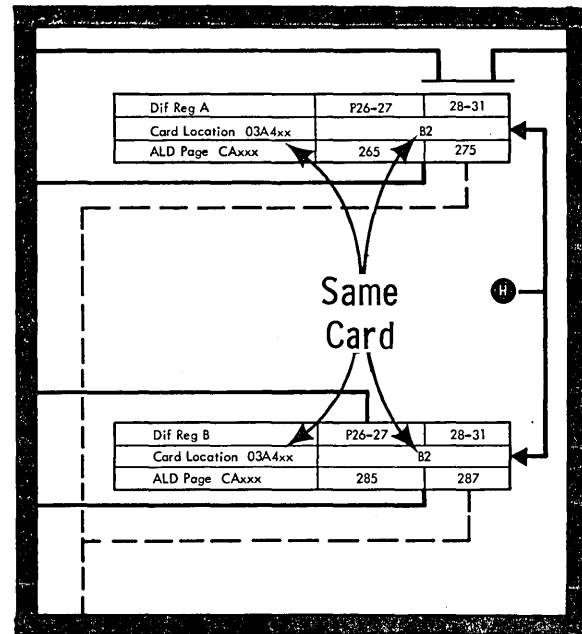
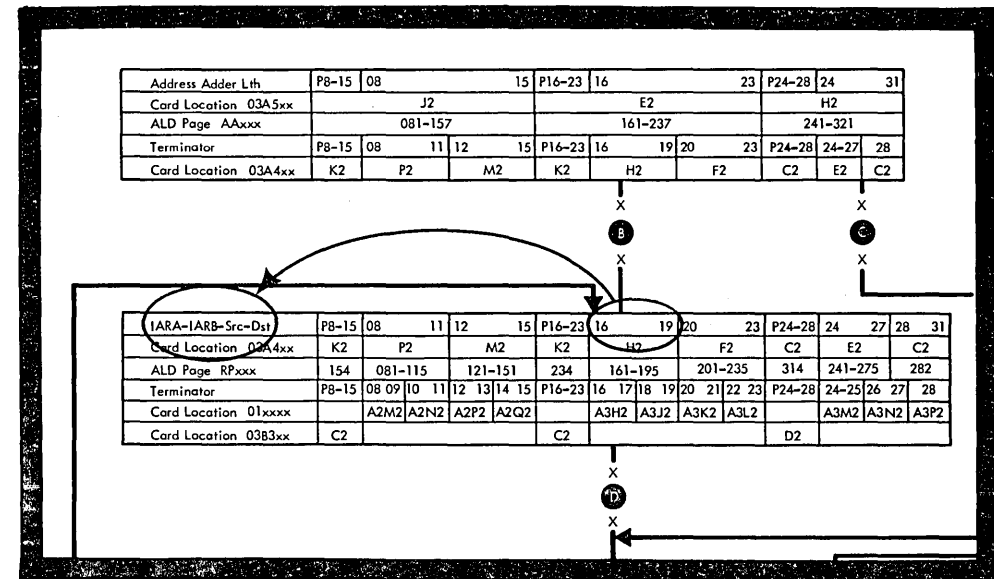


Figure 7-26. Session 7, Question 8 Remedial



This tells you that bits 16 to 19 of the SRC and DST registers, and IARA and IARB, are all on the same card.

Figure 7-27. Session 7, Question 7 Remedial

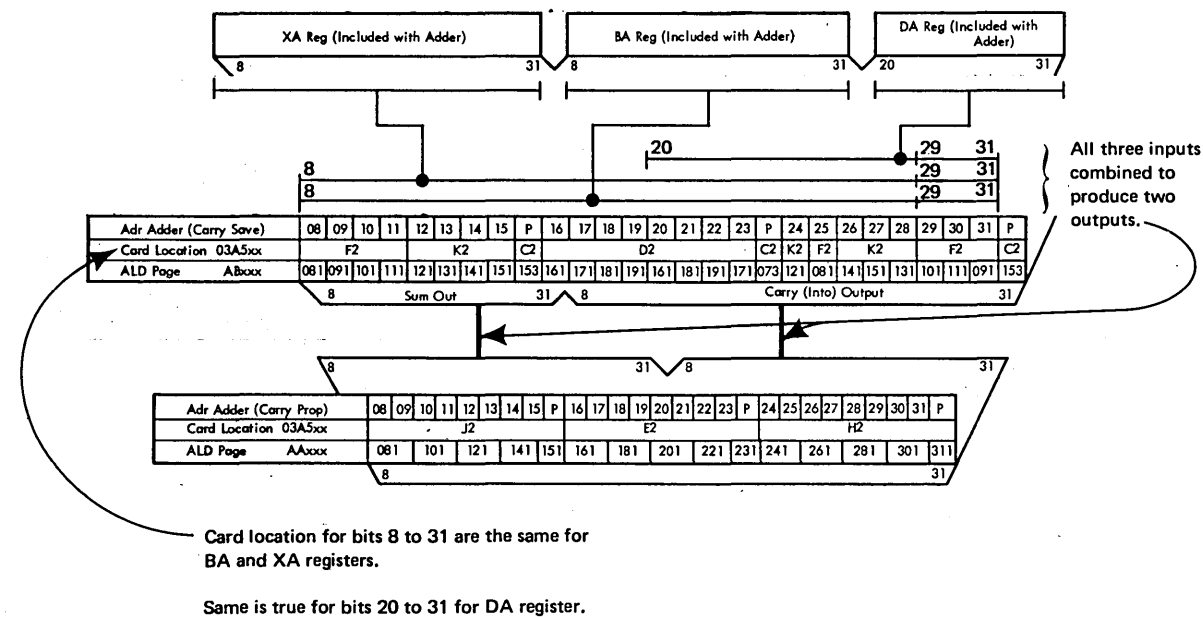
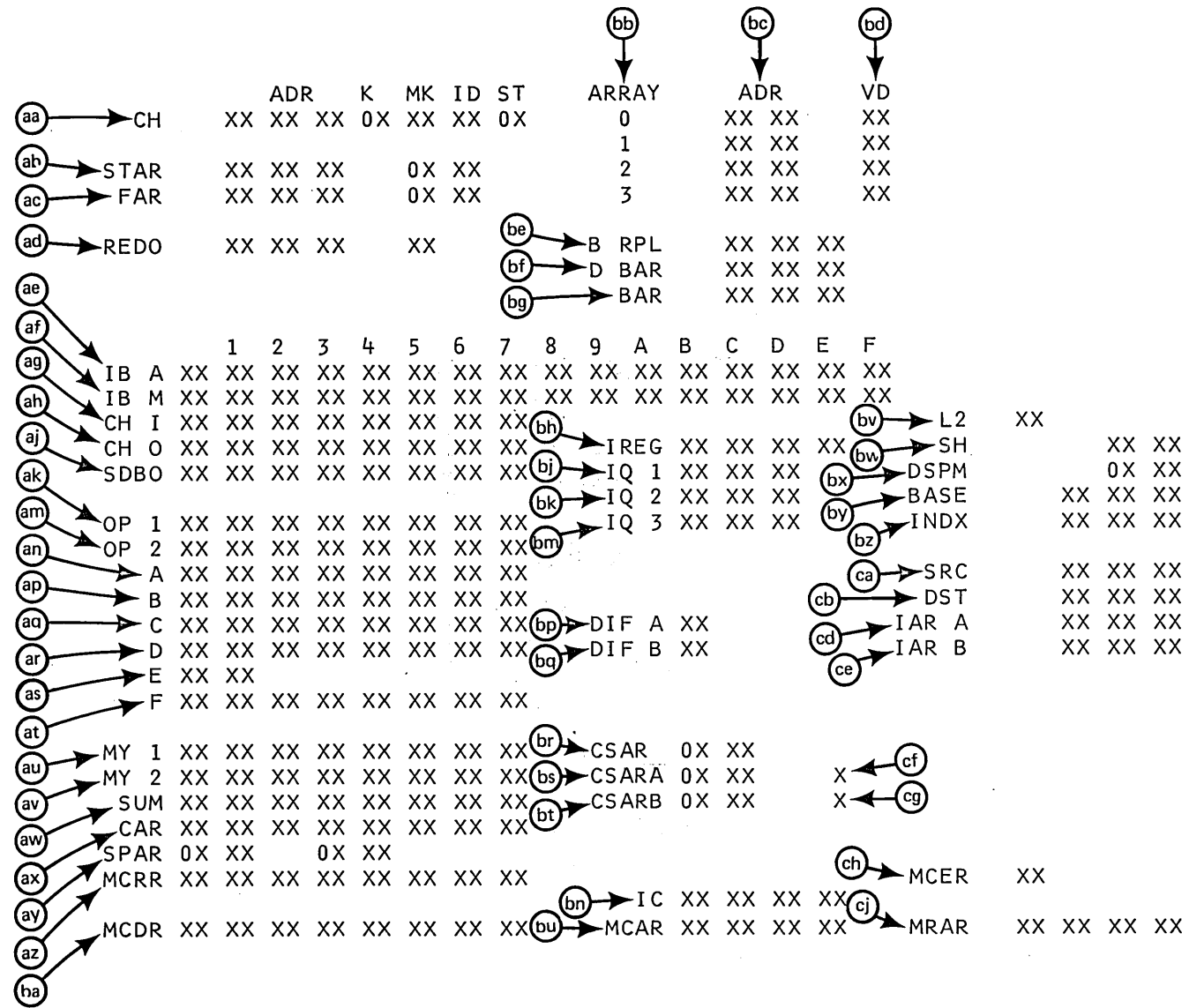


Figure 7-28. Session 7, Question 9 Remedial

PARTIAL LIST OF SYSTEM LOGIC UNITS

1. DBAR
2. Address Adder
3. LAR Buffer Latch
4. ACAL
5. MCDR
6. Buffer Bypass Latch
7. L2 Register
8. Parallel Adder
9. Channel Data-Out Buffer
10. A-Register
11. Shift Control Triggers
12. Destination Register
13. Main I-Buffer
14. A-Pointer
15. C-Register
16. STAR
17. FAR
18. Source Register
19. LAL5
20. F-Register
21. Instruction Queues
22. Serial Adder
23. MCWR
24. Difference Register B
25. CSAR
26. B-Register

Figure 8-1. Sesion 8, Question 1



RED-LIGHT ERRORS

1. Store Check
2. Hang Detect
3. Parallel Adder Halfsum Check
4. Parallel Adder Fullsum Check
5. Difference Check
6. I-Register Check
7. Address Adder Fullsum
8. Serial Adder Halfsum
9. E-Register Check
10. Address Adder Halfsum
11. Serial Adder Fullsum
12. Parallel Adder Carry Check
13. Parallel Adder Halfsum Word Check
14. Outkey Check
15. Buffer Array Check
16. Shifter Input Check
17. Address Incrementer Latch Check
18. Shifter Output Check
19. Non-Retry Storage Check
20. Shifter Control Check
21. Address Storage Check
22. Enter Error

Figure 8-2. Session 8, Questions 10 & 11

Figure 8-3. Session 8, Questions 19 & 20

1. Op I Register
2. CSAR
3. Shifter-In Bus
4. D-Register
5. C40 ROS
6. C50 WCS
7. Output Latch
8. PAL
9. CSDR
10. C-Register
11. LAL3
12. E-Register
13. CSAR A
14. ACAL
15. Mark Buffer Latch

Figure 8-4. Session 8, Question 22

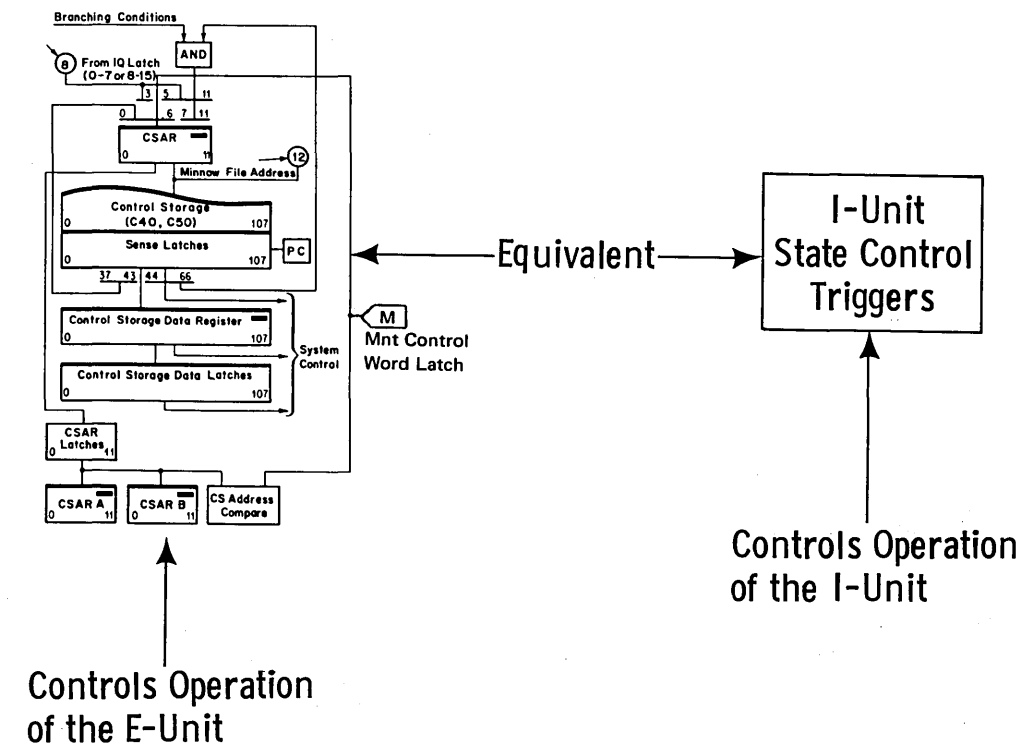


Figure 8-5. E And I-Unit Control Areas

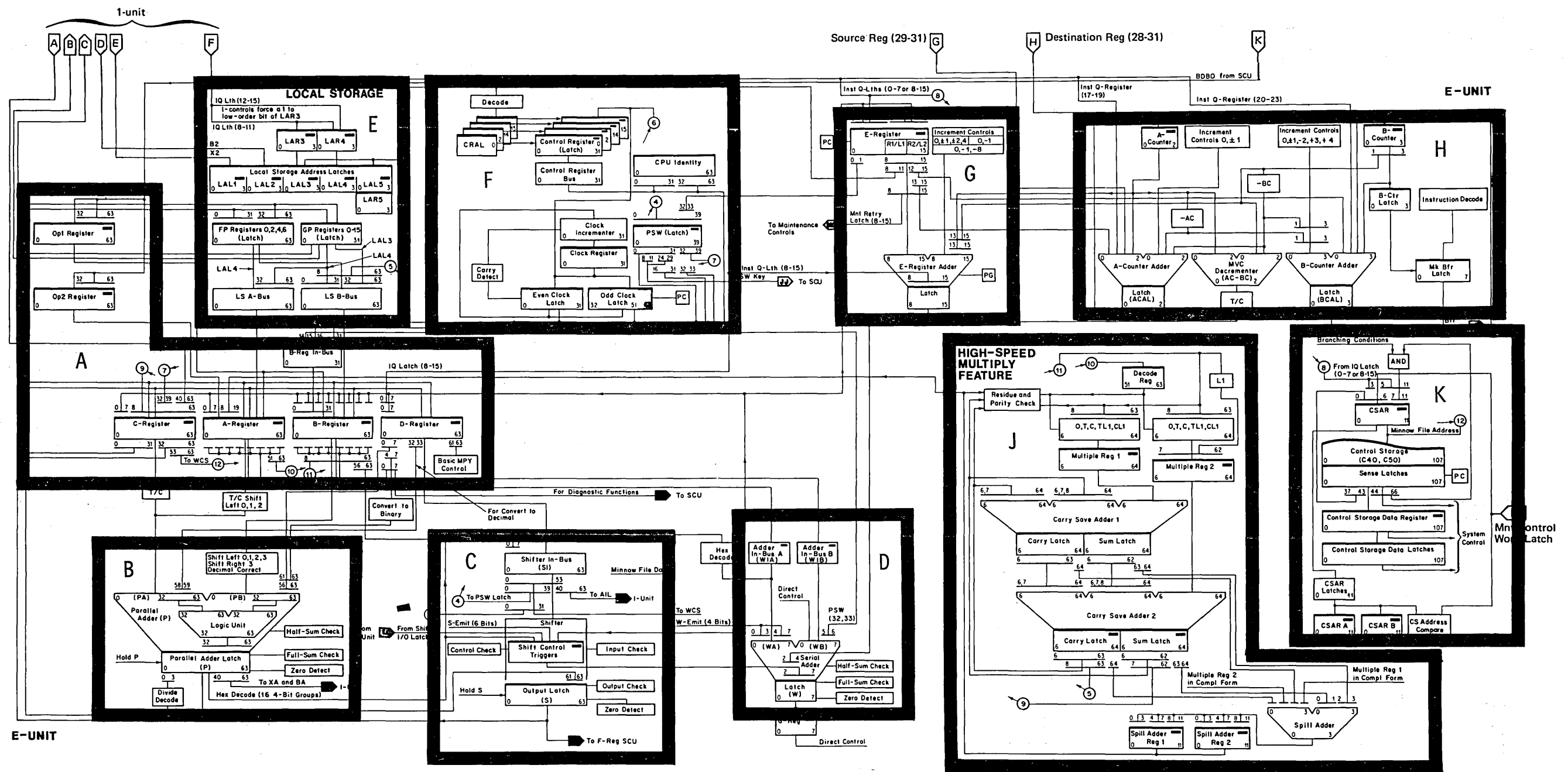
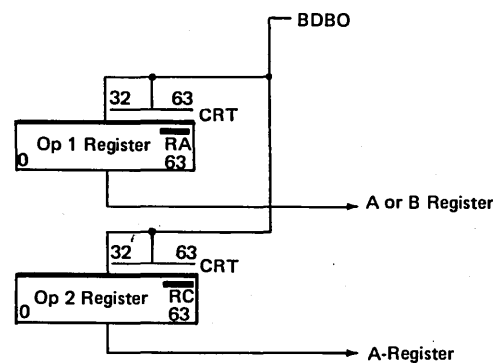


Figure 8-6. E-Unit Logic Units



OPERAND REGISTERS - OP 1, OP 2

The two eight-byte operand registers, referred to as operand register 1 and operand register 2, are used to buffer prefetched storage operands.

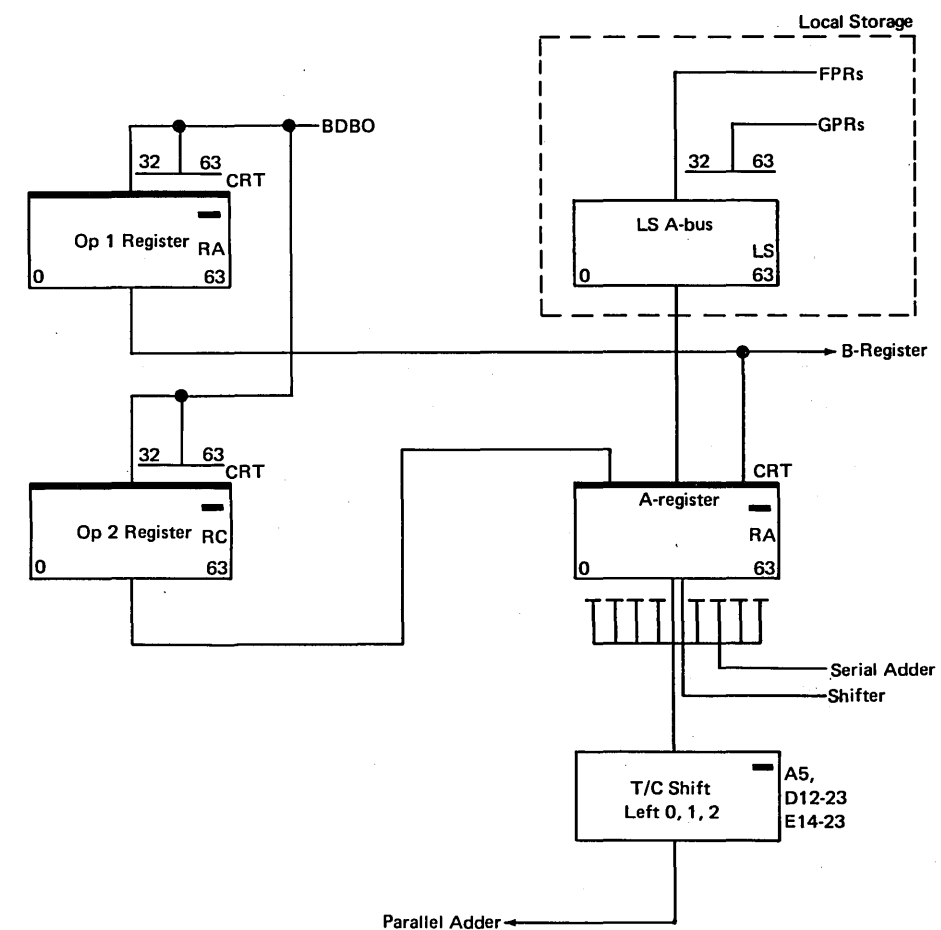
The only ingate to the buffers is the buffer data bus-out (BDBO), which may be gated directly or shifted right 32. The shift allows the I-unit to place all fixed-point and floating-point short operands in the right half of the buffers.

Ingating data to the registers is done by the I-unit.

Transfer of data from the operand registers to the working registers is dependent on the operation performed and upon which operand register contains the active data.

Operand buffer 1 can be gated to the A- or B-register; operand buffer 2 can be gated only to the A-register. This allows the I-unit to use either buffer for RX instruction setup. For SS instructions, operand buffer 1 is used solely for destination operands and operand buffer 2 is used only for source operands.

Figure 8-7. Operand Registers



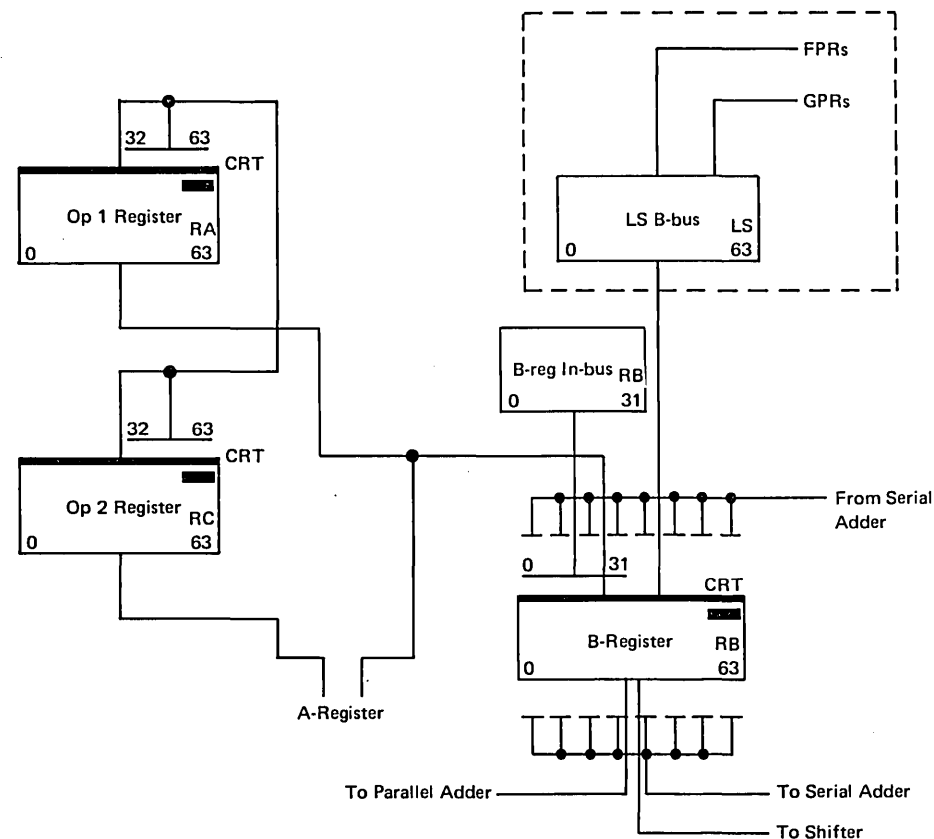
A-REGISTER

The eight-byte A-register is used primarily as the second operand register. The second operand is the contents of a local storage register, or the source operand for RR, RX, and SS formats.

Ingates to the A-register include the parallel adder, shifter, operand register 1, operand register 2, and local storage. The serial adder latch may be gated into the high-order byte of the A-register to handle floating-point characteristics.

The A-register can be outgated to the parallel adder (true or complement form) with shifts of 0, 1, or 2. The A-register also feeds the shifter and contains byte gates to the serial adder.

Figure 8-8. A-Register



B REGISTER

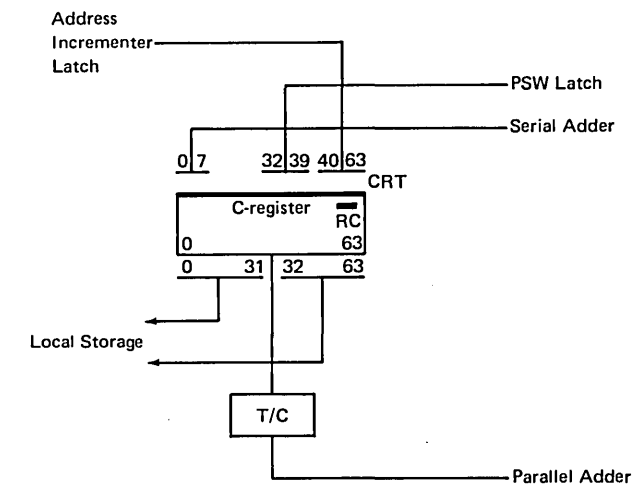
The eight-byte B-register is used primarily as the first operand register. The first operand is the content of a local storage register for RR and RX formats and the destination field for SS format.

The ingates to the B-register include the parallel adder, the shifter, operand register 1, local storage, the B-reg prebus and the byte ingates from the serial adder.

The B-reg prebus is a 32-bit bus to the high-order 32-bits of the B-register. This bus accommodates inputs from the PSW, the time of day clock, the control registers, the CPU identification and the machine check interruption code.

The B-register can be outgated to the parallel adder with a "right three" shift or a left shift of 0, 1, 2, and 3. The B-register also feeds the shifter and the serial adder by byte.

Figure 8-9. B-Register



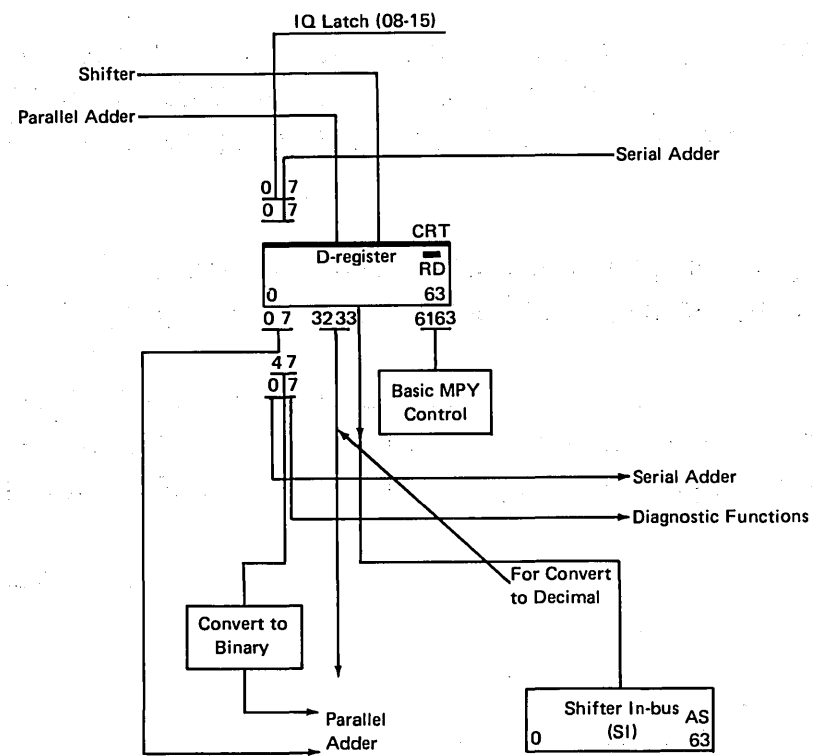
C-REGISTER

The eight-byte C-register is used primarily as a buffer facility to input data to the local storage. For those RR and RX format instructions that require a result to be placed in local storage, the result is held in the C-register and written in local storage during the first cycle of the next instruction. The C-register is used in fixed- and floating-point multiply to hold a multiple of the multiplicand.

The ingates to the C-register include the parallel adder, shifter, the I-unit address incrementer latch (used for Load Address, PSW handling, VFL instructions, and such, and the serial adder to the high-order byte (used in floating-point characteristic handling).

The C-register can be outgated to local storage and (in true or complement form) to the parallel adder.

Figure 8-10. C-Register

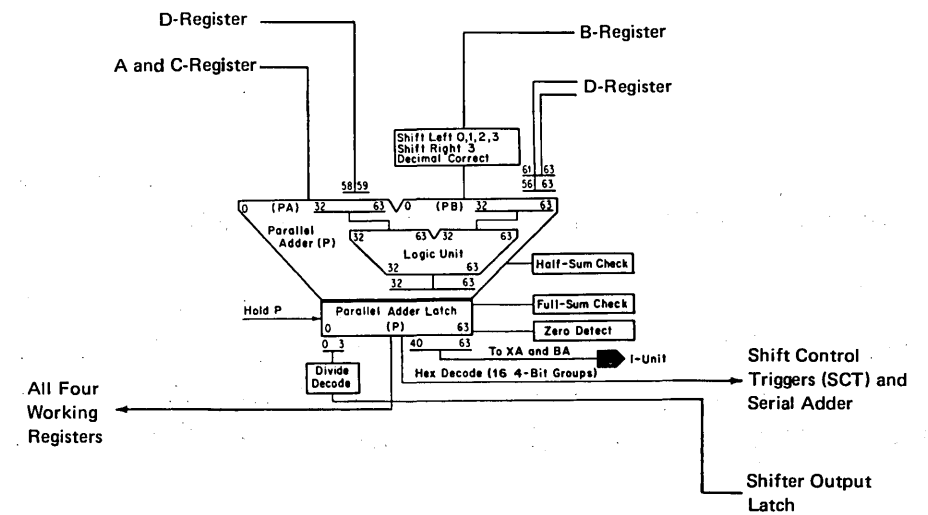


D-REGISTER

The eight-byte D-register is used for multiplier decoding in fixed- and floating-point multiply and as the quotient accumulator in divide instructions. The high-order byte may be ingated from and outgated to the serial adder and serves as a byte buffer for serial adder operations.

The ingates to the D-register include the parallel adder, shifter, and the serial adder (to the high-order byte). The high-order byte may be gated to the serial adder as previously mentioned.

Figure 8-11. D-Register



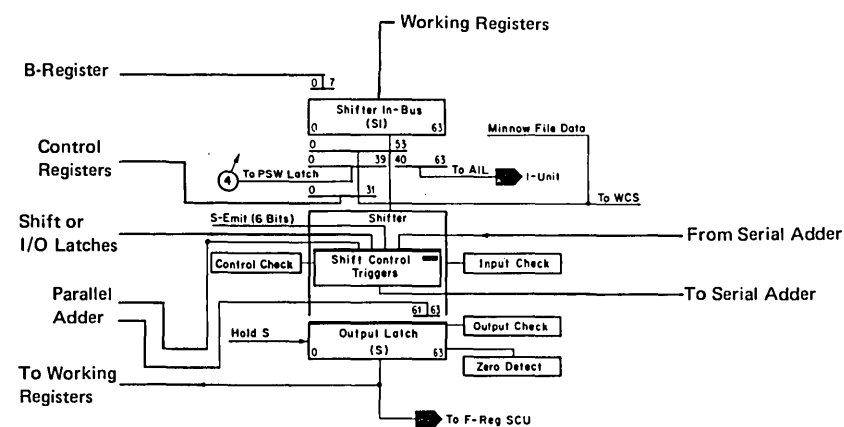
PARALLEL ADDER

The parallel adder is a 64-bit (plus parity) full-binary arithmetic unit. In addition to arithmetic operations, the parallel adder performs the following operations: four-byte-wide logical (AND, OR, exclusive OR), algebraic compare, convert-to-decimal (CVD), convert-to-binary (CVB), and simple data transfer. Error-checking facilities within the adder consist of: (1) a halfsum check that verifies the validity of the incoming data (operands) and (2) a fullsum check that verifies the validity of the adder result. As part of the fullsum check, parity is predicted on a byte basis. These parity bits accompany the adder result to its destination.

Important points concerning the adder are:

- Is 64-bit (plus parity) full-binary adder.
- Includes halfsum and fullsum error checking.
- Inputs are from A-, B-, C-, and D-registers.
- Outputs go to shifter, serial adder, address adder, and A-, B-, C-, and D-registers.
- Operation rate is one operation per machine cycle.
- Adder operates every machine cycle. If no register data is gated into the adder, zero bytes with good parity are forced through the adder.

Figure 8-12. Parallel Adder



SHIFTER

An eight-byte shifter in the E-unit displaces the bits of an operand from 0-63 positions to the right or left for fast data alignment, multiplication, and division. The shifter is also used as a "feed-thru" device to transfer data from one arithmetic register to another. It performs left or right, arithmetic, or logical shifts. If a left shift is given, bits are moved from low-order to high-order positions, and vice versa for a right shift. On arithmetic shifts, the sign bit is propagated as the operand is shifted; during logical shifts, the sign is shifted in the same manner as other bits (zeros fill in vacated positions).

The shifter requires only one machine cycle to perform a shift operation, regardless of the number of positions shifted. Thus, any Shift instruction can be executed within one CS cycle.

The shifter is logically divided into six stages: shifter in-bus, stage A, stage B, stage C, stage D, and the shifter output latches. The shifter in-bus (SI) provides the ingating from the E-unit arithmetic registers. Shifter-stages A-D perform the actual shifting operations. Data is gated to SI, filters through the shifter stages, and is then set into the output latches. Each stage shifts the data a different amount. The contents of the shifter output latches are gated to the A-, B-, C-, D-, or F-register.

Figure 8-13. Shifter

SHIFT CONTROL TRIGGERS (SCTs)

The direction (left or right) of shifts, the number of positions shifted, and sign propagation are controlled by shift control triggers (SCTs). The SCTs are a "left shift" trigger which is on for left shifts and off for right shifts, a "shift single arithmetic" trigger which is on for a word-length operand during an arithmetic shift operation, a "shift double arithmetic" trigger which is on for a doubleword length operand during arithmetic shifts, and three groups of four SCTs which control the number of positions shifted. Each group of the last-mentioned SCTs is associated with a certain stage of the shifter. The SCTs associated with stage B cause the operand to be shifted 0, 1, 2, or 3 positions in stage B; the SCTs associated with stage C cause the operand to be shifted 0, 4, 8, or 12 positions in stage C; and the SCTs associated with stage D cause the operand to be shifted 0, 16, 32, or 48 positions in stage D.

The SCTs are set up by micro-orders that specify an operation to be performed by the shifter. For most shifts, the shift amount is ingated from a specific register, is decoded, and is sent to stage B, C, and D SCTs. One SCT is set in each of these three groups. The arithmetic and left shift triggers are set according to the operation.

Figure 8-14. SCTs

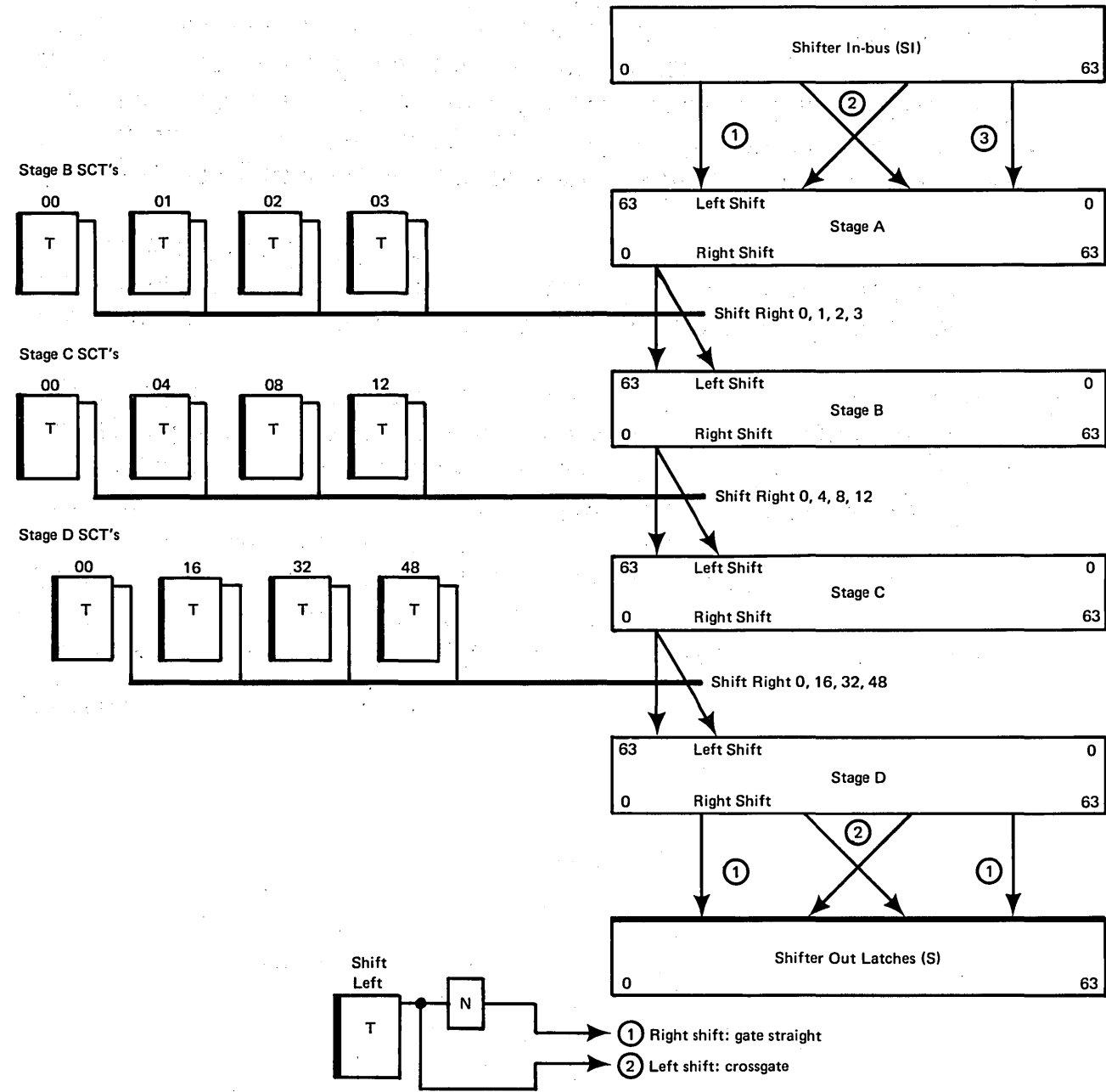
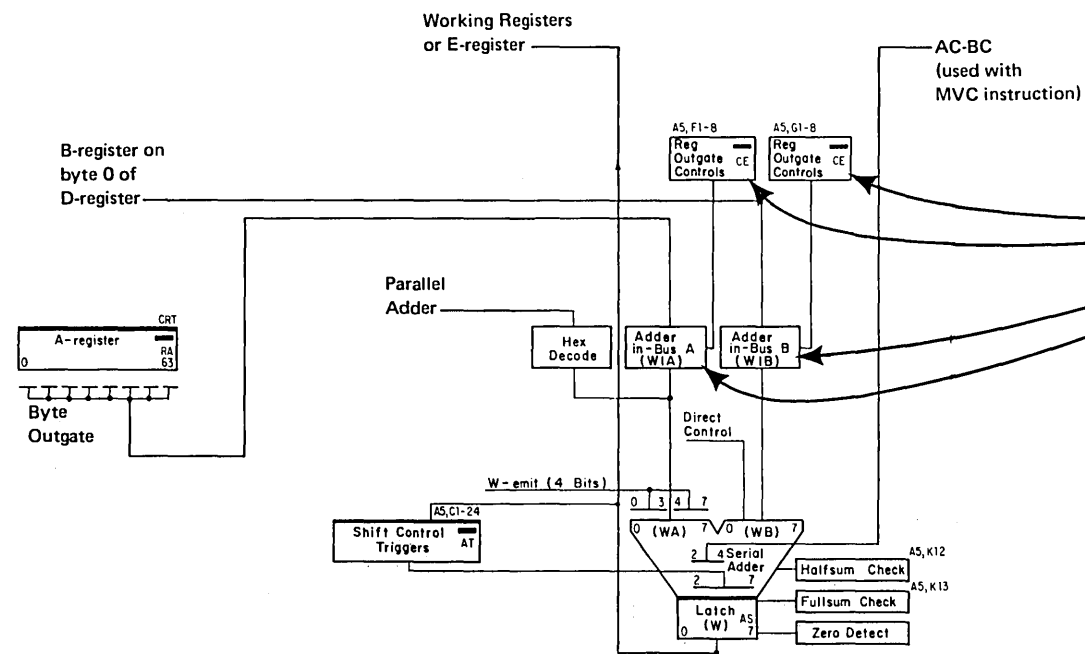


Figure 8-15. Shifter Stages



Preliminary Input Buses, WIA and WIB

A particular A-register byte is selected for outgating to WIA by turning on one of eight gate control triggers ('A GCT 0' through 'A GCT 7'). Decoding of ACAL determines which of these GCTs turns on. A particular B-register byte or byte D0 is selected for outgating to WIB by turning on one of nine GCTs ('B GCT 0' through 'B GCT 7' and the GCT for D0). The control program determines whether a B-register byte or byte D0 is selected, and decoding of BCAL determines which of the B-register GCTs turns on.

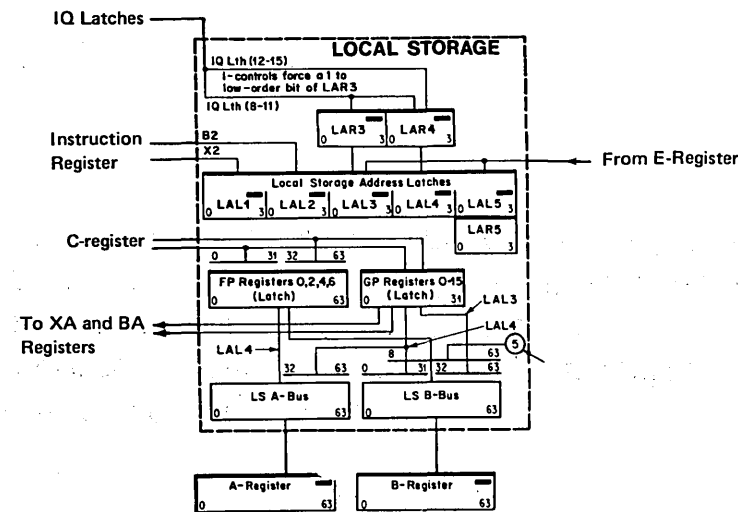
SERIAL ADDER

- Handles information on a byte basis.
- Processes information from the A-register, the B-register, and byte D0.
- Operation rate is one operation per machine cycle.
- Adder proper must add in every cycle. In serial-adder no-op cycles, zero is added to zero and good parity is forced into the 'W parity' latch.

The primary function of the serial adder is to perform arithmetic operations (binary or decimal) and logical operations (AND, OR, or Exclusive OR) on two one-byte-wide operands. The miscellaneous functions of the serial adder include the following:

1. Check for valid decimal data and sign.
2. Generate preferred decimal signs and zones.
3. Produce constants or increments by use of the four-bit emit field in control storage.
4. Post-normalize the floating-point characteristic. To enable this, the parallel-adder-hex-decode constant is placed on WA for addition to the characteristic that is entering the serial-adder B-side from D0.
5. Act as a straightforward data path. This is done by adding zero to data that is being routed through the serial adder. Further, the data that is being thus routed may be manipulated by cross-gating or by gating only one of the two incoming digits.
6. Decode the pattern characters for the Edit instruction.

Figure 8-16. Serial Adder



LOCAL STORAGE

A high speed local storage (LS) reduces the number of main storage references that are required by the CPU during each operation. Local storage consists of 20 latch registers: 16 general-purpose registers (GPRs) for fixed-point operands and addressing components and four floating-point registers (FPRs) for floating-point operands. The GPRs are fullword registers (32 bits); the FPRs, doubleword registers (64 bits). Information can be stored in or fetched from an LS register during one machine cycle (80 nsec), and up to four LS fetch (plus one LS store) operations can occur simultaneously. In other words, LS can be accessed from four sources and written into from one source during a single machine cycle.

The 16 GPRs can be used as base and index registers in address calculations and indexing and as accumulators in fixed-point arithmetic and logical operations. The four FPRs are used for floating-point operands and are used only during execution of floating-point instructions.

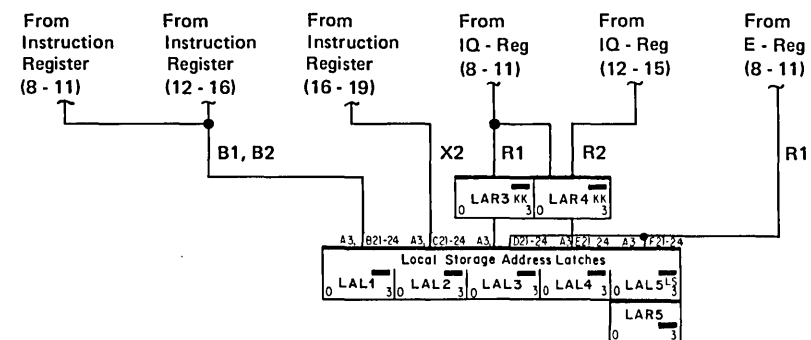
Figure 8-17. Local Storage

Local storage is shared by the I-unit and the E-unit in their efforts to set up and execute instructions, respectively. Therefore, to provide complete I-unit/E-unit overlap and the ability to process an instruction in one cycle, four GPRs can be read and a fifth can be written into the same cycle. This multiple-accessing ability of LS allows the operand put-away initiated by one instruction to be overlapped with the execution of the next instruction. In addition, execution of an instruction may require that the contents of one or two LS registers be fetched at the same time that the I-unit is calculating an effective address, which may also require the use of one or two registers of LS.

The I-unit accesses LS for two operations: E-unit setup and address calculations. When an instruction is passed from the I-unit to the E-unit, the E-unit registers must be setup with the values needed to begin instruction execution. Setup includes fetching operands from local storage and ingating them into the A- or B-register as required. To perform address calculations, the I-unit contains a three-input address adder. Two of the three principal inputs to address-adder input registers are two local storage buses, LS-X-data bus and LS-B-data bus. During the instruction decode cycle, the contents of the required GPRs are fetched from LS, and the other addressing components to be added are set up. The addressing components are ingated to the adder input registers (XA, BA, and DA), and the add occurs, producing a main storage address which is sent to one of the I-unit address registers.

LS fetches by the E-unit are always for operands. As directed by the control program in the E-unit, the contents of the specified GRP or FPR are gated to the A- and/or B-register, as required. Local storage stores are always performed by the E-unit. The control program gates the contents of the C-register to the specified GPR or FPR.

Figure 8-18. Local Storage



LOCAL STORAGE ADDRESS LATCHES

Read addressing is performed by four sets of local storage address latches: LAL1, LAL2, LAL3, and LAL4; write addressing is performed by local storage address register 5 (LAR5).

LAL1 addresses LS to fetch the index component of an effective address. The index component is a 24-bit number contained in a GPR that is specified by the X-field of an RX format instruction. When LAL1 is addressed from the I-unit instruction register, data from the specified GPR is gated to the I-unit XA register.

LAL2 addresses LS to fetch the base-address component of an effective address. The base address is a 24-bit number contained in a GPR that is specified by the B-field of an instruction that references main storage. When LAL2 is addressed by the I-unit instruction register, data from the specified GPR is gated to the I-unit BA register.

LAL3 addresses LS for GPR and FPR fetches to the B-register. If the I-unit initiates the operation, the address is received from the IQ register via LAR3. If the E-unit initiates the operation, the address is received from the E-register.

LAL4 addresses LS for GPR and FPR fetches to the A-register and to bytes 0-3 of the B-register. If the I-unit initiates the operation, the address is received from the IQ register via LAR4. If the E-unit initiates the operation, the address is also received from the IQ register via LAR4. (LAR4 can be addressed from the E-unit only on the first cycle of an instruction execution.)

LAR5 addresses LS for GPR and FPR stores. The contents of E (8-11) are always used to address LS on a write operation via LAL5. LS stores are controlled by the E-unit.

Figure 8-19. LS Address Latches

CALENDAR CLOCK

- Programmer can read precision calendar time.
- 52 latches provide 135-year cycle.
- One-microsecond increments are independent of other system activities.
- Parity check assures clock validity.
- Security switch reduces chance of erroneous update.

The calendar clock provides a high-precision calendar time to the programmer. The clock is set by the system programmer and a switch on the console helps assure its security. A programmer can read (store) the clock at any time.

The calendar clock is a 52-bit counter increased by one every microsecond. Each clock advancement is independent of other CPU and channel activities. The clock content ranges from one microsecond to 135 years. Clock overflow is recorded but no interrupt condition is provided.

Bits 0 through 51 of a doubleword latch arrangement provide the binary storage needed to count to 135 years by microseconds. The doubleword latch is advanced each microsecond by adding 1 to bit 51. Bits 52 through 63 retain the status originally set, while bits 0 through 51 hold the binary representation of the current time of day.

The programmer reads the clock by means of the store clock instruction. Store clock reads the current calendar time and puts it in main storage. Reading and storing the clock does not affect the content of the latches or the incremental activity.

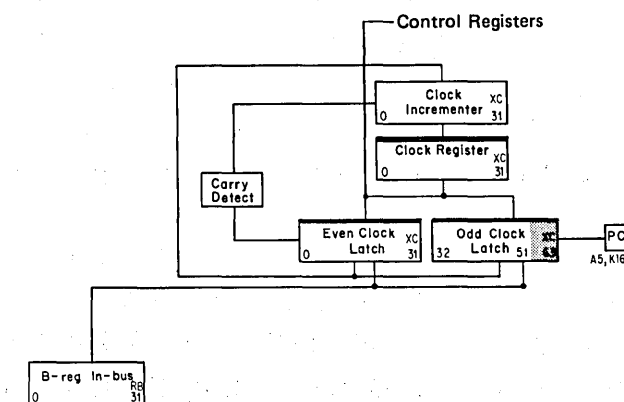


Figure 8-20. Calendar Clock

CPU IDENTITY REGISTER

- Register is composed of jumper wires.
- Programmer requests readout.

The CPU identity register provides processor identification to the system programmer. The programmer requests CPU identification and the control storage microprogram routines transfer the data to main storage. The CPU identity register is composed of jumper wires. The bits, when tied up, represent the desired data. Any arrangement may be set into the register for CPU identification; however, the data set into the register can not be readily changed.

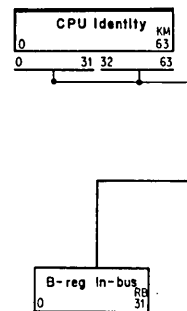


Figure 8-21. CPU Identity Register

CONTROL REGISTERS

Extended system control requires four of sixteen control registers. The control registers, accessible to the system programmer, are addressed 0, 2, 14, and 15. The four control registers provide extended control of external masks, channel masks, error recovery and logout.

Control registers are not addressable as part of main storage. The programmer must store the register data in main storage when required; but the store operation does not affect the content of the registers. The programmer must load data from main storage to change the register content. Store and load instructions provide the only control-register access method available to the programmer.

Store and load operations employ control storage microprogram concepts. When control registers read out (microprogram control) the data transfers to working register B for further manipulation.

Control address latches and registers select the desired control registers and gate the control register word (32 data bits and four parity bits) onto the control register bus. When loading, data enters the control register latches via the shifter in-bus.

The program status word (PSW) mode gates the control registers. Extended control mode (PSW bits 12 is one) allows system control through control register mask bits, while basic control mode (PSW bit 12 is zero) negates the content of the control registers. System programmer access to the control registers requires the following RS instructions: load control, LCL; store control, STCL.

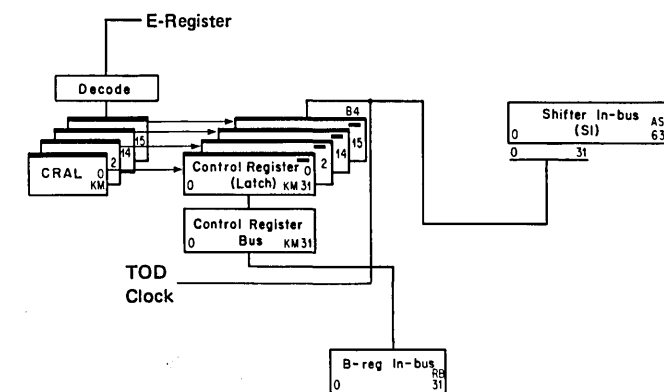


Figure 8-22. Control Registers

PROGRAM STATUS WORD LATCH

The PSW latch has 40 latches to hold the current PSW data. When a new PSW is set, bits 0 through 15 and 36 through 39 are set into the corresponding PSW latches. The PSW control data is then available for system control during the entire clock cycle for every clock cycle until the next PSW is set. When an interrupt occurs, the remaining PSW latch bits are set to reflect the interruption code, the instruction length code (ILC), and the condition code (CC).

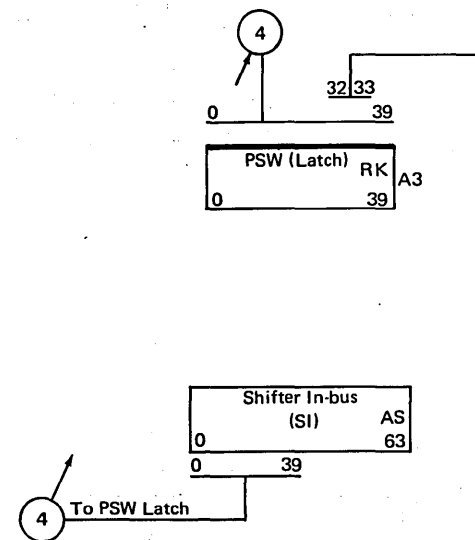


Figure 8-23. PSW Latch

E-REGISTER AND ADDER

The E-register adder increments or decrements bits 8-15 of the instruction in the E-register during execution of VFL, load multiple, and store multiple instructions. This adder can increment or decrement bits 8-15, which correspond to the R1/R2, R1/R3, L1/L2, or L fields of the instruction (depending upon the format), as two separate four-bit values (8-11 and 12-15) or as one value under microorder control. Bits 8-11 can be incremented or decremented by 1, 2, or 4; bits 12-15 can be decremented by 1 only; and, when considered as a single field, bits 8-15 can be decremented by 1 or 8. In addition, bits 8-15 can be decremented by the contents of ACAL or BCAL. Note that data that is gated into the E-register adder is always bits 8-15 of the instruction, whether the input is from the E-register or the instruction queue register.

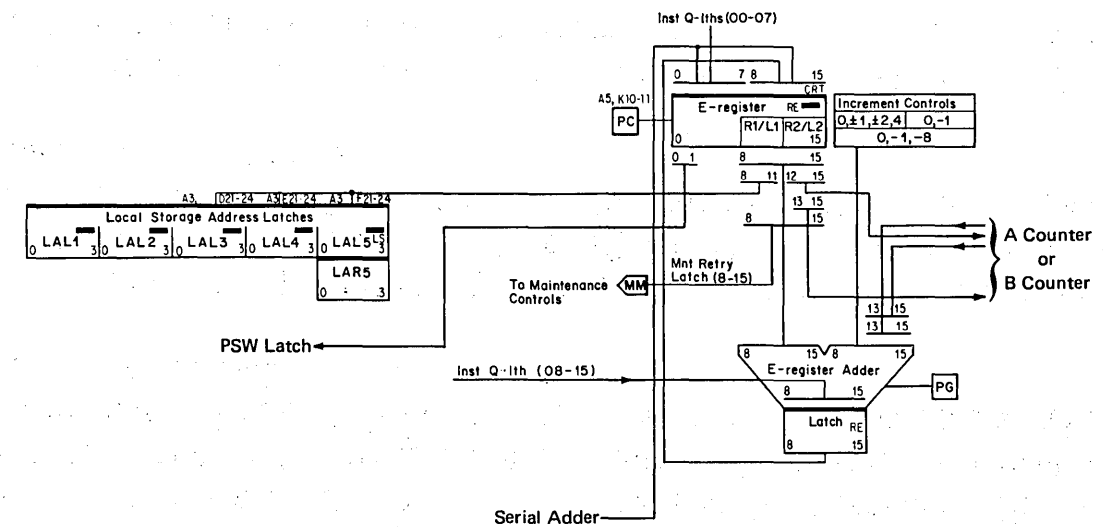
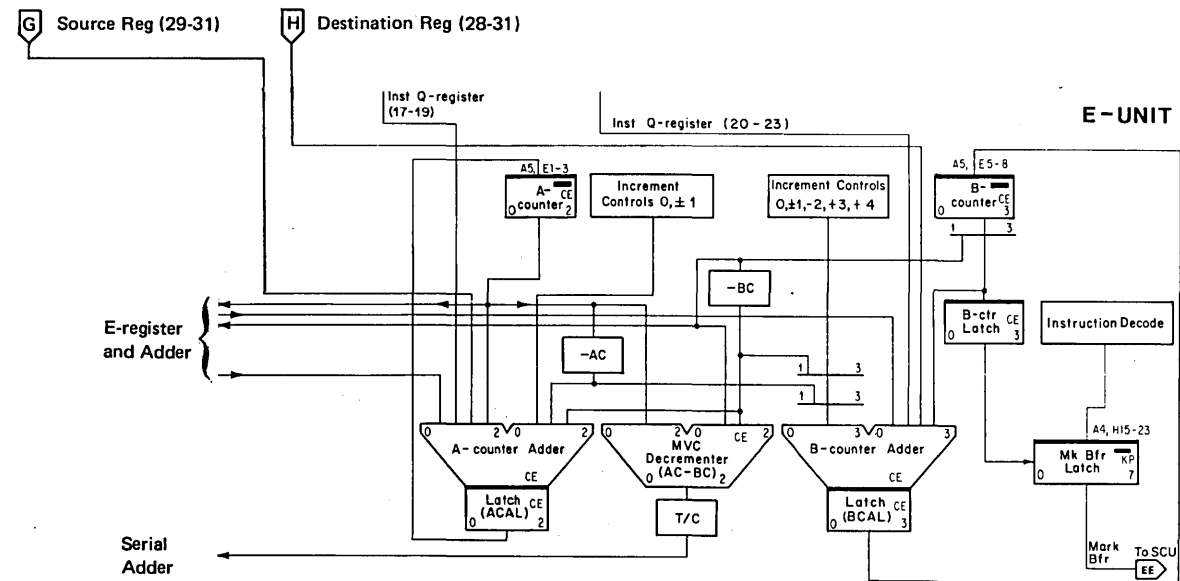


Figure 8-24. E-Register And Adder



A-COUNTER

The AC consists of a three-bit register, a binary adder (A-counter adder), and adder latches (ACAL). These components perform operations on values of 000 through 111, that can be incremented, decremented, complemented, or have other values added to them via the A-counter adder. In operation, these binary values (000 through 111) specify A-register bytes 0-7 for gating to the serial adder. The AC also serves as a general-purpose counter to hold the low-order three bits of source address values for byte locations during execution of VFL instructions and for specification tests during execution of RX format instructions.

Initial values are gated to the A-counter adder under control storage or I-unit control from E (13-15), Src (29-31), or IQ (17-19). In addition, initial values of 000, 001, or 111 can be set into the A-counter adder by means of the increment controls.

For control of the A-register bytes that are gated to the serial adder, the contents of ACAL are gated to a decoder which sets an A-register gate control trigger per the decoded ACAL value. This occurs every cycle; thus, when a control storage microorder is issued that gates an A-register byte to the serial adder, the gated byte is dependent upon which gate control trigger is set and, hence, on the value in ACAL.

B-COUNTER

The BC consists of two four-bit trigger registers (BC and BCAL triggers), a binary adder (B-counter adder), and two latch registers (BCAL and BCL). These components gate a byte of data from the B-register to the serial adder and ingate a byte of data from the serial adder to the B-register. The BC also serves as a general-purpose counter to hold the four low-order bits of the destination address. This latter usage enables the BC to be used to set marks for storage operations.

Initial values are gated to the B-counter adder under control storage or I-unit control from E (12-15), Dst (28-31), or IQ (20-23). In addition, initial values of 0, 1, 3, 4, E, and F (hex) can be set into the B-counter adder by means of the increment controls.

For control of the B-register bytes that are gated to the serial adder, the contents of BCL (01-03) are gated to a decoder which sets a B-register gate control trigger per the decoded BCL value. This occurs every cycle; thus, when a microorder is issued that gates a B-register byte to the serial adder, the gated byte is dependent upon which gate control trigger is set and, hence, on the value in BCL.

B-register ingating from the serial adder is under control of BCL (B-counter latch). The contents of BCL are decoded to select the specified byte of the B-register to which data from W is gated.

AC-BC DECREMENTER

The AC-BC decrementer is a three-position binary adder that sets up proper shift amounts in W during execution of the MVC instruction.

Figure 8-25. AC And BC

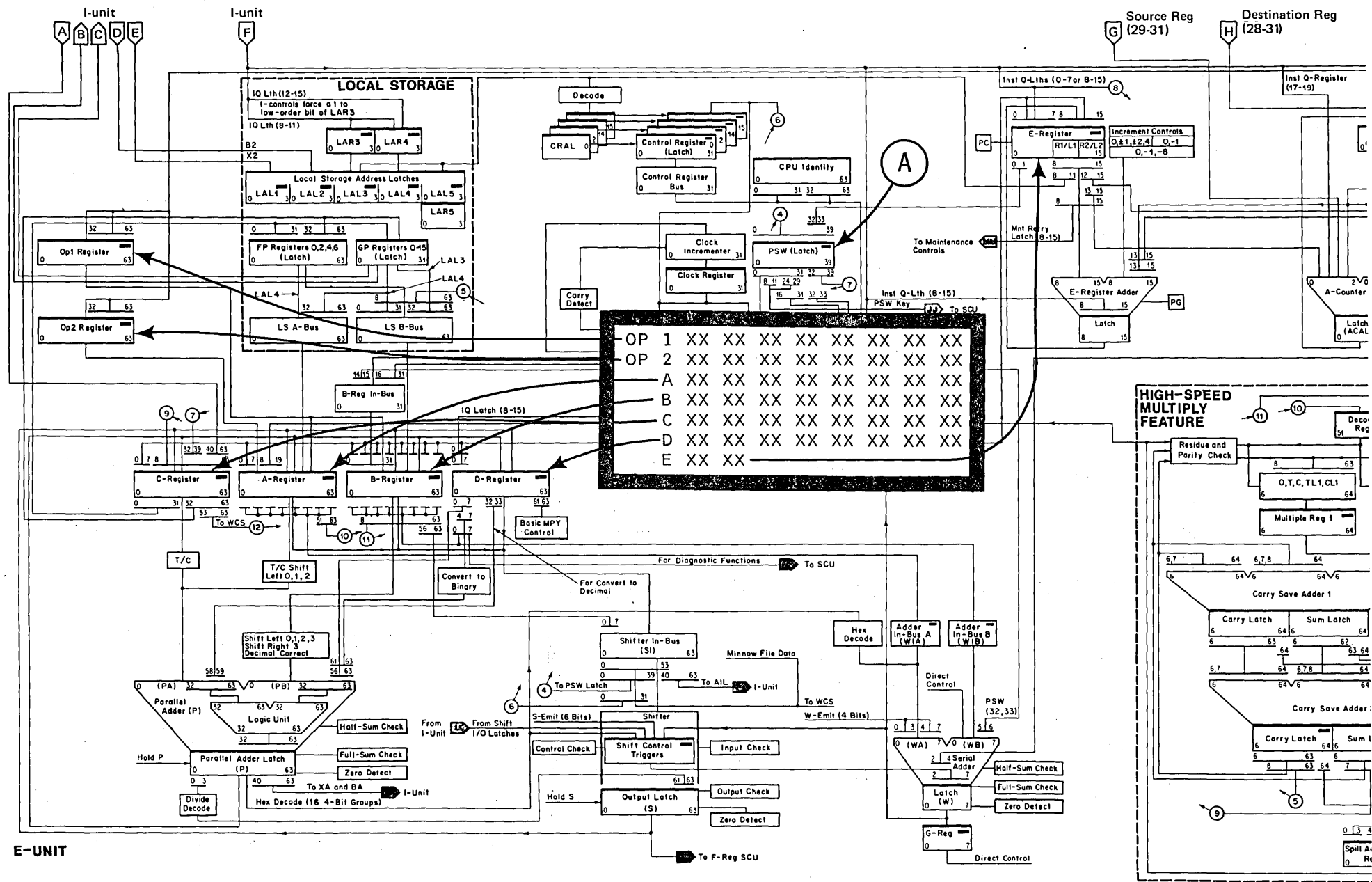


Figure 8-26. OP And Working Registers

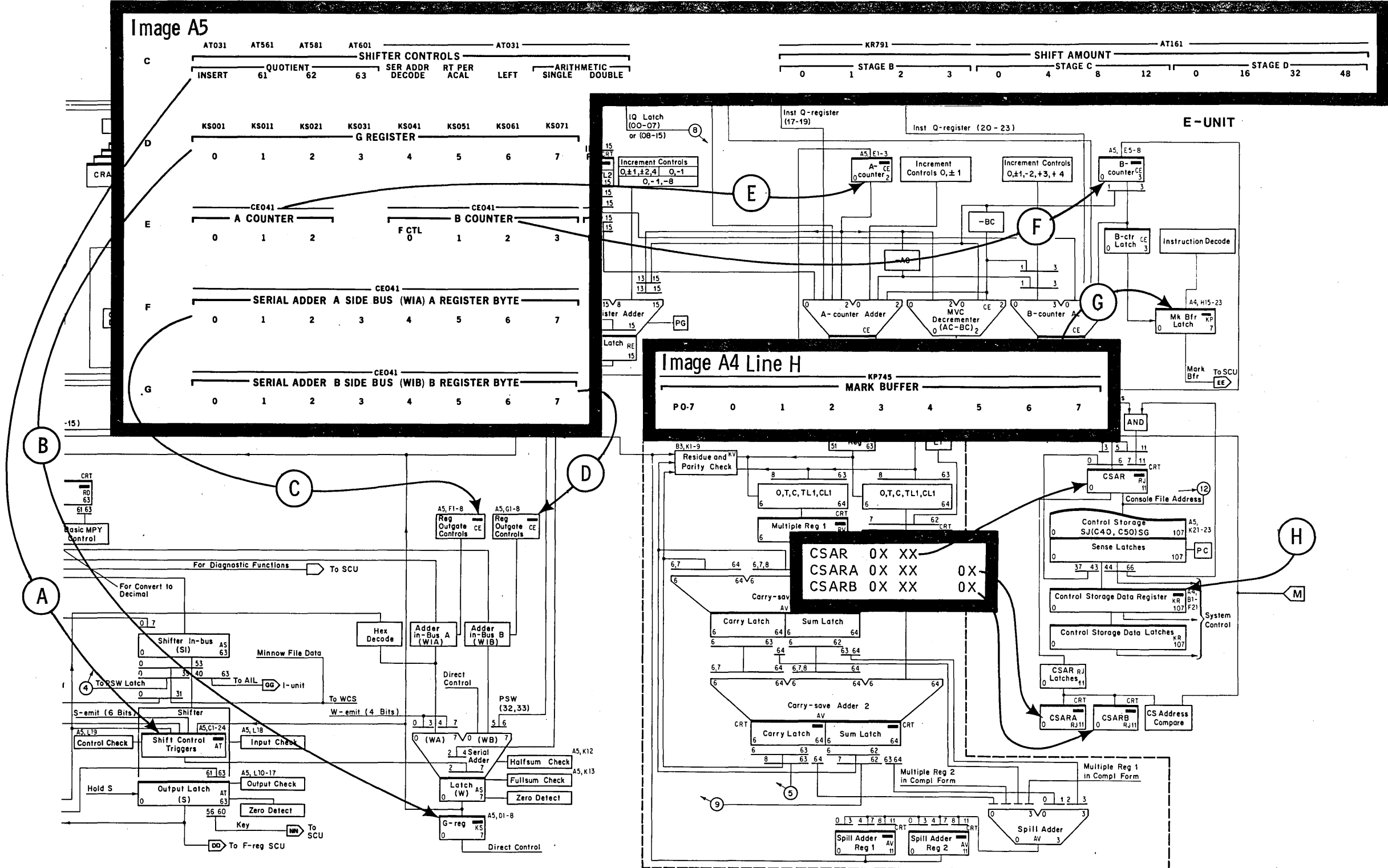


Figure 8-27. Misc Display

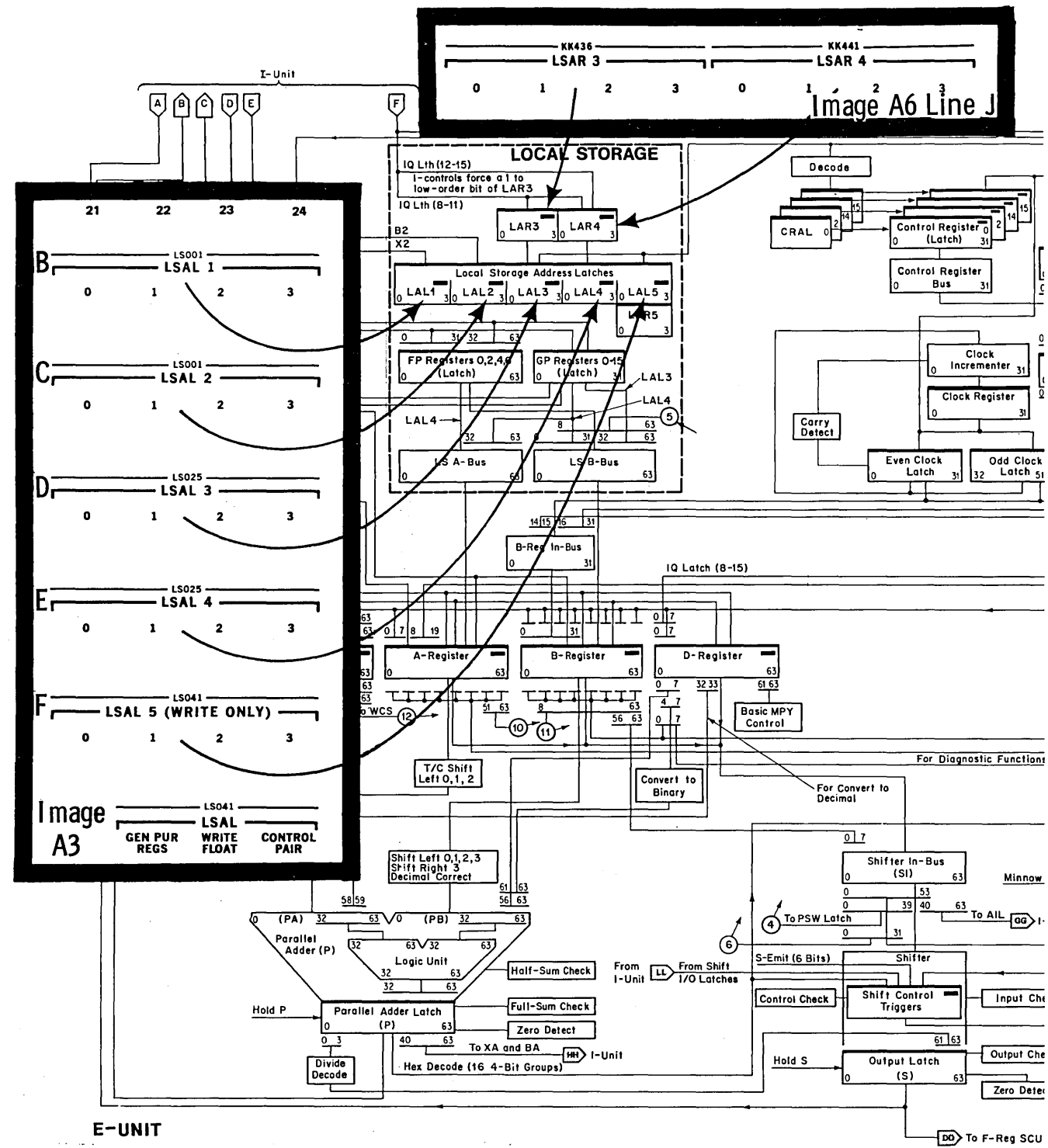


Figure 8-28. LS Display

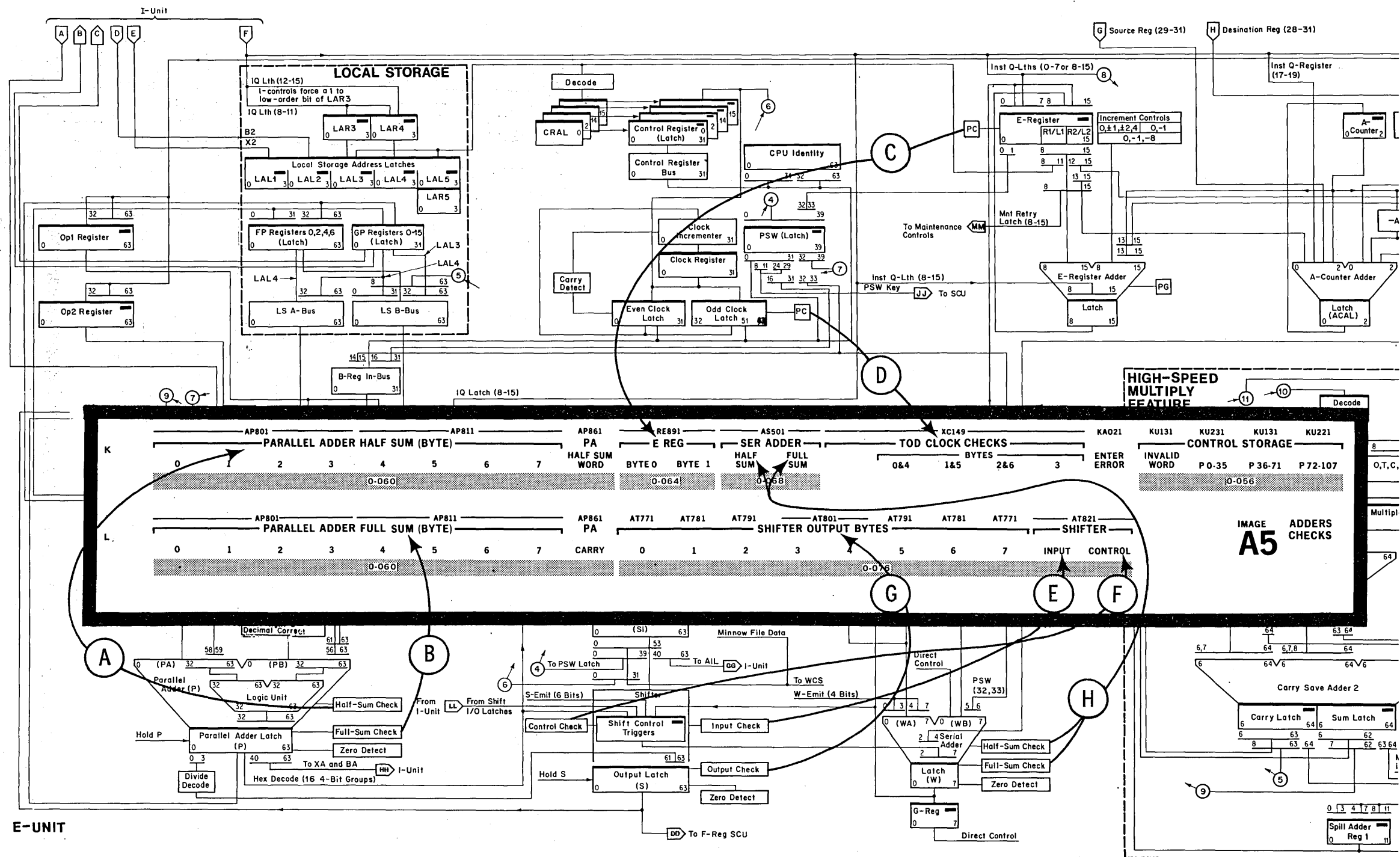
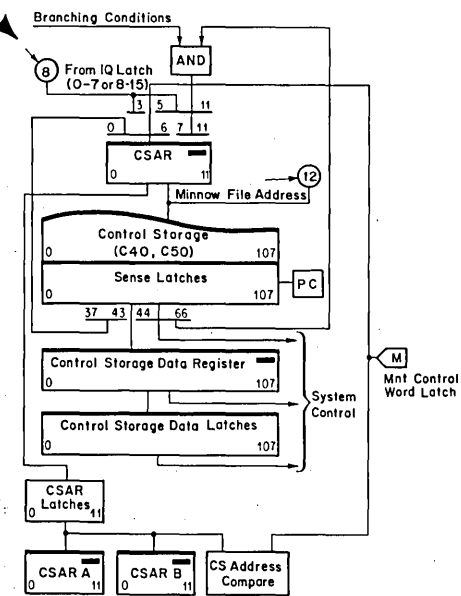


Figure 8-29. E-Unit Errors

CS address sent to CSAR from instruction queue—part of the E-unit setup by the I-unit.



In the E-unit, the state/control triggers are replaced by CS words that are sometimes called micro-instructions. Each CS word consists of a predetermined bit pattern that represents a state of the CPU and controls a portion of the CPU (the E-Unit) for one machine cycle. When decoded, the CS word defines all control lines that are to be activated during that machine cycle. Also contained in the CS word is the information required to address the next CS word.

Control storage for the E-unit consists of 2,048 108-bit words of read-only storage (C50) and 512 108-bit words of writeable control storage (C40). Each control storage word contains a unique bit pattern. When decoded, the bits control gates to route data through the E-unit.

For the C50, information can be read out as required, but a physical modification is necessary to change the stored information. For the C40 writeable control storage, information may be changed by using the load microprogram instruction.

In general, a control word is read out of the control storage (either the C40 or the C50) at the end of each machine cycle and controls the E-unit during the following machine cycle. Each control storage (CS) word contains the address of the CS word to control the E-unit during the following cycle. The number of control words (and machine cycles) required to perform a particular operation may vary because the individual functions and the address of the next CS word are modifiable by the operation in progress, the data or control bit configuration, and the detection of interrupts or exceptional conditions.

CONTROL STORAGE (CS)

The CS logic units are shown above. Control storage holds the program (called the "microprogram") that provides the control of the E-unit as it executes instructions.

To understand the operations of control storage, it is helpful to note its relationship to conventional controls. Conventional controls are characterized by state/control triggers that activate control lines in accordance with the operation to be performed and existing machine conditions. Each cycle that the CPU may take represents a state of the CPU as defined by the control circuitry. Each state, in turn, specifies the control lines that are to be activated during that cycle and the state that is to follow next. The specified state causes the next state/control trigger to be set in the following cycle. In some cases, the next state may be contingent upon a branch condition which selects one of two or more state/control triggers.

Figure 8-30. Control Storage

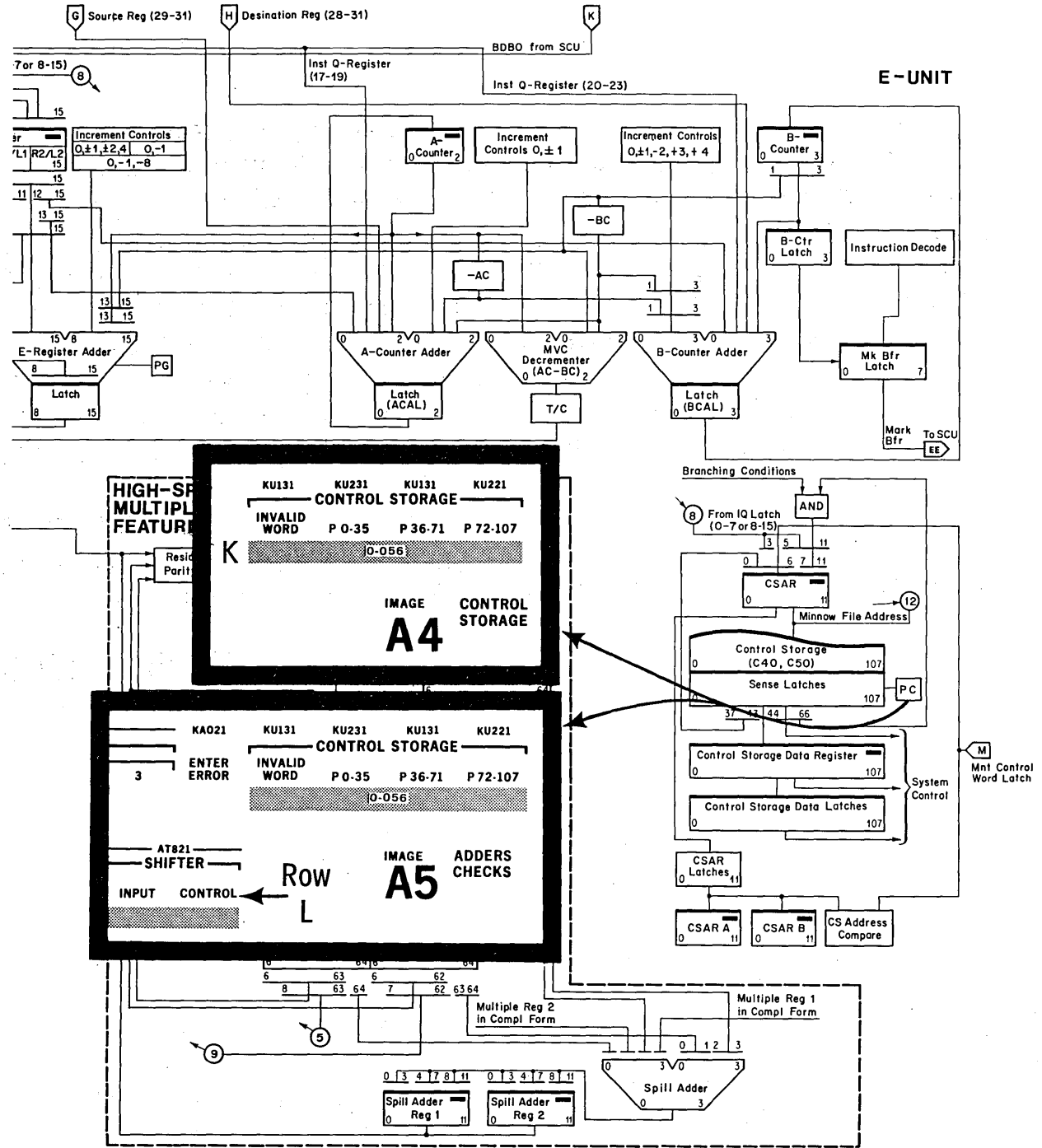
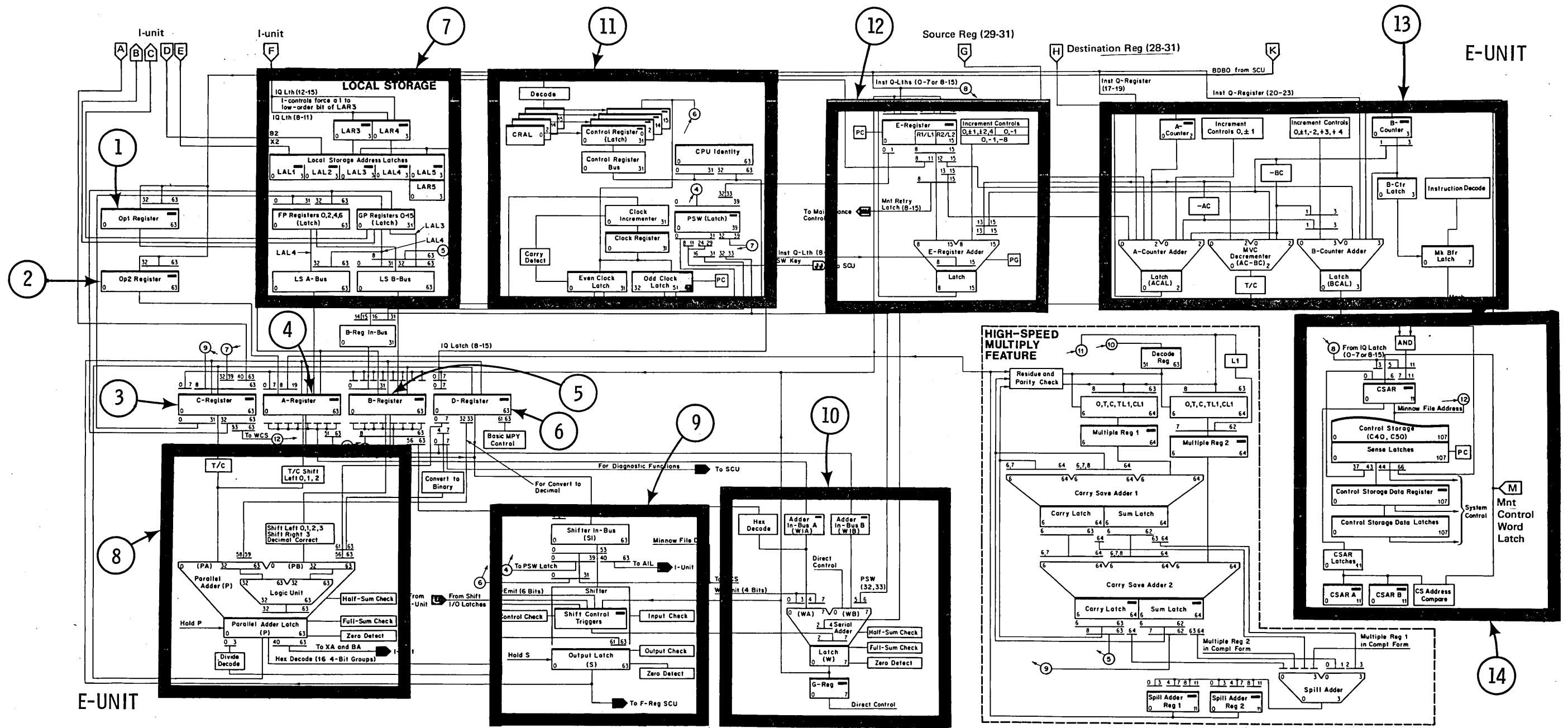


Figure 8-31. CS Error



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Figure 9-1. Session 9, Questions 6-10

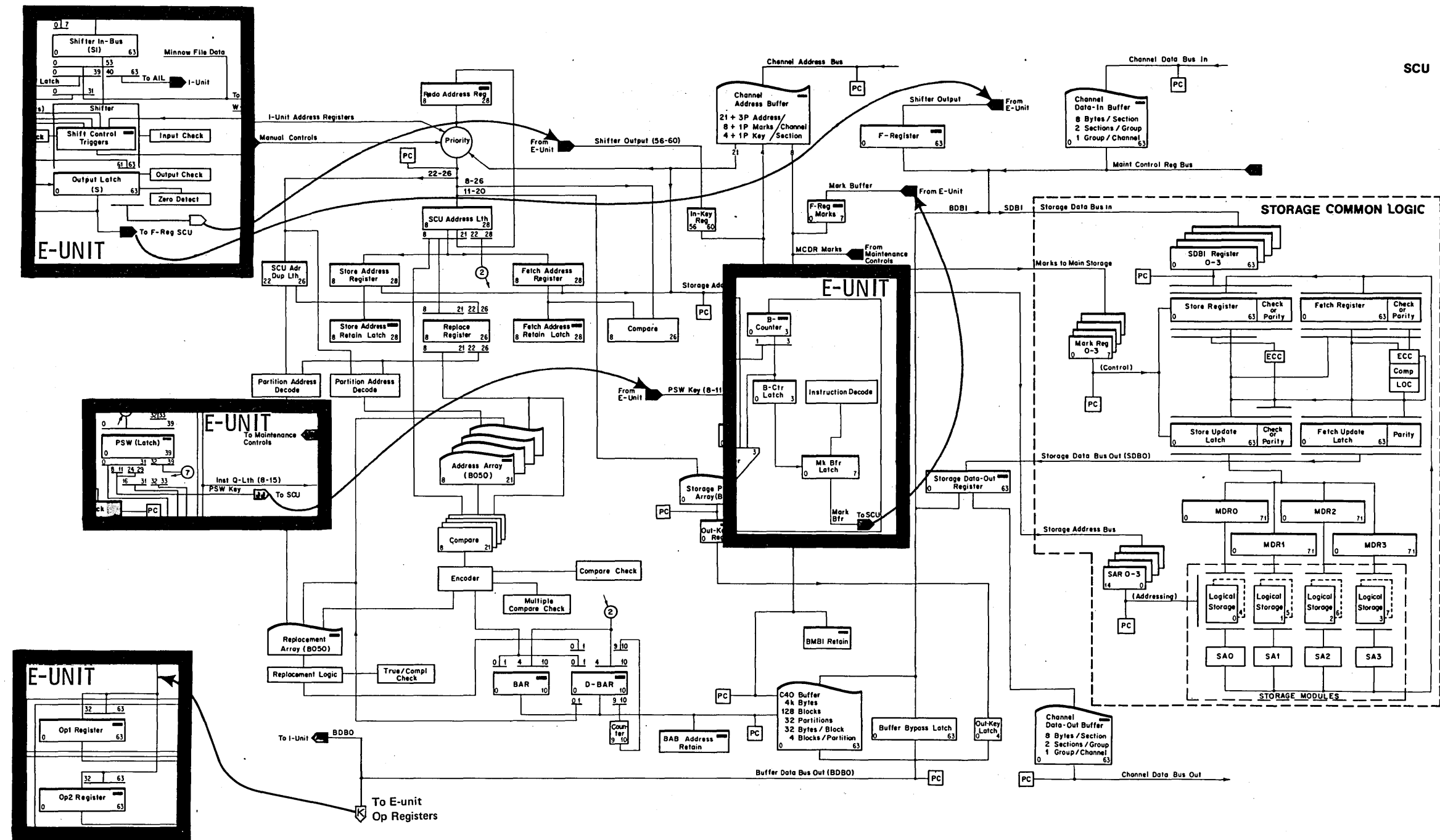


Figure 9-2. E-SCU Data Paths

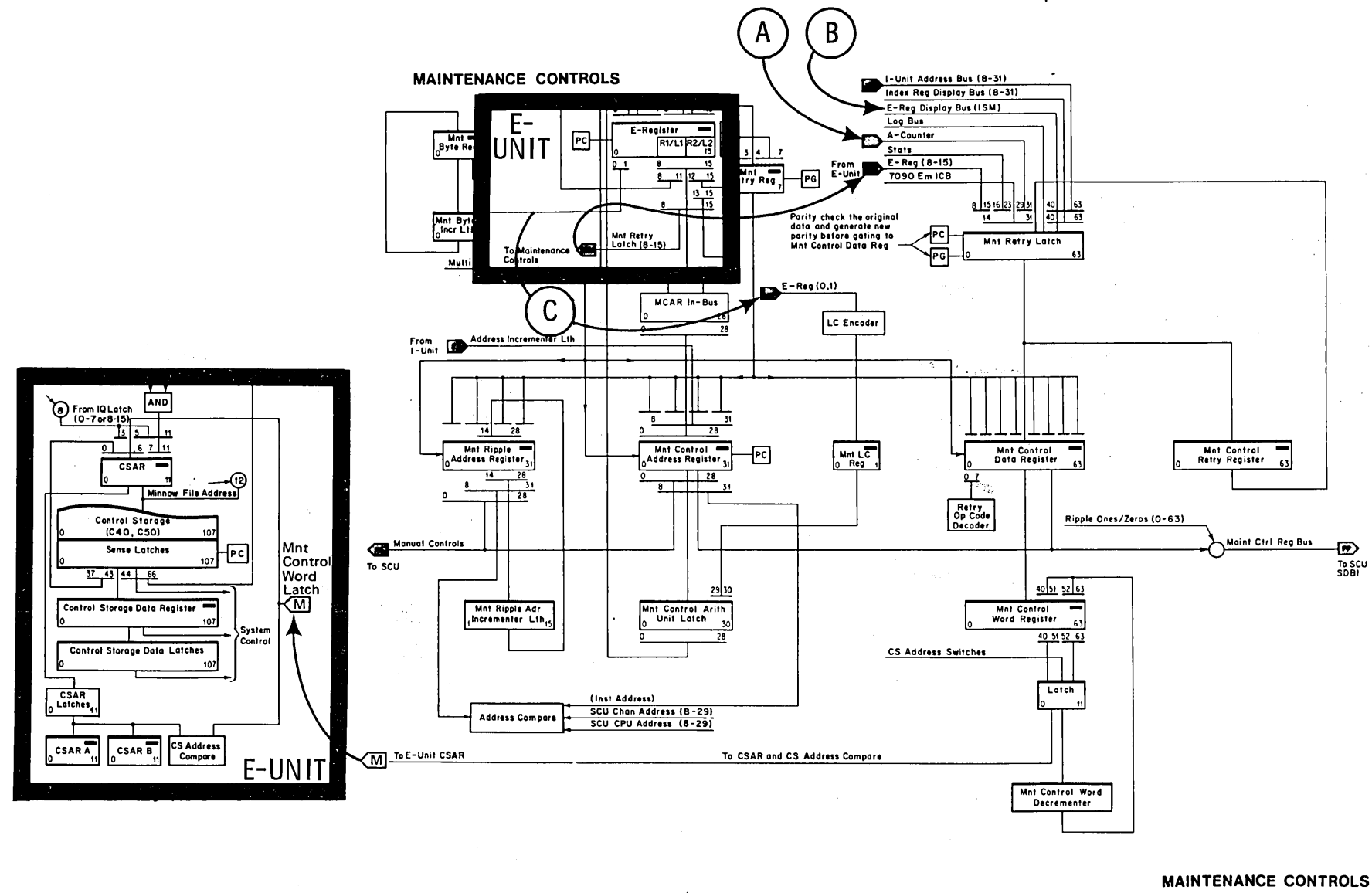


Figure 9-3. E-MC Data Paths

BASIC DATA FLOW

The basic data flow through the E-unit consists of gating a register (or two registers) through the parallel adder, the serial adder, or the shifter, to another register in a single E-unit cycle.

From the main storage or the high-speed buffer, data enters either the operand 1 (Op 1) or the operand 2 (Op 2) register, where it is held until the E-unit is ready to process it. When the E-unit is ready, data enters a working register (register A, B, C, or D), and the E-unit cycle begins by gating data from the working register(s) into the adder or shifter being used. After passing through the adder or shifter, the manipulated data is latched up in the adder or shifter output latch to wait for the next clock pulse, which gates it back either to a working register for additional processing on a subsequent cycle or to the F register in the SCU, where the data is placed back in main storage and the high-speed buffer.

Figure 9-4. E-Unit Basic Data Flow

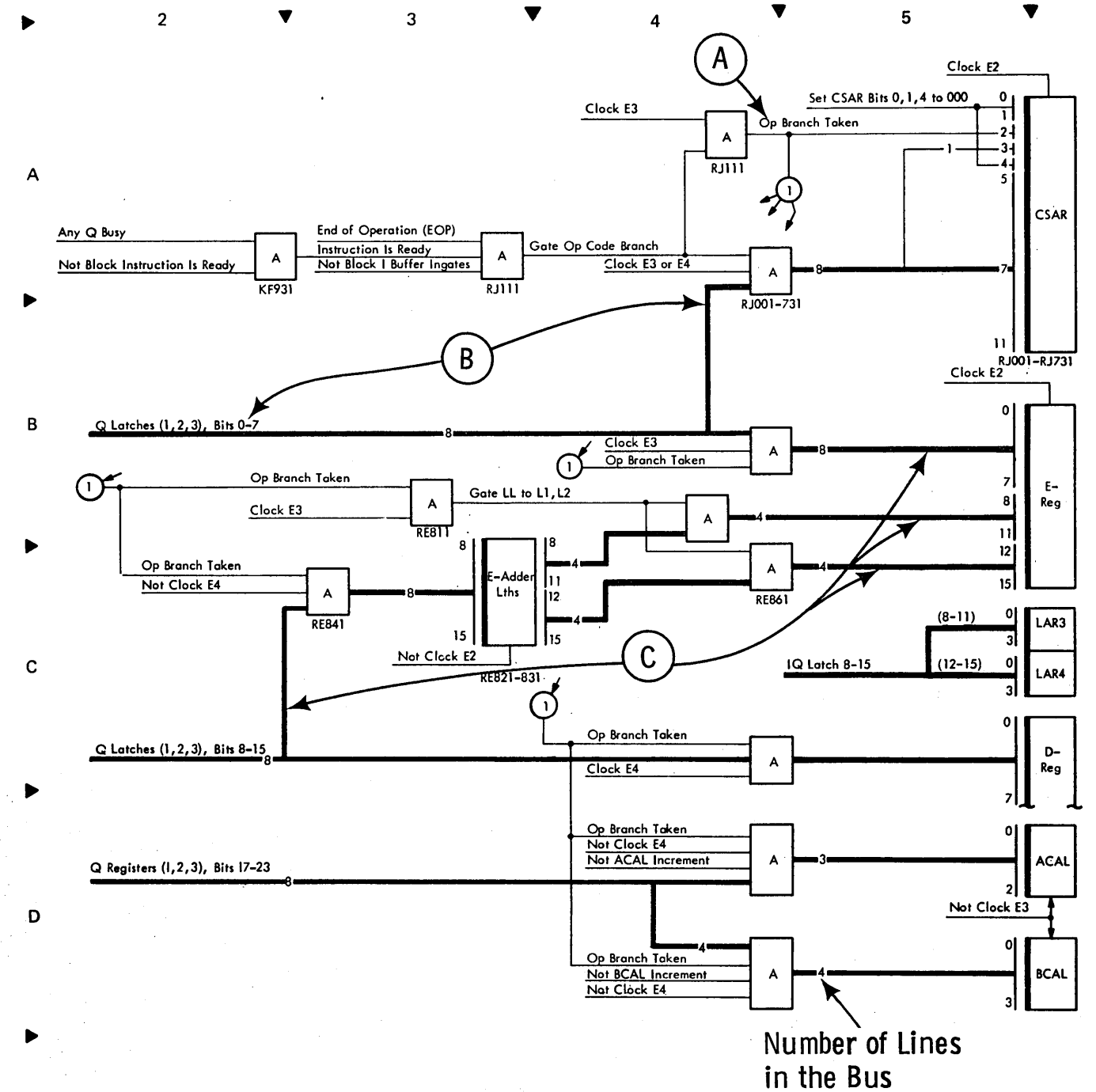


Figure 9-5. I-Unit Setup Of E-Unit

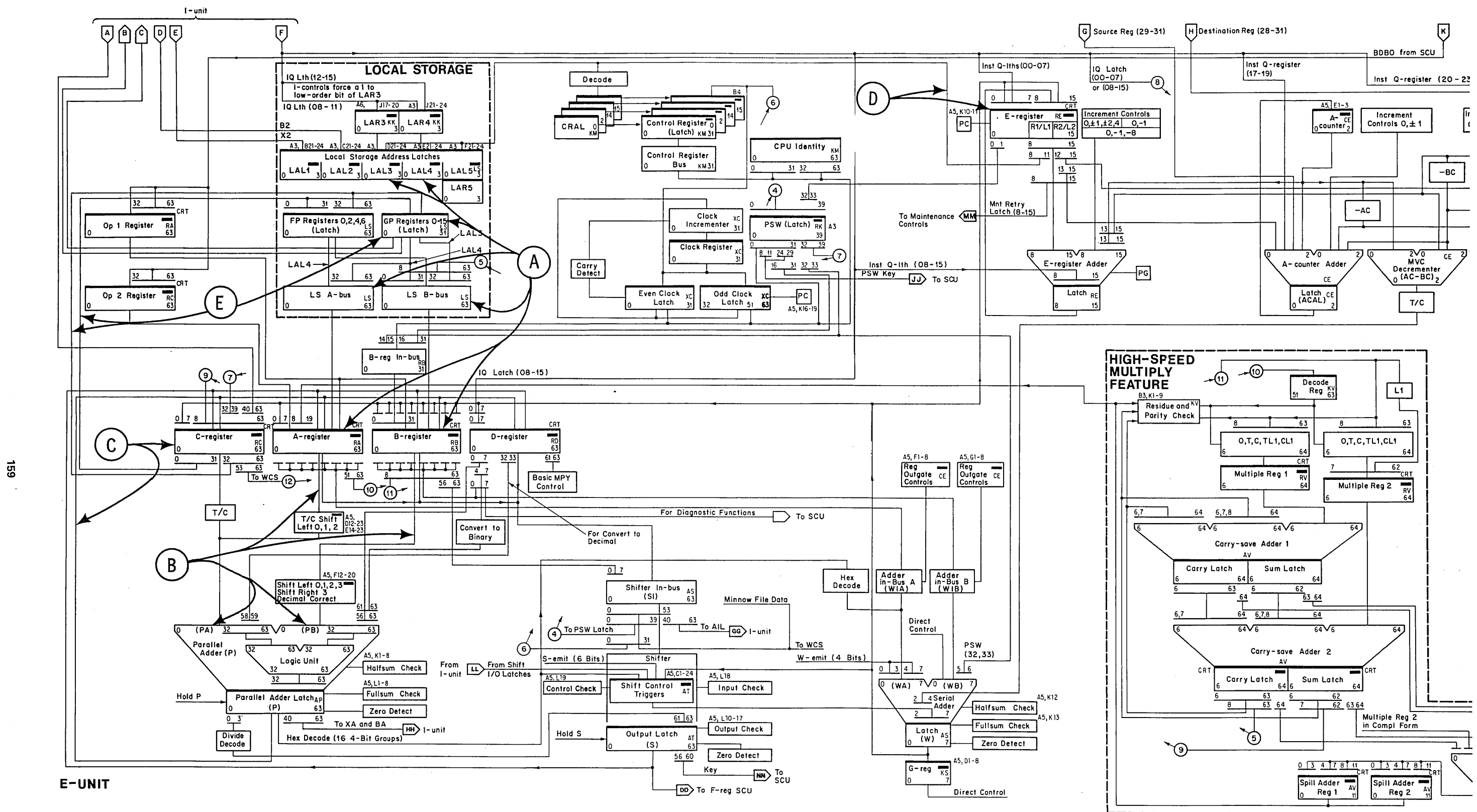


Figure 9-6. RR Add

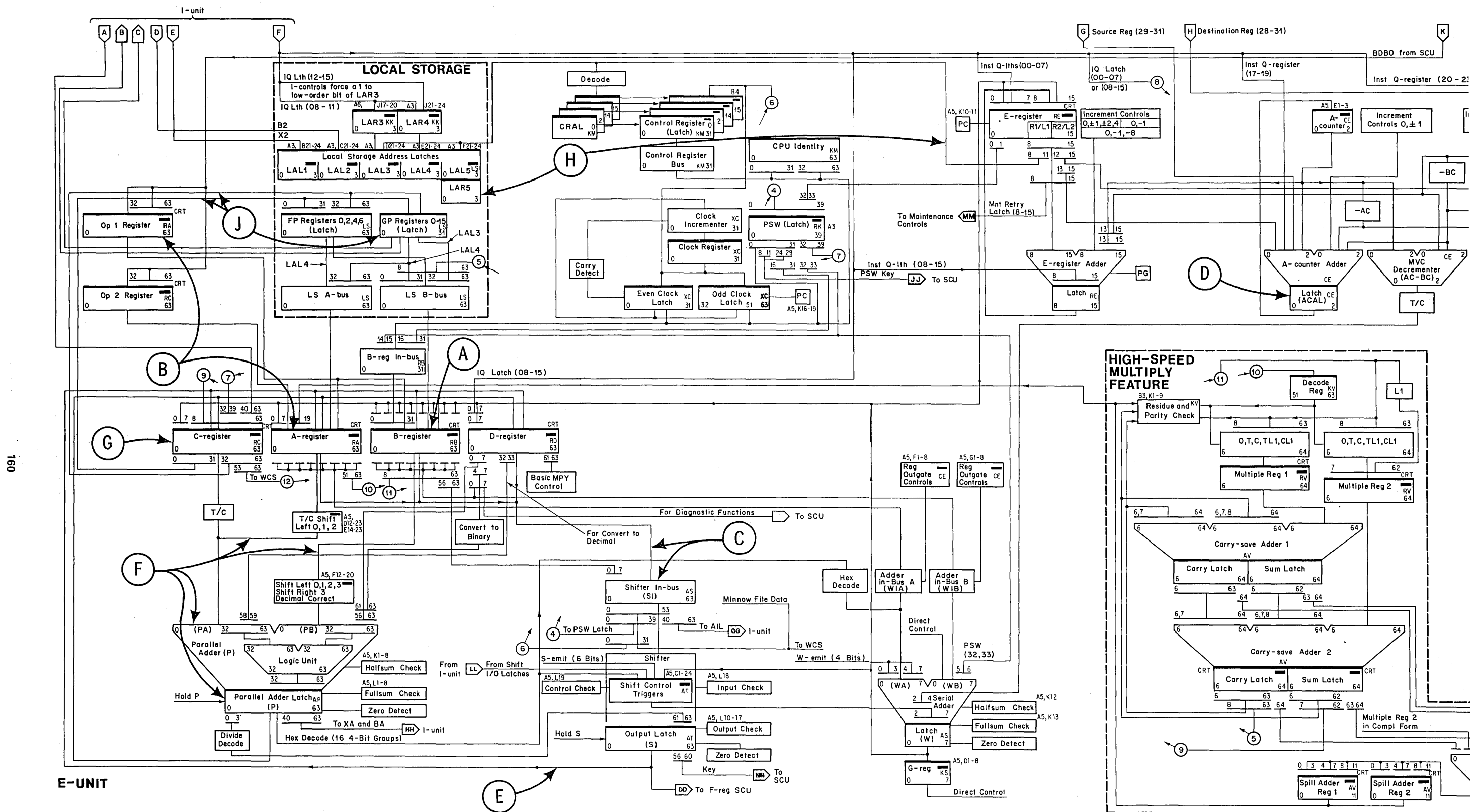


Figure 9-7. RX Add

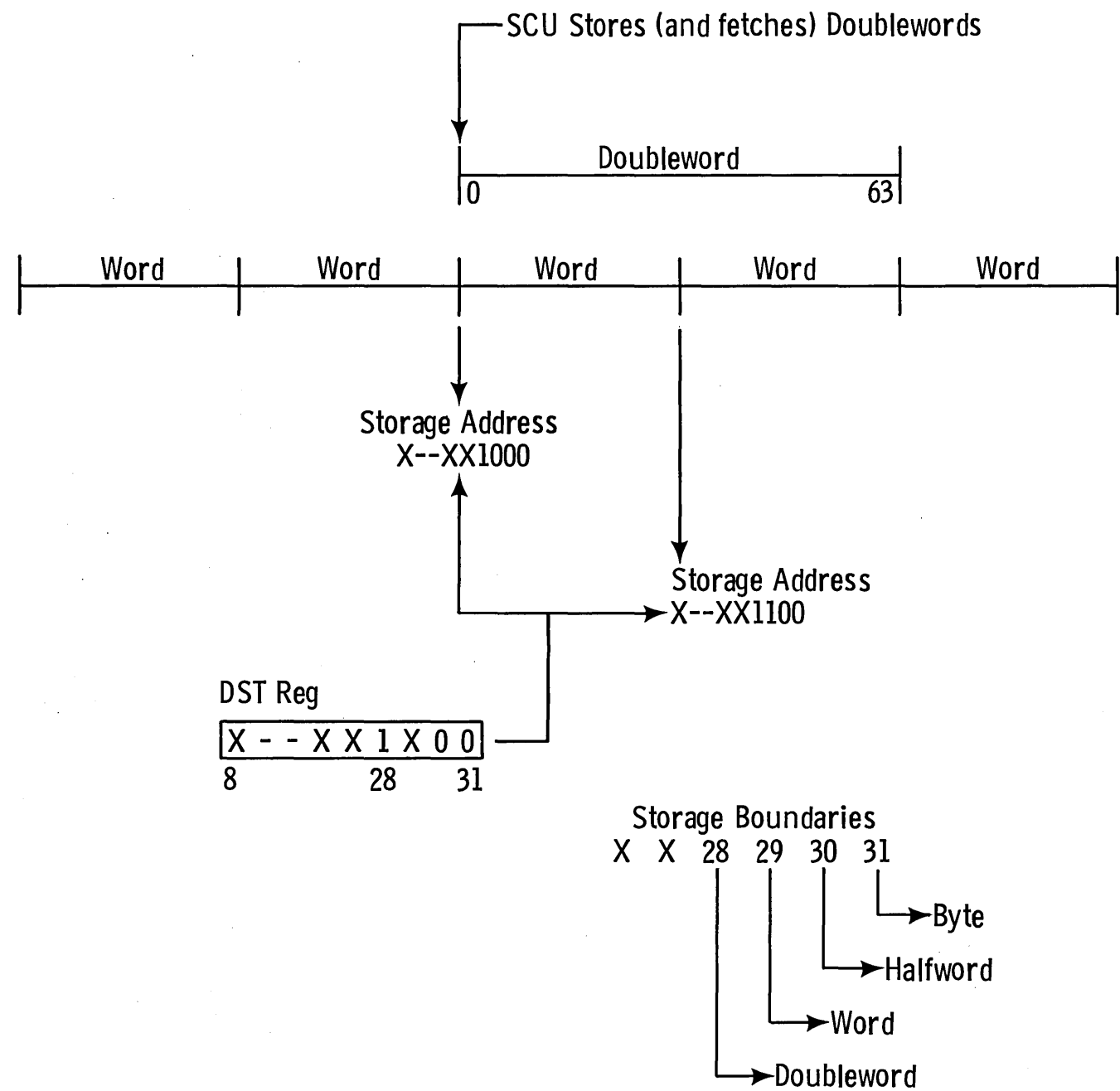


Figure 9-8. Store Concept 1

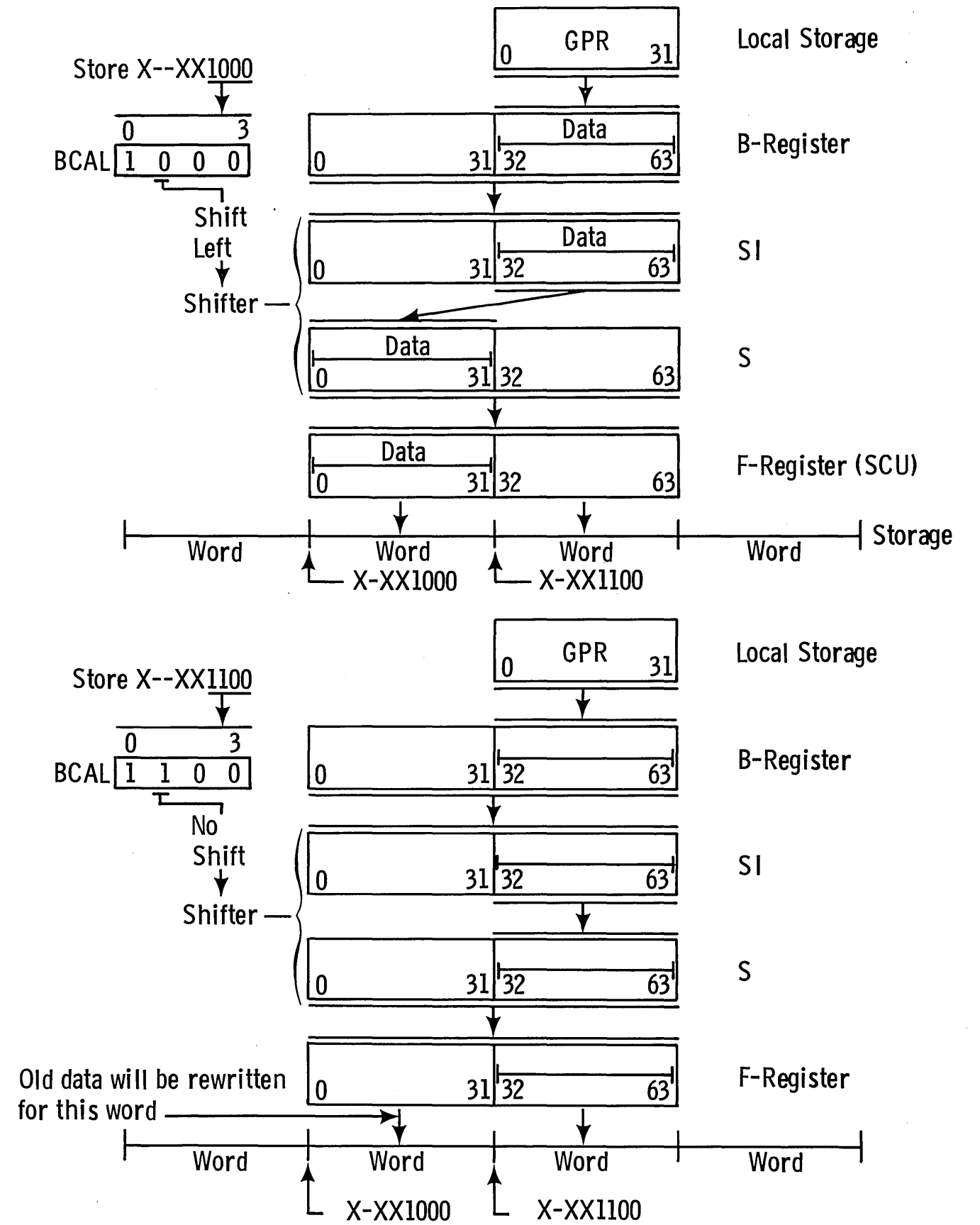


Figure 9-9. Store Concept 2

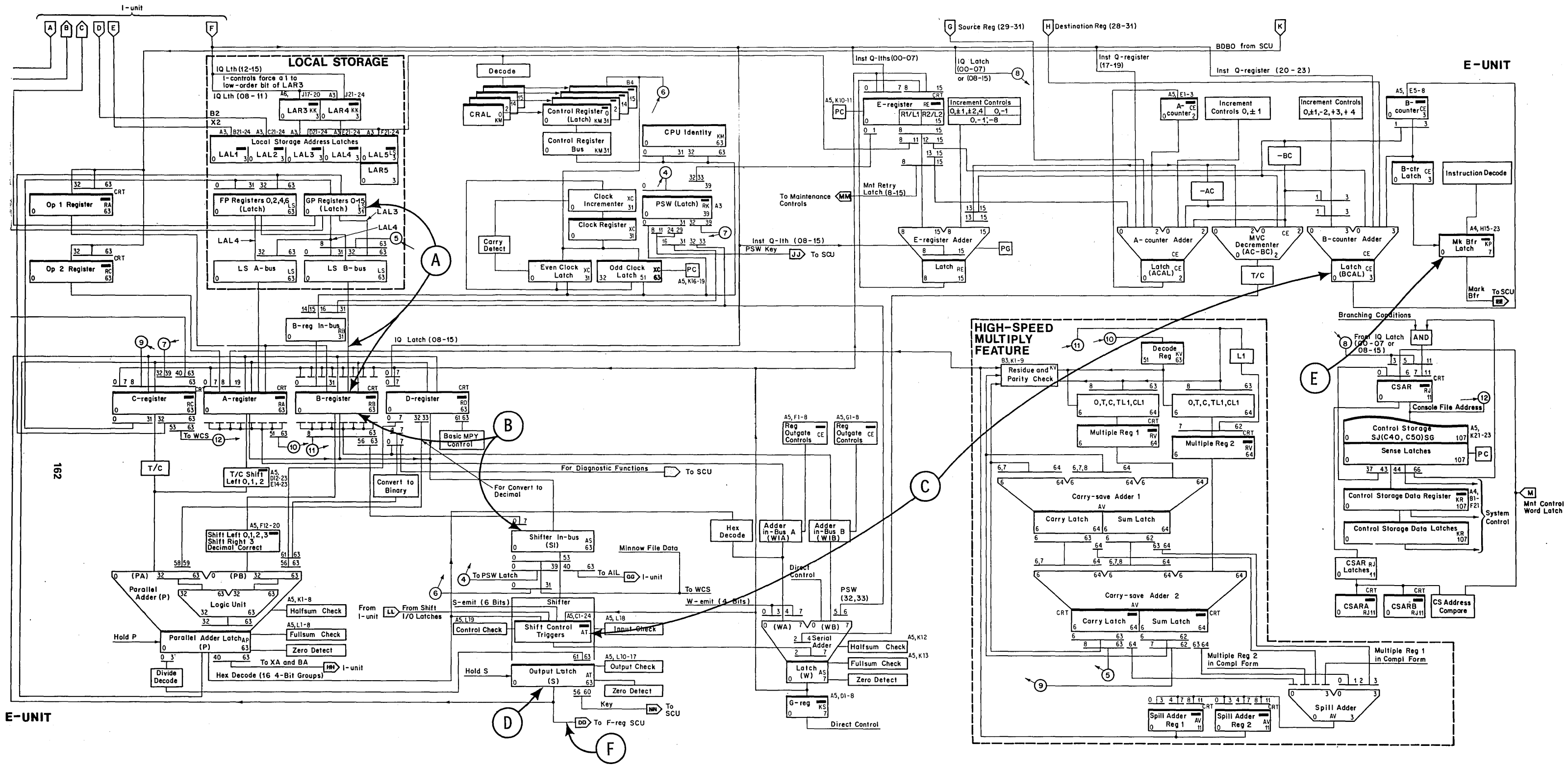


Figure 9-10. RX Store

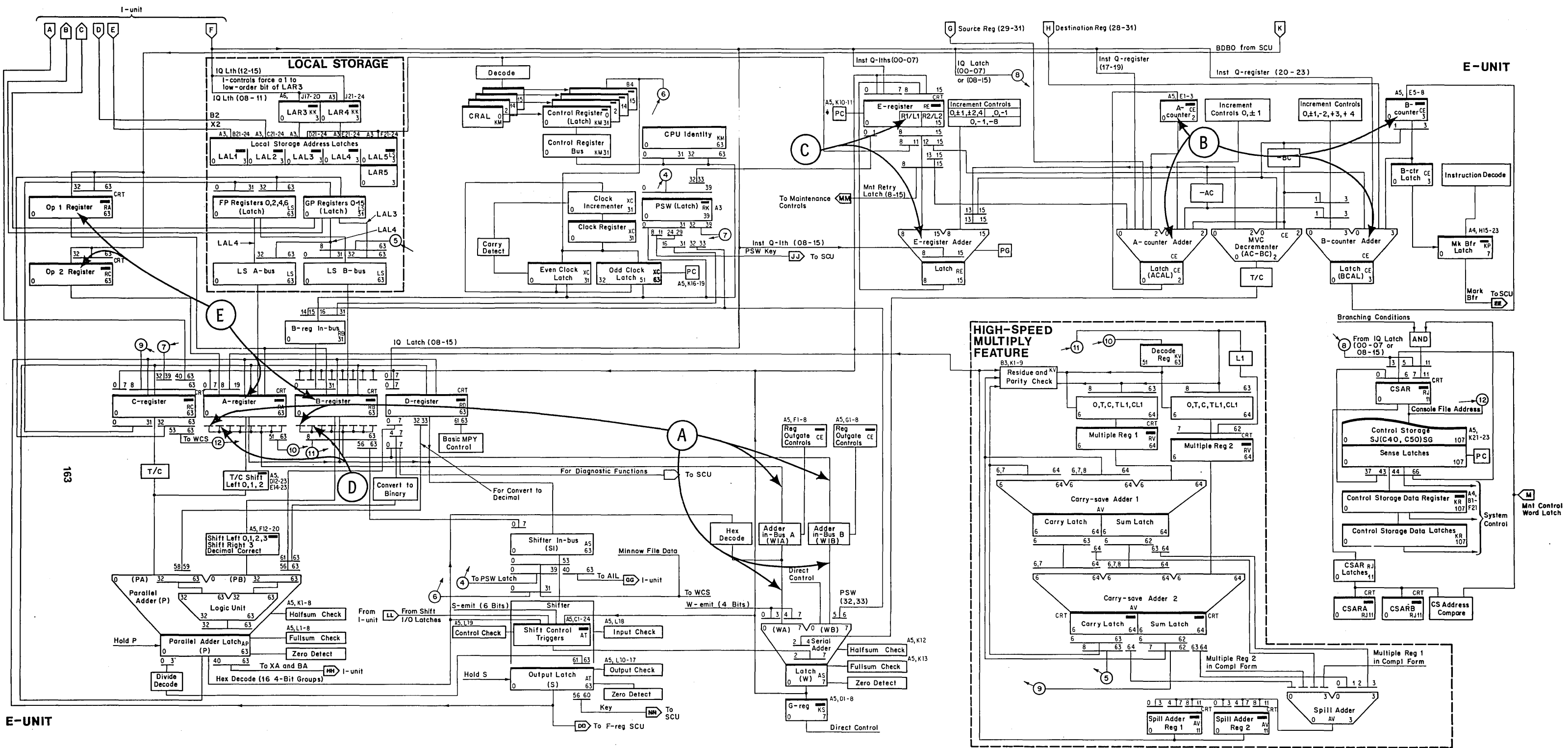


Figure 9-11. SS Compare Logical

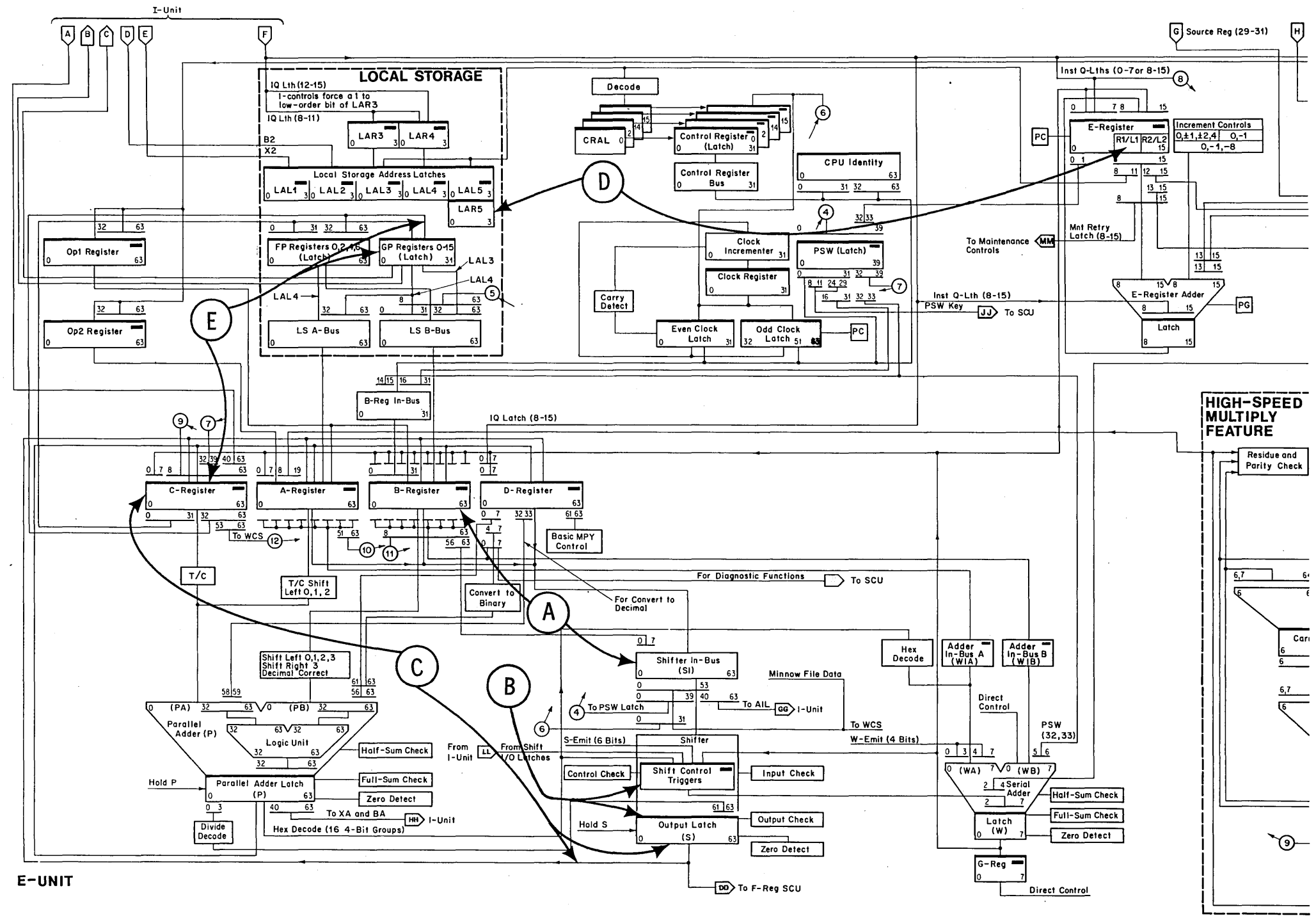


Figure 9-12. RS Shift Logical

START I/O

The start I/O (SIO) instruction selects a specified I/O device and initiates a channel command to that device. The following channel commands can be issued with the SIO instruction: read, read backward, write, sense, and control. The effective operand address (base plus displacement), determined during I-fetch of the SIO instruction, addresses the channel and I/O device. Bits 19-23 of the effective operand address are decoded to select the channel; bits 24-31 are sent to the channel as an eight-bit I/O device address, selecting the correct I/O device.

At the start of execution, the first 16 bits of the instruction are in the E-register and the second operand address is in the shift or I/O register; the first operand is not applicable. Because this instruction is an I/O instruction, the address in the shift or I/O register is the address of the channel and I/O device and is not to be interpreted as a main-storage address. Therefore, no data is requested from main storage. The SIO instruction can be executed only when the CPU is in the supervisor state. The first operation of the instruction, therefore, is to determine the state of the CPU. If the CPU is not in the supervisor state, a privileged-operation check occurs, causing a privileged-operation interrupt. If the CPU is in the supervisor state, execution of the SIO instruction begins by setting the select channel trigger. This trigger causes a select signal to be sent to the proper channel as determined by shift or I/O register bits 19-23.

The unit address in the shift or I/O register bits 24-31 also is sent to the channel. If at this point the selected channel is busy or in test mode, a CC of 2 or 3, respectively, is sent to the CPU. A release signal is also sent to the CPU, releasing it for execution of other instructions. If the channel is available, the unit address is gated to the unit address register in the channel. The channel then fetches the CAW from main-storage address 48 (hex). The CAW specifies the address of the first CCW and the storage protection key for all the channel commands associated with the SIO instruction. If any errors are discovered in the CAW or the unit address, a status byte is stored in the channel and a CC of 1 is sent to the CPU. A release signal is also sent to the CPU, releasing it for execution of other instructions.

Two operations, fetching the CCW and selecting the I/O unit per the unit address, are now started simultaneously. The channel starts a CCW fetch by raising a storage request to main storage. After the proper exchange of control signals, the command information (command code, data address, flags, and counts) is set into the proper registers in the channel. The CCW-valid trigger is set, if there were no errors, to show that the CCW has been received. The CCW information is then checked for correct parity.

The second operation, selection of the proper I/O devices, is started at the same time as the CCW fetch. To select the proper I/O device, the channel puts the unit address on the bus out to the control unit and sends an address-out signal followed 400 ns later by a select-out signal. The control unit responds with an operation-in signal, which causes the channel to drop the address-out signal, it puts the address of the selected device on the bus in and raises its address-in signal. The channel then compares the address it received from the control unit with the address it sent to the control unit to determine that proper selection has been made.

If the addresses are equal, the CCW-valid trigger is set, and if no errors occurred, the operation continues. The command code is placed on the bus out, and the command-out signal is sent to the control unit. The control unit responds with 0 status if it can accept the command. The channel then sends a condition code of 0 and a release signal to the CPU, releasing the CPU for further instruction execution. When the CPU receives the release signal, the select channel trigger is reset and an end-op cycle is taken, completing the operation.

Figure 9-13. Start I/O

Figure 9-13. Start I/O (Cont'd)

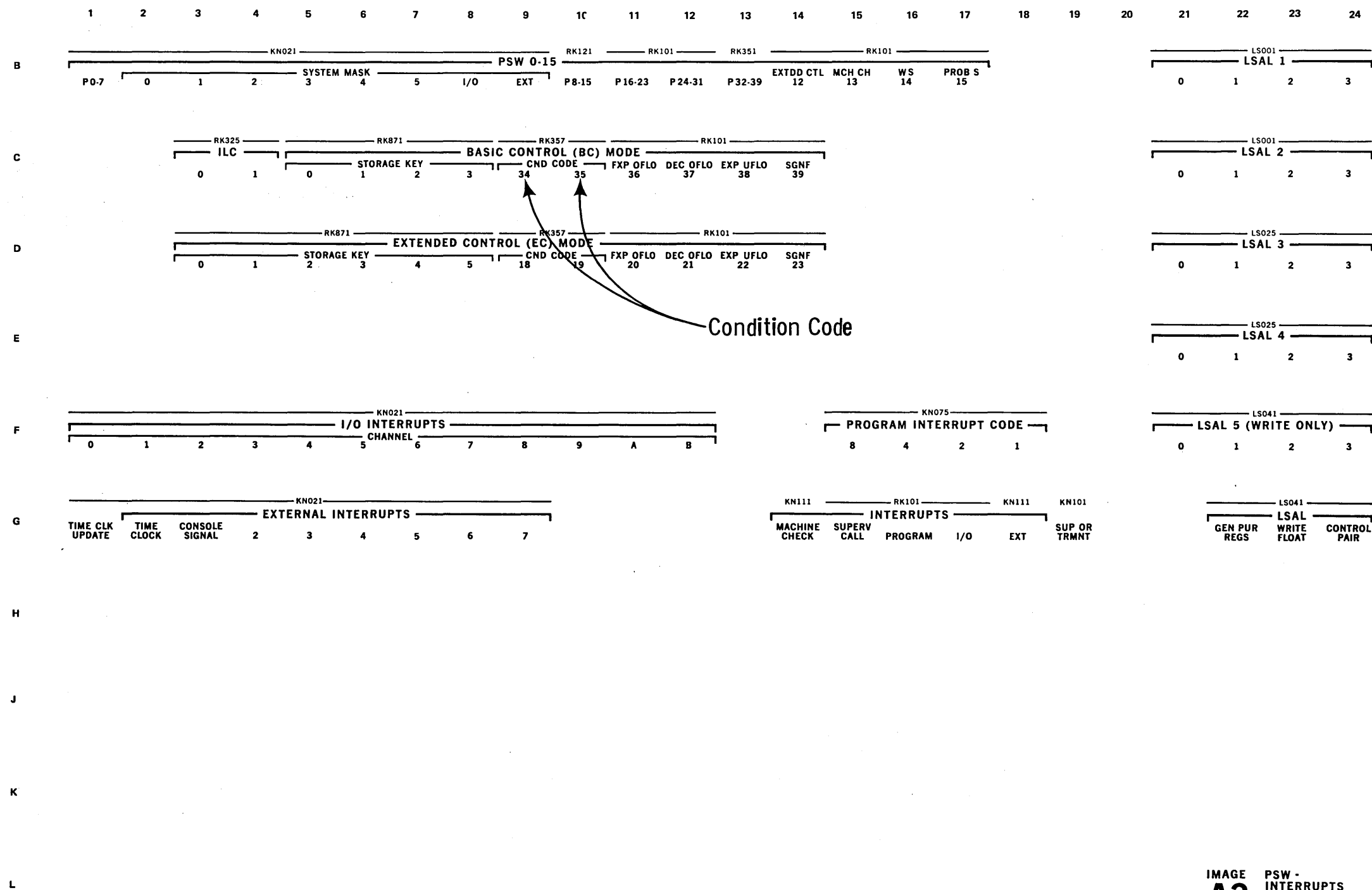


Figure 9-14. Condition Code

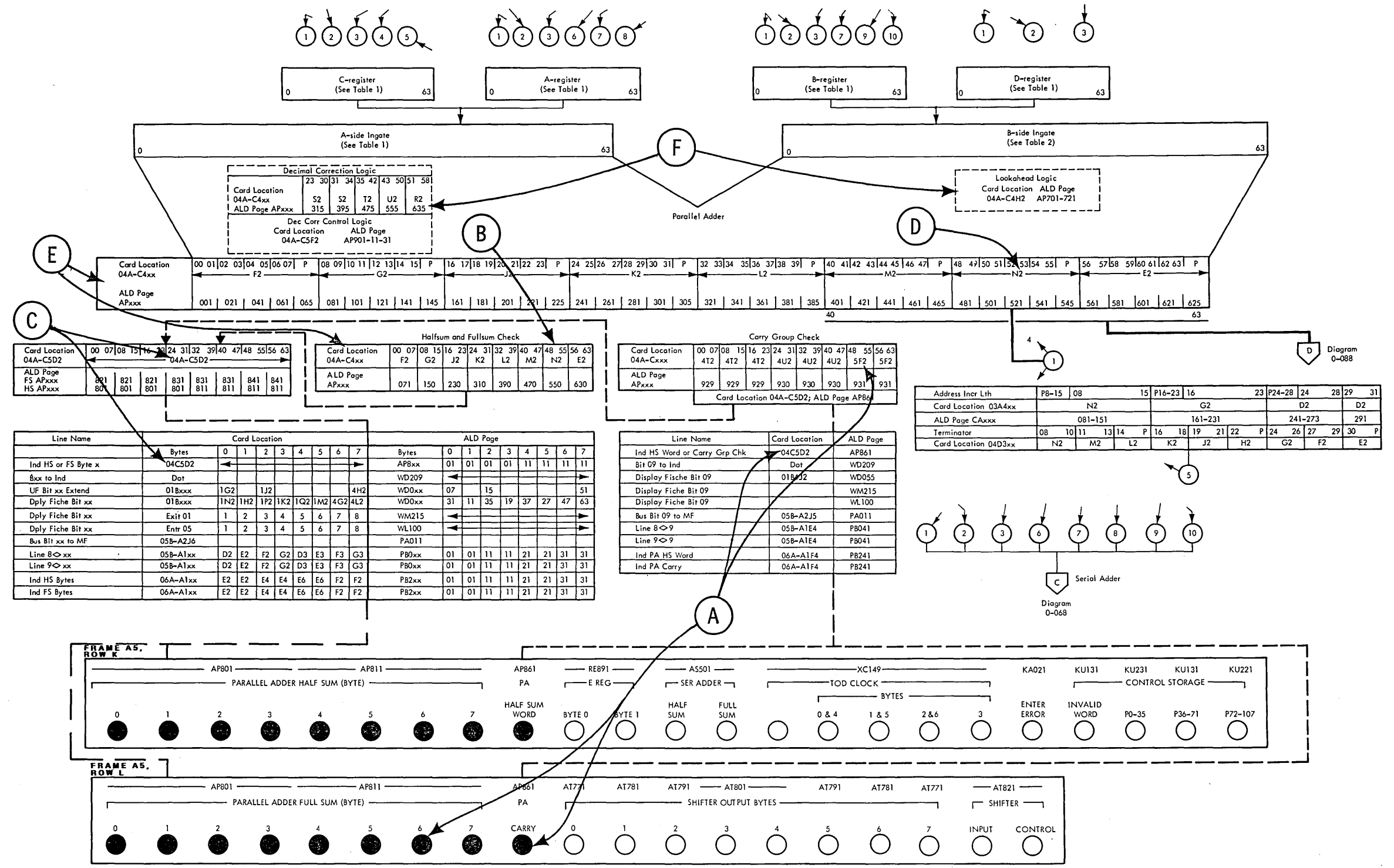


Figure 10-1. Parallel Adder No 1

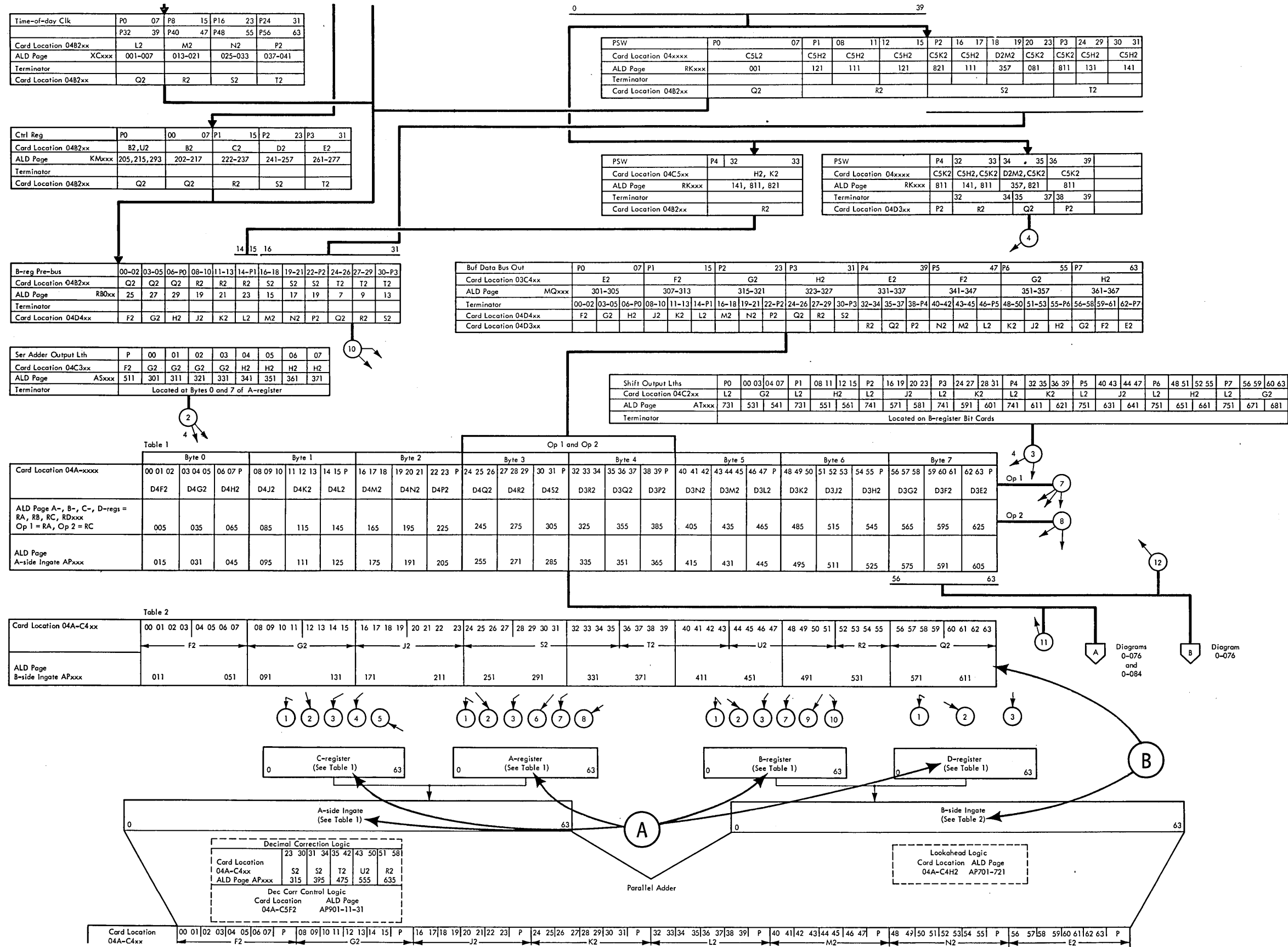


Figure 10-2. Parallel Adder No 2

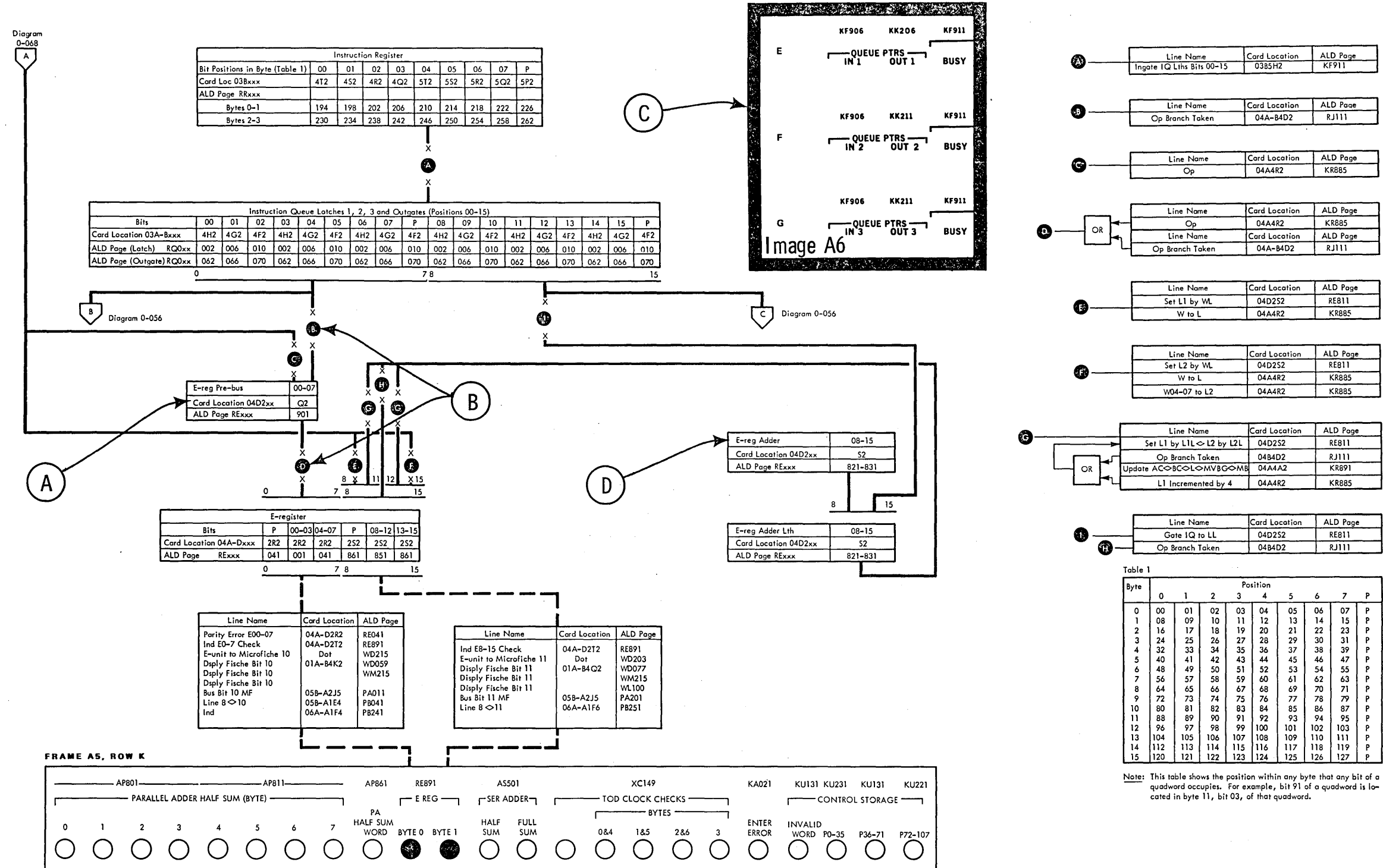


Figure 10-3. E-Register ECAD

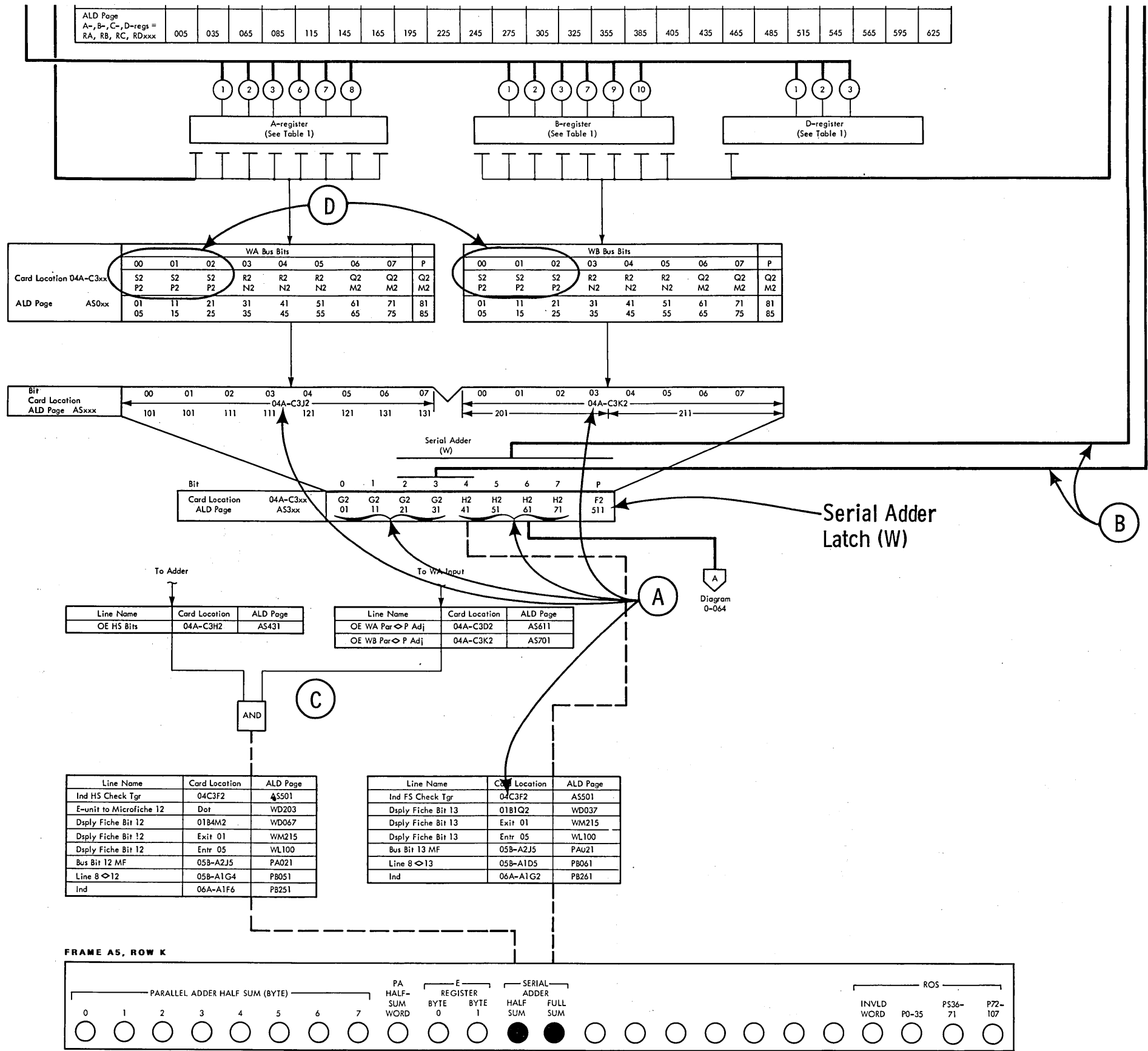
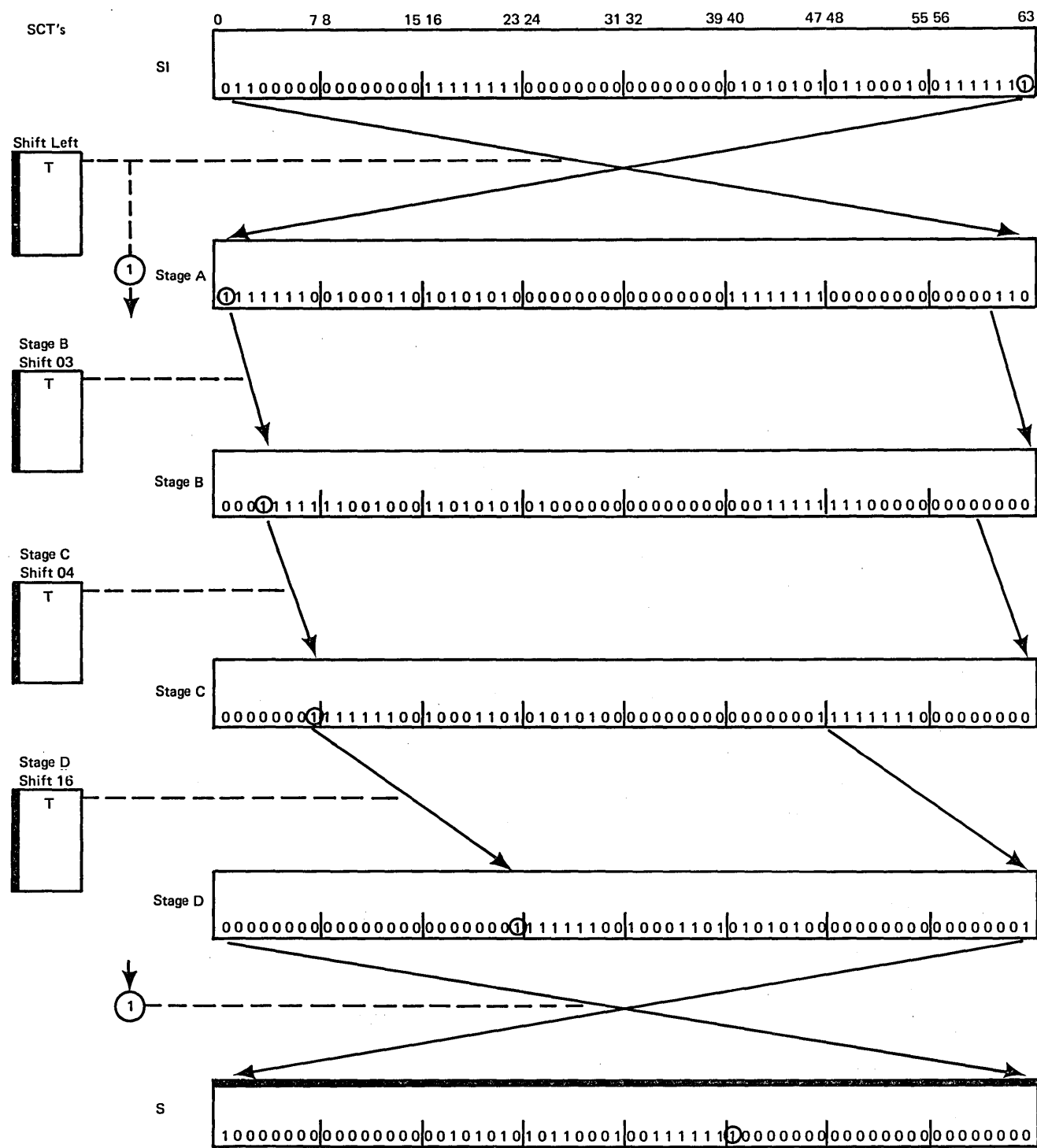
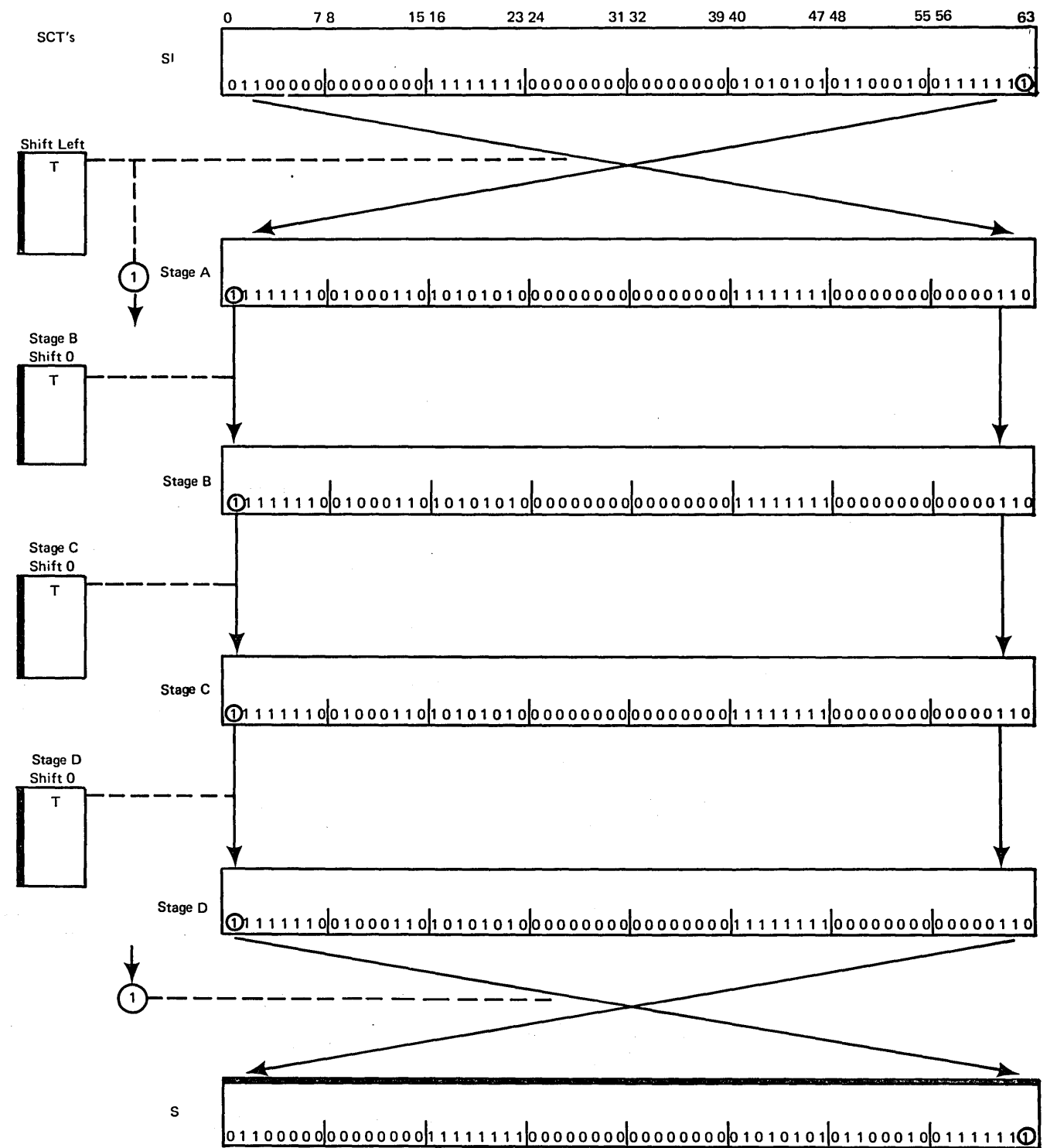


Figure 10-4. Serial Adder



LOGICAL LEFT SHIFT 23

Figure 10-5. Logical Left Shift 23



NO SHIFT

Figure 10-6. No Shift

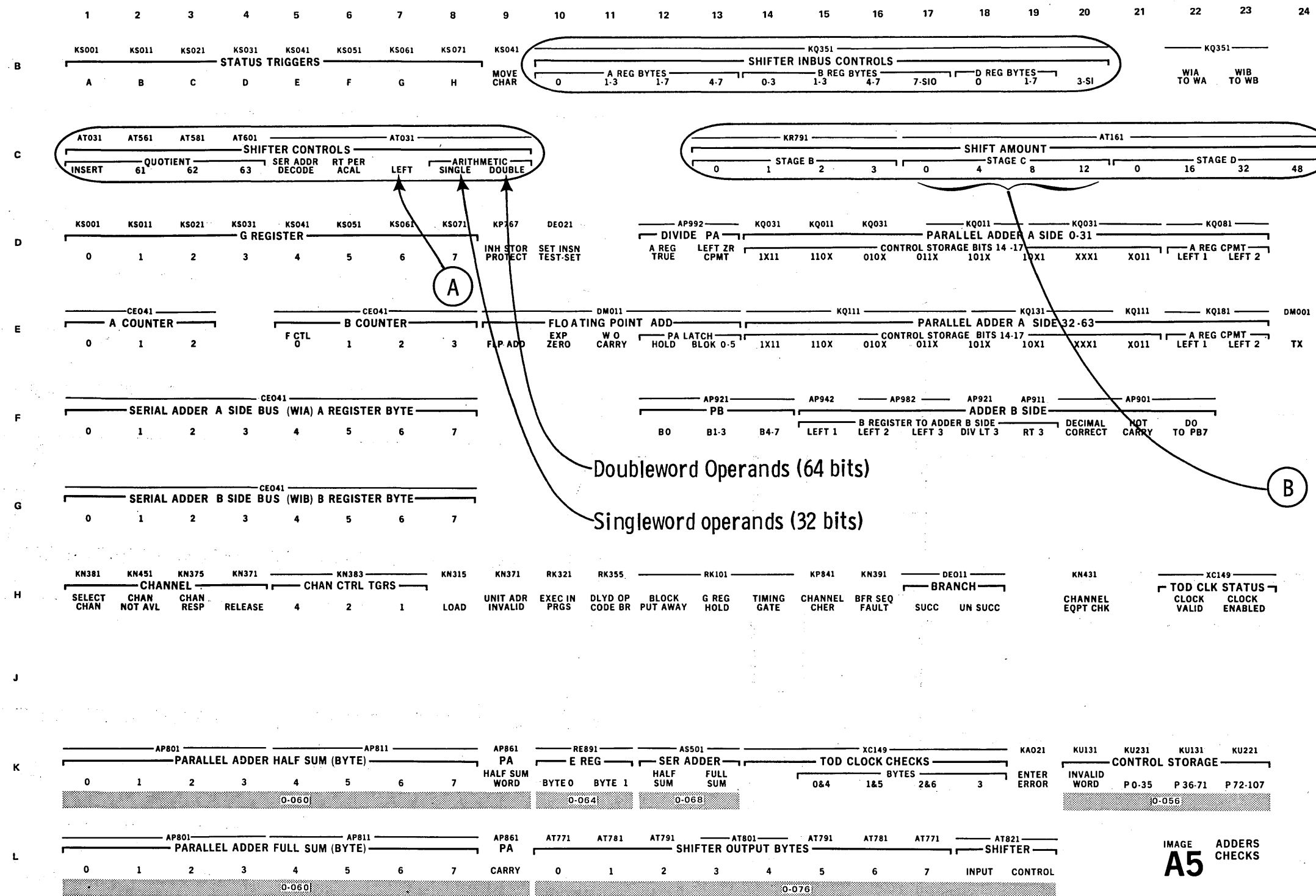


Figure 10-7. Shifter Control Indicators

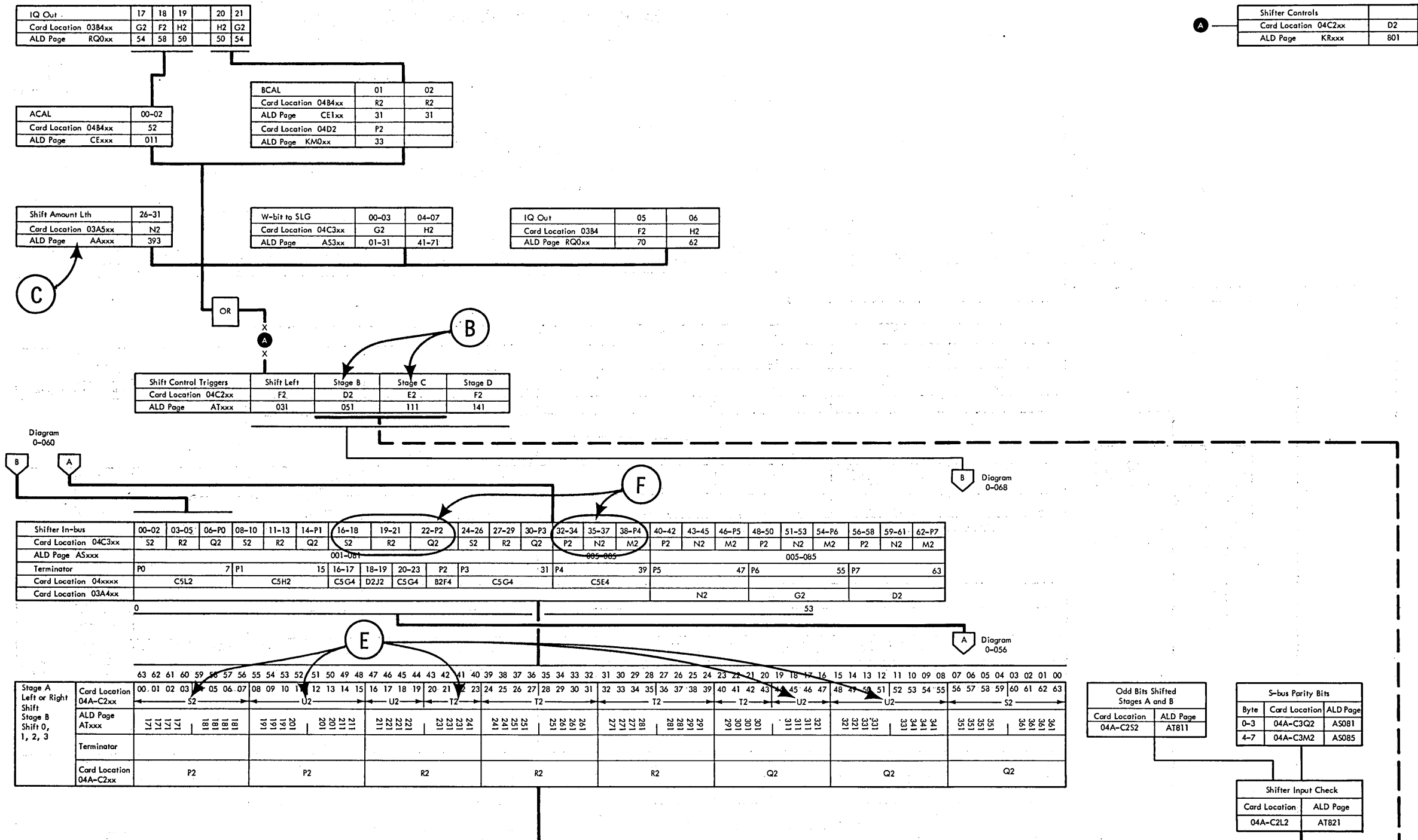


Figure 10-8a. Shifter ECAD

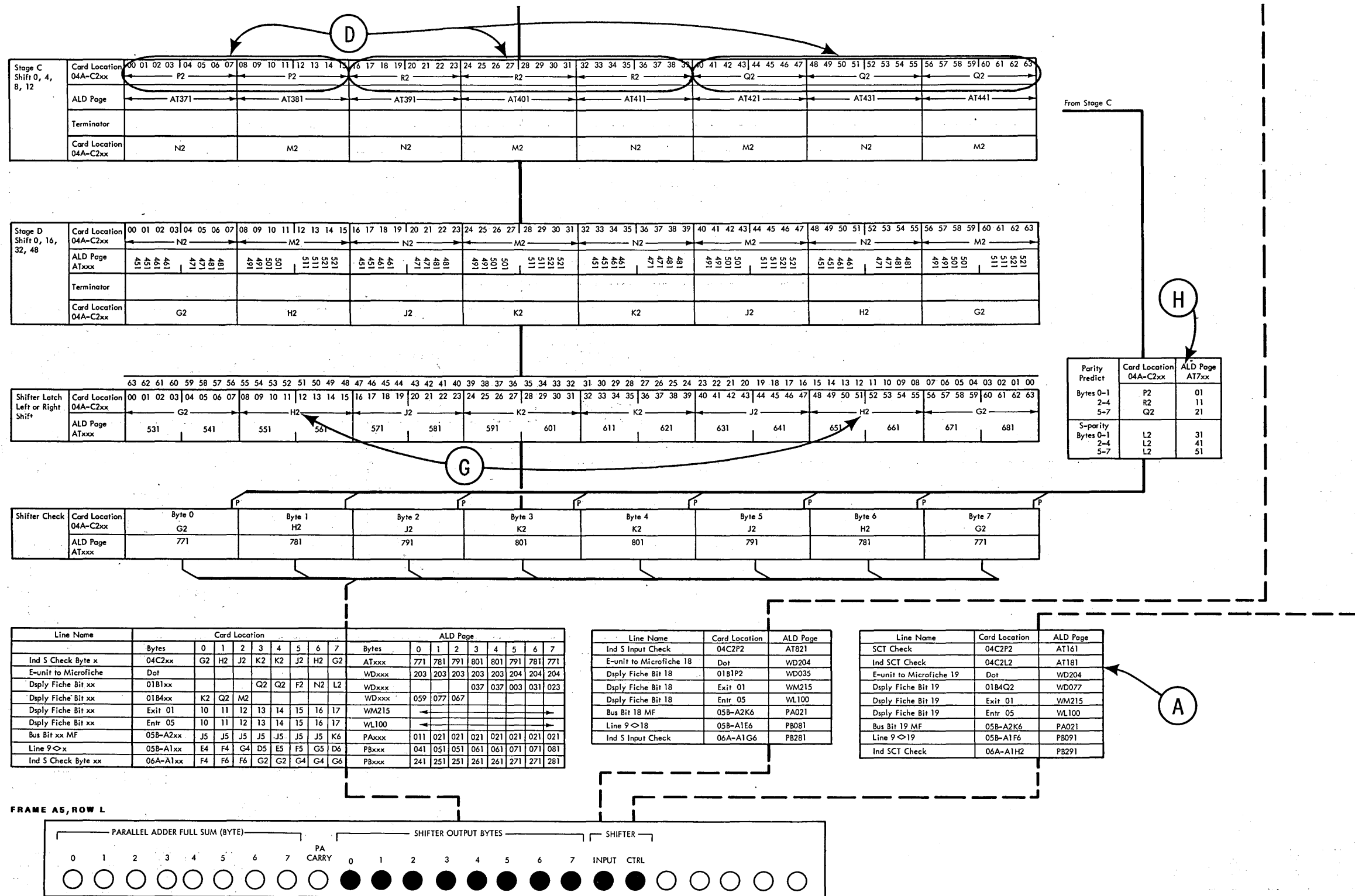


Figure 10-8b. Shifter ECAD

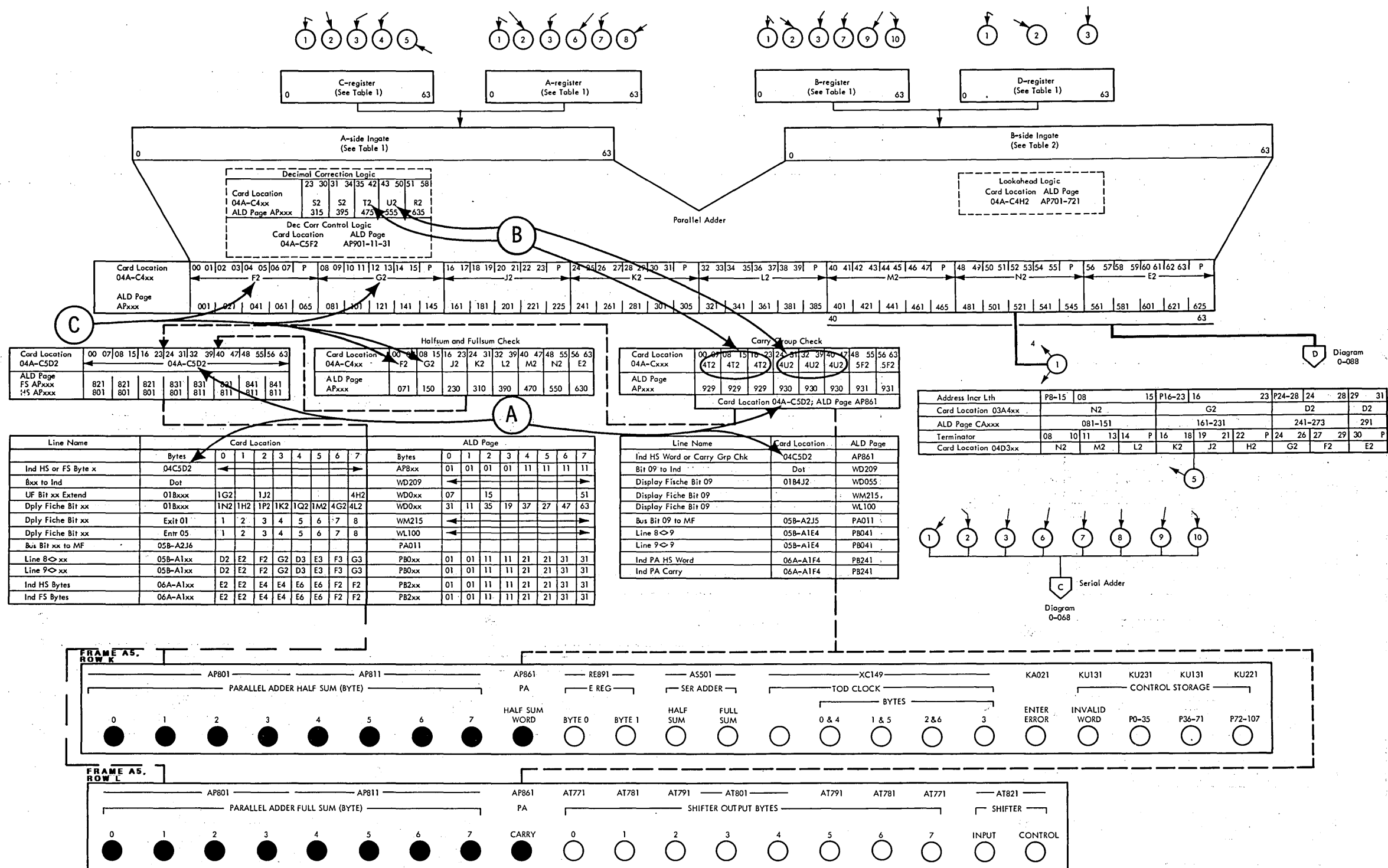


Figure 10-9. Parallel Adder Functional Packaging

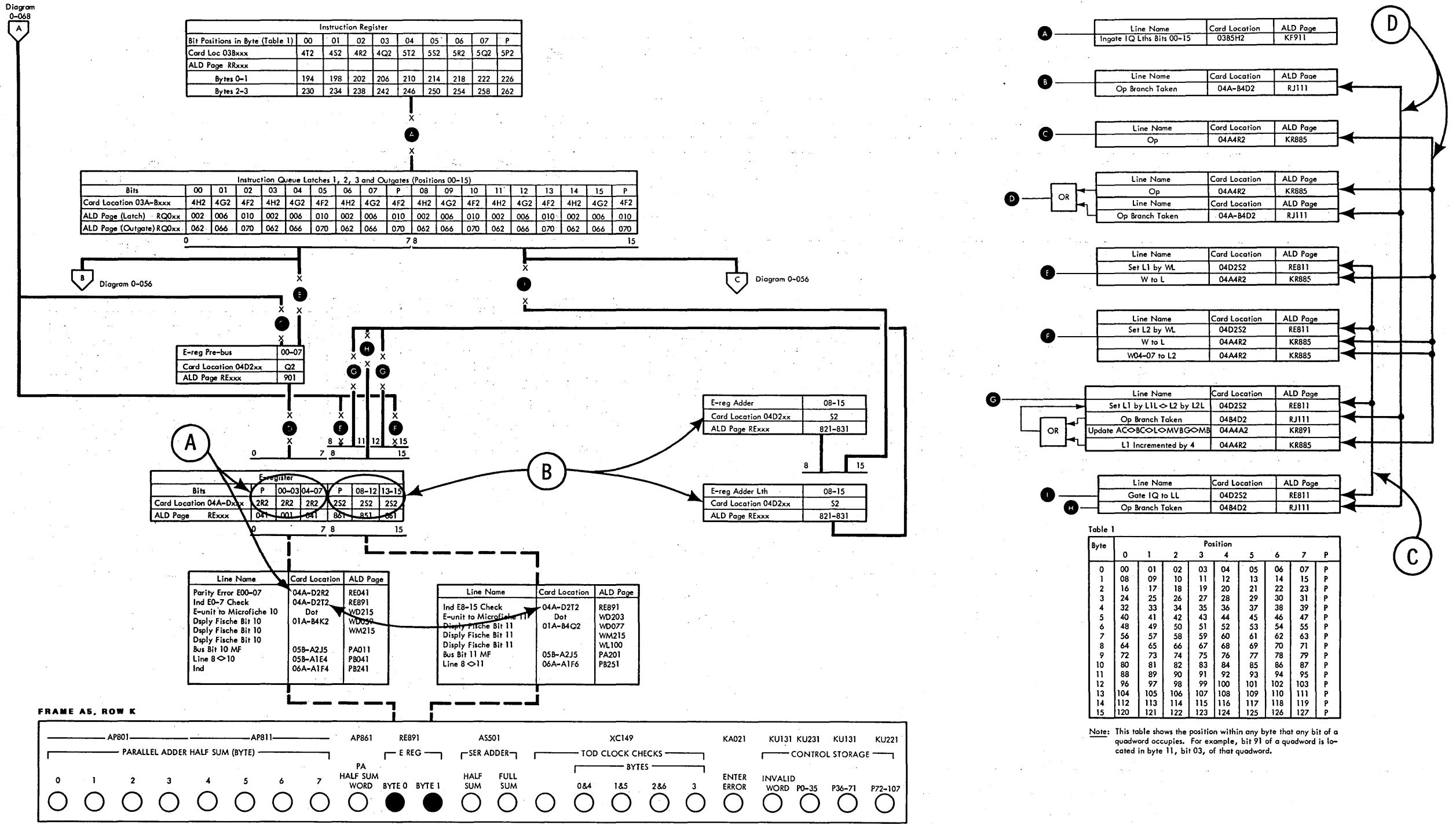


Figure 10-10. E-Register Functional Packaging

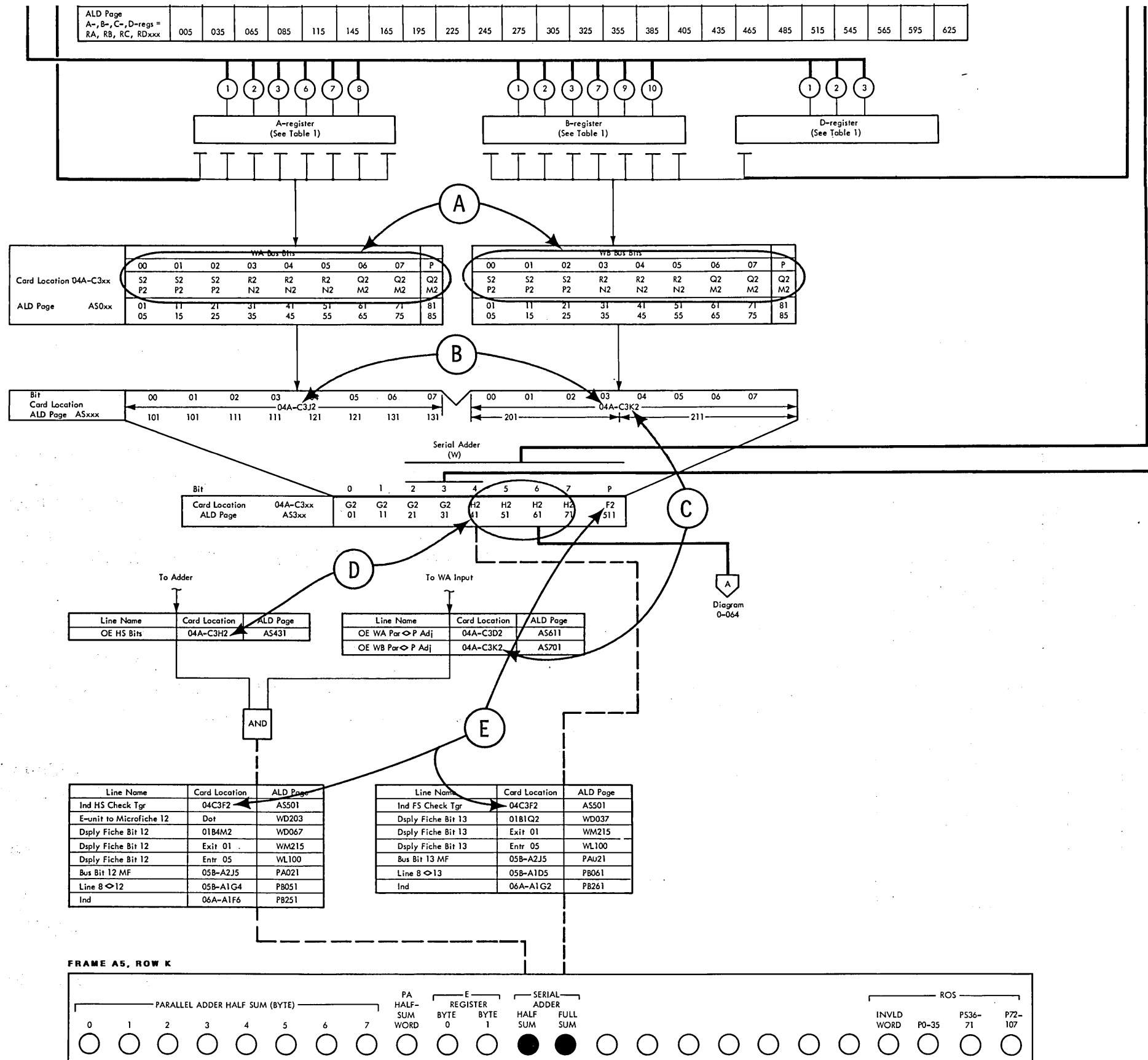


Figure 10-11. Serial Adder Checks

SCU TASKS

The tasks assigned to SCU are divided into seven main variations.

1. CPU fetch - data not in buffer
2. CPU fetch - data in buffer
3. CPU store - data not in buffer
4. CPU store - data in buffer
5. Channel fetch
6. Channel store - data not in buffer
7. Channel store - data in buffer

Each of the above seven main tasks starts with a request to SCU controls. The requesting unit starts the SCU by sending its request signal and by placing an address on the SCU address bus. Requests can come to SCU from either CPU or channels and can arrive at SCU in any sequence or any number of simultaneous requests.

CPU requests come from the I-unit address registers - IARA, IARB, source and destination. Each of these registers has its own request line to SCU which turns on a corresponding request latch. These latches in SCU start the sequence of operation and generate an identifying code so that SCU can know during the processing of a request where it came from.

Channel requests are identified in a similar way, but because of the speed requirements of the faster I/O devices, channels have the highest priority and channel requests are handled by SCU slightly differently from CPU requests.

Four of the seven SCU tasks are necessary to fetch and store from the two users of main storage, CPU and channel. The use of the high-speed buffer makes the additional three tasks necessary. Because of the way the high-speed buffer is used, CPU requests always check the buffer to see if the addressed main storage location is in the buffer, but the buffer is checked only on a store for channel requests.

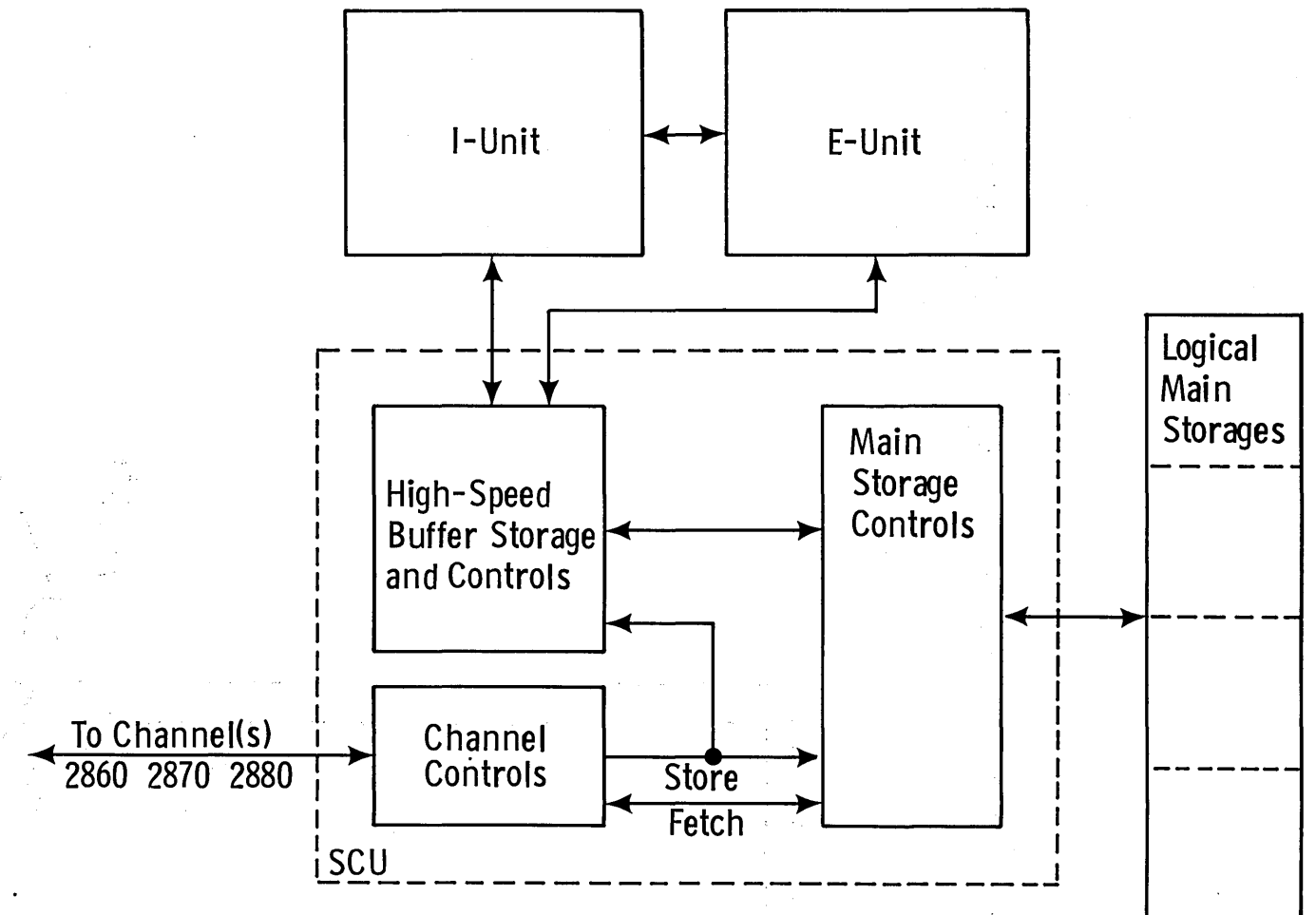


Figure 11-1. SCU Tasks

Figure 11-2. Storage Control Unit (SCU)

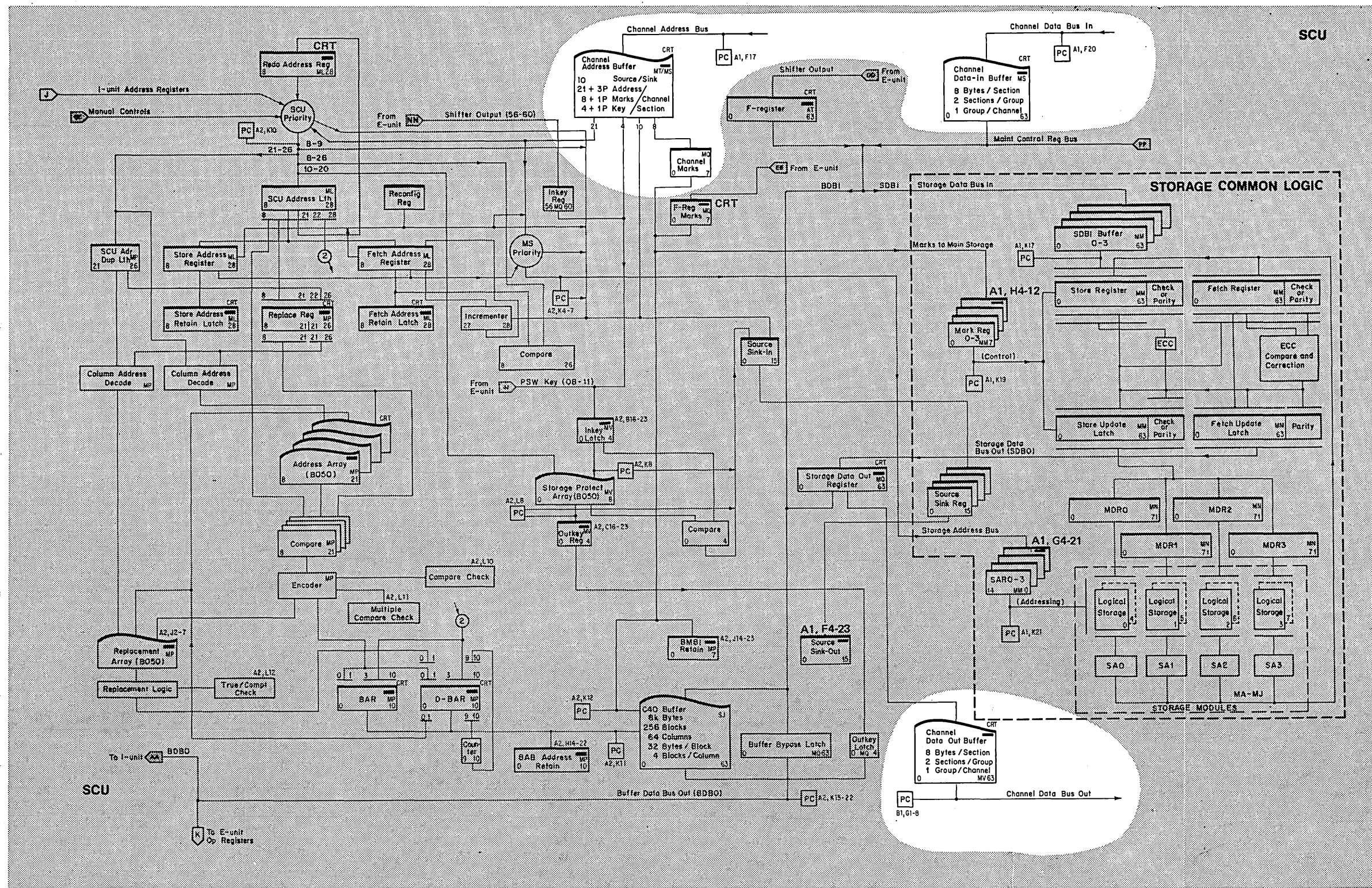


Figure 11-3. Channel Control Area

HIGH-SPEED BUFFER CONTROL AREA

The storage control unit (SCU) contains the high-speed buffer and controls all buffer and main storage references made by the CPU, the channels, and manual controls. The buffer storage control portion of the SCU handles CPU to main storage references, both fetches and stores. Parity checking is used for data verification in the buffer.

When a data fetch request is made by the CPU, buffer storage control determines whether or not the requested data is in the high-speed buffer in interrogating its address array of the buffer's contents. If the data requested is present in the buffer, it is sent directly to the CPU without a main storage reference. If the requested data is not currently in the buffer, a main storage fetch is made. The data obtained is sent to the CPU. The data is also assigned a buffer location and stored in the buffer. When data is stored by the CPU, both the buffer and main storage are updated if the main storage location being altered is one whose contents are currently being maintained in the buffer.

The channels never access the buffer directly. They read into and write from main storage only. When a channel stores data in main storage, the address array is interrogated. If data from the affected main storage address is being maintained in the buffer, the data is placed in the buffer as well as in main storage.

The entire buffer can be disabled manually by a system console switch or via execution of a DIAGNOSE instruction. When the buffer is disabled, all CPU fetches are made directly to main storage and effective system execution speed is reduced.

Figure 11-4. High-Speed Buffer Control Area

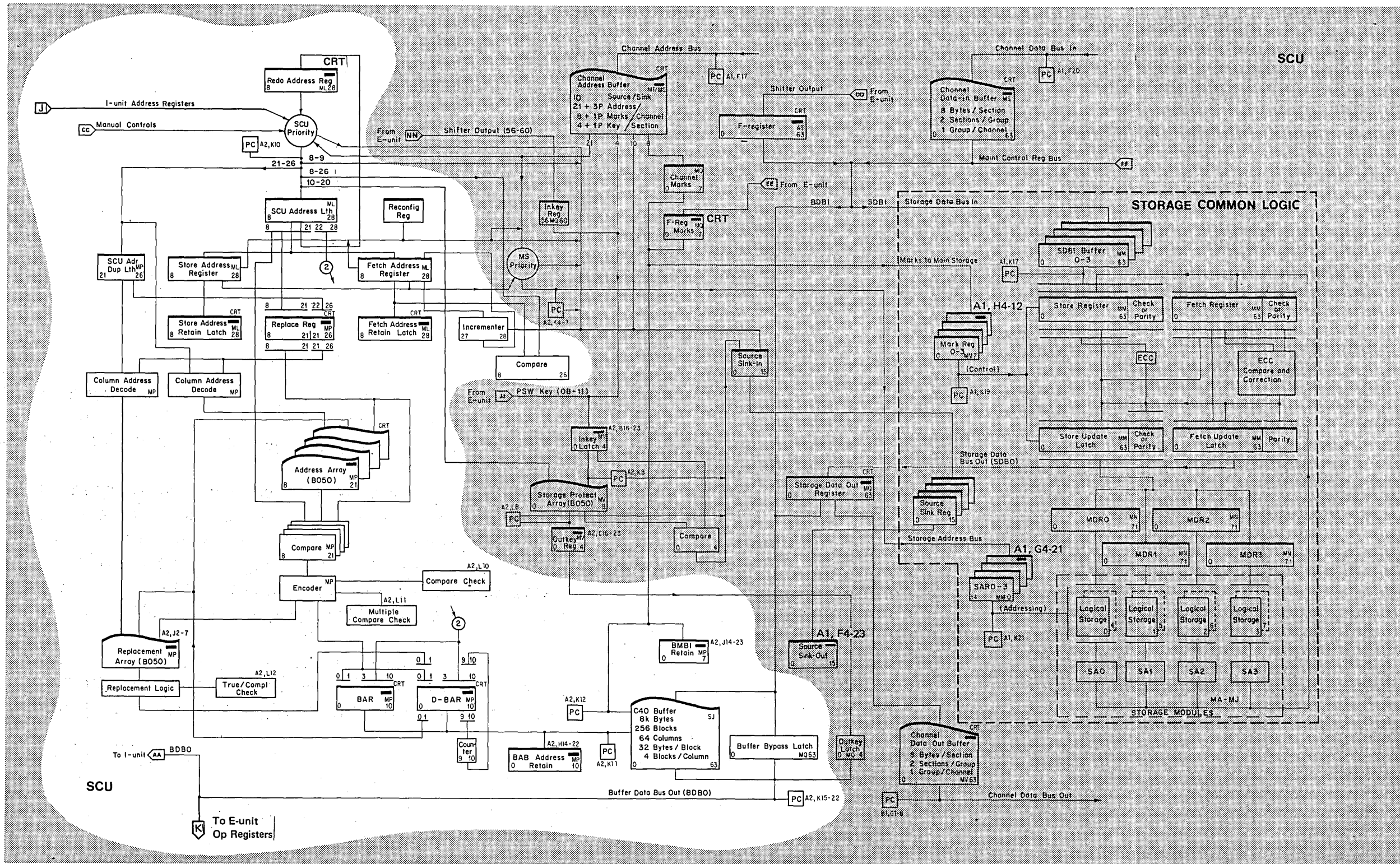


Figure 11-5. High-Speed Buffer Control Area.

MAIN STORAGE CONTROLS

All control signals and data pass through the main storage control section of SCU. Circuits to assign priority between requests for channel and the various parts of CPU are located in this section of SCU.

The main storage control section receives requests from the high-speed buffer controls or the channel controls. The request is then processed first through the priority circuits. Then a select is sent to main storage along with an address, source-sink bits, and data and marks if a store. At advance time, main storage controls receive the source-sink bits as well as the data for a fetch and sends the information to its proper destination.

The main storage control section also has the circuits that permit pluggable control in interleaving addresses. Under control from the console, serial, two-way, or four-way interleaving is possible.

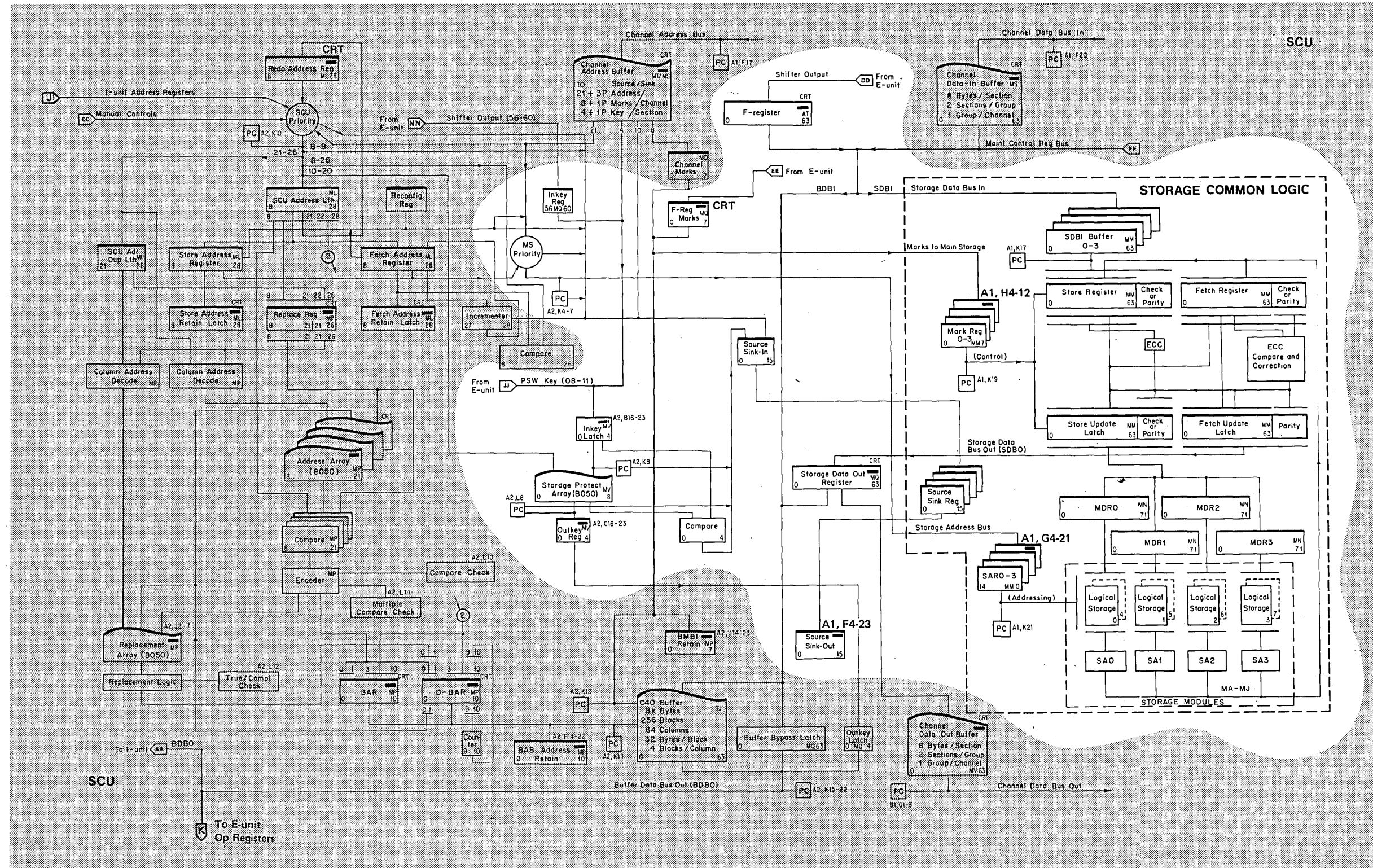


Figure 11-7. Main Storage Control Area

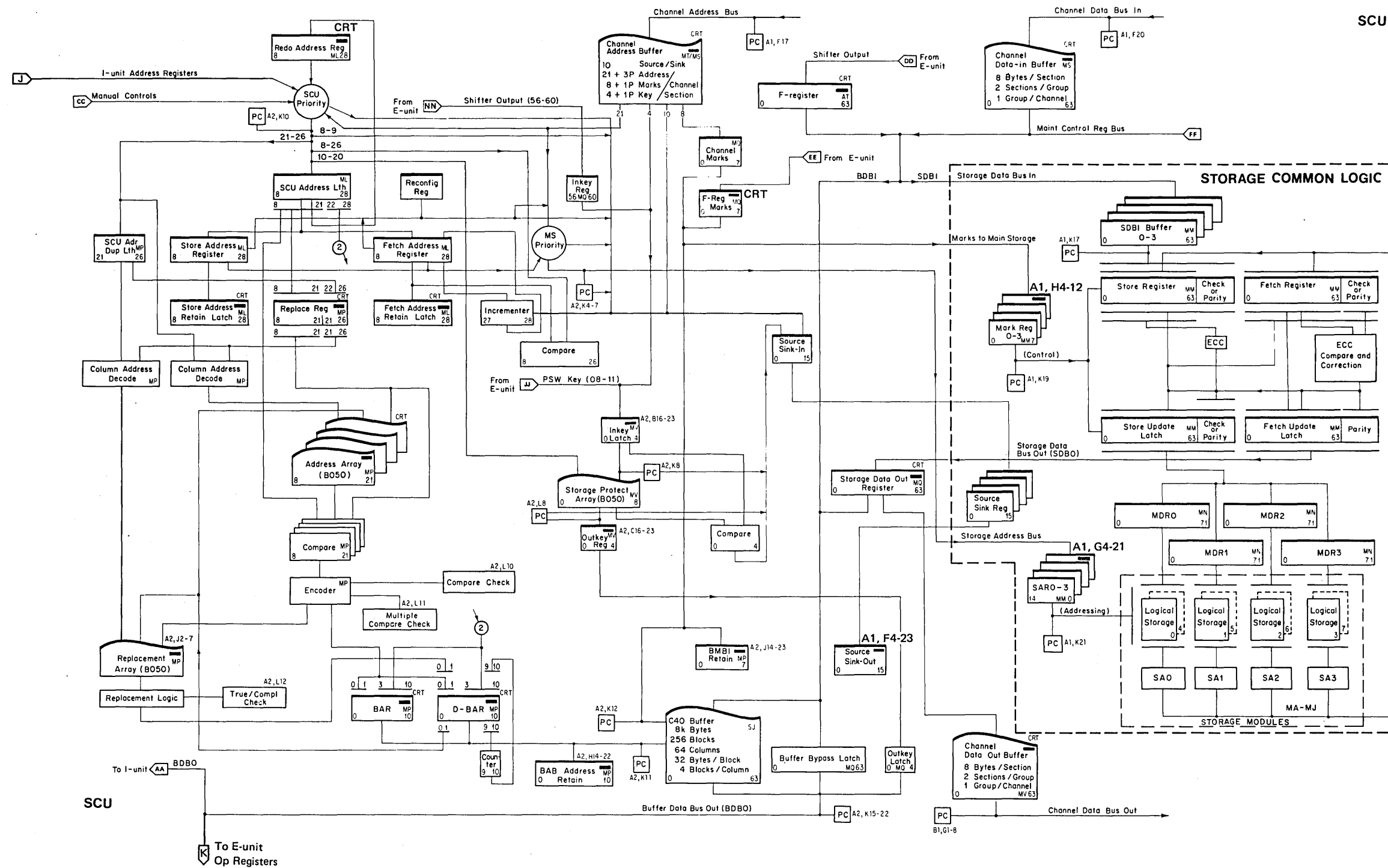


Figure 11-8. SCU Data Flow

CHANNEL BUFFERS

The basic machine includes three channel buffers which are divided into fourteen sections; two sections per channel. The sections are numbered 1-0, 1-1, 2-0, 2-1, etc., 7-0, and 7-1. When the extended channel feature is added, the buffers are divided into 24 sections numbered from 1-0 through D-1 but skipping 8-0 and 8-1. The three channel buffers are channel address-in, channel data-in, and channel data-out. The channel address in buffer has 48 data bits which are organized as follows: ten bits for source-sink information, 24 bits for address, nine bits for store marks, and five bits for protect key. Each of the data buffers include 72 bits for a doubleword of data.

Although two sections are provided for each channel, the only channel that makes use of both sections is the 2880. The other channels will always be using the first section or x-0 (x = the channel buffer group assigned to the channel). Channel buffer sections are assigned to the channels by group numbers. The group numbers are not necessarily synonymous with the digit of the channel address.

Figure 11-9. Channel Buffers

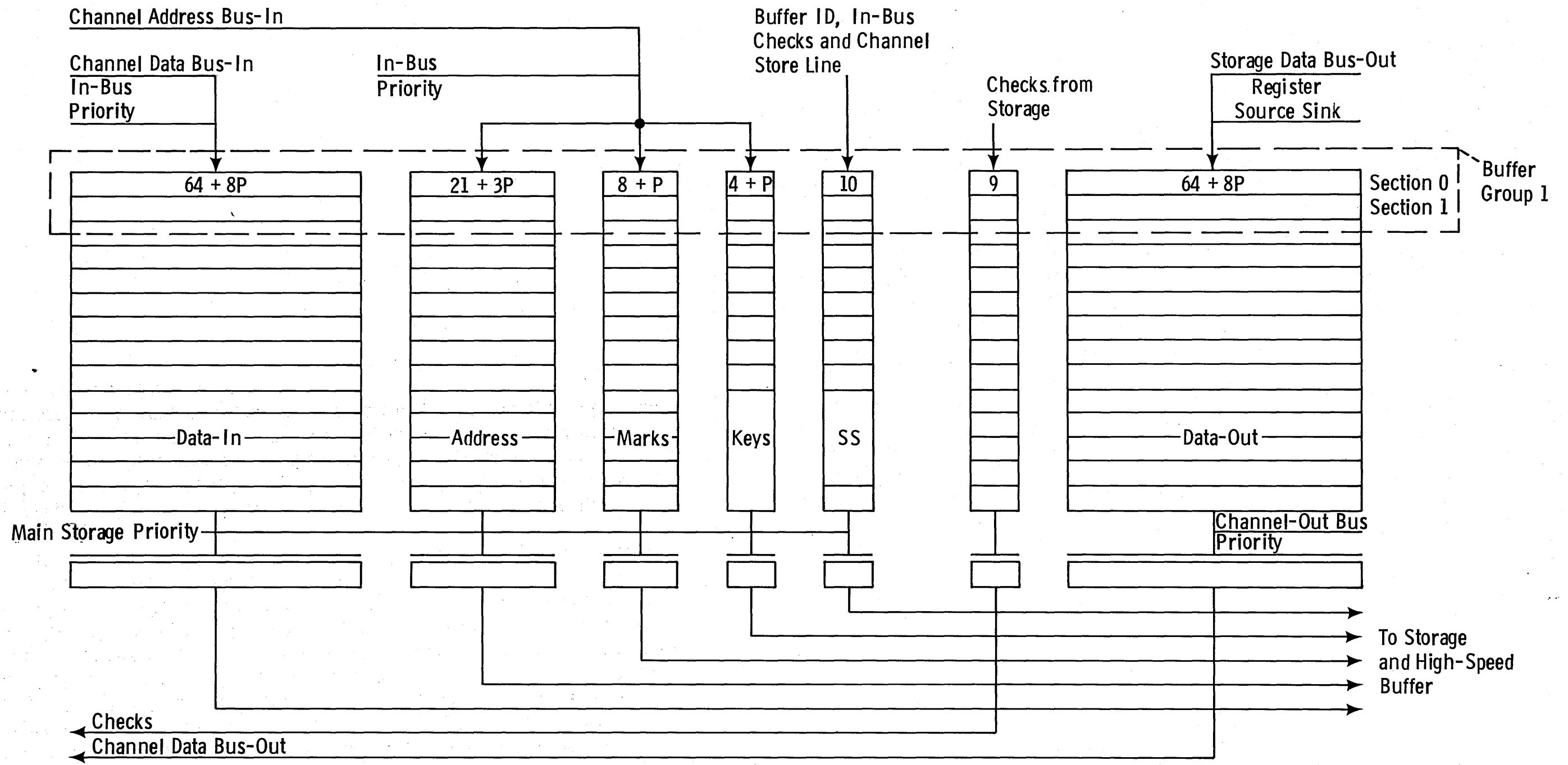


Figure 11-10. Channel Buffers

ERROR CORRECTION

- Error correction detects and corrects single-bit errors.
- Error correction uses four data registers.
- Error correction converts parity bits to ECC bits.

Each main storage access moves a doubleword (72 bits--64 data and eight error correction) through storage common logic. The error correction bits provide a means of automatically detecting and correcting single-bit errors. However, multiple-bit errors (though detected) are uncorrectable and must be stored as is. Either type of error is indicated to allow the CPU to determine any necessary action.

Before considering the method used to generate error correction bits, consider parity checking. In parity checking (used when ECC is disabled), one position of a byte is reserved for a parity bit. The parity-check logic sets this bit to a 1 or 0, as required, to make the total number of 1s contained in the byte an odd number (odd parity). If any bit position changes status during the transmission of data, the byte parity becomes even and the parity-check logic detects the error. No method of correction is provided by parity checking, and even multiples of errors in a byte will go undetected.

The error correction bits constitute a special type of parity checking. In a normal parity scheme, as described above, each data bit contributes to the status of the associated parity bit. Note that each data bit exhibits an equal amount of influence on the status of the parity bit. With error correction code (ECC) logic, the parity bits are replaced by a group of seven bits which record a parity sum. Each data bit contributes to this sum. No two data bits contribute the same amount; however, the amount contributed by any one bit is equivalent to the position of that bit in the doubleword. Thus, bit position 1 contributes to ECC bit 1, position 2 contributes to ECC bit 2, and position 3 contributes to both ECC bits 1 and 2. Additionally, bits 0-32 contribute to ECC bit 0, and bit 0 also contributes to ECC bit 32.

Eight check bits are identified as C0, C1, C2, C4, C8, C16, C32, and Ct. The last check bit, Ct, acts as a parity bit for the other check bits. Odd parity is always maintained.

The purpose of the high-speed buffer is to speed up CPU request for data. The buffer produces the effect of a faster main storage by storing selected sections of main storage that are likely to be used next by the CPU. When the required information is in the buffer a request for data can be filled quickly. This leaves the times that CPU must wait for the longer main storage access time to the requests that do not find the needed data in the buffer. The buffer is constructed and used in such a way that better than 90% of the time, the buffer will contain the requested data.

The overall effect of the buffer and the way it is used is to make main storage appear to have an 80-nsec cycle time instead of its actual two usec cycle time. To use the buffer, the SCU processes all request from the CPU for data by first checking to see if the buffer has the requested data. If the buffer has the data, the request is filled by cycling the buffer and sending the data to the requesting section of the CPU.

If the buffer does not have the requested data, a fetch is made to main storage and the CPU must wait the full main storage access time.

When the SCU receives a request to store data into main storage from the CPU, the buffer again is checked to see if the addressed location is in the buffer. If the buffer contains the addressed location on a CPU store, both the buffer and main storage are stored into. If the buffer does not have the addressed location, the store is made to main storage only.

A fetch request for main storage data from a channel does not involve the buffer. Main storage is addressed and the data is sent to the requesting channel. When a channel wants to store information into main storage, the buffer is checked to see if the store location is in the buffer. If the store location is in the buffer, SCU stores the information into both the buffer and main storage.

Figure 11-11.

Figure 11-12-1.

When data is stored, the data bits in the store register are used to generate the stored ECC check bits. When data is fetched, the data bits in the fetch register are used to generate new ECC check bits. These new ECC check bits are then compared with the check bits in the fetch register that had been stored and were fetched with the data bits. An equal comparison of the fetched check bits and the newly generated check bits indicates no error. An unequal comparison indicates an error, and bits known as syndromes are generated from the two sets of check bits.

The syndrome bits, identified as S0, S1, S2, S4, S8, S16, S32, and St are decoded to indicate and correct the changed bit (even a change of the check bit) if only one bit has changed. If two or more bits have changed the syndrome bits decode and signal an uncorrectable error.

The error correction circuit uses four registers to hold data before, during, and after error detection and correction. Two registers (RS and RF) hold the data before and during detection and two registers (SUL and FUL) hold the data after detection and correction. The correction circuit always operates regardless of error occurrence. Error correction circuits also prepare new ECC bits for store operations.

The four ECC registers, RS, SUL, RF, and FUL, are identical; each consists of 64 data bits and eight parity or check bits for the left half and 64 data bits and eight parity or check bits for the right half.

STORE REGISTER

The store register (RS) receives data from one of two sources, the storage data buffer-in registers for new data or the storage bus-out (SBO) from the LSU's.

Gating into RS is on a byte basis under mark bit or "cancel" signal control. Each mark bit is associated with a byte; if the mark bit is set, the byte is transferred from the buffer register, and, if the mark bit is clear, the byte is transferred from the LSU. The "cancel" signal causes all bytes to be transferred from the LSU.

The setting of RS occurs approximately 1200 nsec into the storage cycle.

The ECC logic generates check bits from the data bits in RS; the check bits, as well as the data bits, are available for transfer to SUL.

Figure 11-12-2.

STORE UPDATE LATCHES

The store update latches (SUL) register receives data from one of two places: RS (during a normal fetch, store, or TAS cycle) or from RF if an uncorrectable error has occurred.

If, during a fetch cycle or a partial store cycle, a correctable had been detected, during the transfer from RS to SUL, the faulty bit and the associated ECC bit would have been corrected. However, if a correctable error had occurred in a marked byte, the correction would have been blocked since the marked byte contains new data.

The transfer from RF to SUL occurs if an uncorrectable error occurs; this transfer overrides the transfer from RS since the data is to be regenerated exactly as it was received from the LSU.

The data in SUL is made immediately available to the applicable LSU.

FETCH REGISTER

The fetch register (RF) unconditionally receives data from the LSU at about 1200 nsec into the cycle.

The ECC logic generates new check bits from the data bits in RF. These new check bits are compared with the check bits that are received from the LSU (and stored in RF with the data bits). If an equal comparison is found (indicating no error), the data bits in RF are transferred to FUL and the check bits are replaced with newly generated parity bits. If a correctable error had been detected, the failing bit and associated parity bit would have been corrected during the transfer from RF to FUL. Also, if a fetch or a partial store cycle had been in process, the failing bit and the associated check bit would have been corrected during the transfer from RS to SUL.

If an uncorrectable error occurs, the data and the check bits in RF are transferred to SUL, bypassing the ECC logic associated with RS.

FETCH UPDATE LATCHES

The fetch update latches (FUL) register always receives data from RF. The content of FUL is gated to the CPU about 20 nsec after the setting of FUL.

Figure 11-12-3.

CHANNEL BUFFERING

Each channel has a fixed assignment of one buffer group and each group consists of two sections. A buffer section stores all the information for one main storage access. Each buffer section stores data in, data out, marks, key, address, and various check and identification information.

Channel requests for input or output information must first vie for priority on the channel-in bus. The order of in-bus priority is established by inserting jumpers on a matrix card located in Frame 03. The wiring of the jumpers for a particular system results in a fixed-buffer assignment to each channel which is displayed on the microfiche viewer.

When in-bus priority is resolved, the appropriate channel is signalled. The channel, in turn, responds with address, marks, key and, if a store operation, a doubleword of data and a store signal. Upon the receipt of an address valid signal, this information is loaded into one of the channel's assigned buffer sections. If both buffer sections are empty (X 0 and X 1 where X is the buffer group number), the channel transfer is loaded into section X0. If a buffer section is not available for use (empty), that channel is blocked from receiving in-bus priority.

Once a buffer section is loaded, it is set to a busy state and entered as a contender into main storage priority. After main storage priority has been received, the storage unit is selected. Identification of the channel buffer section is placed on the source-sink bus-in, and the buffer section contents are gated to main storage. Main storage control receives the address, marks, and key. In the case of a store, the buffer section contents are also gated to the high-speed buffer control section to update the buffer if the address block is in the buffer.

When the channel request processing is completed by main storage, a storage signal followed by data, source-sink identification, and error information is sent to the main storage control which assembles and sends the information to the initiating channel buffer section.

Figure 11-13-1.

When the information from storage is loaded into a channel buffer section, use of the channel out-bus is vied for by entering channel-out bus priority. When priority is resolved in favor of a buffer section the contents of that buffer section are gated onto the channel-out bus. At this point that buffer section is made not busy. All address and data type checks, associated with this channel request, are sent to the channel at the same time as the channel buffer data.

Figure 11-13-2.

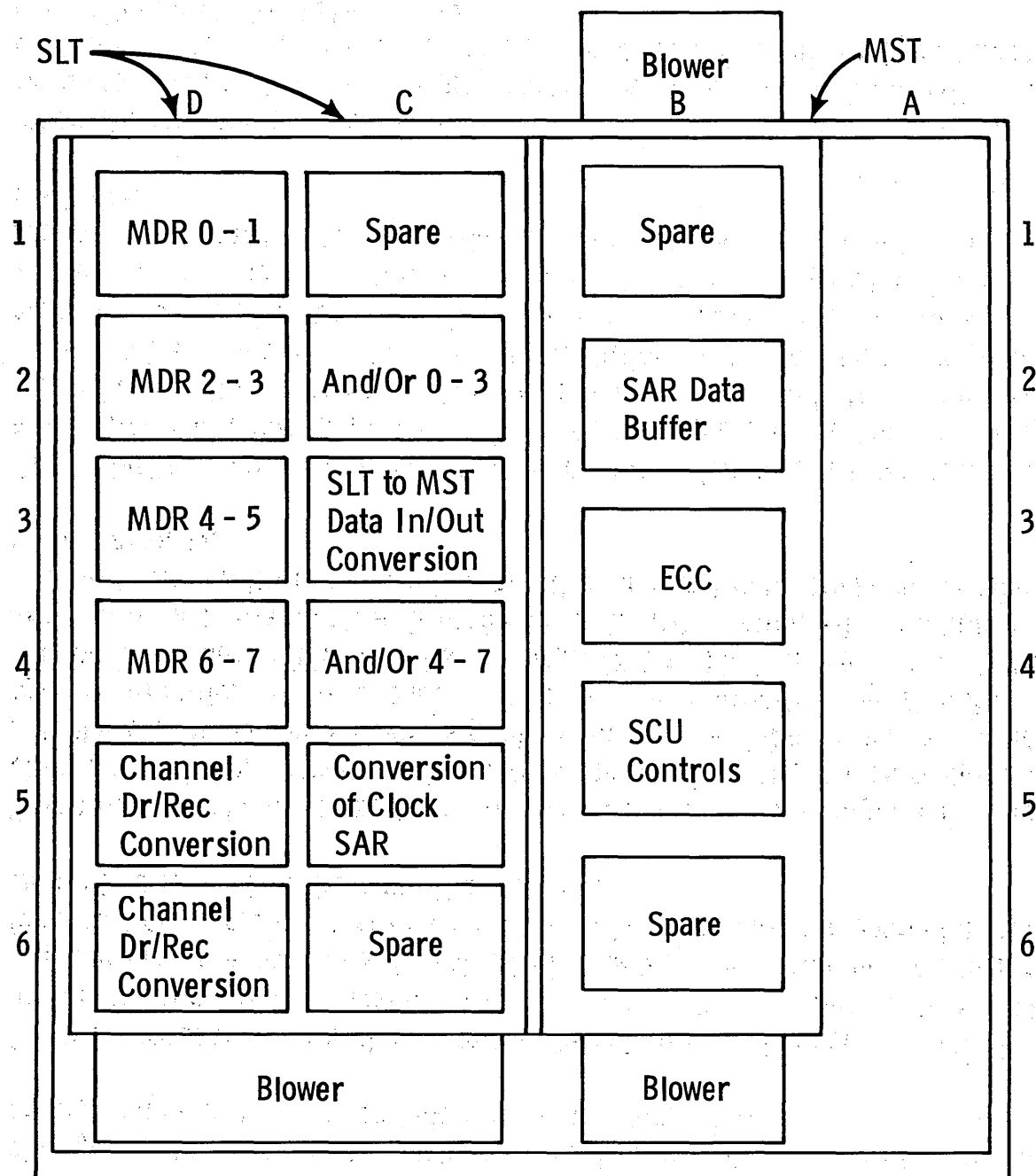


Figure 11-14. CPU Frame 02

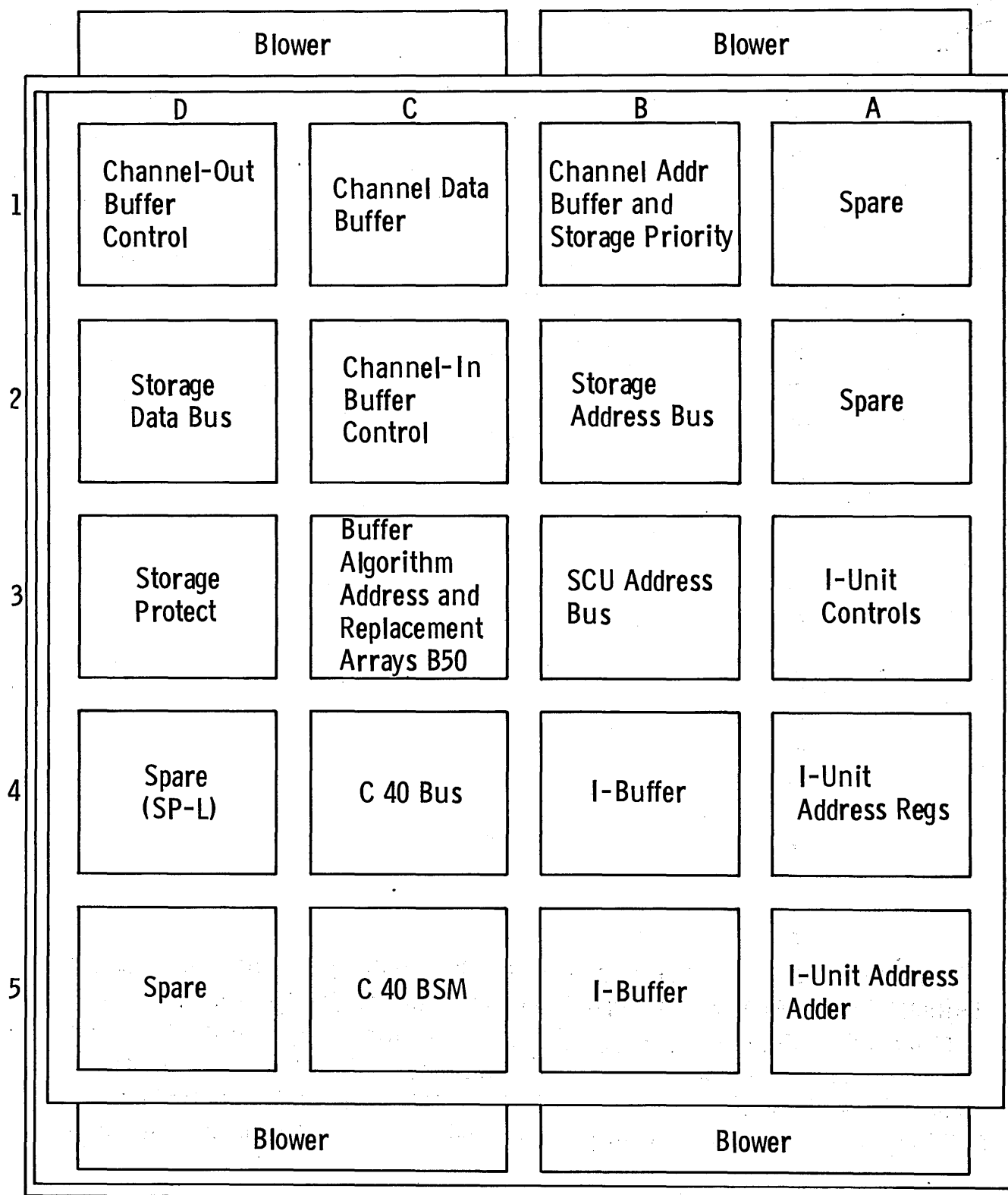


Figure 11-15. CPU Frame 03

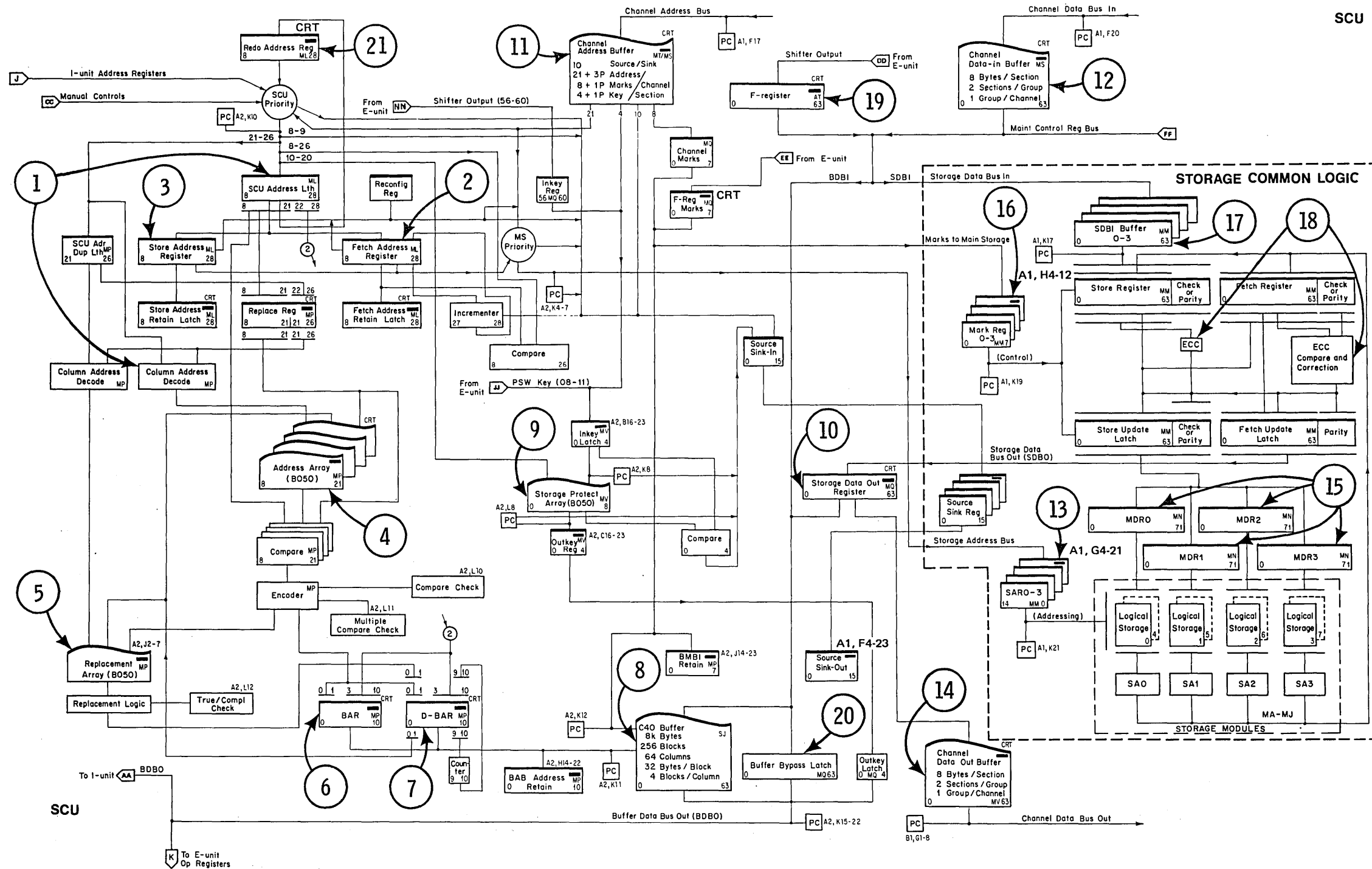


Figure 12-1. SCU Data Flow

CPU FETCH - DATA NOT IN BUFFER

All SCU operations begin when the originator of a request to either store or fetch data presents an address and sends a request signal. The address arrives at SCU at the input to the SCU address latches. A simplified data flow is shown on SCM 12-4. High speed buffer controls are not shown because the example chose does not find the data in the buffer. Note that the address input path to SCU enters by way of the priority circle. The circle in this figure represents the input control to SCU. All requests must go through the priority circuits to start an SCU operation.

Each part of the system that makes requests to SCU has its own request latch located in the SCU. When a request latch is turned on, SCU operation starts.

For an example, the SCU starts the fetch processing when the I-unit turns on the source request latch. (Address in Source Request Latch). This latch makes an entry into the SCU priority circuit. If there are no higher priority requests waiting - destination, redo, nor any channel request - source is given priority. The I-unit can alter the priority sequence by sending a control line that can give instruction address register A or B preference over the source request.

Once the SCU grants priority to a request, the source request in this example, several things must take place. First, a test (MS CPU Adv) to see if some previous request is being filled on this cycle, because if data is returning from main storage the buffer would be in use. The "source address gate trigger" is turned on to gate the address from the source address register to the SCU address latches. The "accept" signal is sent to the I-unit to tell that the source register contents have been taken and that the source register can be made not busy.

Also, the granting of priority generates the identification bits that are passed through SCU to serve as control bits and at the end of the request handling to direct the data to the proper place. (Source Sink).

Another important item started by source priority is the reference to the high speed buffer. Although for the chosen example the requested data is not in the buffer, all CPU requests unconditionally check the buffer. The address from the source register is compared against the addresses in the address array and a decision is made in time to stop the request to main storage if the addressed data is in the buffer.

After a test to see if the fetch address register (FAR) is busy, the address is moved from the SCU address latches to FAR. If FAR is found busy at this point, the address and the identification bits are moved to the redo register and the request starts over as a redo request into SCU priority.

When the address is moved into FAR the bits are decoded to see which logical storage unit (LSU) is needed. The busy latches for the LSU's are used to see if the addressed LSU is available and if so a request for main storage priority is made.

If the FAR Busy trigger is on, to signify that the addressed data was not in the buffer, and if no higher priority request is in process, FAR is granted main storage priority. If a higher priority, or a busy LSU blocks FAR main storage priority, the FAR request can wait until the blocking condition ends. The address would stay in FAR and the ID bits would stay in the FAR ID triggers with the FAR busy trigger on to block any following request to use FAR.

FAR main storage priority sends the select signal to the selected LSU and gates the address in FAR onto the storage address bus. Also timing gate "FAR Op B" is turned on to gate the ID bits into the source sink latches.

The timing controls to the selected main storage BSM's have various time delay circuits that are needed to synchronize the BSM to the SCU. The "gated select and ready LSU" line gates the SAB into the selected SAR and also starts the two "delay line clocks" in the selected pair of BSM's.

Figure 12-2-1.

Figure 12-2-2.

About one microsecond after the start of the BSM's "delay line clock", a busy signal from each BSM occurs. The upper BSM "busy" starts a delay line in the SCU. This delay line controls the flow of the data returning from the BSM pair through the ECC circuits and finally into the storage data out register. And also gates out the source sink ID bits to the CPU. The lower BSM "busy" is used to control restarting the BSM delay line for the write half of the BSM cycle.

The data will pass out of the SDBO register, through the Buffer bypass latch to the CPU. Where it is directed to the area it is needed by the CPU's decode of the ID bits it received.

At this time the SCU will load the buffer with the block of data associated with the previous fetch. But we will not get into that right now.

Timings for the important parts of the fetch operation through the SCU can be seen on SCM 12-5.

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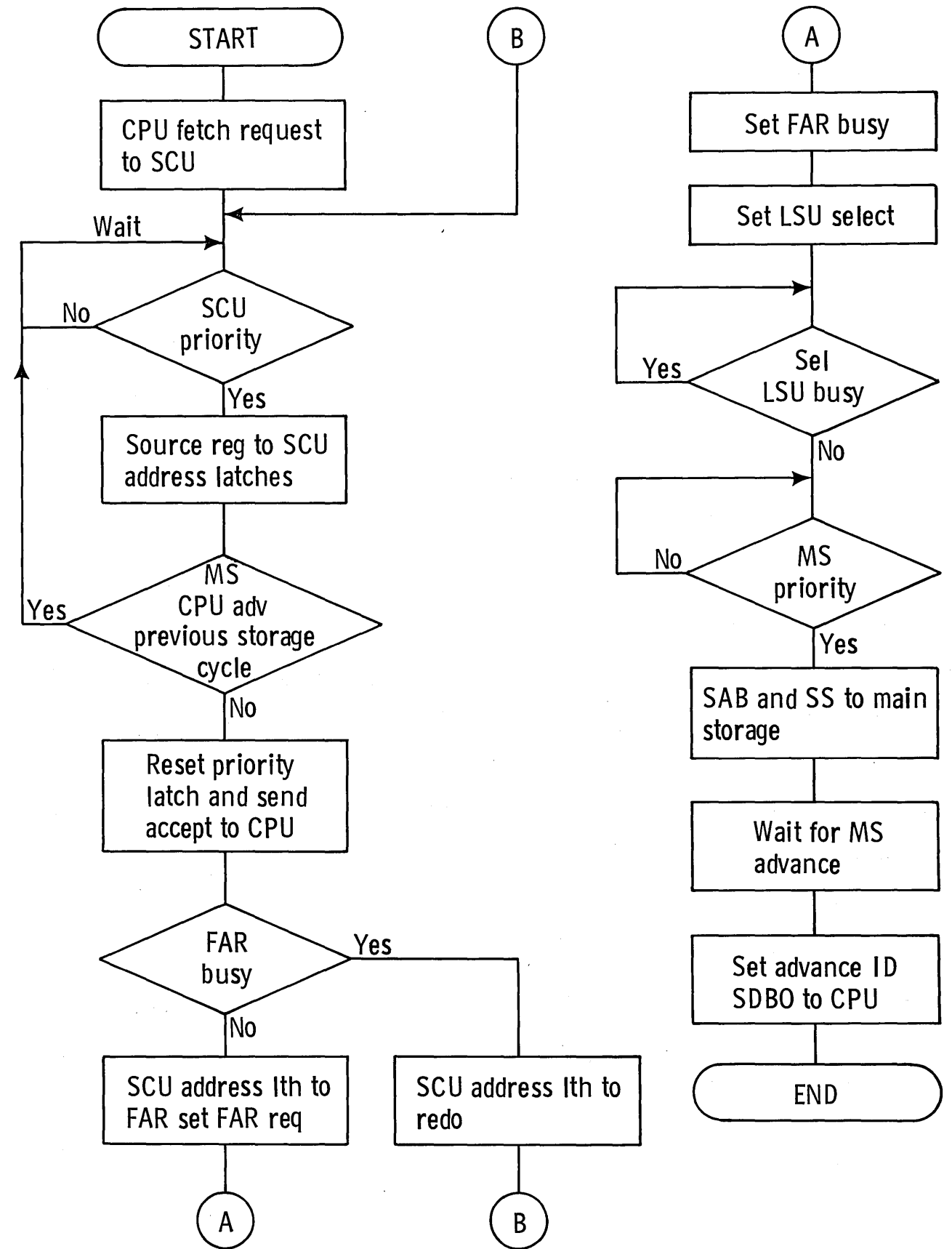


Figure 12-3. CPU Main Storage Fetch (Ignore Buffer Circuits)

Figure 12-2-3.

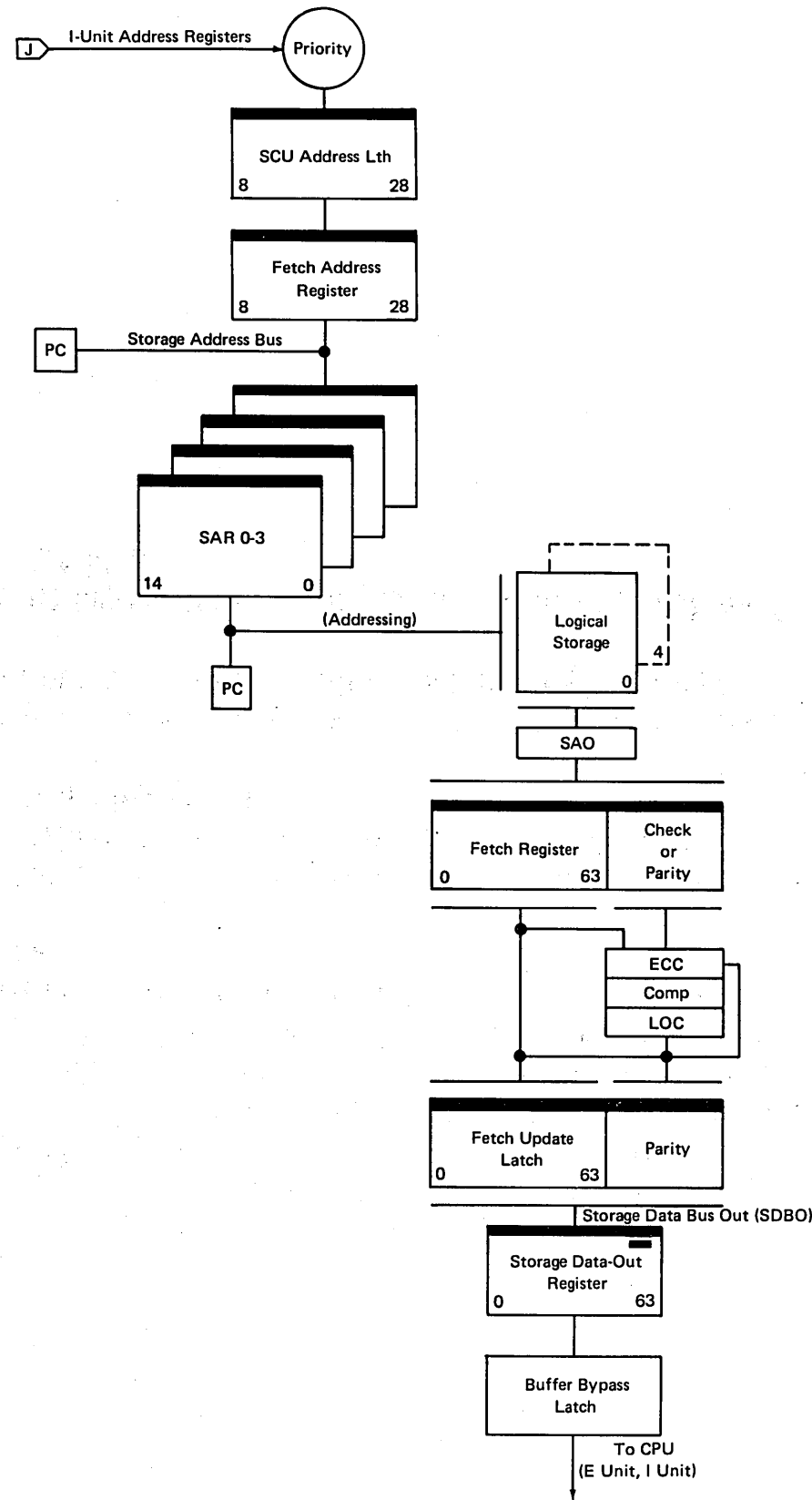


Figure 12-4. Simplified Data Flow - CPU Fetch

Reference Clock

- 1 Source Request
- 2 Source Priority
- 3 Source Accept
- 4 Gate SRC to BCU
- 5 SCU Address Latches
- 6 FAR
- 7 AGT ID Tgrs
- 8 Address Compare Latches
- 9 Possible FAR Req Lth
- 10 FAR ID Tgrs
- 11 FAR Busy Tgr
- 12 FAR Req Tgr
- 13 FAR MS Priority Lth
- 14 FAR Op B Tgr
- 15 SS Bits
- 16 CPU Select Mem (x)
- 17 Tgr Sample FAR to SAB

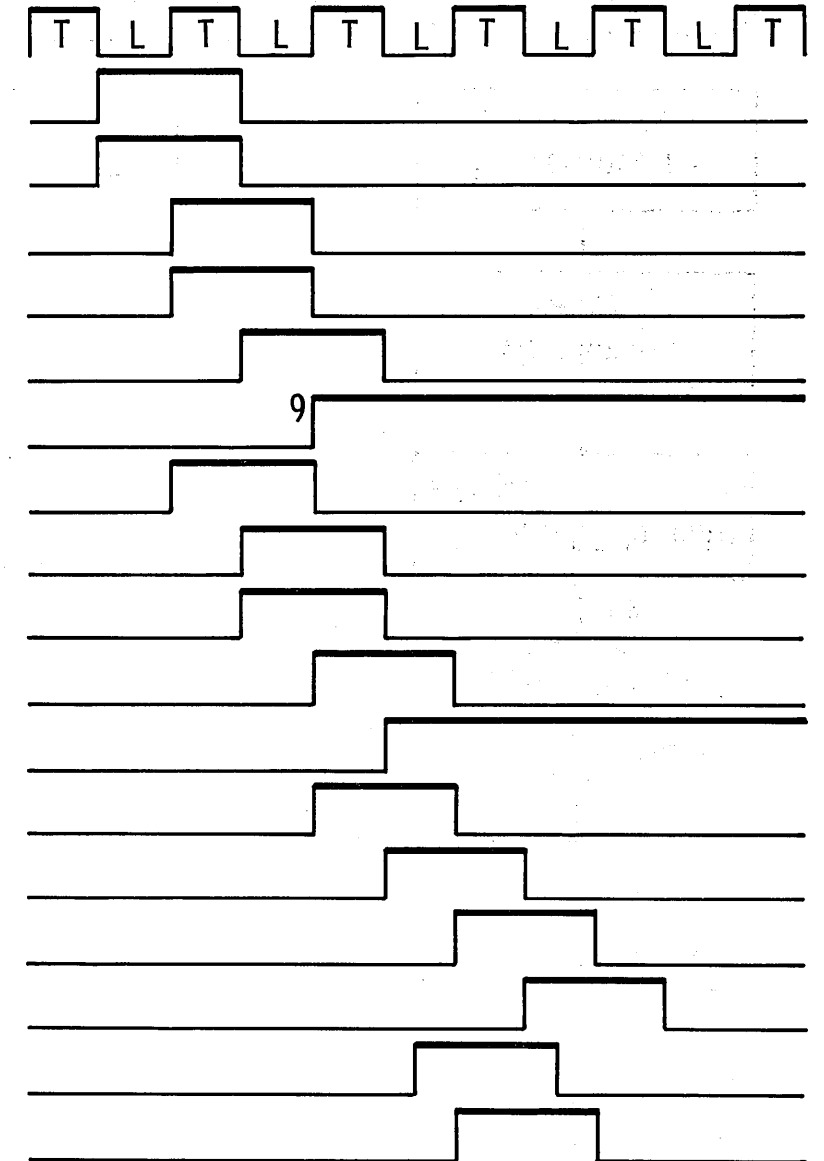


Figure 12-5. Source Fetch Timings

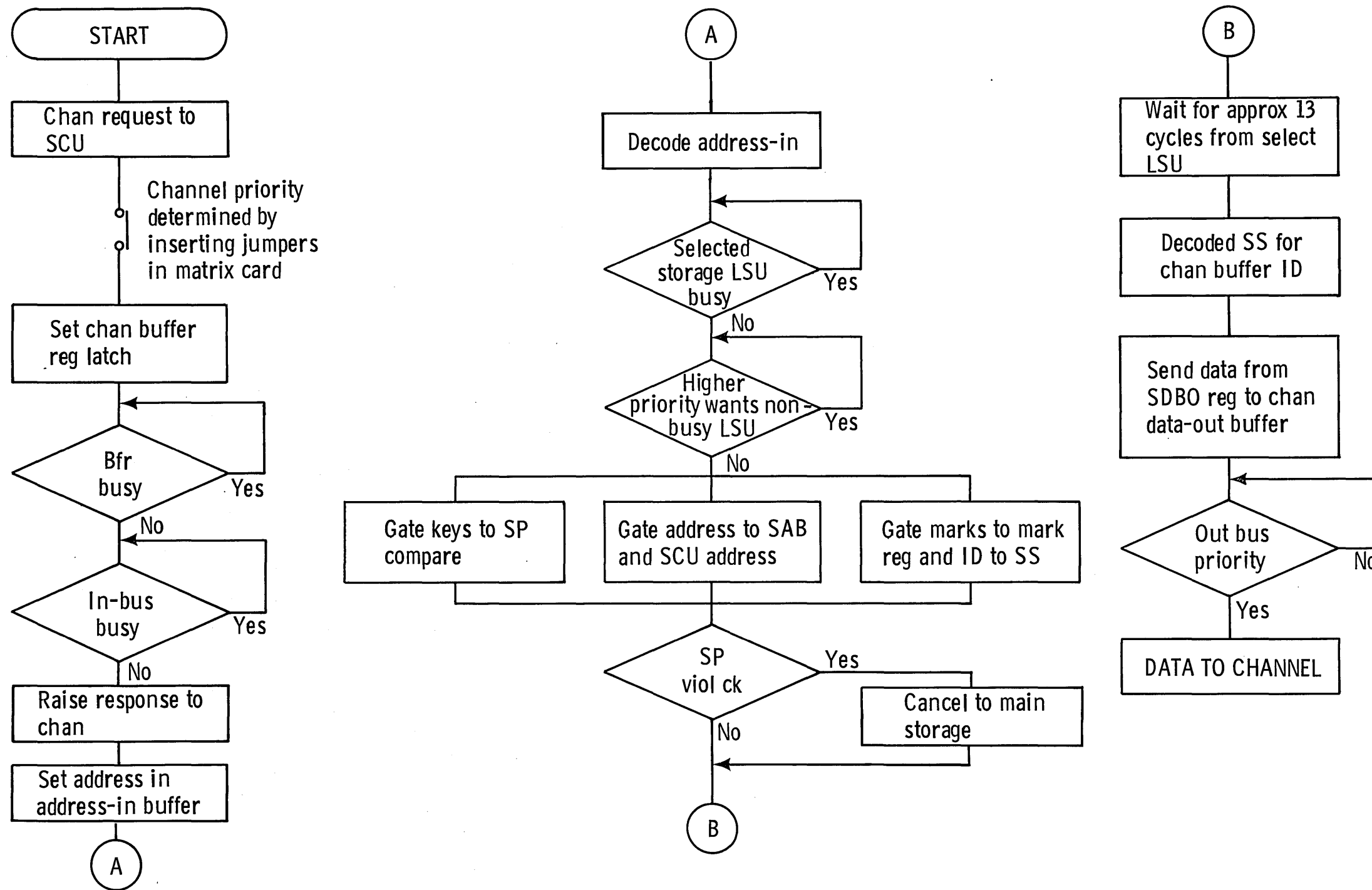


Figure 12-6. Channel Fetch

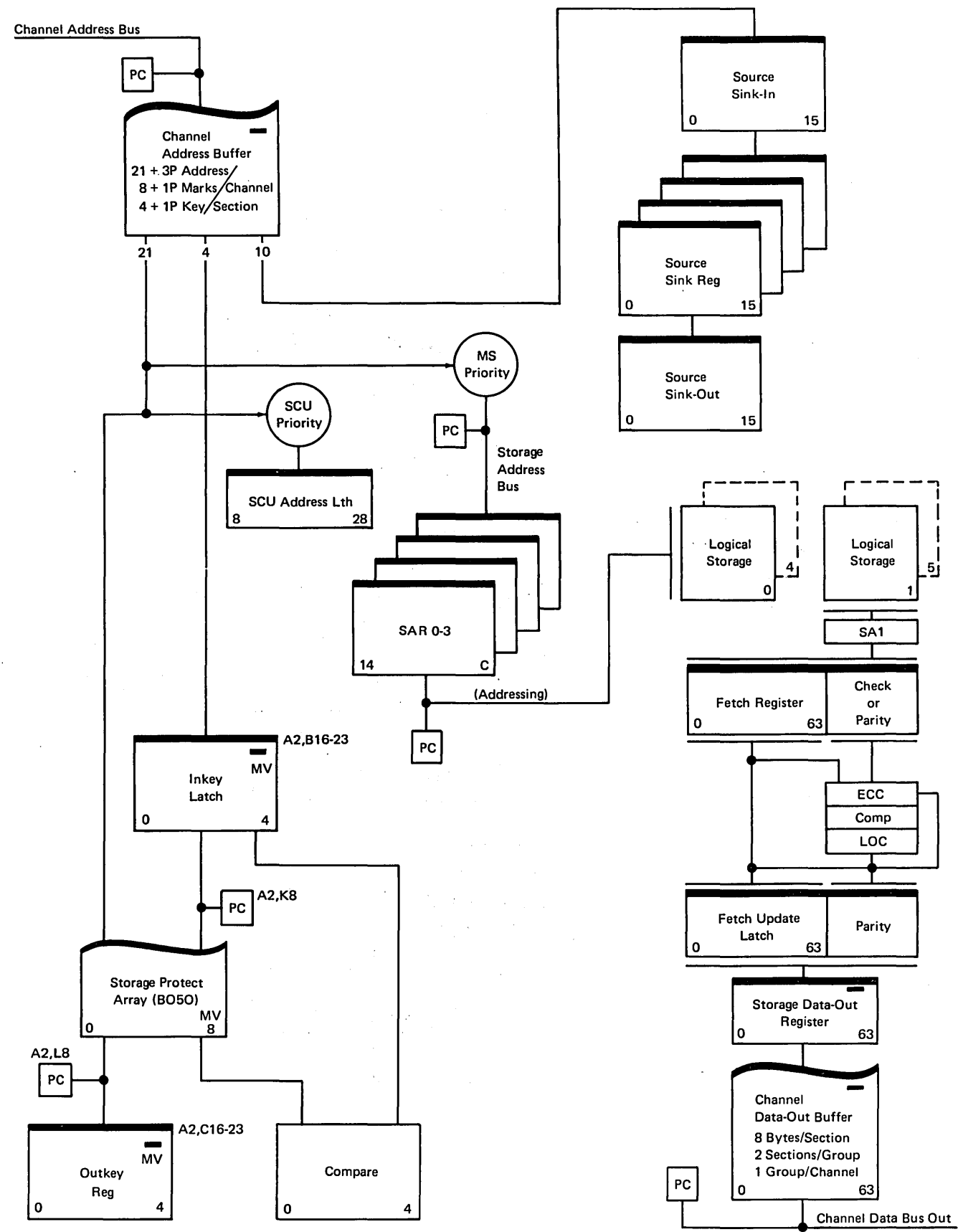


Figure 12-7. Simplified Data Flow - Channel Fetch

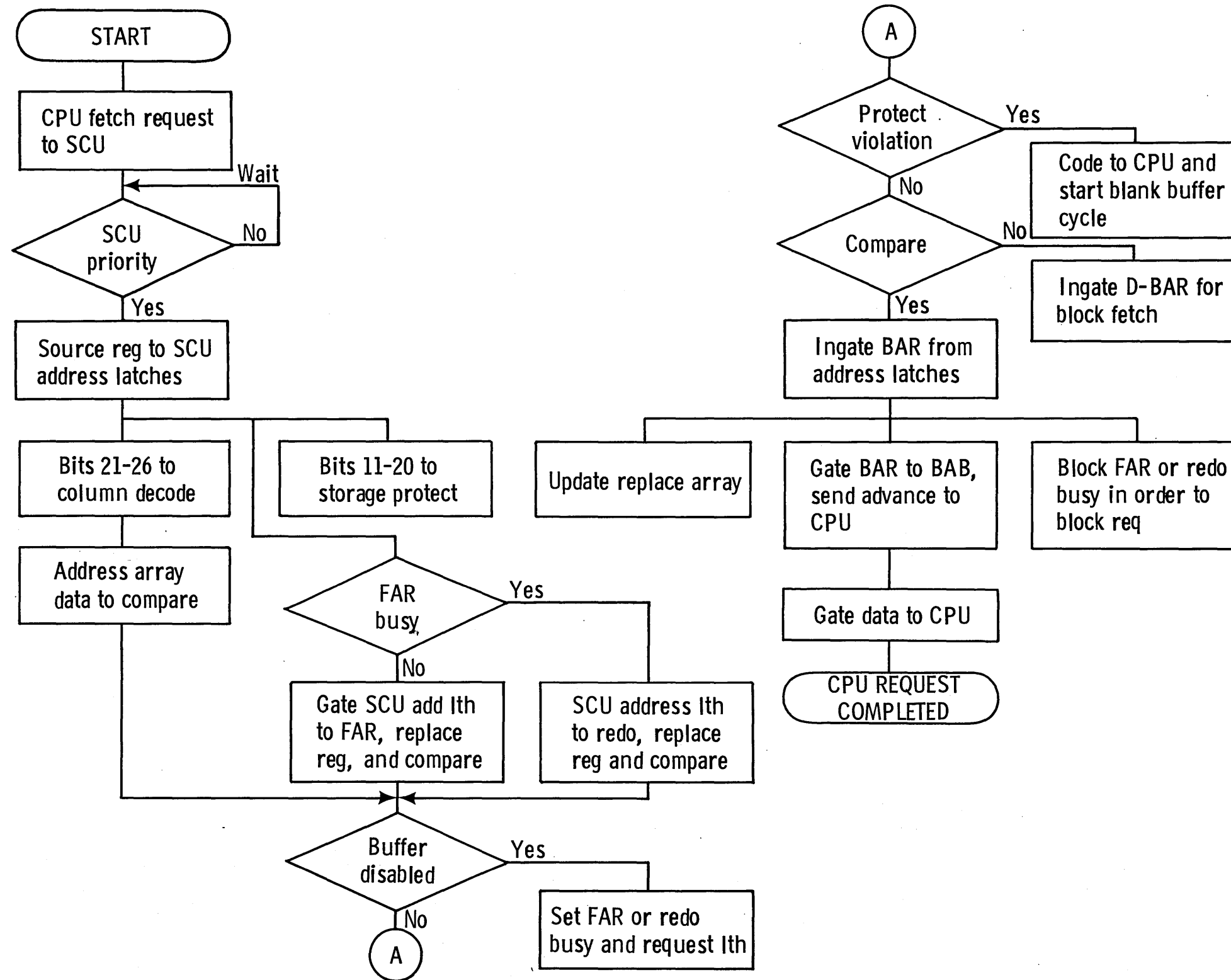


Figure 12-8. CPU Fetch, Data In High-Speed Buffer

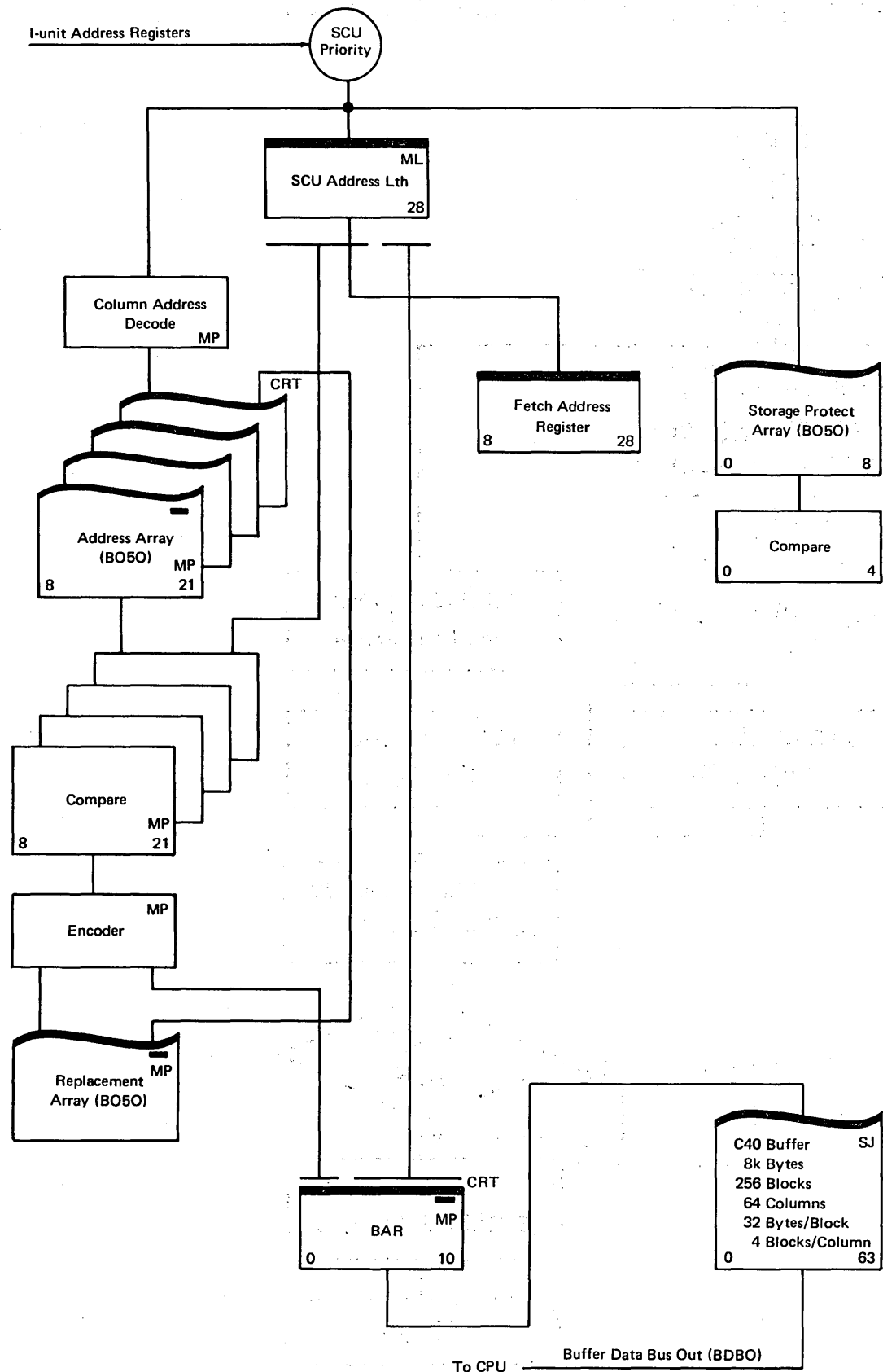


Figure 12-9. Simplified Data Flow - CPU Fetch, Data Found In HS Buffer

CPU STORE

All CPU stores are made from the destination register and except for channel or maintenance controls are under the control of the E-unit. The E-unit does a store by placing the data in the F-register and then sending the request signal to SCU. In most cases the I-unit will have already put the address in the destination register for the E-unit's use.

The address and request are sent to SCU. The priority circuits generate the ID bits for the source sink. Use the simplified flow chart, SCM 12-11 and simplified Data Flow SCM 12-12 to follow the store operation through the SCU.

As soon as the store gets SCU priority, the buffer is checked in the same way as the buffer was checked for a fetch.

With the address in the SCU address latches, accept is sent to CPU which allows the destination register to be made not busy. However, the data in the F-register must be held until the store vies for and gets main storage priority.

The address is next moved to the store address register and to the Buffer Address Register (BAR), (STAR) if STAR is not busy. STAR busy at this point would cause the request to start over as a redo request.

The address in STAR next causes a check to see which LSU is to be used and if the desired LSU is available (not busy). STAR then has to vie for main storage priority.

At this point the store could be blocked only by a channel request to some non busy LSU. When the store receives main storage priority, "STAR op time B" gates through the source sink-in bits into the desired LSU's source sink register and then turns on "STAR op time C" to gate the data to be stored from the F-register to the selected SDBI register. At the same time, BAR will address the high-speed buffer and F-register data will also be gated to the high-speed buffer.

Also the granting of main storage priority gates the address from STAR to the storage address bus and the select signal to the selected LSU. This gated select signal also gates the mark bus into the selected mark register.

Figure 12-10-1.

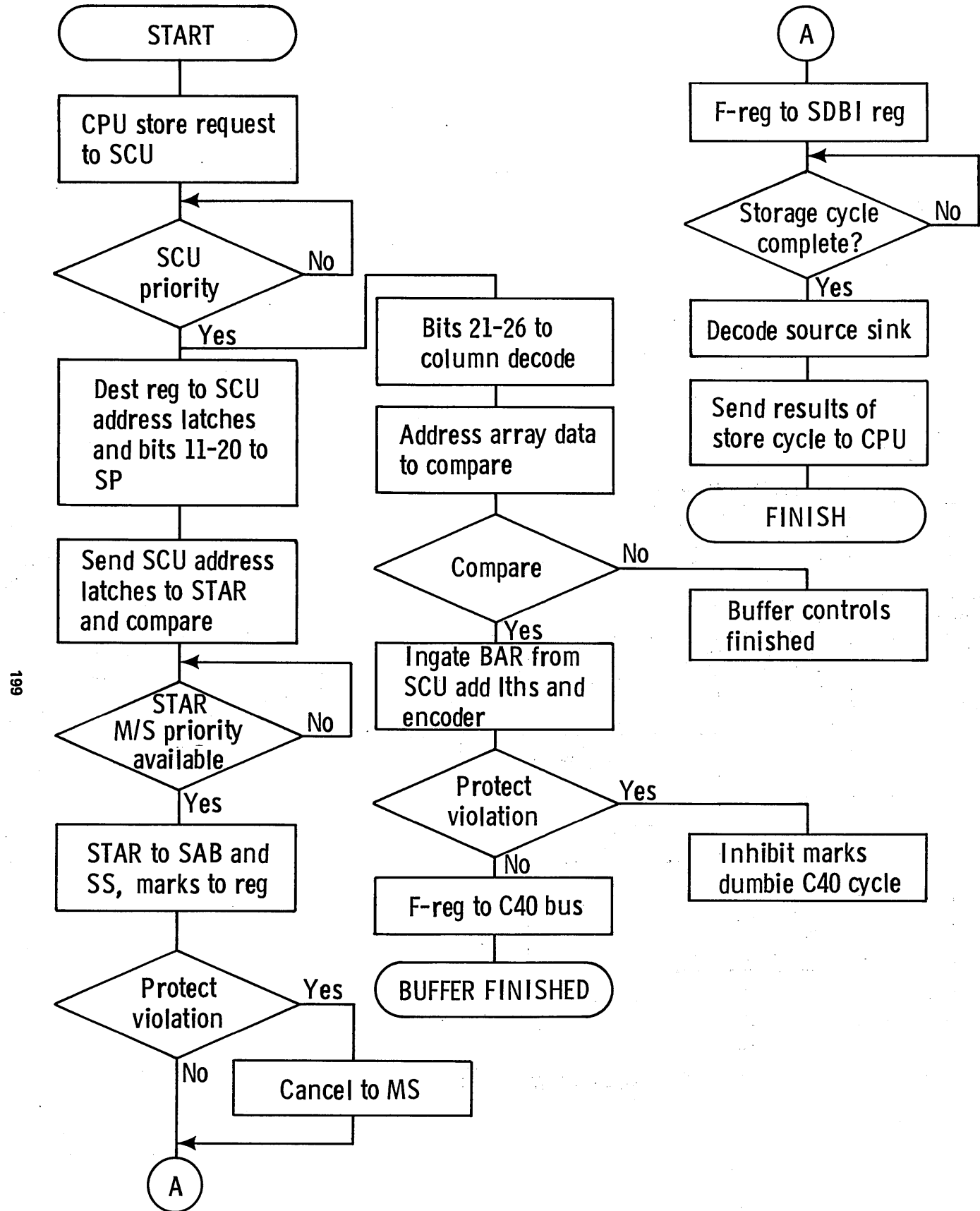


Figure 12-11. CPU Store (Address In High-Speed Buffer)

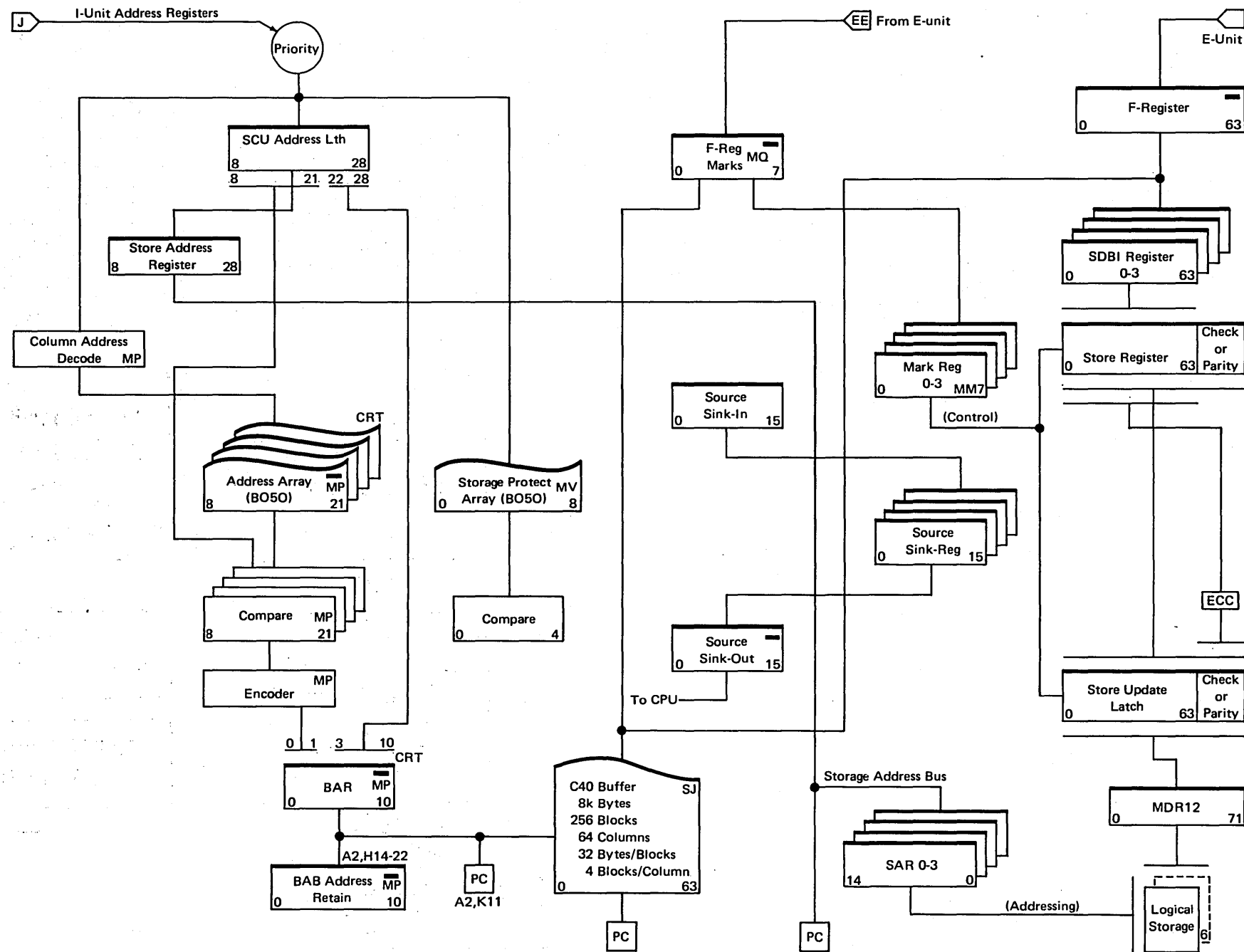


Figure 12-12. Simplified Data Flow - CPU Store

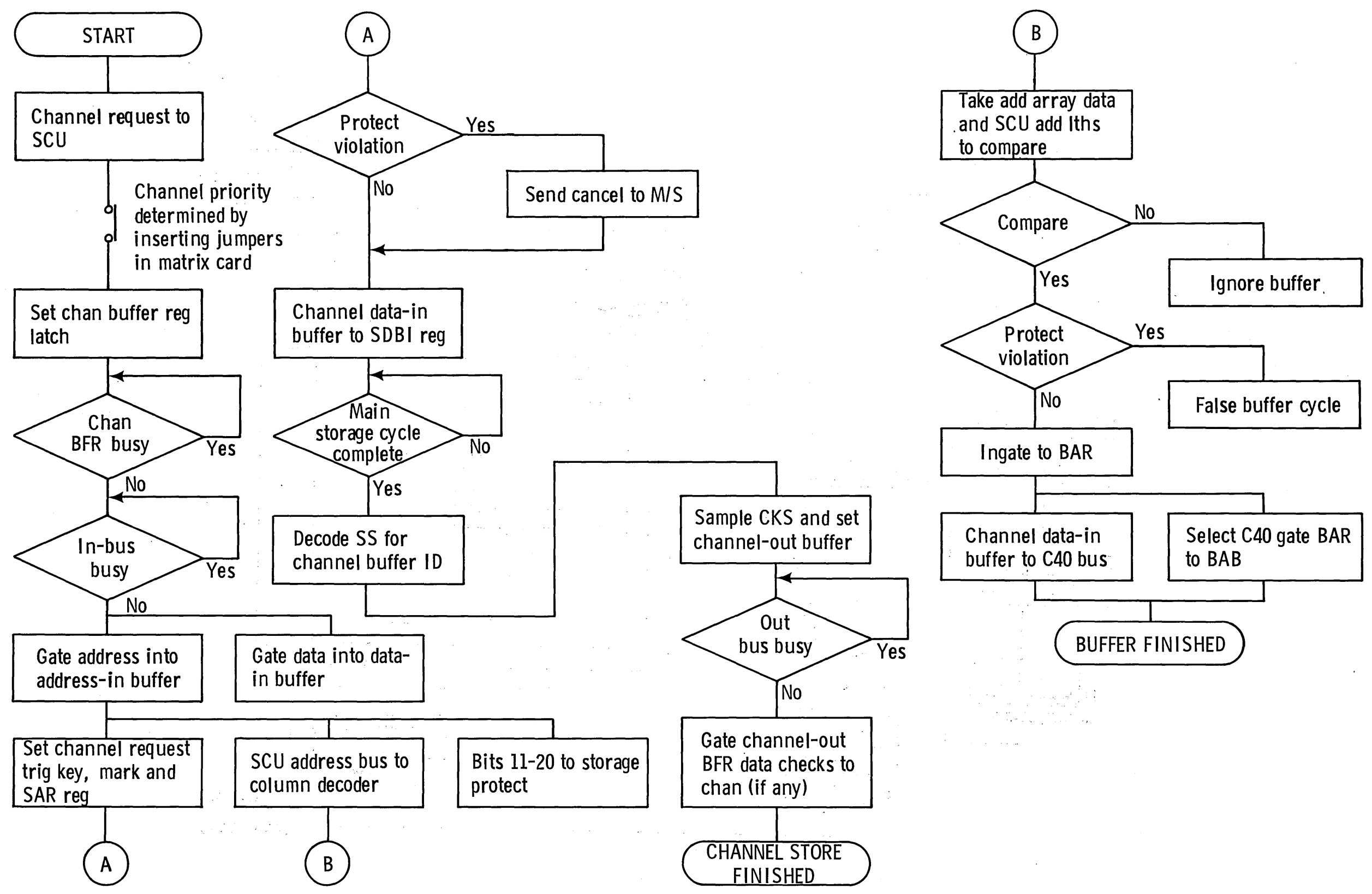


Figure 12-14. Channel Store (Address In High-Speed Buffer)

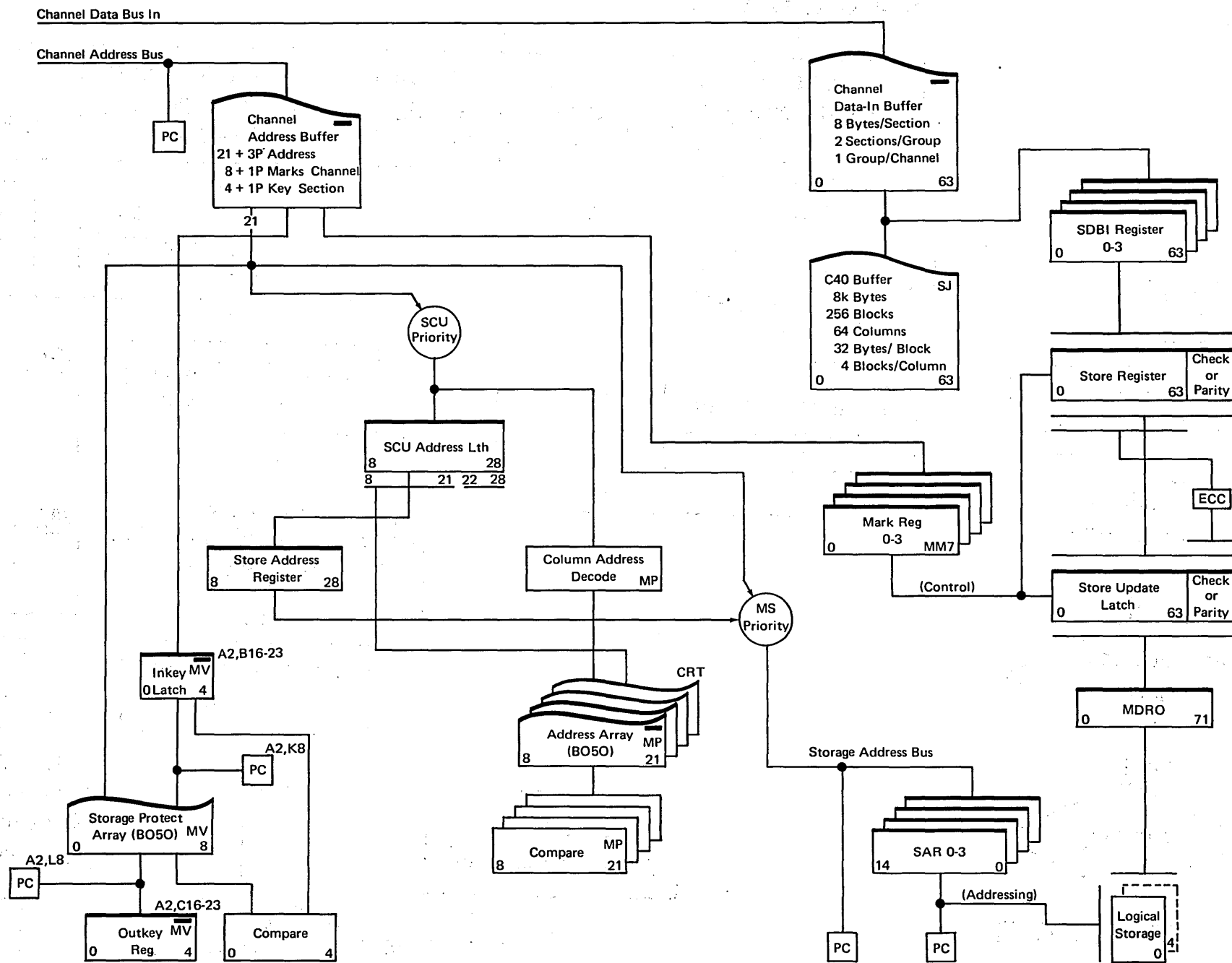


Figure 12-15. Simplified Data Flow - Channel Store

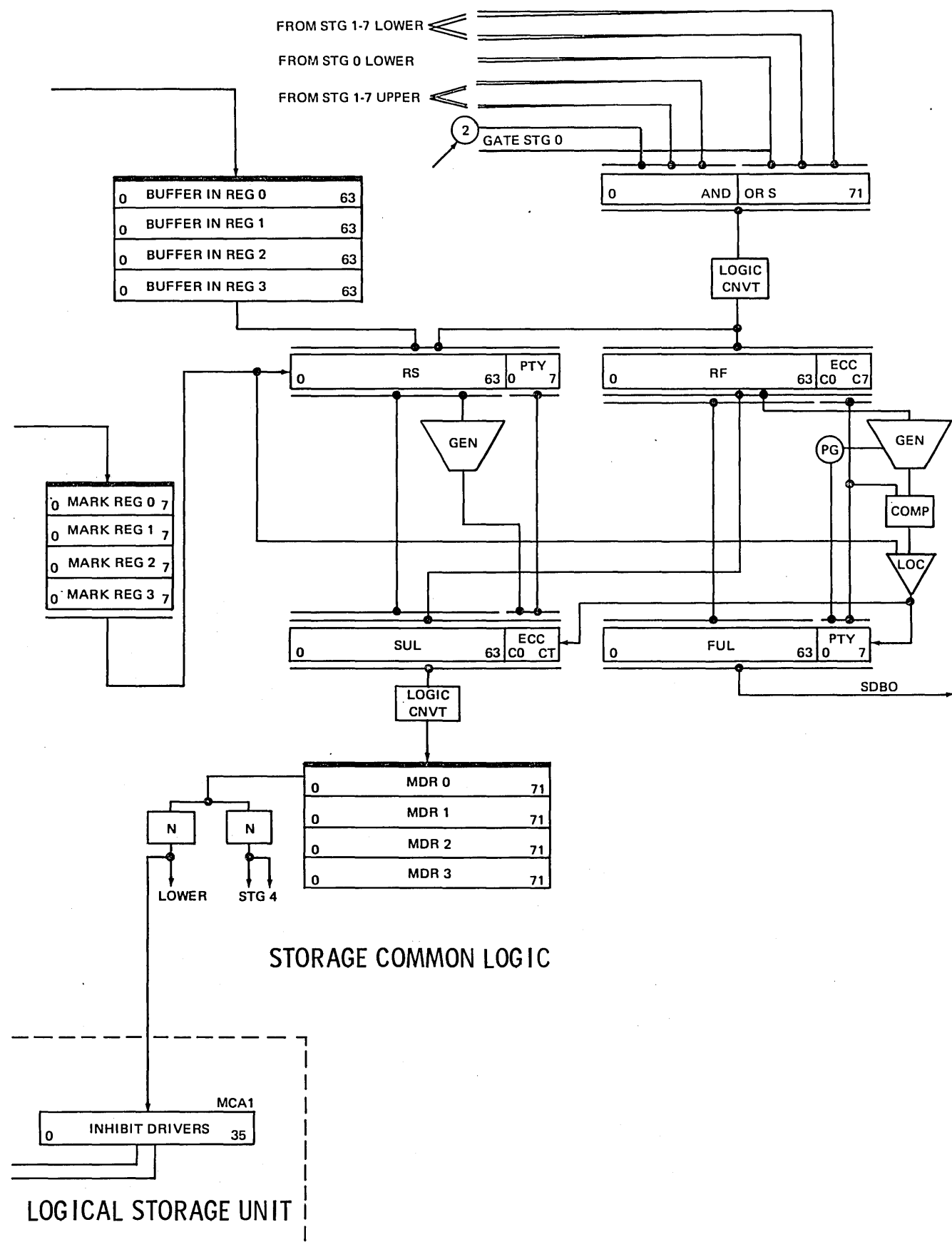


Figure 12-16. ECC Logic

CHANNEL BUFFERING

Each channel has a fixed assignment of one buffer group and each group consists of two sections. A buffer section stores all the information for one main storage access. Each buffer section stores data in, data out, marks, key, address, and various check and identification information.

Channel requests for input or output information must first vie for priority on the channel-in bus. The order of in-bus priority is established by inserting jumpers on a matrix card located in Frame 03. The wiring of the jumpers for a particular system results in a fixed-buffer assignment to each channel which is displayed on the microfiche viewer.

When in-bus priority is resolved, the appropriate channel is signalled. The channel, in turn, responds with address, marks, key and, if a store operation, a doubleword of data and a store signal. Upon the receipt of an address valid signal, this information is loaded into one of the channel's assigned buffer sections. If both buffer sections are empty (X 0 and X 1 where X is the buffer group number), the channel transfer is loaded into section X0. If a buffer section is not available for use (empty), that channel is blocked from receiving in-bus priority.

Once a buffer section is loaded, it is set to a busy state and entered as a contender into main storage priority. After main storage priority has been received, the storage unit is selected. Identification of the channel buffer section is placed on the source-sink bus-in, and the buffer section contents are gated to main storage. Main storage control receives the address, marks, and key. In the case of a store, the buffer section contents are also gated to the high-speed buffer control section to update the buffer if the address block is in the buffer.

When the channel request processing is completed by main storage, a storage signal followed by data, source-sink identification, and error information is sent to the main storage control which assembles and sends the information to the initiating channel buffer section.

When the information from storage is loaded into a channel buffer section, use of the channel out-bus is vied for by entering channel-out bus priority. When priority is resolved in favor of a buffer section the contents of that buffer section are gated onto the channel-out bus. At this point that buffer section is made not busy. All address and data type checks, associated with this channel request, are sent to the channel at the same time as the channel buffer data.

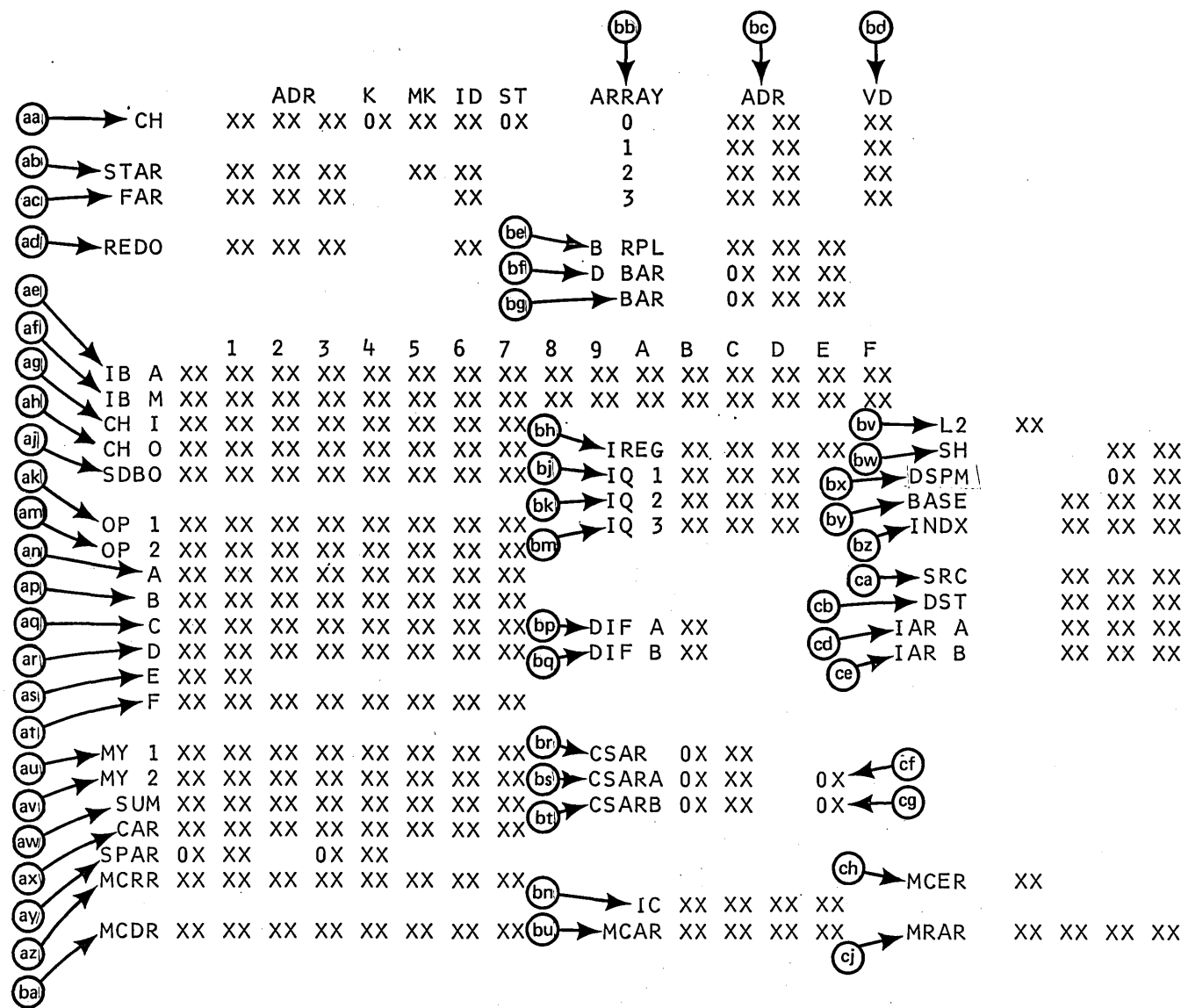


Figure 13-1.

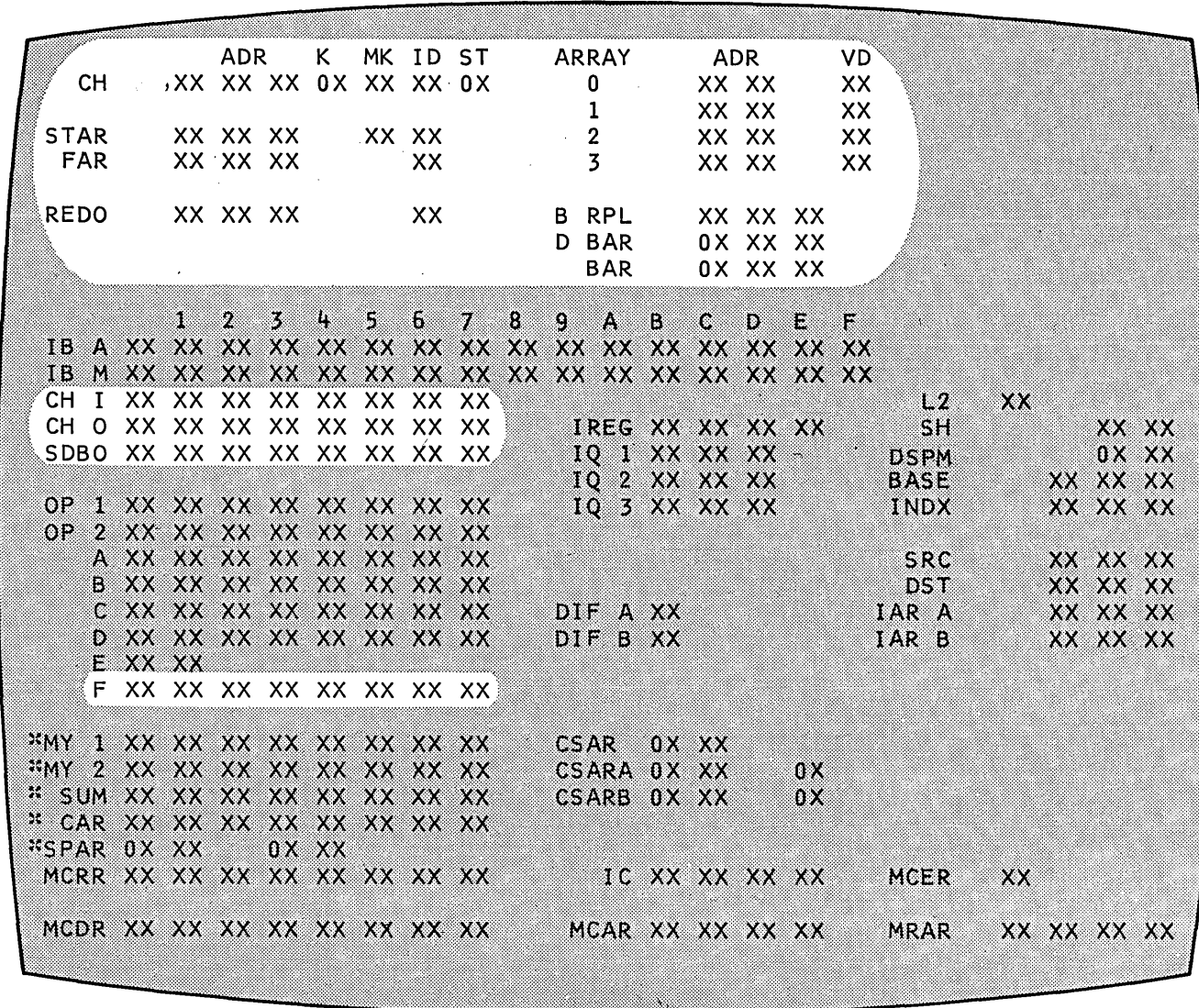


Figure 13-2. CRT With SCU Units Hi-Lighted

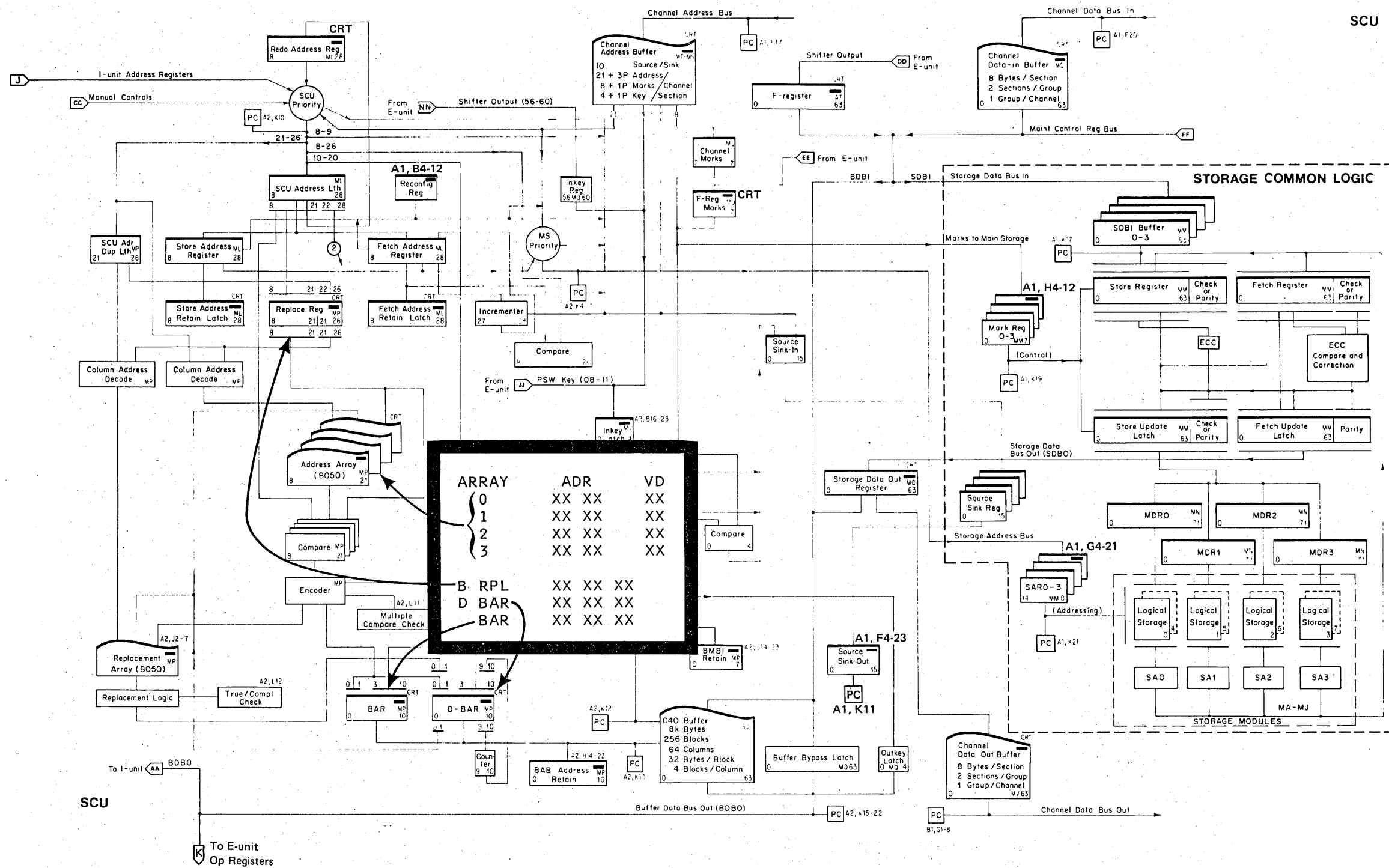


Figure 13-3. SCU Data Flow

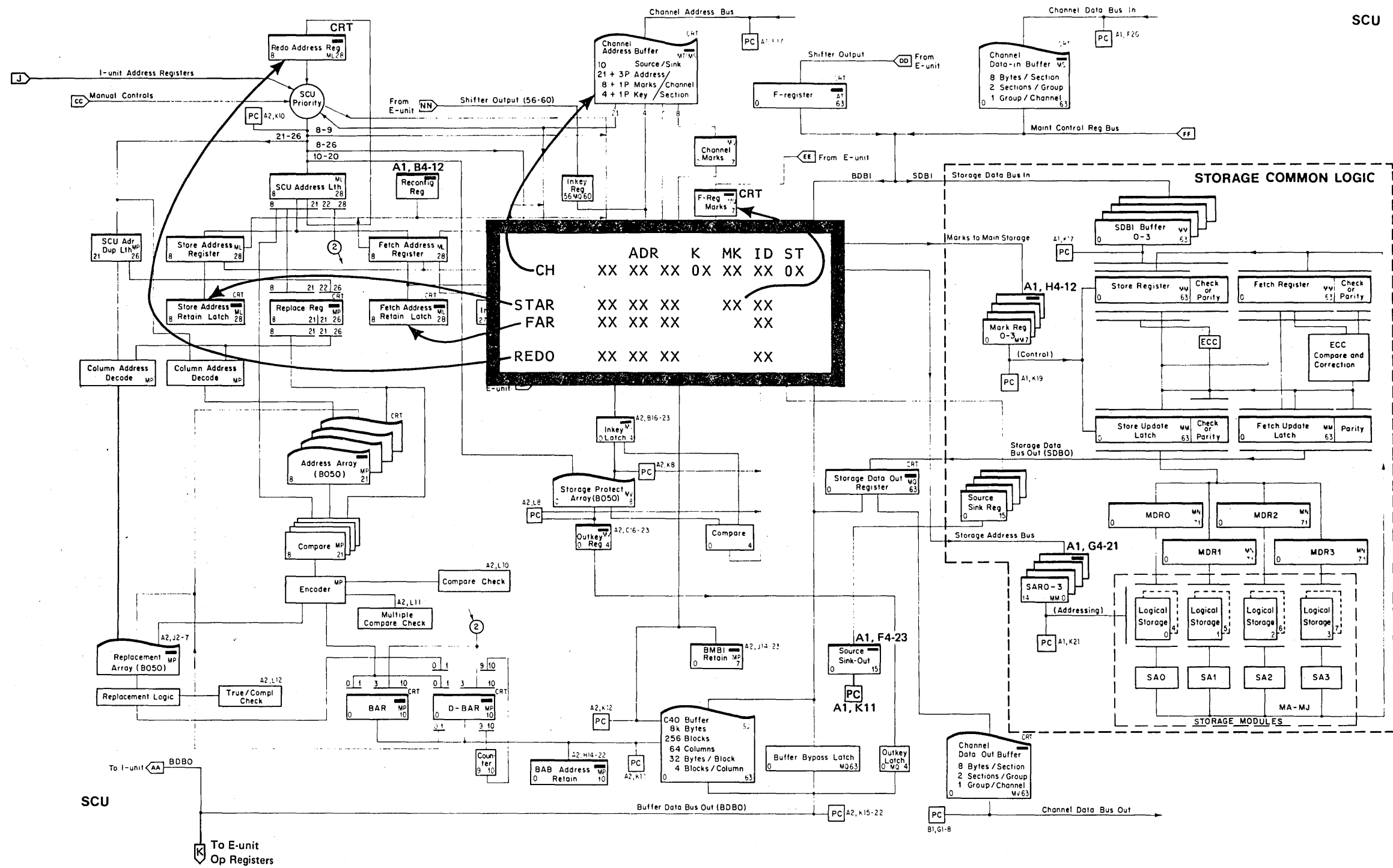


Figure 13-4. SCU Data Flow

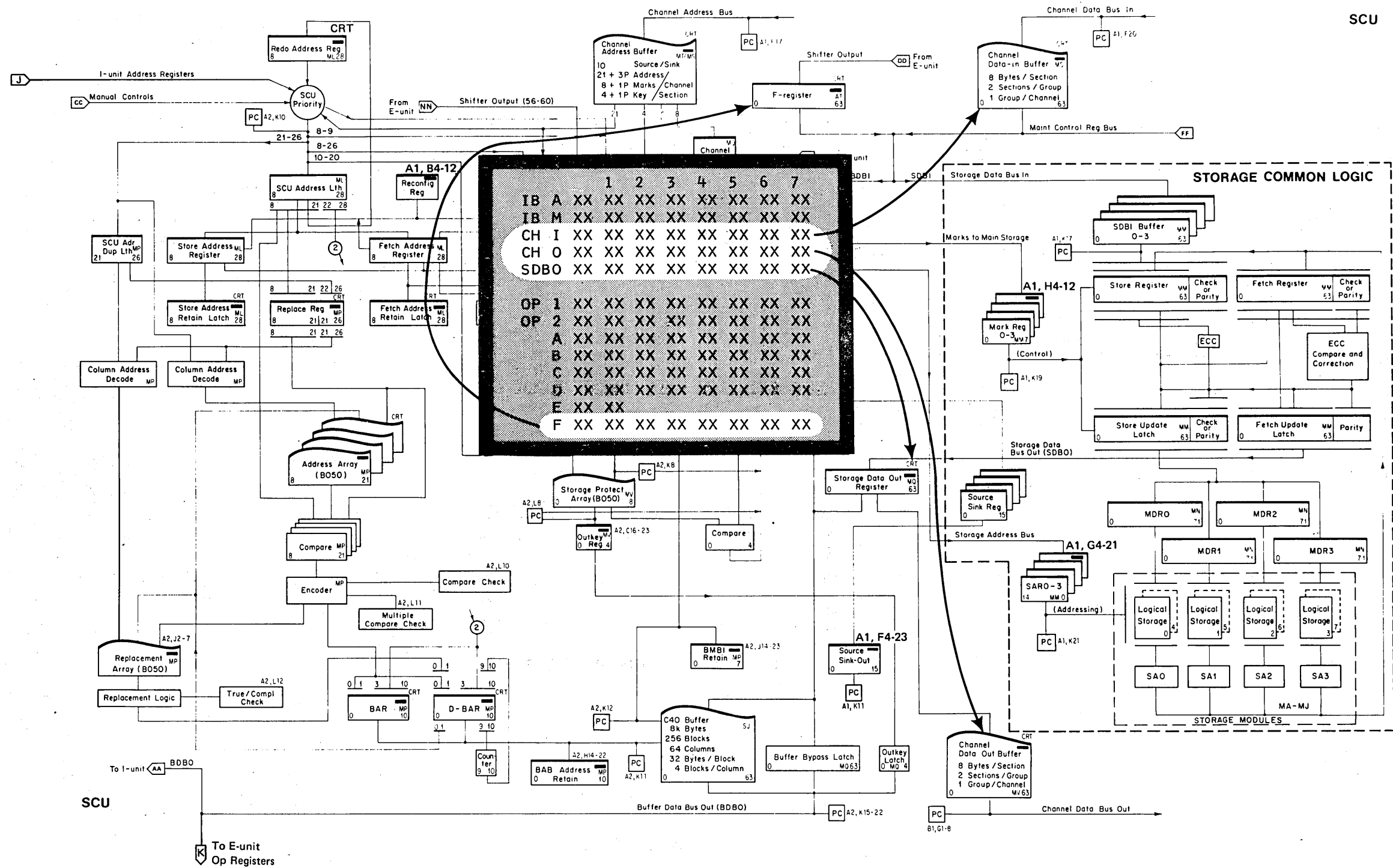


Figure 13-5. SCU Data Flow

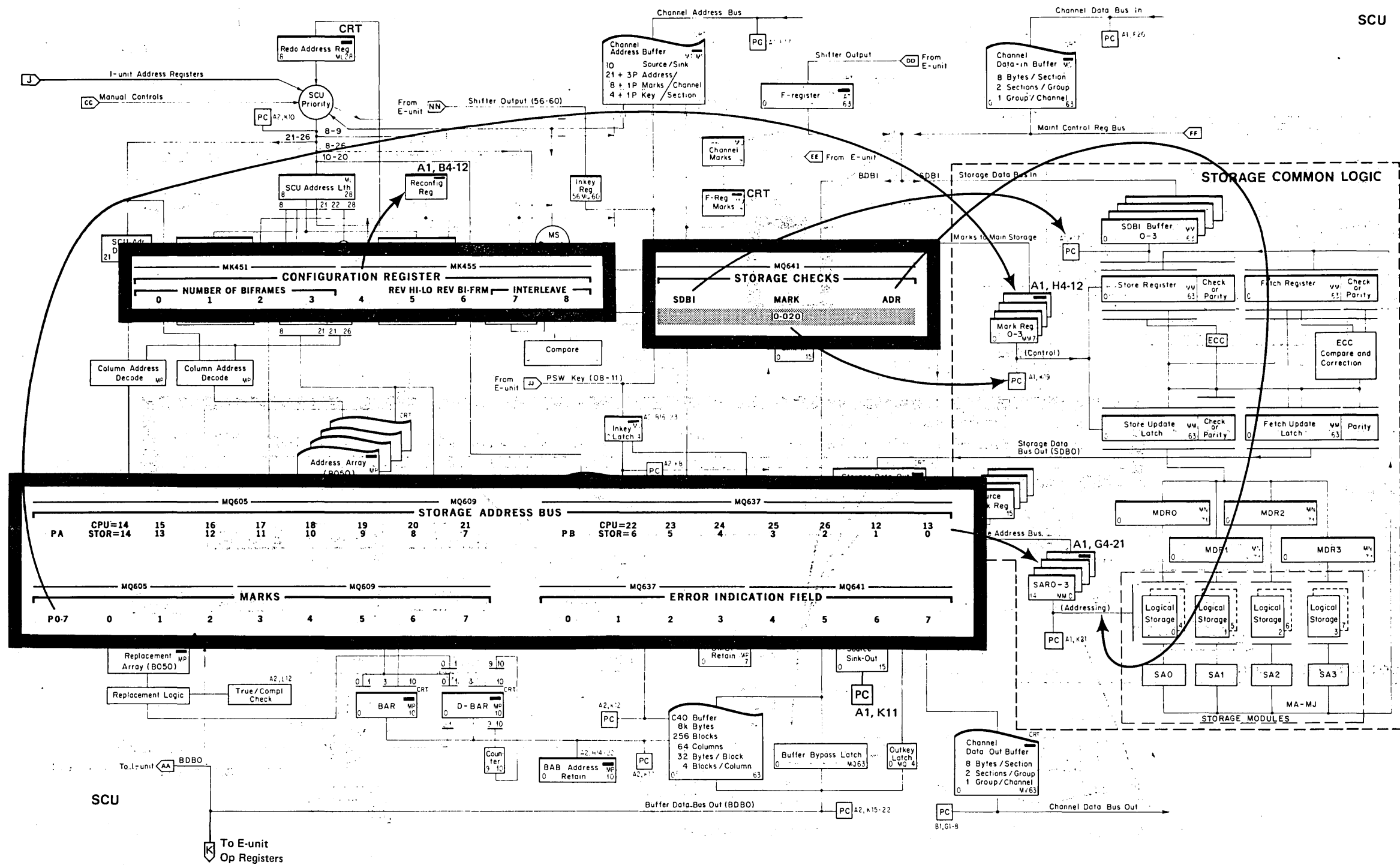


Figure 13-6. SCU Data Flow

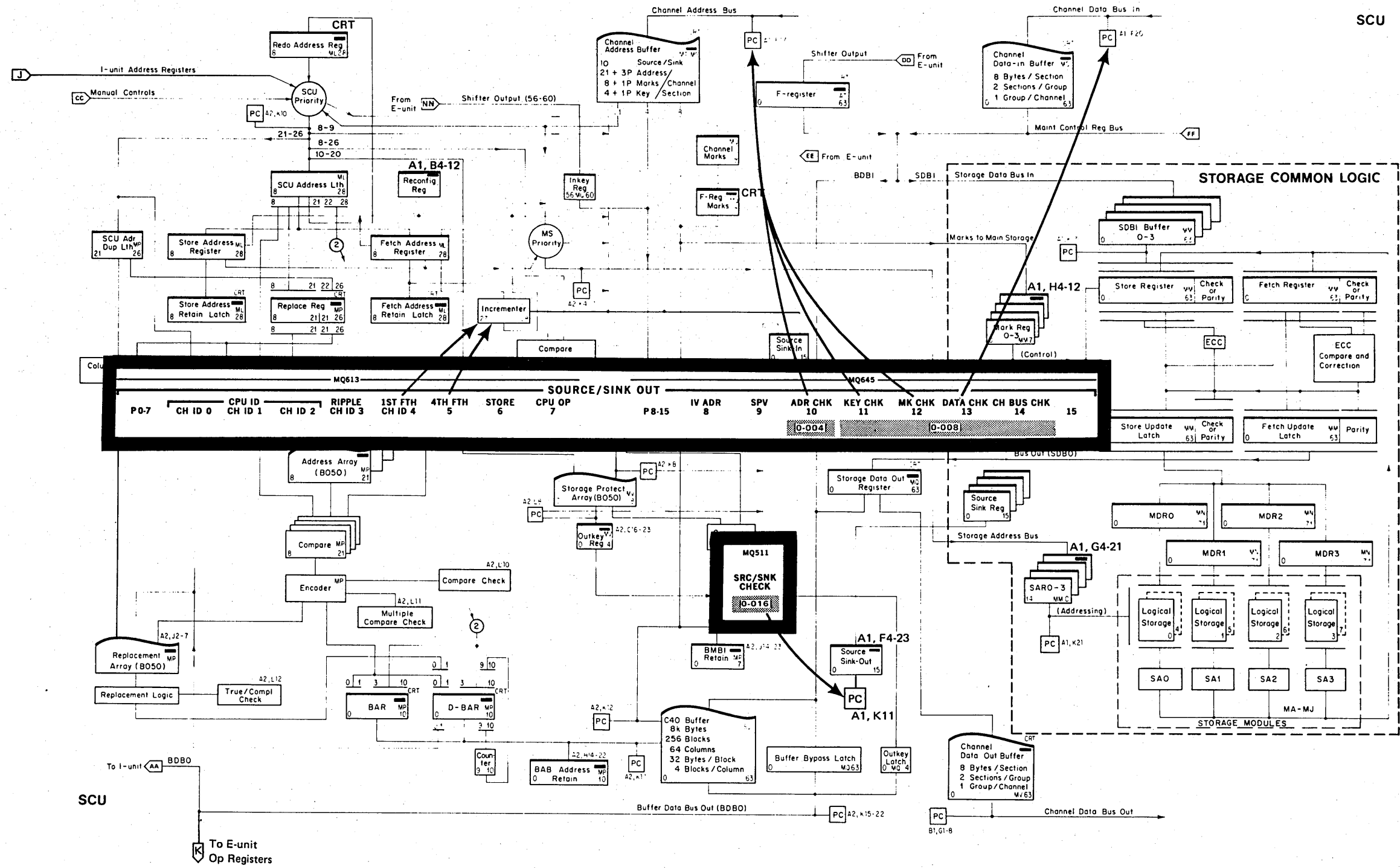


Figure 13-7. SCU

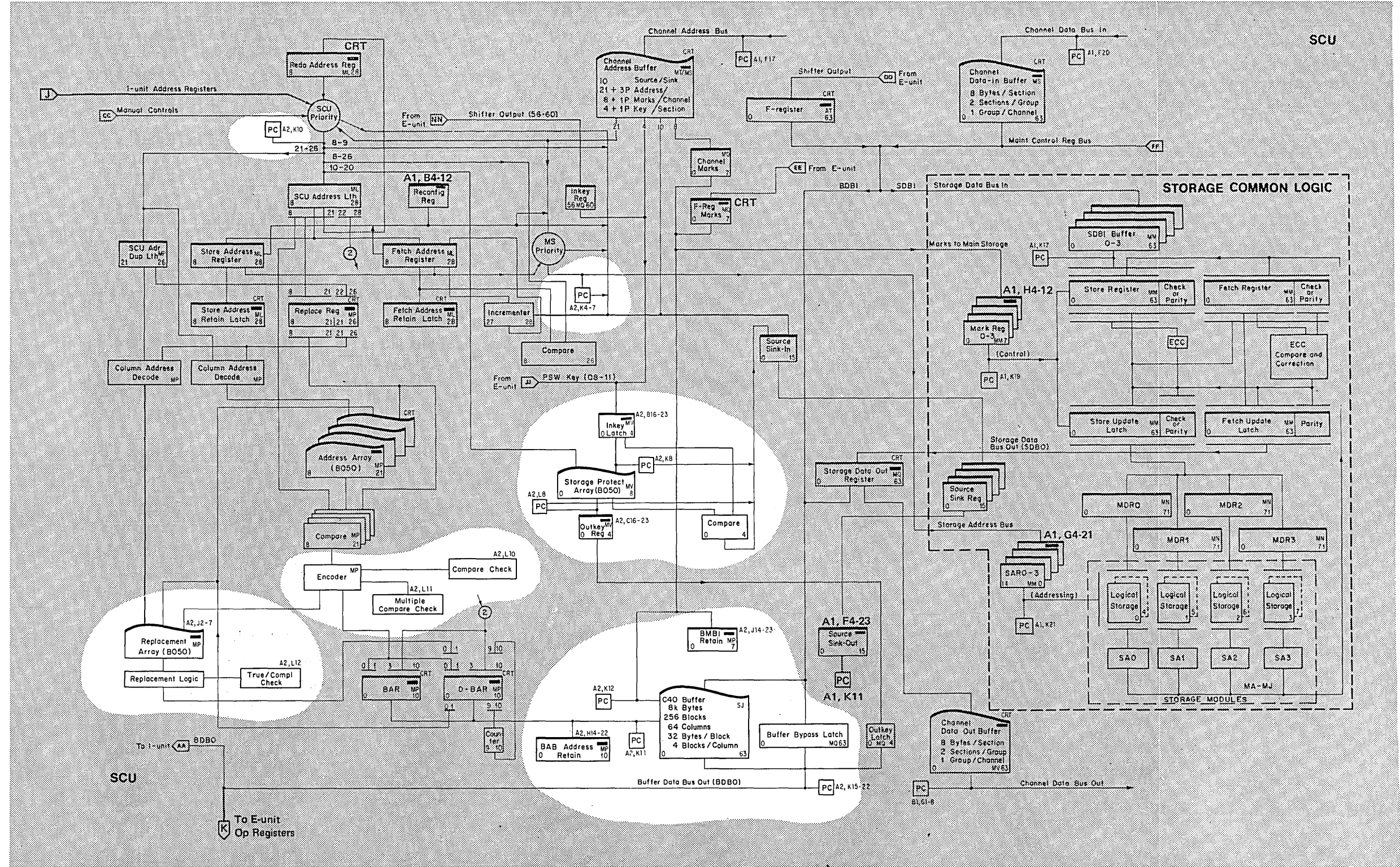


Figure 13-8. SCU

CPU Advance Lines
(From SCU to I-Unit, E-Unit, and Mnt. Ctrls.)

Advance 0 and 1
(Encoded as follows)

00	Null
01	Normal Advance
10	Invalid Address
11	Protected

Rescind Lines
(Within SCU)

00	No Request in FAR
01	Request in FAR
10	Not Used
11	I-Unit Rescinded

SCU Address Gate
(Within SCU)

Priority
ID Bits

0 1 2	
0 0 0	Not Used
0 0 1	Maint. Request
0 1 0	Unused
0 1 1	Maint. Ripple
1 0 0	Destination
1 0 1	Source
1 1 0	IARA
1 1 1	IARB

Figure 13-9. CPU Advance Lines

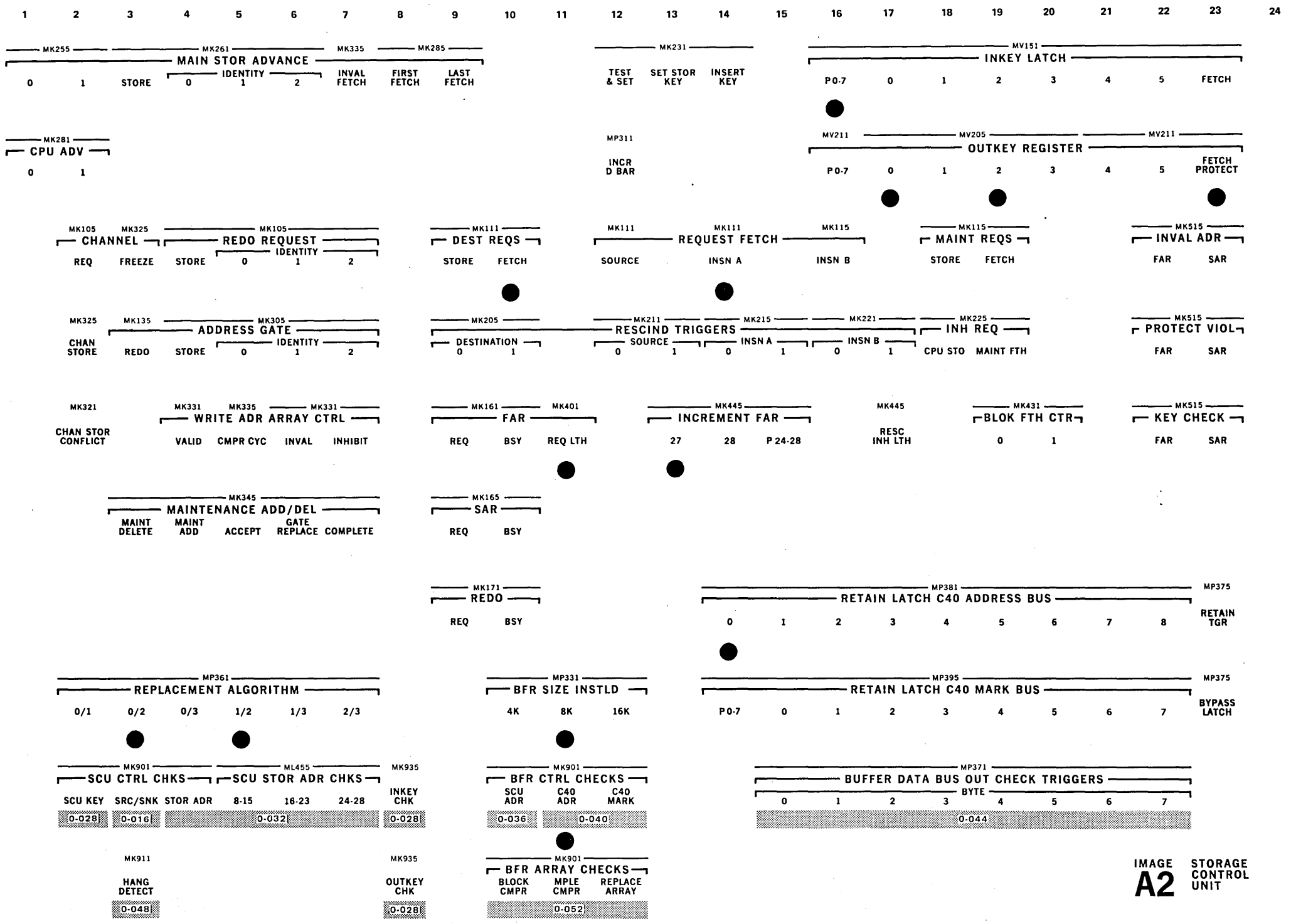
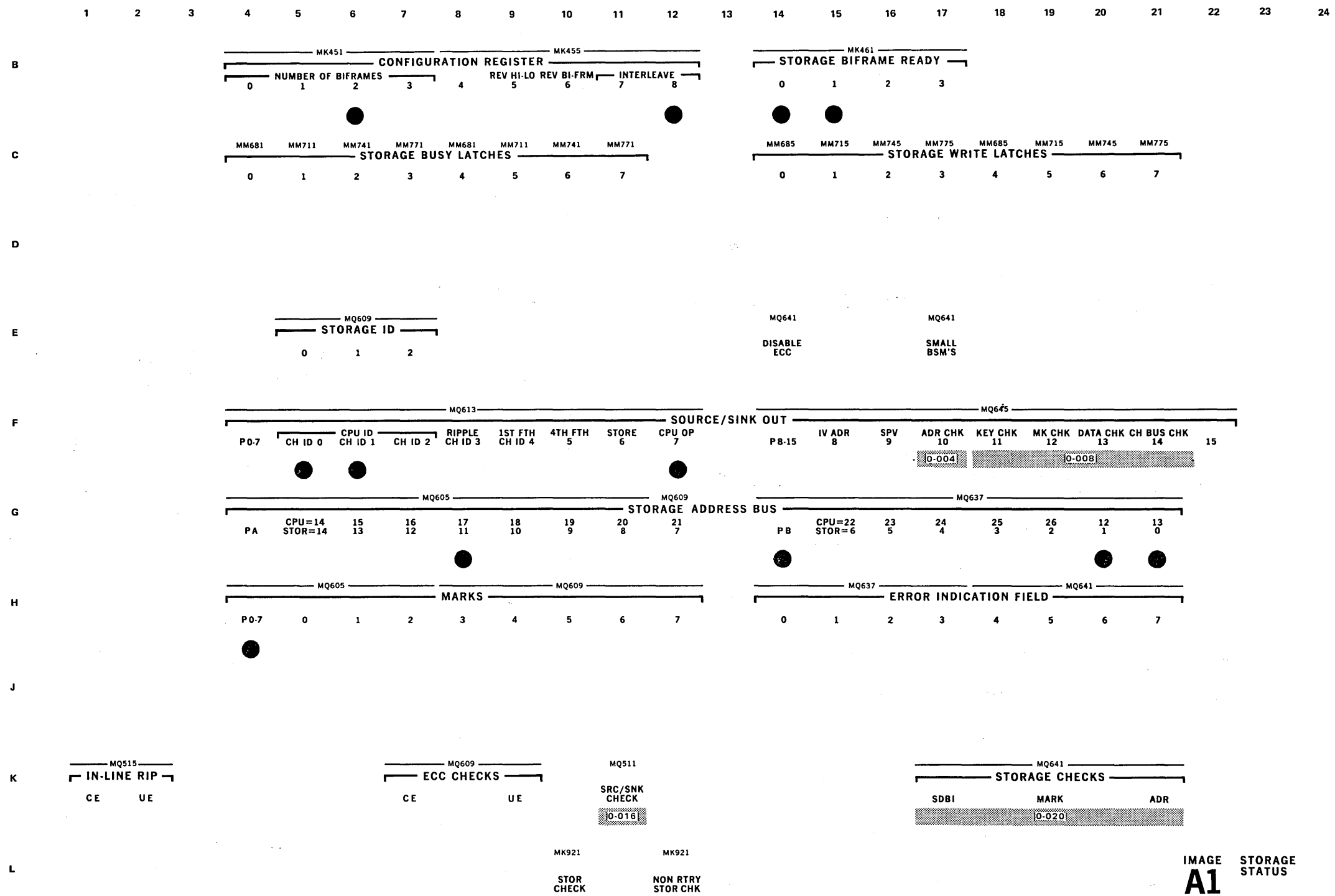


Figure 14-1. Microfiche Image A2

213



214

IMAGE STORAGE STATUS
A1

Figure 14-2. Microfiche Image A1

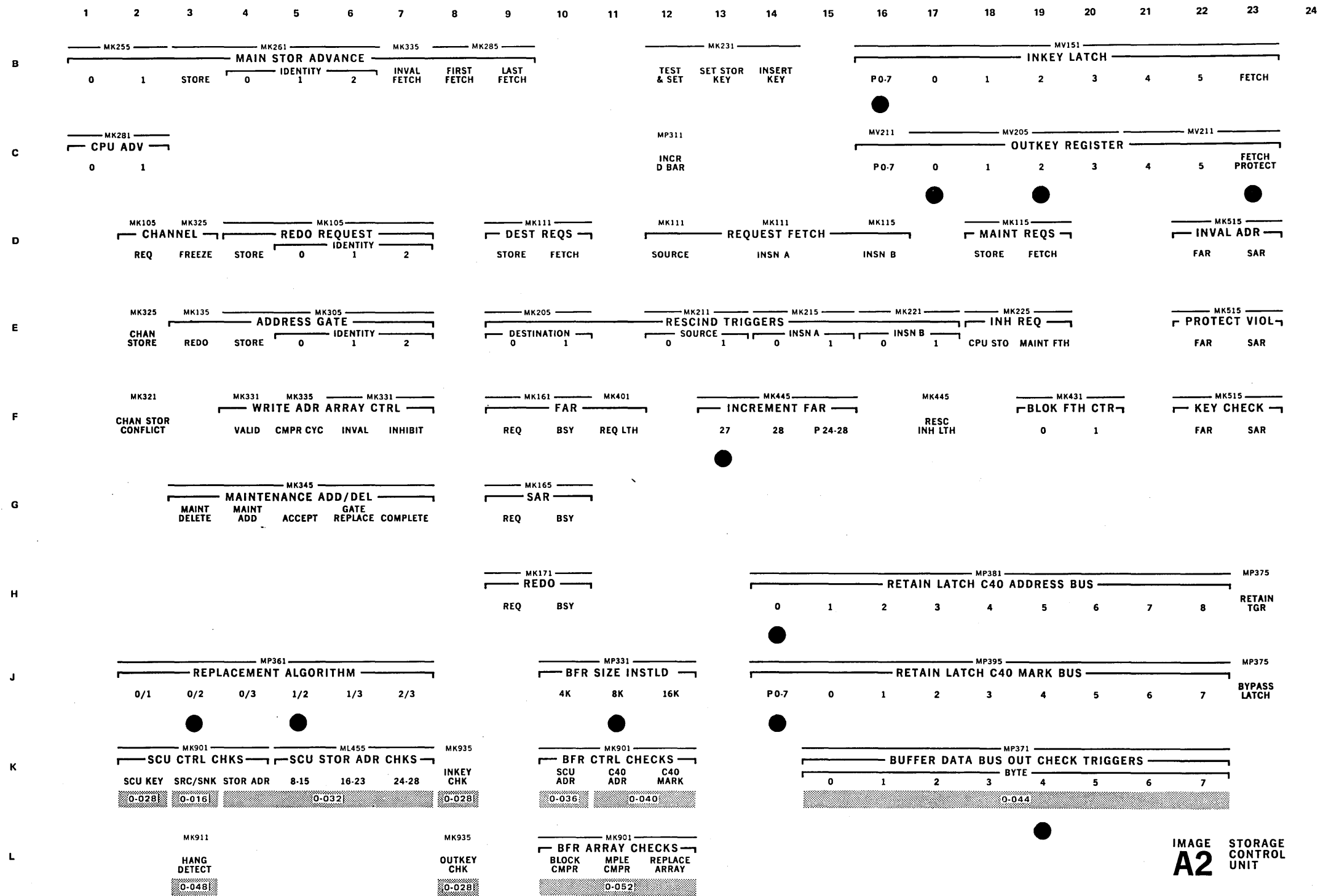


IMAGE STORAGE CONTROL UNIT
A2

Figure 14-3. Microfiche Image A2

CH	ADR	K	MK	ID	ST	ARRAY	ADR	VD
	XX XX XX	0X	XX XX	XX 0X		0	XX XX	XX
						1	XX XX	XX
STAR	XX XX XX		XX XX			2	XX XX	XX
FAR	XX XX XX		XX			3	XX XX	XX
REDO	XX XX XX		XX			B RPL	XX XX XX	
						D BAR	0X XX XX	
						BAR	0X XX XX	
	1 2 3 4 5 6 7 8 9					A B C D E F		
IB A	XX XX XX XX XX XX XX XX XX					XX XX XX XX XX XX		
IB M	XX XX XX XX XX XX XX XX XX					XX XX XX XX XX XX		
CH I	XX XX XX XX XX XX XX XX						L2	XX
CH O	XX XX XX XX XX XX XX XX					IREG	XX XX XX XX	SH
SDBO	XX XX XX XX XX XX XX XX					IQ 1	XX XX XX	DSPM
						IQ 2	XX XX XX	BASE
OP 1	XX XX XX XX XX XX XX XX					IQ 3	XX XX XX	INDX
OP 2	XX XX XX XX XX XX XX XX							
A	XX XX XX XX XX XX XX XX							SRC
B	XX XX XX XX XX XX XX XX							DST
C	XX XX XX XX XX XX XX XX					DIF A	XX	IAR A
D	XX XX XX XX XX XX XX XX					DIF B	XX	IAR B
E	XX XX							
F	XX XX XX XX XX XX XX XX							
*MY 1	XX XX XX XX XX XX XX XX					CSAR	0X XX	
*MY 2	XX XX XX XX XX XX XX XX					CSARA	0X XX	0X
*SUM	XX XX XX XX XX XX XX XX					CSARB	0X XX	0X
*CAR	XX XX XX XX XX XX XX XX							
*SPAR	0X XX 0X XX							
MCRR	XX XX XX XX XX XX XX XX					IC	XX XX XX XX	MCER
MCDR	XX XX XX XX XX XX XX XX					MCAR	XX XX XX XX	MRAR
								XX XX XX XX

Figure 14-4.

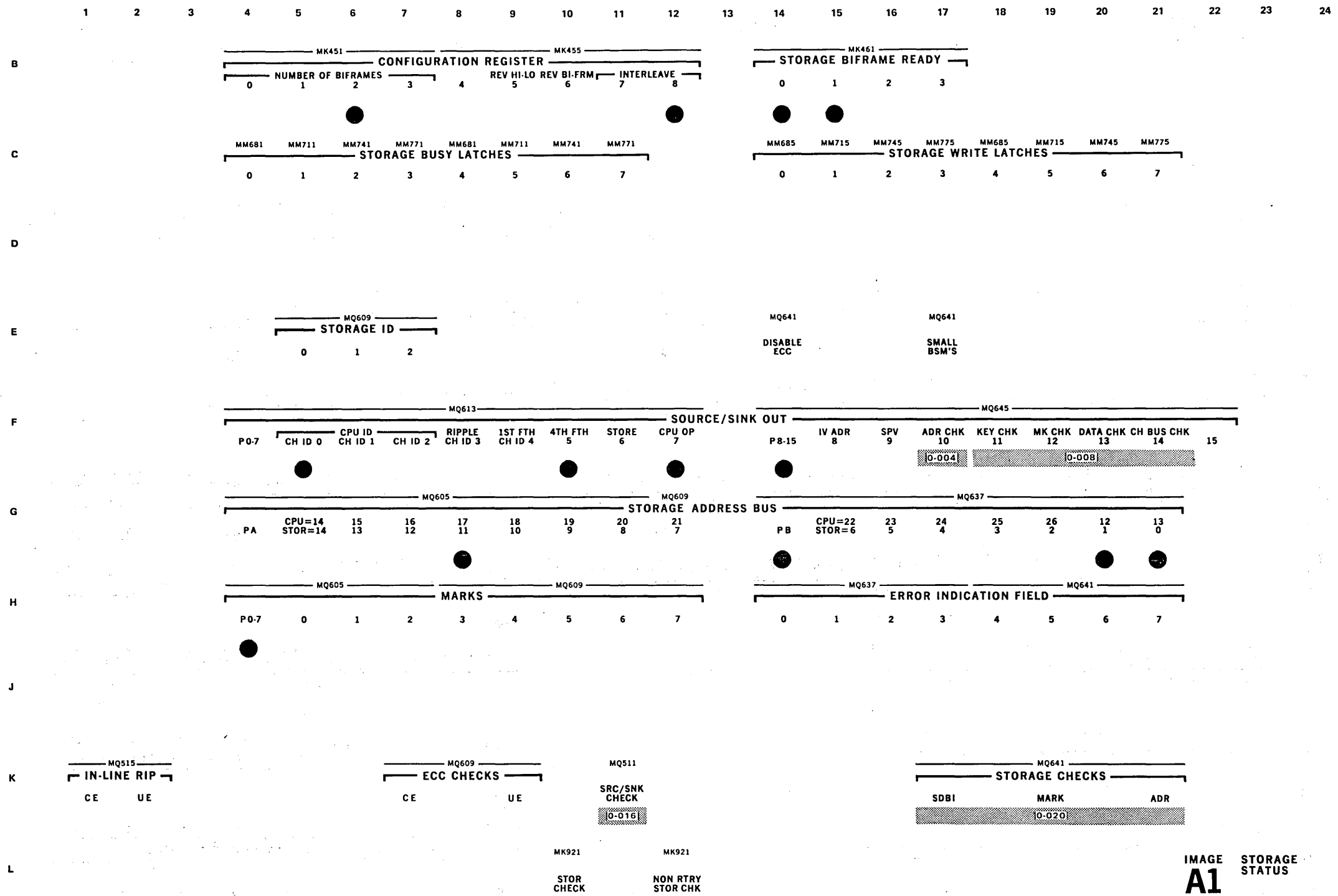


IMAGE **A1** STORAGE STATUS

Figure 14-5. Microfiche Image A1

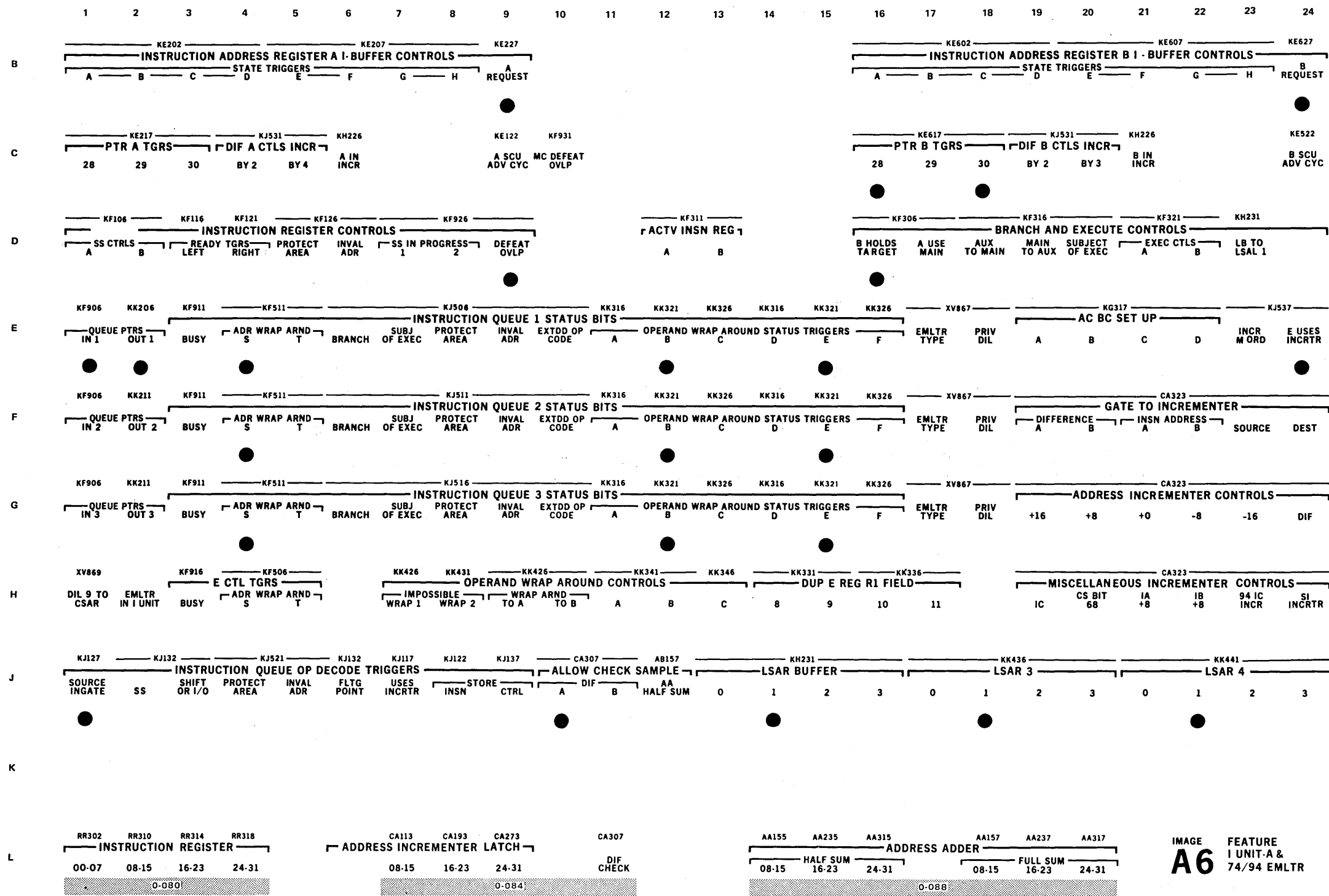


Figure 14-6. Microfiche Image A6

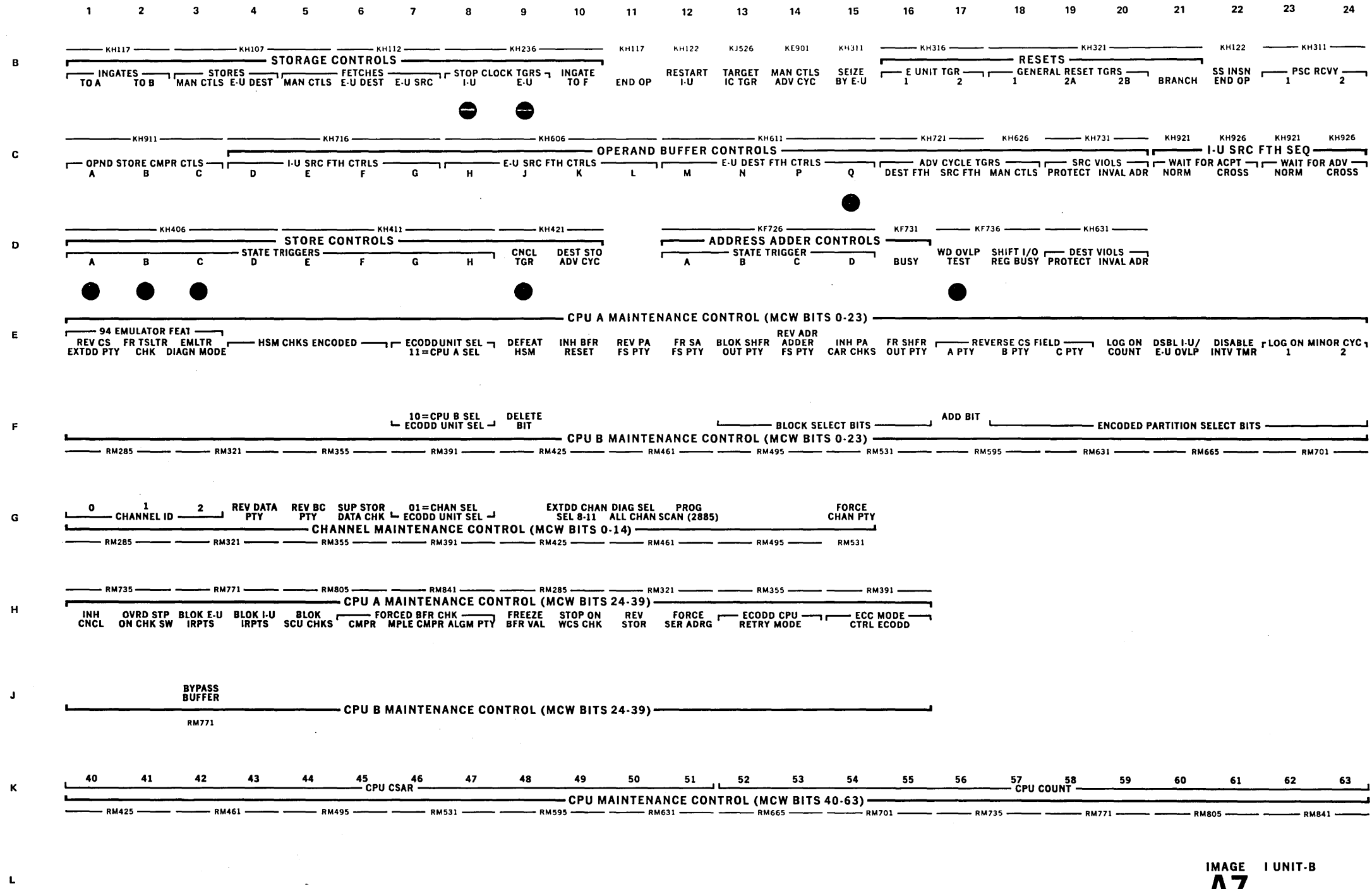


Figure 14-7. Microfiche Image A7

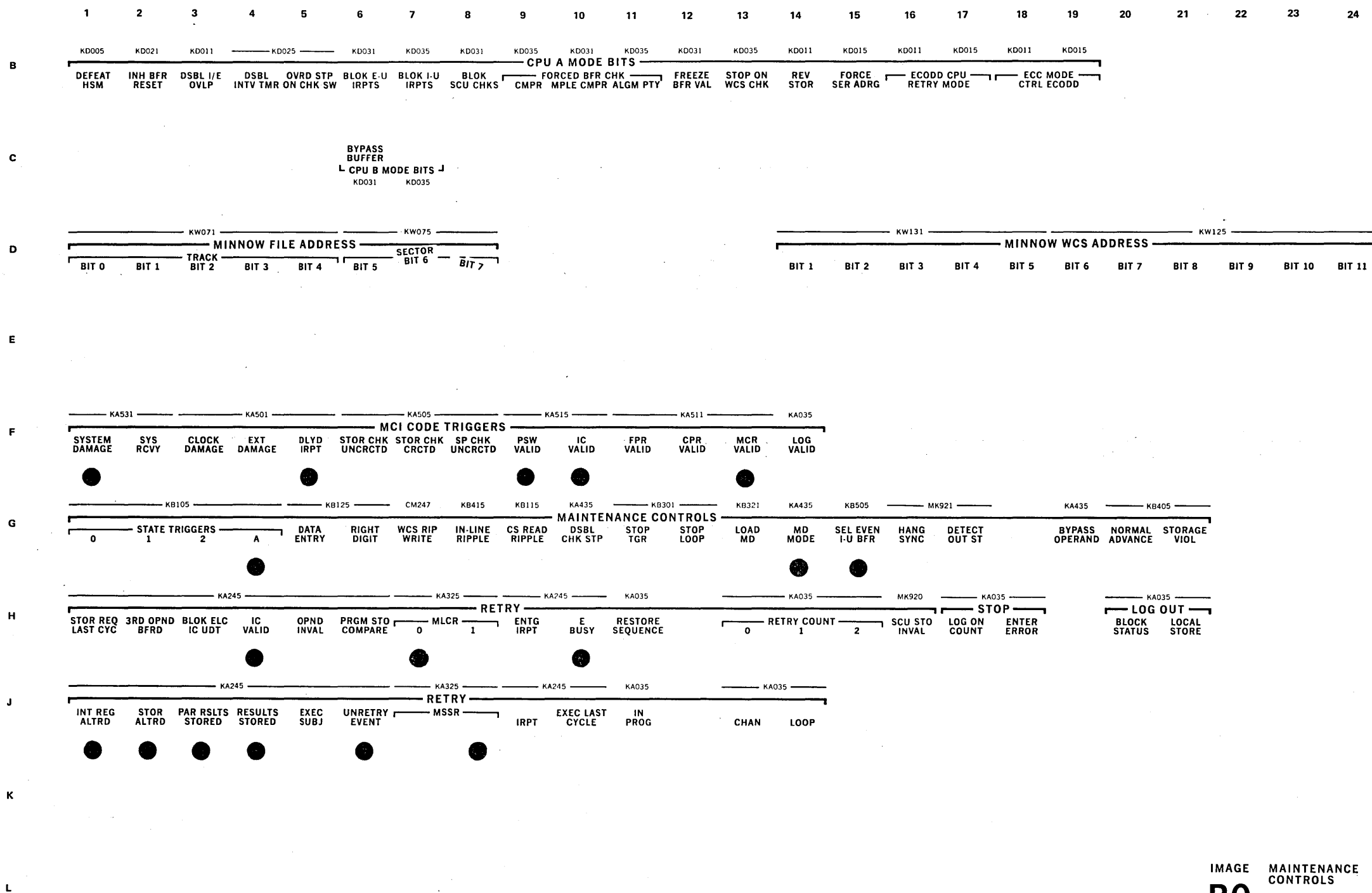
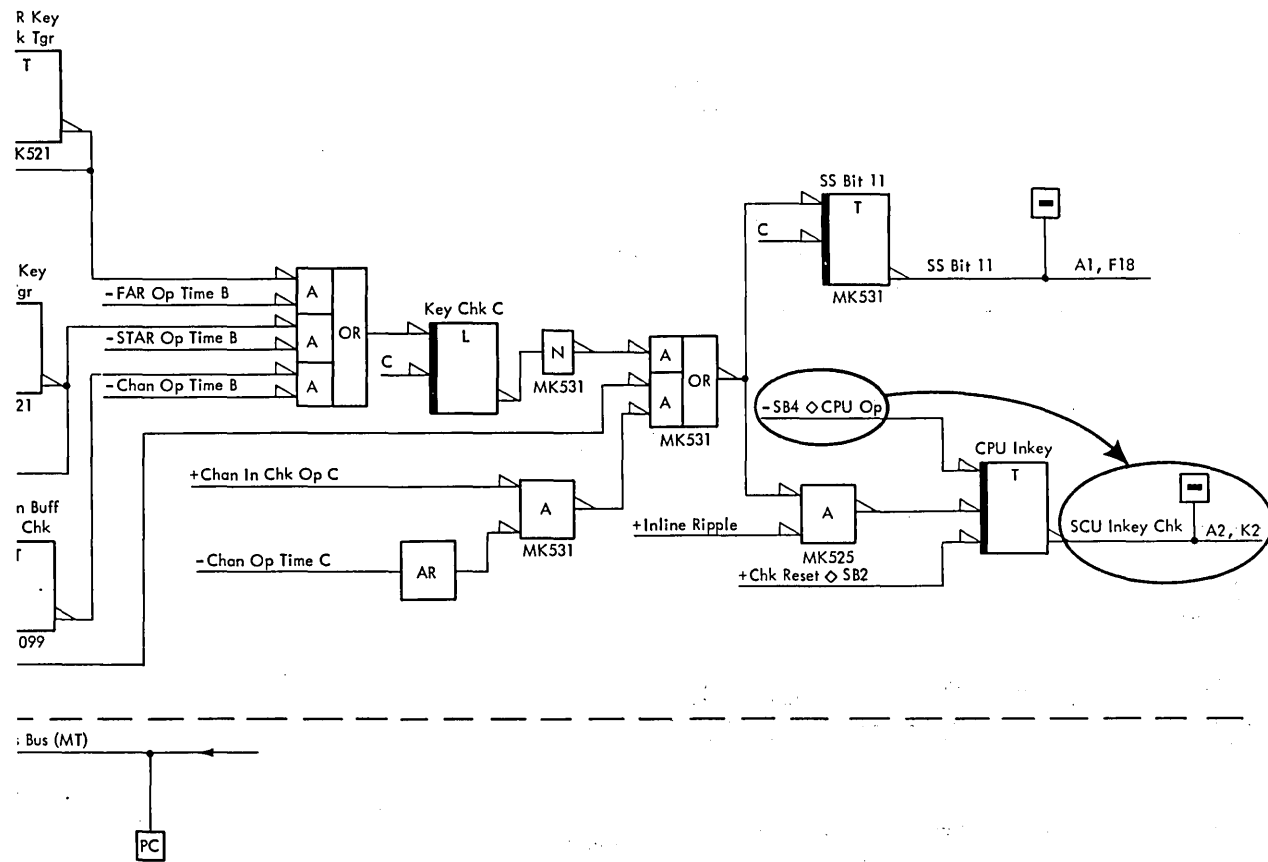


IMAGE MAINTENANCE
B0 CONTROLS

Figure 14-8. Microfiche Image B0



SCU Key Control Check Indicator (A2, K2): This light turns on if an SP inkey or outkey check occurs during a CPU operation.

Inkey Check Indicator (A2, K8) and Outkey Check Indicator (A2, L8): These lights turn on when errors are detected at their respective sides of the storage protect unit.

Suggested Diagnostics:

- 1017 Micro Error Check Section
- 1391 SCU Buffer and Addressing
- 13CB Storage Protect
- 13E0 Random
- E401, E402, E403 for 2860/2870
- E431, E436 for 2870

Related Diagrams:

- SCU Channel Controls
- Advance, Key, and Data Indicators; Microfiche Frame A2
- SCU HS Buffer Controls, Change Key Sequence
- SCU HS Buffer Controls, Timing for Block Load and Change Key Sequence
- Functional Significance of Storage Address Bits

Figure 14-9. SCU Key Control Check

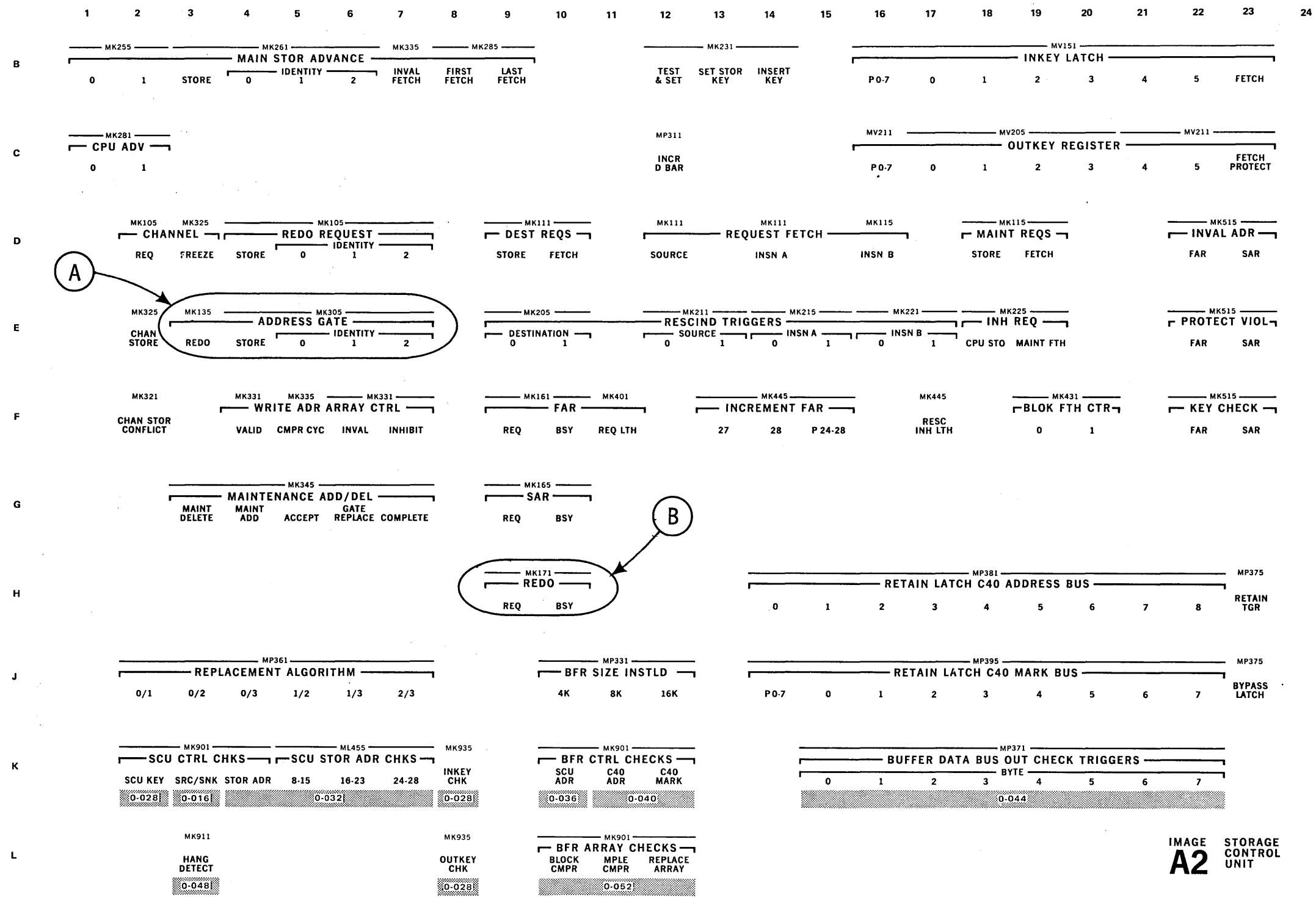


Figure 14-10. Microfiche Image A2

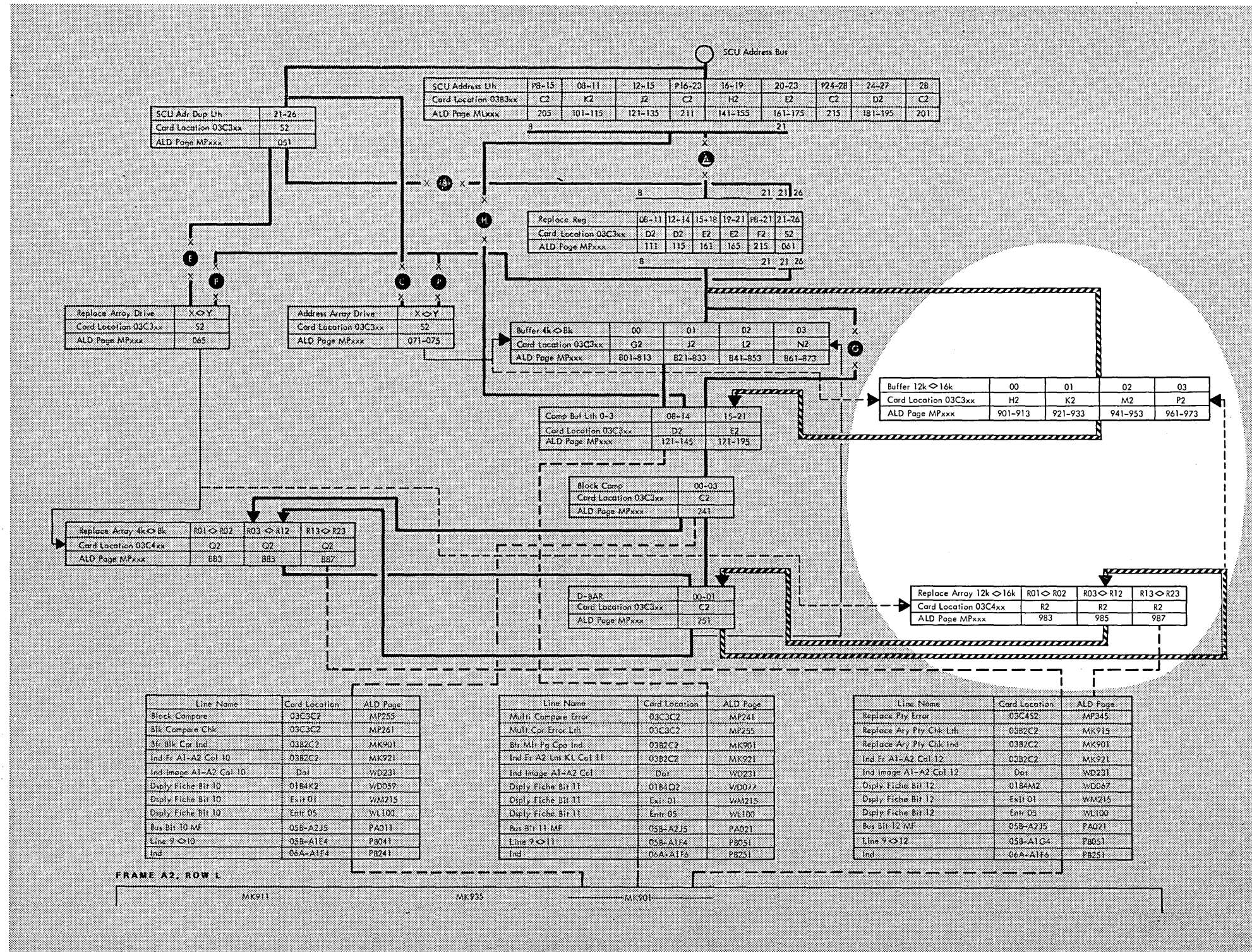


Figure 14-11. Buffer Array Checks

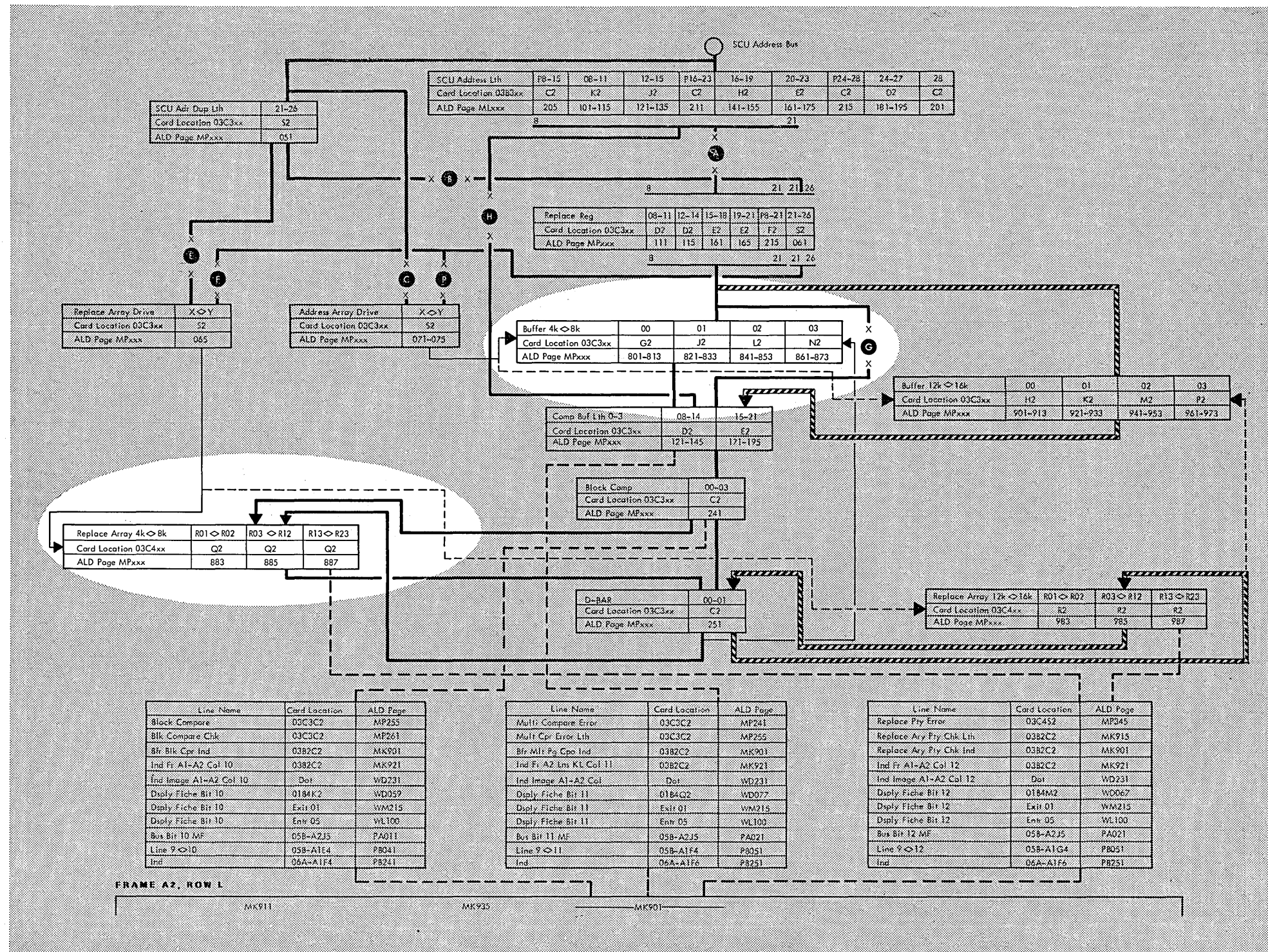
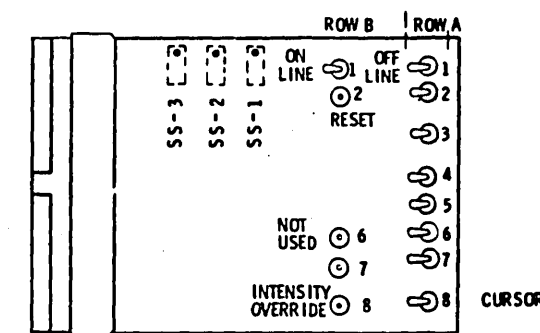


Figure 14-12. Buffer Array Checks

19" DISPLAY HEAD

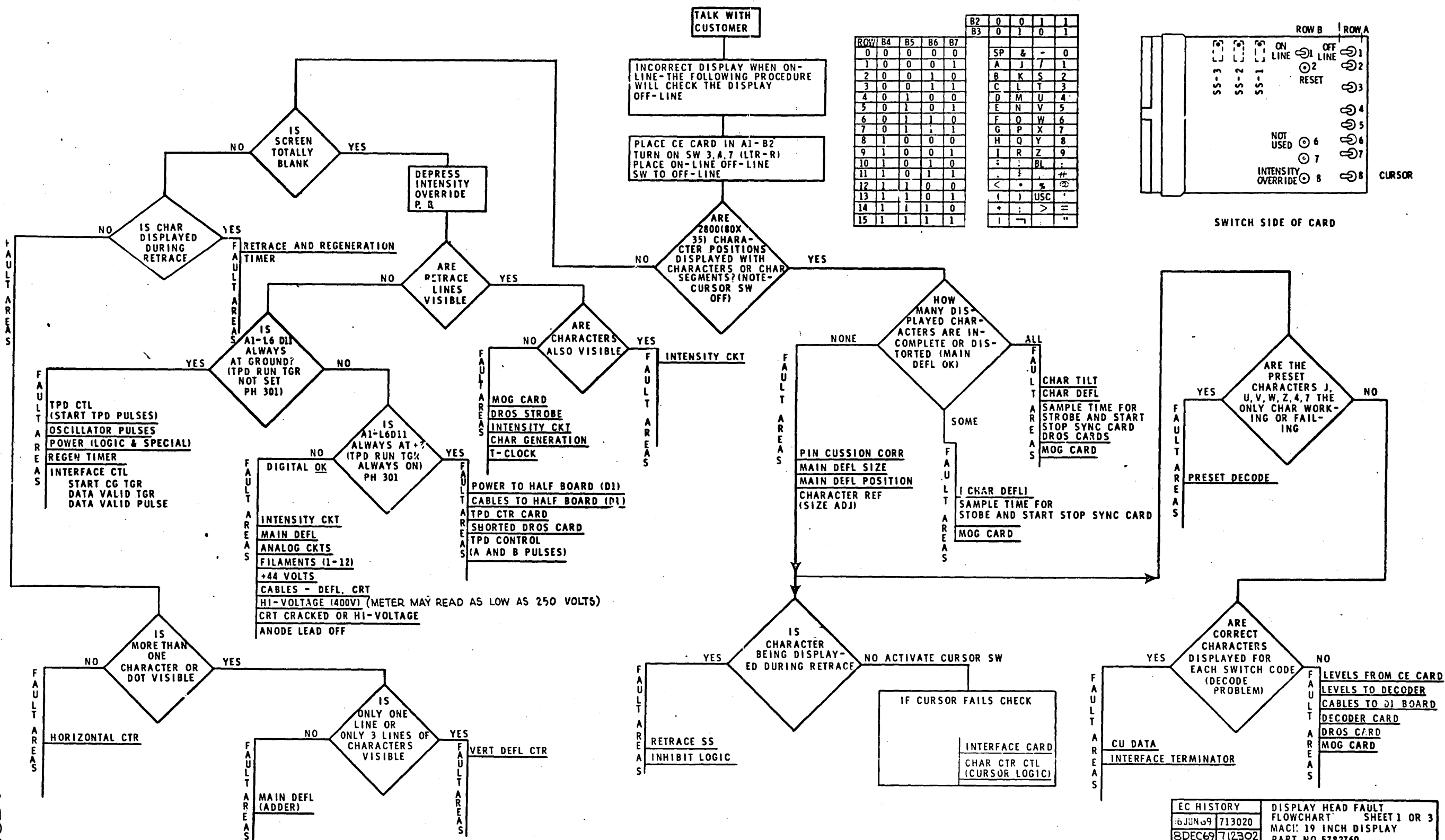
CHARACTER CODE SELECTION



ROW	B4	B5	B6	B7
0	0	0	0	0
1	0	0	0	1
2	0	0	1	0
3	0	0	1	1
4	0	1	0	0
5	0	1	0	1
6	0	1	1	0
7	0	1	1	1
8	1	0	0	0
9	1	0	0	1
10	1	0	1	0
11	1	0	1	1
12	1	1	0	0
13	1	1	0	1
14	1	1	1	0
15	1	1	1	1

B2	0	0	1	1
B3	0	1	0	1
SP	&	-	0	
A	J	7	1	
B	K	S	2	
C	L	T	3	
D	M	U	4	
E	N	V	5	
F	O	W	6	
G	P	X	7	
H	Q	Y	8	
I	R	Z	9	
:	:	BL	:	
<	:	:	#	
(:	:	%	
	:	:	USC	
+	:	:	>	
	:	:	=	
	:	:	"	

SWITCH SIDE OF CARD



EC HISTORY		DISPLAY HEAD FAULT FLOWCHART SHEET 1 OR 3	
6JUN69	713020	MACI: 19 INCH DISPLAY	
8DEC69	712302	PART NO 5782760	
27MAY70	713670		
		IBM CORP SDD	

Figure 18-1-1. 19" Display Head

0000

0000

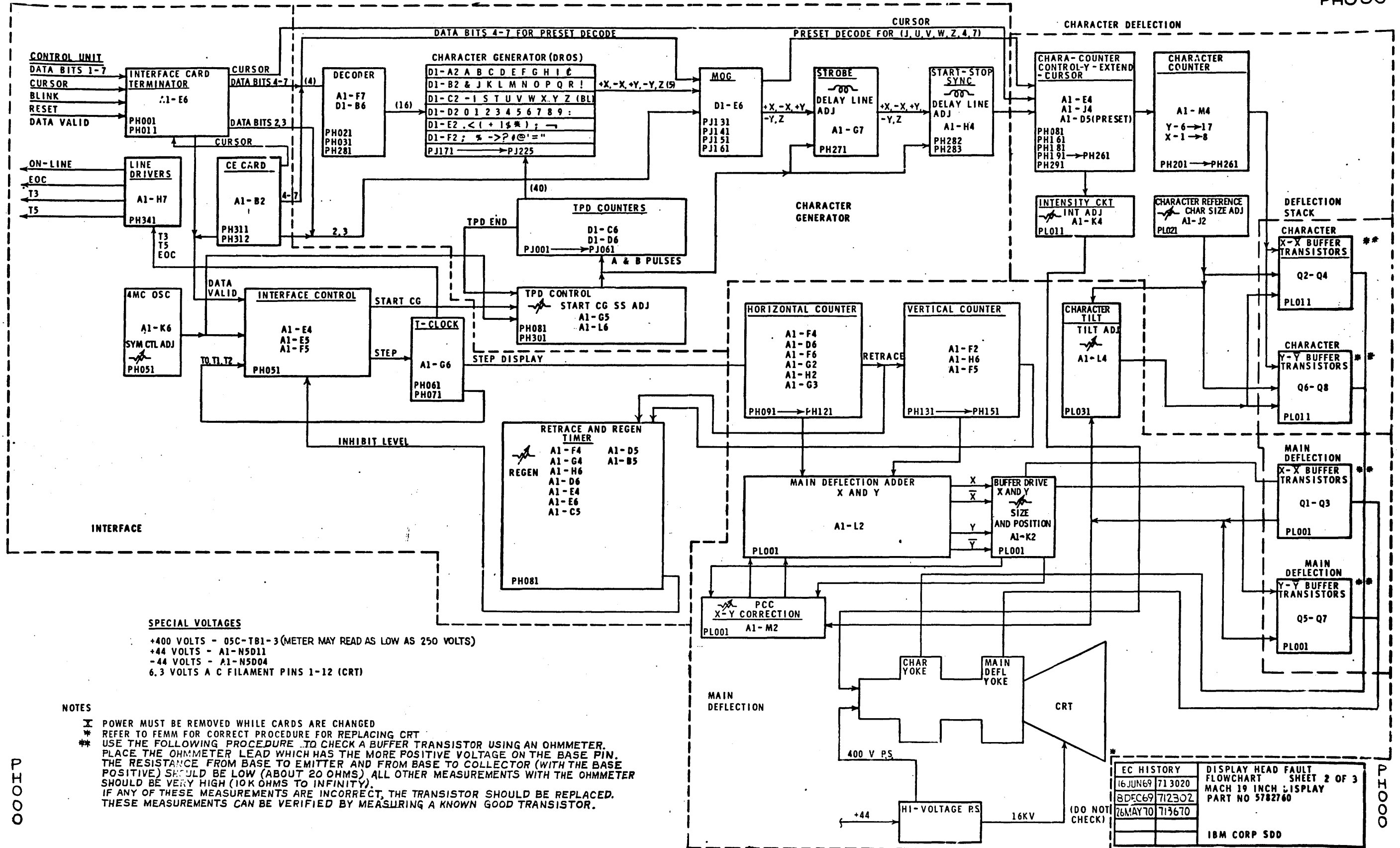


Figure 18-1-2. 19" Display Head

226

PH000

PH000

1.0 SINGLE SHOT ADJUSTMENT:

SET EACH SINGLE SHOT OUTPUT WITH AN OSCILLOSCOPE TO THE NOMINAL SETTING AS INDICATED IN THE FOLLOWING PROCEDURE:

1.1 CE CARD ADJUSTMENTS (SEE SHEET 1 OF 3)

1.1.1 SELECT DOUBLE CARD (CE TEST CARD) AND PLACE IN HOME LOCATION 05C-A1B2. SYNC SCOPE INTERNAL. SWITCH TO OFF LINE MODE (SWITCH 1 ROW B). THIS WILL GIVE A NEGATIVE LEVEL AT 05C-A1B2J11
 NOTE: FOR THE FOLLOWING TWO SINGLE SHOT ADJUSTMENTS, IT IS NECESSARY TO USE THE ON/OFF LINE SWITCH (SWITCH 1 ROW B)

1.1.2 (CE RESET SS) WITH A POSITIVE GOING INPUT SIGNAL AT B2J10, ADJUST SS1 (ROW C) FOR A 100 ±10 USEC WIDTH NEGATIVE PULSE AT B2G04

1.1.3 (CE DATA VALID SS) WITH A POSITIVE GOING INPUT SIGNAL AT B2G04 ADJUST SS3 (ROW C) FOR A MINIMUM WIDTH NEGATIVE PULSE AT B2G02, 1.5 ±0.25 USEC

1.2 SINGLE SHOT-HOME LOCATION 05C-A1G5

1.2.1 DATA VALID SS
 INSERT CARD IN SPARE LOCATION 05C-A1C7. CONNECT JUMPER BETWEEN B2J11 AND C7B03. FLIP ON LINE-OFF LINE SWITCH ON CE CARD AND ADJUST MIDDLE POTENTIOMETER ON CARD IN LOCATION C7 FOR .3 MICROSECONDS ±5% NEGATIVE OUTPUT AT C7D13. LOGIC REFERENCE PAGE PH061

1.2.2 START TPD
 CONNECT JUMPER BETWEEN B2J11 AND C7D04. FLIP ON LINE-OFF LINE SWITCH ON CE CARD AND ADJUST BOTTOM POTENTIOMETER ON CARD IN LOCATION C7 FOR .8 MICROSECONDS NEGATIVE OUTPUT AT C7B13. LOGIC REFERENCE PAGE PH081

1.3 INHIBIT START CLOCK

SINGLE SHOT-HOME LOCATION 05C-A1G4
 INSERT CARD IN SPARE LOCATION 05C-A1C7. CONNECT JUMPER BETWEEN B2J11 AND C7B12. CONNECT JUMPER BETWEEN C7B04 AND C7B03. FLIP ON LINE-OFF LINE SWITCH ON CE CARD AND ADJUST BOTTOM POTENTIOMETER ON CARD IN LOCATION C7 FOR 105 MICROSECONDS ±5% NEGATIVE OUTPUT AT C7D04

1.4 REGEN SS

SINGLE SHOT CARD - HOME LOCATION 05C-A1C5
 INSERT CARD IN SPARE LOCATION 05C-A1C7. CONNECT JUMPER BETWEEN B2J11 AND C7B03, C7D02 AND C7D05. FLIP ON LINE-OFF LINE SWITCH ON CE CARD AND ADJUST POTENTIOMETER ON CARD IN LOCATION C7 FOR 8 MILLISECONDS ±5% NEGATIVE OUTPUT AT C7B10

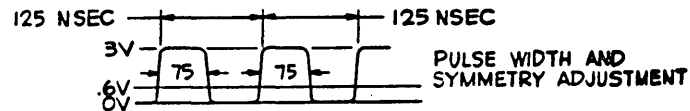
1.5 REGEN SS

SINGLE SHOT-HOME LOCATION 05C-A1B5

1.5.1 USE SAME PROCEDURE AS IN SECTION 1.4

1.5.2 A AND B PULSE WIDTH AND SYMMETRY

SCOPE "A OR B" DELAY PULSE AT 05C-A1G7D02. ADJUST POTENTIOMETERS ON CARD IN LOCATION 05C-A1I6 FOR 75 NSEC POSITIVE PULSES. FOR OSCILLATOR SYMMETRY ADJUST POTENTIOMETER ON CARD IN LOCATION 05C-A1K6 FOR BALANCED WAVE SHAPE. NOTE: INITIAL DELAY SETTING MUST BE MADE ON CARD AT 05C-A1G7 AS PER PARAGRAPH 1.7.2



1.6 DELAY LINE ADJUSTMENT

JUMPER AND DELAY ARRANGEMENT FOR DROS GATING AND START STOP SYNC CARDS:

PIN	1	2-3	4-5	6-7	8-9	10-11	12
FUNCTION	INPUT	50	40	20	10	5	OUTPUT
EXAMPLE:	90 NANoseconds: INSERT JUMPERS 1-2, 3-4, 5-12						

1.7 DROS GATING CARD - HOME LOCATION 05C-A1G7

1.7.1 THE PURPOSE OF THIS ADJUSTMENT IS TO POSITION THE "A OR B DELAYED PULSES" SUCH THAT THE OUTPUT PULSE OBTAINED FROM THE GATE HAS A CONSTANT WIDTH WITH MINIMUM SKEW

1.7.2 INITIAL DELAY SETTING--ADJUST THE DELAY LINE FOR 65 NANoseconds AS SHOWN IN PARAGRAPH 1.6

1.7.3 INSERT CARD IN HOME LOCATION. SELECT CHARACTER "A" (BIT 7) AND COMPARE THE +X, -X, +Y, -Y AND INTENSITY PULSES COMING FROM THE DROS (LOGIC PAGE PH271) WITH THE SAMPLE PULSE AT 05C-A1G7D02 (LOGIC PAGE PH271)

IF THE SAMPLE PULSE IS NARROWER THAN THE DROS PULSE, THE SAMPLE PULSE SHOULD FALL WITHIN THE DROS PULSES. IF THE SAMPLE PULSE IS WIDER THAN THE DROS PULSE, THE SAMPLE PULSE SHOULD COVER THE DROS PULSES. ADJUST THE DELAY SO THAT THIS CONDITION IS OPTIMIZED.

1.8 START - STOP SYNC CARD - HOME LOCATION 05C-A1H4

1.8.1 THE PURPOSE OF THIS ADJUSTMENT IS TO ESTABLISH THE CORRECT SAMPLE TIME OF THE X AND Y STORAGE TRIGGERS, NOMINAL 30 NANoseconds.

1.8.2 DELAY LINE SHALL BE SET ACCORDING TO THE PROCEDURE DESCRIBED BELOW. USE THE NOMINAL TIMING FOR INITIAL SETTING. THE DELAY TIME CAN BE VARIED WITHIN THE MINIMUM AND MAXIMUM RANGE FOR FINE ADJUSTMENT DURING THE ALIGNMENT PROCEDURE.

1.8.3 SET UP PROCEDURES:

1.8.3.1 SWITCH CE CARD TO "OFF LINE" MODE. SET DATA SWITCHES FOR CHARACTER "X" (CHARACTER CODE 1100111)

1.8.3.2 SYNC THE OSCILLOSCOPE POSITIVE AT PIN 05C-A1H5D13.

1.8.3.3 CONNECT PROBE 1 AT THE FOLLOWING POINT:



1.8.3.4 CONNECT PROBE 2 TO THE "A OR B DELAY PULSE" AT 05C-A1H4D05. ADJUST THE DELAY LINE SO THAT THE POSITIVE TRANSITION OF THE "DELAYED PULSE" LAGS THE POSITIVE TRANSITION ON PROBE 1 BY 30 ±5 NANoseconds AT THE 20% POINT

NOTE: BEFORE REMOVING OR INSERTING CARDS SET THE DISPLAY HEAD POWER SWITCH TO OFF (LOCATED ON BACK OF FRAME 05)

2.0 INTENSITY:

2.1 THE INTENSITY CARD IS LOCATED AT 05C-A1K4. TURN INTENSITY CONTROL FULLY CCW AND THEN ADJUST "BIAS ADJUST" POTENTIOMETER ON INTENSITY CARD SO THAT THE RETRACE LINES ARE VISIBLE. NOW ADJUST THIS POTENTIOMETER UNTIL THESE LINES (OR A DOT WHICH APPEARS IN THE UPPER LEFT CORNER OF THE CRT DURING A RESET CONDITION) JUST DISAPPEAR. INTENSITY CONTROL NOW CAN BE ADJUSTED TO PRODUCE DESIRED BRIGHTNESS

NOTE: IF THE RETRACE LINES (OR RESET DOT) CANNOT BE MADE VISIBLE WITH THE BIAS ADJUST POTENTIOMETER, TURN THE POTENTIOMETER COUNTER-CLOCKWISE TO STOP. THEN ADJUST THE INTENSITY CONTROL FOR DESIRED BRIGHTNESS

2.2 FOCUS

THE SPOT QUALITY OF THIS DISPLAY IS SUCH THAT NO OPERATOR FOCUS IS REQUIRED

CE FOCUS ADJUSTMENT IS PROVIDED. CRT GRID 4 (SINGLE LEAD #5 WITH RING TONGUE TERM) MAY BE RETURNED TO EITHER +400 ±15% VOLTS (05C-TB1-3), 267 VOLTS ±15% (05C-TB1-4), 133 VOLTS ±15% (05C-TB1-5) OR GROUND (05C-TD1-6). SELECT WHICHEVER VOLTAGE GIVES BETTER FOCUS OVER THE ENTIRE DISPLAYED IMAGE

3.0 DISPLAY ADJUSTMENT AND MEASUREMENT:

3.1 DEFLECTION YOKE ADJUSTMENT

3.1.1 POSITION MASK AGAINST FRONT OF DISPLAY FRAME AND SECURE WITH TAPE. REFER TO FEMM FOR BEZEL AND FRAME REMOVAL

3.1.2 LOOSEN THE YOKE CLAMP

3.1.3 PUSH THE YOKE FORWARD SO THAT IT SEATS FIRMLY AGAINST THE CRT BELL

3.1.4 ROTATE THE YOKE SO THAT THE DISPLAY FRAME IS PARALLEL WITH THE GUIDELINES OF MASK, P/N 5787159

3.1.5 TIGHTEN THE YOKE CLAMP SO AS TO HOLD THE YOKE FIRMLY IN POSITION

3.2 ADJUST THE IMAGE TO THE VALUES GIVEN BELOW, WITH THE FOUR POTS. LOCATED ON 05C-A1K2. THE TOP TWO CONTROLS ADJUST HEIGHT AND VERTICAL CENTERING WHILE THE BOTTOM TWO ADJUST WIDTH AND HORIZONTAL CENTERING. CENTER THE DISPLAY ON THE TUBE WITH MASK A AS A GUIDE. USE A FULL PATTERN OF "H" 'S FOR WIDTH ADJUSTMENT, AND A FULL PATTERN FOR "E" 'S FOR HEIGHT ADJUSTMENT

3.2.1 X-Y PIN CUSHION AND KEYSTONE CORRECTION

IMAGE PIN CUSHIONING AND KEYSTONING ARE CORRECTED BY ADJ THE FOUR POTS ON THE CARD IN LOC 05C-A1M2. THE TOP AND BOTTOM POTS CONTROL THE TOP/BOTTOM AND LEFT/RIGHT PIN CUSHIONING RESPECTIVELY WHILE THE SECOND AND THIRD POTS CONTROL THE LEFT/RIGHT AND TOP/BOTTOM WIDTH RATIOS RESPECTIVELY

3.2.2 THE ADJ SHALL BE MADE SUCH THAT THE BOUNDARIES OF THE DISPLAY IMAGE SHALL FALL WITHIN THE GUIDELINES OF THE MASK. BOTH IMAGE SIZE AND IMAGE CENTERING SHALL BE CAPABLE OF MOVING ±.500 (12.7) FROM THE NOMINAL SETTING AFTER BEING ADJUSTED TO ITS PROPER DISCERNIBLE SETTING

3.4 IMAGE DRIFT

3.4.1 SHORT TERM

THERE WILL BE NO DISCERNIBLE MOVEMENT OF ANY POINT OF A CHARACTER FROM A REFERENCE CROSSHAIR OVER A PERIOD OF 70 SECONDS WHEN VIEWED FROM A MINIMUM DISTANCE OF 18,000 INCHES

4.0 CHARACTER ADJUSTMENTS

4.1 OVERDRIVE

4.1.1 WITH A FULL DISPLAY OF "B" 'S ADJUST THE OVERDRIVE POT LOCATED IN 05C-A1I2 UNTIL THE BOTTOM LINES OF THE CHARACTER JUST CLOSE. CHARACTERS IN THE FIRST COLUMN WILL NOT BE AFFECTED BY THE OVERDRIVE POTENTIOMETER

4.2 CHARACTER SIZE

THE CHARACTER SIZE IS ADJUSTABLE. THE POTENTIOMETER IN LOCATION 01A-A1J2 WILL CHANGE THE SIZE OF THE HEIGHT AND WIDTH SIMULTANEOUSLY (THE RATIO OF THE HEIGHT/WIDTH IS CONSTANT) THE SETTING OF THIS POTENTIOMETER CAN BEST BE DONE BY ENTERING VARIOUS CHARACTERS ON THE SCREEN AND THEN ADJUSTING FOR THE BEST COMPROMISE BETWEEN SEPERATION OF CHARACTERS AND CONTINUITY BETWEEN ADJACENT CHARACTERS

4.3 CHARACTER TILT

4.3.1 CHARACTER TILT CORRECTION CARD IS LOCATED AT 05C-A1I4

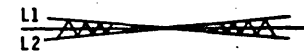
CAUTION: THIS CARD MUST NOT BE INSERTED OR REMOVED WITH POWER ON.

4.3.2 ADJUSTMENT OF CHARACTER CORRECTION CARD IS AS FOLLOWS:

4.3.2.1 SYNC SCOPE ONE PER FRAME (05C-J2D13)

4.3.2.2 ADJUST THE POT. UNTIL THE SIGNAL AT L4J09 HAS AN AVERAGE VALUE OF 6 VOLTS ±1 VOLT. AMPLITUDE OF THIS SIGNAL IS APPROXIMATELY 4 VOLTS PEAK TO PEAK. THIS IS A COARSE ADJUSTMENT

4.3.2.3 ADJUST THE POT. UNTIL THE SIGNAL AT L4G13 IS SYMMETRICAL. SEE BELOW



4.3.2.4 FOR FINAL ADJUSTMENT, OBSERVE A DISPLAY OF CHARACTERS SUCH AS "P" AND ADJUST THE POT. FOR MINIMUM TILT IN ALL FOUR CORNERS

EC HISTORY	DISPLAY HEAD FAULT
16JUN69 713020	FLOWCHART SHEET 3 OF 3
8DEC69 712302	MACH 19 INCH DISPLAY
26MAY70 713670	PART NO 5782760
	IBM CORP SDD

Figure 18-1-3. 19" Display Head Adjustments

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